

- Monte Carlo recap
- Markov Chain Monte Carlo (MCMC)
 - Gibbs sampling
 - Metropolis-Hastings
- Diagnostics
 - Warm-upConvergence
 - S_{eff}, MCSE, and autocorrelation

Bayesian Statistics and Data Analysis Lecture 5

Måns Magnusson Department of Statistics, Uppsala University Thanks to Aki Vehtari, Aalto University



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$$E_{p(\theta|y)}[f(\theta)] = \int f(\theta)p(\theta|y)d\theta,$$
 where $p(\theta|y) = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$



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We can easily evaluate $p(y|\theta)p(\theta)$ for any θ , but the integral $\int p(y|\theta)p(\theta)d\theta$ is usually difficult.



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• Monte Carlo methods which can sample from $p(\theta^{(s)}|y)$ using only $q(\theta^{(s)}|y)$

$$E_{p(\theta|y)}[f(\theta)] \approx \frac{1}{S} \sum_{s=1}^{S} f(\theta^{(s)})$$



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- Monte Carlo methods we have discussed so far
 - Inverse CDF works for 1D



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 - Markov chain Monte Carlo (Ch 11-12)
 - Laplace, Variational*, EP* (Ch 4, 13*, next course)



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- The probability of each event depends only on the state attained in the previous event (or finite number of previous events)

$$p(\theta_t|\theta_{t-1},\theta_{t-2},...)=p(\theta_t|\theta_{t-1})$$



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- Goal in MCMC: Construct a transition distribution with $p(\theta|y)$ as the stationary distribution



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• Produce draws $\theta^{(t)}$ given $\theta^{(t-1)}$ from a Markov chain, with stationary distribution $p(\theta|y)$



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 - + generic
 - + combine sequence of easier Monte Carlo draws to form a Markov chain



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 - + asymptotically chain spends the $\alpha\%$ of time where $\alpha\%$ posterior mass is
 - + central limit theorem holds for expectations
 - draws are dependent
 - construction of efficient Markov chains is not always easy



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• Set of random variables $\theta_1, \theta_2, \ldots$, so that with all values of t, θ_t depends only on the previous $\theta_{(t-1)}$

$$p(\theta_t|\theta_1,\ldots,\theta_{(t-1)}) = p(\theta_t|\theta_{(t-1)})$$



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- Transition distribution $T_t(\theta_t|\theta_{t-1})$ (may depend on t)
- Choose a transition distribution so the stationary distribution of the Markov chain is $p(\theta|y)$



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- Alternate sampling from conditional distributions
- Basic algorithm, for $j \in \{1,...,J\}$

sample
$$\theta_{j,t}$$
 from $p(\theta_j|\theta_{-j,t-1},y)$, where $\theta_{j,t-1} = (\theta_{1,J},\ldots,\theta_{j-1,t},\theta_{j+1,t-1},\ldots,\theta_{t-1,J})$

• Will converge (in total variation) to $p(\theta|y)$ as $T \to \infty$



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- 1D sampling (|j| = 1) is generally easy



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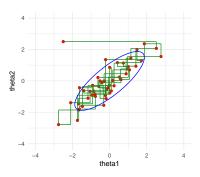
- Will converge (in total variation) to $p(\theta|y)$ as $T \to \infty$
- *j* can be multiple (blocked) parameters
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- Related to the (stochastic) EM algorithm



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Gibbs sampling



Draws — Steps of the sampler — 90% HPD

demo



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- BUGS / WinBUGS / OpenBUGS / JAGS



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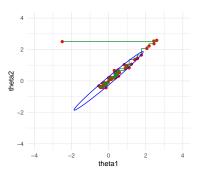
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- For not so easy conditionals, use e.g. inverse-CDF
- Several parameters can be updated in blocks (blocking)
- Slow if parameters are highly dependent in the posterior...



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Sampling conditional vs joint

- How about sampling θ jointly?
 - e.g. it is easy to sample from multivariate normal



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Sampling conditional vs joint

- How about sampling θ jointly?
 - e.g. it is easy to sample from multivariate normal
- Can we use that to form a Markov chain?



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The Metropolis algorithm

- Algorithm
 - 1. starting point θ^0
 - 2. t = 1, 2, ...
 - (a) pick a proposal θ^* from a proposal distribution $J_t(\theta^*|\theta_{t-1})$.

