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# Bayesian Statistics and Data Analysis

## Lecture 5

Måns Magnusson

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Thanks to Aki Vehtari, Aalto University

- Monte Carlo recap
- Markov Chain Monte Carlo (MCMC)
  - Gibbs sampling
  - Metropolis-Hastings
- Diagnostics
  - Warm-up
  - Convergence
  - Convergence
  - $S_{\text{eff}}$ , MCSE, and autocorrelation



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# It's all about expectations

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$$E_{p(\theta|y)}[f(\theta)] = \int f(\theta) p(\theta|y) d\theta,$$

$$\text{where } p(\theta|y) = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$$

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We can easily evaluate  $p(y|\theta)p(\theta)$  for any  $\theta$ , but the integral  $\int p(y|\theta)p(\theta)d\theta$  is usually difficult.

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- Monte Carlo methods which can sample from  $p(\theta^{(s)}|y)$  using only  $q(\theta^{(s)}|y)$

$$E_{p(\theta|y)}[f(\theta)] \approx \frac{1}{S} \sum_{s=1}^S f(\theta^{(s)})$$

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- Monte Carlo methods we have discussed so far
    - Inverse CDF works for 1D



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    - Inverse CDF works for 1D
    - Analytic transformations work for only certain distributions



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  - Grid methods works in less than a few dimensions





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  - Markov chain Monte Carlo (Ch 11-12)



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- What to do in high dimensions?
  - Markov chain Monte Carlo (Ch 11-12)
  - Laplace, Variational\*, EP\* (Ch 4, 13\*, next course)



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# Markov chains

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- Andrey Markov proved weak law of large numbers and central limit theorem for certain dependent-random sequences, which were later named Markov chains
- The probability of each event depends only on the state attained in the previous event (or finite number of previous events)

$$p(\theta_t | \theta_{t-1}, \theta_{t-2}, \dots) = p(\theta_t | \theta_{t-1})$$





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- Under some assumptions  $p(\theta_t | \theta_{t-1})$  will converge (in total variation) to *one* **stationary distribution**  $p(\theta)$



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- Under some assumptions  $p(\theta_t | \theta_{t-1})$  will converge (in total variation) to *one* **stationary distribution**  $p(\theta)$
- Goal in MCMC: Construct a **transition distribution** with  $p(\theta|y)$  as the **stationary distribution**



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# Markov chain Monte Carlo (MCMC)

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  - + generic
  - + combine sequence of easier Monte Carlo draws to form a Markov chain



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  - + chain goes where most of the posterior mass is
  - + asymptotically chain spends the  $\alpha\%$  of time where  $\alpha\%$  posterior mass is



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  - + asymptotically chain spends the  $\alpha\%$  of time where  $\alpha\%$  posterior mass is
  - + central limit theorem holds for expectations
    - draws are dependent
    - construction of efficient Markov chains is not always easy





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- Set of random variables  $\theta_1, \theta_2, \dots$ , so that with all values of  $t$ ,  $\theta_t$  depends only on the previous  $\theta_{(t-1)}$

$$p(\theta_t | \theta_1, \dots, \theta_{(t-1)}) = p(\theta_t | \theta_{(t-1)})$$



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- Chain has to be initialized with some starting point  $\theta_0$



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- Transition distribution  $T_t(\theta_t | \theta_{t-1})$  (may depend on  $t$ )



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- Chain has to be initialized with some starting point  $\theta_0$
- Transition distribution  $T_t(\theta_t | \theta_{t-1})$  (may depend on  $t$ )
- Choose a transition distribution so the stationary distribution of the Markov chain is  $p(\theta | y)$



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- Alternate sampling from conditional distributions
- Basic algorithm, for  $j \in \{1, \dots, J\}$

sample  $\theta_{j,t}$  from  $p(\theta_j | \theta_{-j,t-1}, y)$ ,

where  $\theta_{j,t-1} = (\theta_{1,J}, \dots, \theta_{j-1,t}, \theta_{j+1,t-1}, \dots, \theta_{t-1,J})$

- Will converge (in total variation) to  $p(\theta|y)$  as  $T \rightarrow \infty$



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- 1D sampling ( $|j| = 1$ ) is generally easy



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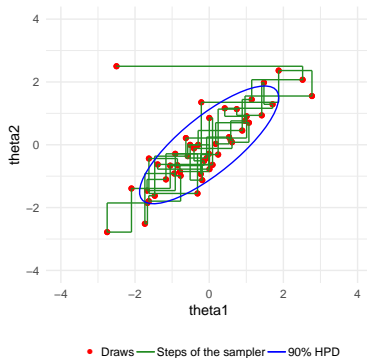
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- Related to the (stochastic) EM algorithm



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# Gibbs sampling



demo





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- BUGS / WinBUGS / OpenBUGS / JAGS



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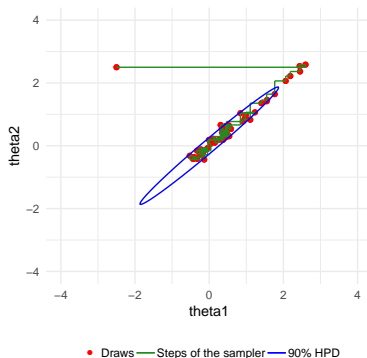
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- For not so easy conditionals, use e.g. inverse-CDF
- Several parameters can be updated in blocks (*blocking*)
- Slow if parameters are highly dependent in the posterior...



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# Gibbs sampling



demo



# Sampling conditional vs joint

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- How about sampling  $\theta$  jointly?
  - e.g. it is easy to sample from multivariate normal





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- How about sampling  $\theta$  jointly?
  - e.g. it is easy to sample from multivariate normal
- Can we use that to form a Markov chain?



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# The Metropolis algorithm

- Algorithm

1. starting point  $\theta^0$

2.  $t = 1, 2, \dots$

- (a) pick a proposal  $\theta^*$  from a **proposal distribution**  $J_t(\theta^*|\theta_{t-1})$ .

Proposal distribution has to be symmetric, i.e.

$$J_t(\theta_a|\theta_b) = J_t(\theta_b|\theta_a), \text{ for all } \theta_a, \theta_b$$



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- (b) calculate acceptance ratio

$$r = \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)}$$



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- (b) calculate acceptance ratio

- (c) set

$$r = \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)}$$

$$\theta_t = \begin{cases} \theta^* & \text{with probability } \min(r, 1) \\ \theta_{t-1} & \text{otherwise} \end{cases}$$



- Monte Carlo recap
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# The Metropolis algorithm

- Algorithm

1. starting point  $\theta^0$

2.  $t = 1, 2, \dots$

- (a) pick a proposal  $\theta^*$  from a **proposal distribution**  $J_t(\theta^*|\theta_{t-1})$ .

Proposal distribution has to be symmetric, i.e.

$J_t(\theta_a|\theta_b) = J_t(\theta_b|\theta_a)$ , for all  $\theta_a, \theta_b$

- (b) calculate acceptance ratio

- (c) set 
$$r = \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)}$$
$$\theta_t = \begin{cases} \theta^* & \text{with probability } \min(r, 1) \\ \theta_{t-1} & \text{otherwise} \end{cases}$$

ie, if  $p(\theta^*|y) > p(\theta_{t-1}|y)$  accept the proposal always  
and otherwise accept the proposal with probability  $r$



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- rejection of a proposal increments the time  $t$  also by one ie, the new state is the same as previous
- step c is executed by generating a random number from  $\mathcal{U}(0, 1)$
- $p(\theta^*|y)$  and  $p(\theta_{t-1}|y)$  have the same normalization terms, and thus instead of  $p(\cdot|y)$ , unnormalized  $q(\cdot|y)$  can be used, **as the normalization terms cancel out!**





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- Example: one bivariate observation  $(y_1, y_2)$ 
  - bivariate normal distribution with unknown mean and known covariance

$$\begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \Big| y \sim \mathcal{N} \left( \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$$

- proposal distribution  $J_t(\theta^* | \theta_{t-1}) = \mathcal{N}(\theta^* | \theta_{t-1}, \sigma_p^2)$

demo



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# Why Metropolis algorithm works

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- Theoretically
  1. Prove that simulated series is a Markov chain which has unique stationary distribution
  2. Prove that this stationary distribution is the desired target distribution



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1. Prove that simulated series is a Markov chain which has unique stationary distribution
  - a) irreducible
  - b) aperiodic
  - c) recurrent / not transient