Proposal distribution has to be symmetric, i.e. $J_t(\theta_a|\theta_b) = J_t(\theta_b|\theta_a)$, for all θ_a, θ_b



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 - (b) calculate acceptance ratio

$$r = \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)}$$



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$$\begin{aligned} r &= \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)} \\ \theta_t &= \begin{cases} \theta^* & \text{with probability min}(r,1) \\ \theta_{t-1} & \text{otherwise} \end{cases}$$



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ie, if $p(\theta^*|y) > p(\theta_{t-1}|y)$ accept the proposal always and otherwise accept the proposal with probability r



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 rejection of a proposal increments the time t also by one ie, the new state is the same as previous



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(c) set
$$\begin{aligned} r &= \frac{p(\theta^*|y)}{p(\theta_{t-1}|y)} \\ \theta_t &= \begin{cases} \theta^* & \text{with probability min}(r,1) \\ \theta_{t-1} & \text{otherwise} \end{cases}$$

- rejection of a proposal increments the time t also by one ie, the new state is the same as previous
- ullet step c is executed by generating a random number from $\mathcal{U}(0,1)$
- $p(\theta^*|y)$ and $p(\theta_{t-1}|y)$ have the same normalization terms, and thus instead of $p(\cdot|y)$, unnormalized $q(\cdot|y)$ can be used, as the normalization terms cancel out!



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 - S_{eff}, MCSE, and autocorrelation

Metropolis algorithm

- Example: one bivariate observation (y_1, y_2)
 - bivariate normal distribution with unknown mean and known covariance

$$\begin{pmatrix} \theta_1 \\ \theta_2 \end{pmatrix} \middle| \ y \sim \mathcal{N} \left(\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$$

• proposal distribution $J_t(\theta^*|\theta_{t-1}) = \mathcal{N}(\theta^*|\theta_{t-1}, \sigma_p^2)$

demo



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 Intuitively more draws from the higher density areas as jumps to higher density are always accepted and only some of the jumps to the lower density are accepted



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- Intuitively more draws from the higher density areas as jumps to higher density are always accepted and only some of the jumps to the lower density are accepted
- Theoretically
 - Prove that simulated series is a Markov chain which has unique stationary distribution
 - Prove that this stationary distribution is the desired target distribution



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- Prove that simulated series is a Markov chain which has unique stationary distribution
 - a) irreducible
 - b) aperiodic

c) recurrent / not transient



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- Prove that simulated series is a Markov chain which has unique stationary distribution
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 - = aperiodic (return times are not periodic)
 - holds for a random walk on any proper distribution (except for trivial exceptions)
 - c) recurrent / not transient
 - = probability to return to a state i is 1 as $T \to \infty$
 - holds for a random walk on any proper distribution (except for trivial exceptions)



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- 2. Prove that this stationary distribution is the desired target distribution $p(\theta|y)$
 - consider starting algorithm at time t-1 with a draw $heta_{t-1} \sim p(heta|y)$



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 - the unconditional probability density of a transition from θ_a to θ_b is

$$p(\theta_{t-1} = \theta_a, \theta_t = \theta_b) = p(\theta_a|y)J_t(\theta_b|\theta_a),$$



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$$p(\theta_t = \theta_a, \theta_{t-1} = \theta_b) = p(\theta_b|y)J_t(\theta_a|\theta_b)\left(\frac{p(\theta_a|y)}{p(\theta_b|y)}\right)$$
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$$= p(\theta_a|y)J_t(\theta_a|\theta_b),$$

which is the same as the probability of transition from θ_a to θ_b , since we have required that $J_t(\cdot|\cdot)$ is symmetric



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which is the same as the probability of transition from θ_a to θ_b , since we have required that $J_t(\cdot|\cdot)$ is symmetric

- since their joint distribution is symmetric, θ_t and θ_{t-1} have the same marginal distributions, and so $p(\theta|y)$ is the stationary distribution of the Markov chain of θ



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- Generalization of Metropolis algorithm for non-symmetric proposal distributions
 - acceptance ratio includes ratio of proposal distributions

$$r = \frac{p(\theta^*|y)/J_t(\theta^*|\theta_{t-1})}{p(\theta_{t-1}|y)/J_t(\theta_{t-1}|\theta^*)}$$