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  - c) recurrent / not transient
    - = probability to return to a state  $i$  is 1 as  $T \rightarrow \infty$ 
      - holds for a random walk on any proper distribution (except for trivial exceptions)



# Why Metropolis algorithm works

2. Prove that this stationary distribution is the desired target distribution  $p(\theta|y)$

- consider starting algorithm at time  $t - 1$  with a draw  $\theta_{t-1} \sim p(\theta|y)$

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which is the same as the probability of transition from  $\theta_a$  to  $\theta_b$ , since we have required that  $J_t(\cdot|\cdot)$  is symmetric



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which is the same as the probability of transition from  $\theta_a$  to  $\theta_b$ , since we have required that  $J_t(\cdot|\cdot)$  is symmetric

- since their joint distribution is symmetric,  $\theta_t$  and  $\theta_{t-1}$  have the same marginal distributions, and so  $p(\theta|y)$  is the stationary distribution of the Markov chain of  $\theta$



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- Generalization of Metropolis algorithm for non-symmetric proposal distributions
  - acceptance ratio includes ratio of proposal distributions

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# Metropolis-Hastings algorithm

---

- Ideal proposal distribution is the distribution itself
  - $J(\theta^*|\theta) \equiv p(\theta^*|y)$  for all  $\theta$
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  - independent draws
  - not usually feasible

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    - many steps accepted, but the chain moves slowly due to small steps
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demo



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demo

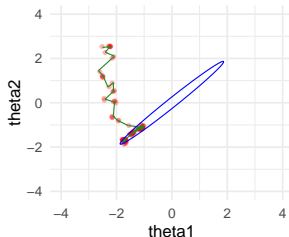
- Generic rule for rejection rate is 60-90%



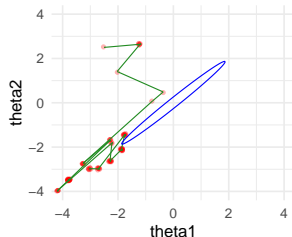
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- Specific case of Metropolis-Hastings algorithm
  - single updated (or blocked)
  - proposal distribution is the conditional distribution
    - proposal and target distributions are same
    - acceptance probability is 1



- Usually doesn't scale well to high dimensions
  - if the shape doesn't match the whole distribution, the efficiency drops



• Draws — Steps of the sampler — 90% HPI



• Draws — Steps of the sampler — 90% HPI



## Warm-up

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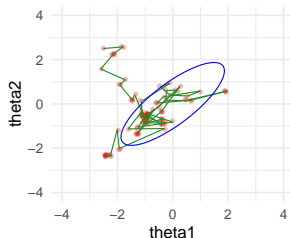
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## Warm-up

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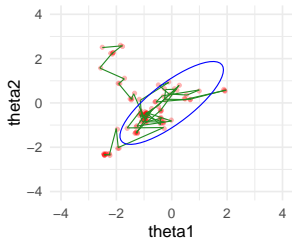
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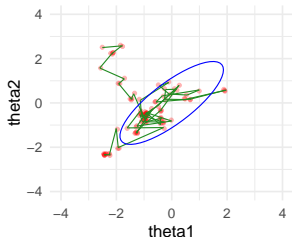




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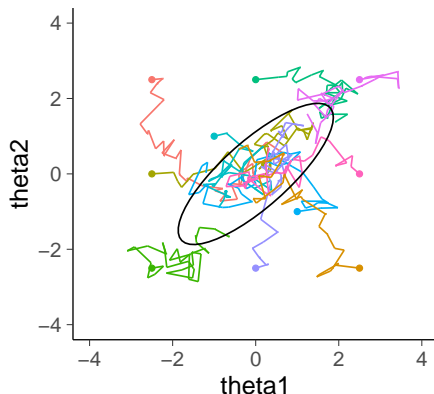
- Warm-up period = (non-representative) draws from the beginning of the Markov chain
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  - warm-up may include also phase for adapting algorithm parameters
- Also called **burn-in**



## Assesing convergence: Several chains

- Use of several chains make convergence diagnostics easier
- Start chains from different starting points – preferably overdispersed

No convergence



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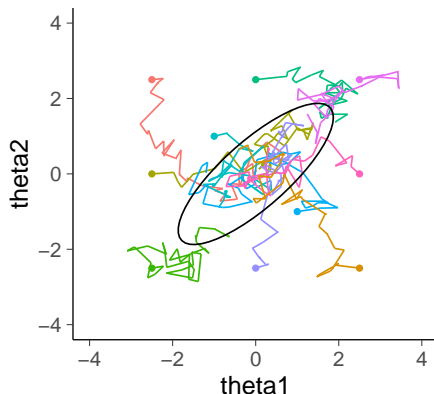


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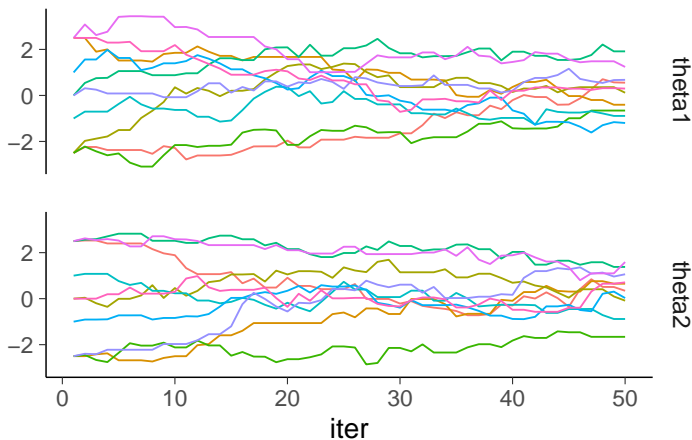


- Remove draws from the beginning of the chains and run chains long enough so that it is not possible to distinguish where each chain started and the chains are well mixed



# Several chains

## Not converged



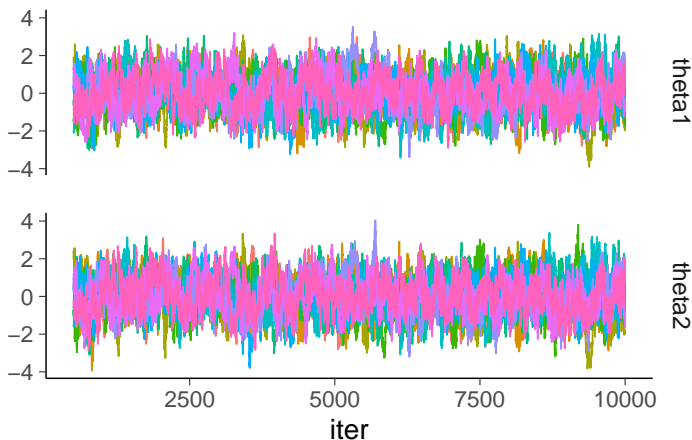
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## Several chains

### Visually converged

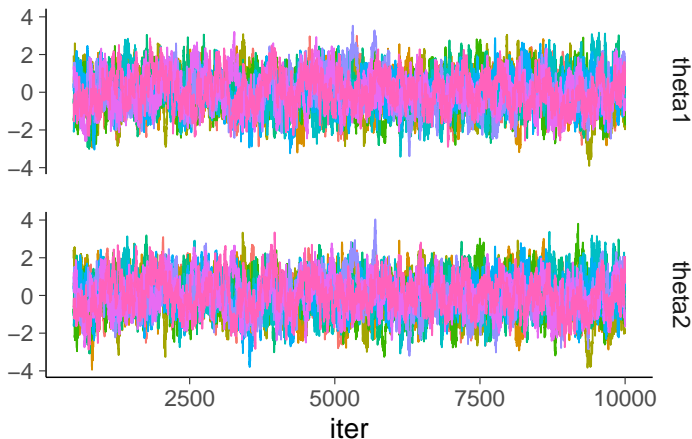




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## Several chains

### Visually converged



Visual convergence check is not sufficient



# $\hat{R}$ : comparison of within and between variances of the chains

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- BDA3:  $\hat{R}$  aka *potential scale reduction factor* (PSRF)
- Compare means and variances of the chains

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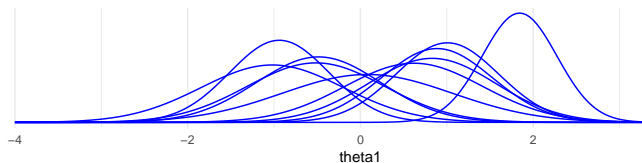