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- Generalization of Metropolis algorithm for non-symmetric proposal distributions
 - acceptance ratio includes ratio of proposal distributions

$$r = \frac{\rho(\theta^*|y)/J_t(\theta^*|\theta_{t-1})}{\rho(\theta_{t-1}|y)/J_t(\theta_{t-1}|\theta^*)} = \frac{\rho(\theta^*|y)J_t(\theta_{t-1}|\theta^*)}{\rho(\theta_{t-1}|y)J_t(\theta^*|\theta_{t-1})}$$



- Monte Carlo recap
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 MCSE ---
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- Ideal proposal distribution is the distribution itself
 - $J(\theta^*|\theta) \equiv p(\theta^*|y)$ for all θ
 - acceptance probability is 1
 - independent draws
 - not usually feasible



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- After the proposal distribution shape has been selected, it is important to select the scale
 - small scale
 - → many steps accepted, but the chain moves slowly due to small steps
 - big scale
 - ightarrow long steps proposed, but many of those rejected and again chain moves slowly

demo



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demo

Generic rule for rejection rate is 60-90%



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Gibbs sampling as a special case

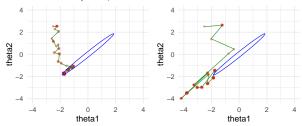
- Specific case of Metropolis-Hastings algorithm
 - single updated (or blocked)
 - proposal distribution is the conditional distribution
 - \rightarrow proposal and target distributions are same
 - ightarrow acceptance probability is 1



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Metropolis

- Usually doesn't scale well to high dimensions
 - if the shape doesn't match the whole distribution, the efficiency drops



- Draws—Steps of the sampler—90% HPI
- Draws-Steps of the sampler-90% HPI



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Warm-up

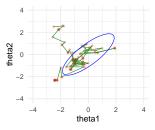
• Asymptotically chain spends the $\alpha\%$ of time where $\alpha\%$ posterior mass is



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Warm-up

- Asymptotically chain spends the $\alpha\%$ of time where $\alpha\%$ posterior mass is
 - but in finite time the initial part of the Markov chain may be non-representative



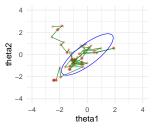
Draws—Steps of the sampler—90% HP



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Draws—Steps of the sampler—90% HPI

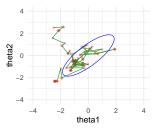
- Warm-up period = (non-representative) draws from the beginning of the Markov chain
 - remove warm-up before using samples for inference
 - warm-up may include also phase for adapting algorithm parameters



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• Draws—Steps of the sampler—90% HP

- Warm-up period = (non-representative) draws from the beginning of the Markov chain
 - remove warm-up before using samples for inference
 - warm-up may include also phase for adapting algorithm parameters
- Also called burn-in



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Assesing convergence

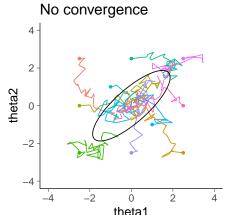
Several Markov chains make convergence diagnostics easier



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Assesing convergence

- Several Markov chains make convergence diagnostics easier
- Start chains from different starting points preferably overdispersed

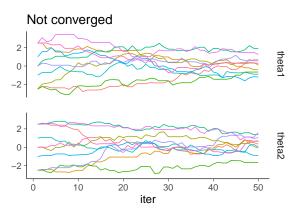


Remove warm-up draws and run chains long enough



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Several chains

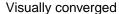


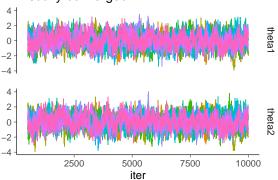


Monte Carlo recap

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Several chains

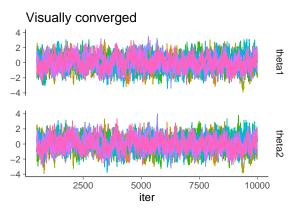






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Several chains



Visual convergence check is not sufficient



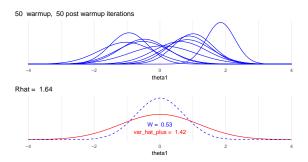
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- \widehat{R} or potential scale reduction factor (PSRF)
- Compare means and variances of the chains