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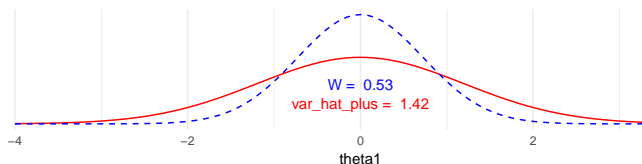
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 $W$  = within chain variance estimate  
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50 warmup, 50 post warmup iterations



Rhat = 1.64





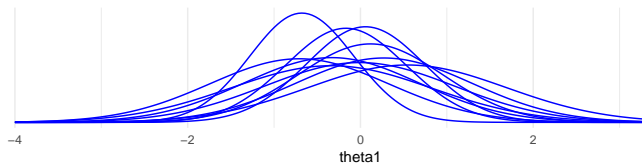


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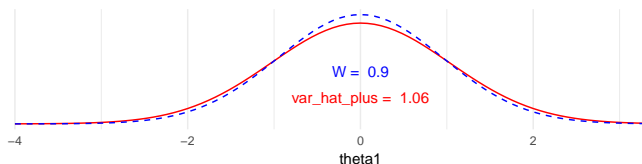
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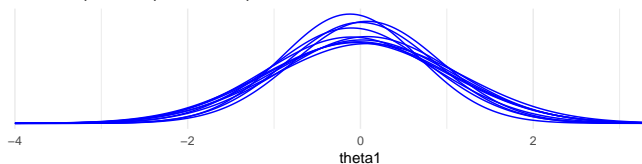




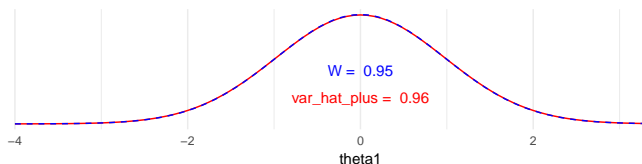
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Rhat = 1





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$\hat{R}$

- $M$  chains, each having  $N$  draws (with new  $\hat{R}$ -hat notation)

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- $B/N$  is variance of the means of the chains
- Estimate total variance  $\text{var}(\theta|y)$  as a weighted mean of  $W$  and  $B$

$$\widehat{\text{var}}^+(\theta|y) = \frac{N-1}{N} W + \frac{1}{N} B$$



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  - single chains have not yet visited all points in the distribution
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- As  $\widehat{\text{var}}^+(\theta|y)$  overestimates and  $W$  underestimates, compute

$$\hat{R} = \sqrt{\frac{\widehat{\text{var}}^+}{W}}$$

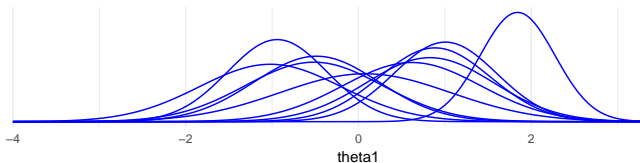


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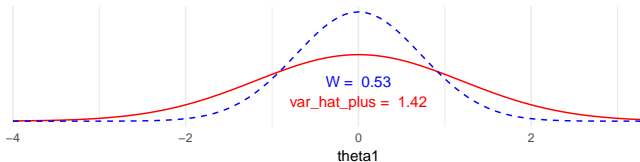
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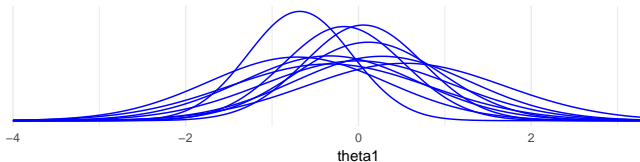


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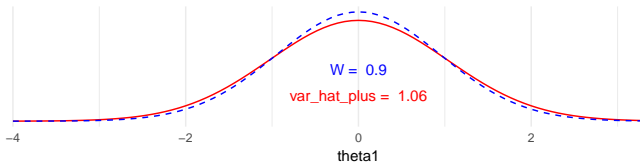
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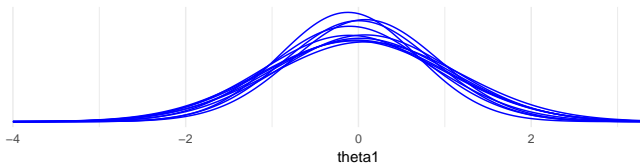


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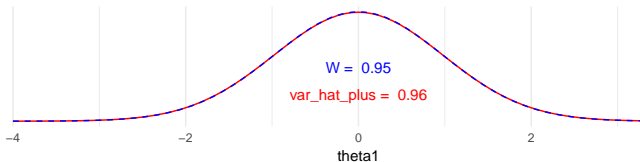
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$\hat{R}$

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$$\hat{R} = \sqrt{\frac{\widehat{\text{var}}^+}{W}}$$

- Estimates how much the scale of  $\psi$  could reduce if  $N \rightarrow \infty$
- $\hat{R} \rightarrow 1$ , when  $N \rightarrow \infty$
- if  $\hat{R}$  is big (e.g.,  $R > 1.01$ ), keep sampling



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- if  $\hat{R}$  is big (e.g.,  $R > 1.01$ ), keep sampling
- If  $\hat{R}$  close to 1, it is still possible that chains have not converged
  - if starting points were not overdispersed
  - distribution far from normal (especially if infinite variance)
  - just by chance when  $N$  is finite



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    - $S_{\text{eff}}$ , MCSE, and autocorrelation
- BDA3: split- $\hat{R}$
  - Examines *mixing* and *stationarity* of chains
  - To examine stationarity chains are split to two parts
    - after splitting, we have  $M$  chains, each having  $N$  draws
    - scalar draws  $\theta_{nm}$  ( $n = 1, \dots, N; m = 1, \dots, M$ )
    - compare means and variances of the split chains





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# MCMC draws are dependent

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- Monte Carlo estimates still valid (central limit theorem holds)

$$E_{p(\theta|y)}[f(\theta)] \approx \frac{1}{S} \sum_{s=1}^S f(\theta^{(s)})$$

- Estimation of Monte Carlo error is more difficult
  - evaluation of *effective* sample size

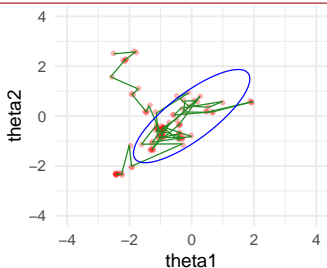


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- Auto correlation function
  - describes the correlation given a certain lag
  - can be used to compare efficiency of MCMC algorithms and parameterizations



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# Auto correlation



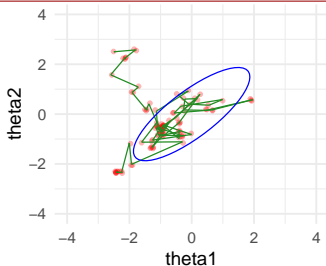
• Draws — Steps of the sampler — 90% HPI





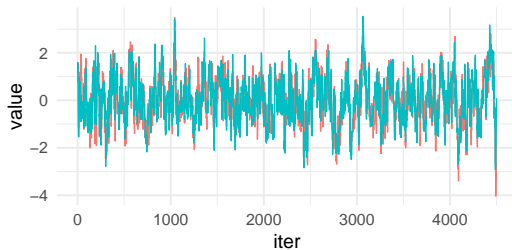
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## Trends

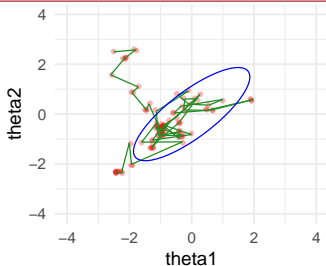


—  $\theta_1$  —  $\theta_2$



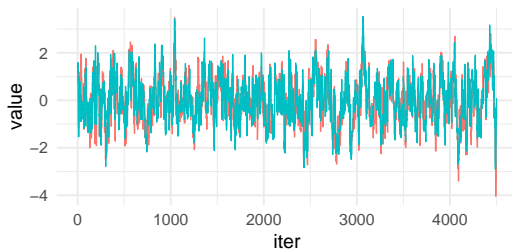
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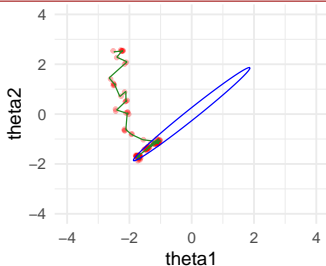


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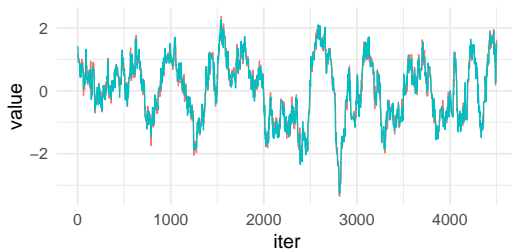
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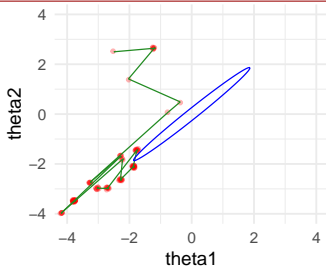


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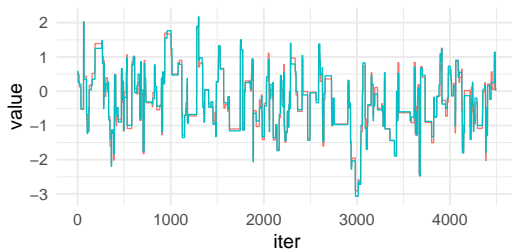
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— theta1 — theta2



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# Time series analysis

---

- Time series analysis can be used to estimate Monte Carlo error in case of MCMC
- For expectation  $\bar{\theta}$

$$\text{Var}[\bar{\theta}] = \frac{\sigma_{\theta}^2}{S_{E_{\max}}}$$

where  $S_{E_{\max}} = S/\tau$ , and  $\tau$  is sum of autocorrelations



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- new R-hat paper  $S = NM$  (in BDA3  $N = nm$  and  $n_{E_{\max}} = N/\tau$ )
- BDA3 focuses on  $S_{E_{\max}}$  and not the Monte Carlo error directly  
new R-hat paper discusses more about MCSEs for different quantities





- Estimation of the autocorrelation using several chains

$$\hat{\rho}_n = 1 - \frac{W - \frac{1}{M} \sum_{m=1}^M \hat{\rho}_{n,m}}{2\widehat{\text{var}}^+}$$

where  $\hat{\rho}_{n,m}$  is autocorrelation at lag  $n$  for chain  $m$

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# Time series analysis

- Estimation of the autocorrelation using several chains

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- This combines  $\hat{R}$  and autocorrelation estimates
  - takes into account if the chains are not mixing (the chains have not converged)



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- This combines  $\hat{R}$  and autocorrelation estimates
  - takes into account if the chains are not mixing (the chains have not converged)
- BDA3 has slightly different and less accurate equation. The above equation is used in Stan 2.18+
- Compared to a method which computes the autocorrelation from a single chain, the multi-chain estimate has smaller variance



- Estimation of  $\tau$

$$\tau = 1 + 2 \sum_{t=1}^{\infty} \hat{\rho}_t$$

where  $\hat{\rho}_t$  is empirical autocorrelation

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- empirical autocorrelation function is noisy and thus estimate of  $\tau$  is noisy
- noise is larger for longer lags (less observations)

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$$\hat{\tau} = 1 + 2 \sum_{t=1}^T \hat{\rho}_t$$

- As  $\tau$  is estimated from a finite number of draws, it's expectation is overoptimistic
  - if  $\hat{\tau} > MN/20$  then the estimate is unreliable





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## Geyer's adaptive window estimator

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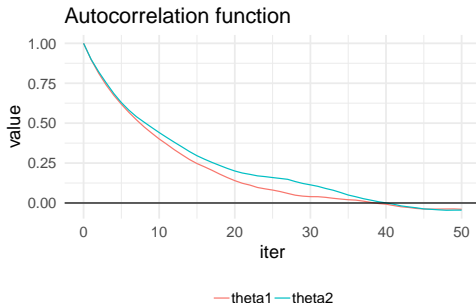
- Truncation can be decided adaptively
  - for stationary, irreducible, recurrent Markov chain
  - let  $\Gamma_m = \rho_{2m} + \rho_{2m+1}$ , which is sum of two consequent autocorrelations
  - $\Gamma_m$  is positive, decreasing and convex function of  $m$



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  - let  $\Gamma_m = \rho_{2m} + \rho_{2m+1}$ , which is sum of two consequent autocorrelations
  - $\Gamma_m$  is positive, decreasing and convex function of  $m$
- Initial positive sequence estimator (Geyer's IPSE)
  - Choose the largest  $m$  so, that all values of the sequence  $\hat{\Gamma}_1, \dots, \hat{\Gamma}_m$  are positive





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# Effective sample size

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Effective sample size  $ESS = S_{E_{\max}} \approx S/\hat{\tau}$

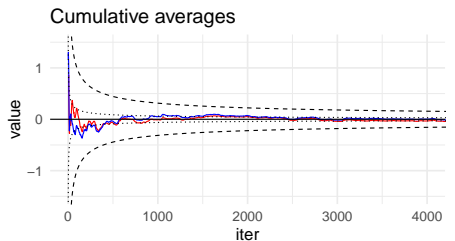
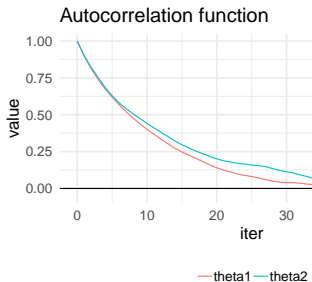
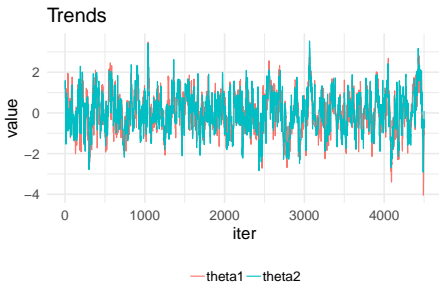
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# Effective sample size

$$\text{Effective sample size } ESS = S_{E_{\max}} \approx S / \hat{\tau}$$



$$\hat{\tau} = 1 + 2 \sum_{t=1}^T \hat{\rho}_t$$

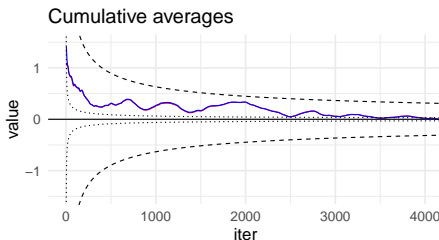
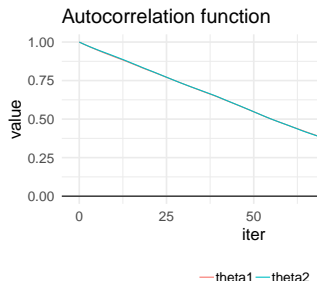
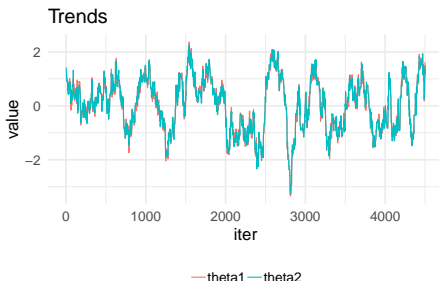
$$\approx 24$$



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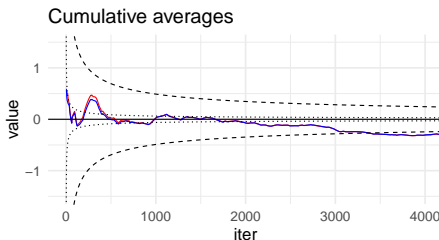
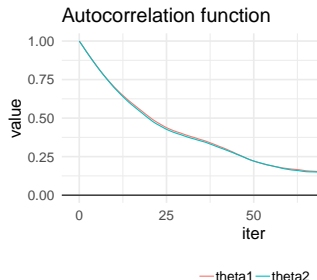
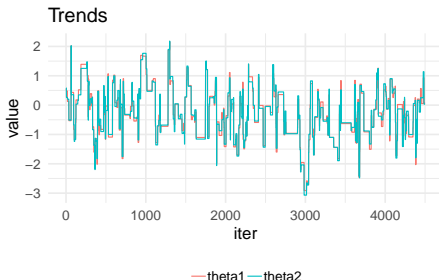
$$\approx 104$$



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# Effective sample size

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$$\approx 63$$



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- Nonlinear dependencies
  - optimal proposal depends on location



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- Funnels
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- Long-tailed with non-finite variance and mean
  - central limit theorem for expectations does not hold