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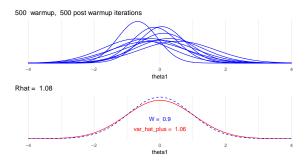
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 W = within chain variance estimate
 var_hat_plus = total variance estimate





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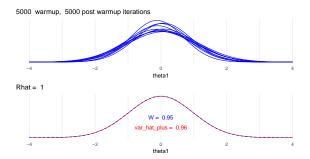
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• *M* chains, each having *N* draws



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- *M* chains, each having *N* draws
- Within chains variance W

$$W = rac{1}{M} \sum_{m=1}^{M} s_m^2$$
, where $s_m^2 = rac{1}{N-1} \sum_{n=1}^{N} (heta_{nm} - ar{ heta}_{.m})^2$



UNIVERSITET Monte Carlo recap

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Between chains variance B

$$B = \frac{N}{M-1} \sum_{m=1}^{M} (\bar{\theta}_{.m} - \bar{\theta}_{..})^{2},$$

where
$$\bar{\theta}_{.m} = \frac{1}{N} \sum_{n=1}^{N} \theta_{nm}$$
, $\bar{\theta}_{..} = \frac{1}{M} \sum_{m=1}^{M} \bar{\theta}_{.m}$



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• B/N is variance of the means of the chains



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Between chains variance B

$$\begin{split} B &= \frac{N}{M-1} \sum_{m=1}^{M} (\bar{\theta}_{.m} - \bar{\theta}_{..})^2, \\ \text{where } \bar{\theta}_{.m} &= \frac{1}{N} \sum_{n=1}^{N} \theta_{nm}, \ \bar{\theta}_{..} = \frac{1}{M} \sum_{n=1}^{M} \bar{\theta}_{.m} \end{split}$$

- B/N is variance of the means of the chains
- Estimate total variance $var(\theta|y)$ as a weighted mean of W and B

$$\widehat{\operatorname{var}}^+(\theta|y) = \frac{N-1}{N}W + \frac{1}{N}B$$



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• Estimate total variance $\mathrm{var}(\theta|y)$ as a weighted mean of W and B

$$\widehat{\operatorname{var}}^+(\theta|y) = \frac{N-1}{N}W + \frac{1}{N}B$$

 this overestimates marginal posterior variance if the starting points are overdispersed



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- Given finite N, W underestimates marginal posterior variance
 - single chains have not yet visited all points in the distribution
 - when $N \to \infty$, $E(W) \to var(\theta|y)$



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- Given finite N, W underestimates marginal posterior variance
 - single chains have not yet visited all points in the distribution
 - when $N \to \infty$, $E(W) \to var(\theta|y)$
- As $\widehat{\text{var}}^+(\theta|y)$ overestimates and W underestimates, compute

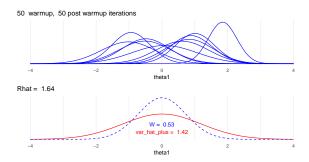
$$\widehat{R} = \sqrt{\frac{\widehat{\text{var}}^+}{W}}$$



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- BDA3: \hat{R} aka potential scale reduction factor (PSRF)
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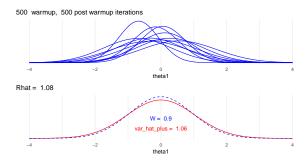




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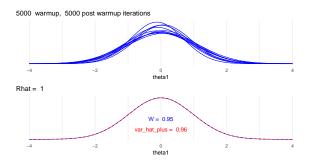




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- BDA3: \hat{R} aka potential scale reduction factor (PSRF)
- Compare means and variances of the chains
 W = within chain variance estimate
 var_hat_plus = total variance estimate





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$$\widehat{R} = \sqrt{\frac{\widehat{\mathrm{var}}^+}{W}}$$

- Estimates how much the scale could reduce if $N \to \infty$
- $\widehat{R} \to 1$, when $N \to \infty$
- If \widehat{R} is big (e.g., R > 1.01), keep sampling



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- $\widehat{R} \to 1$, when $N \to \infty$
- If \widehat{R} is big (e.g., R > 1.01), keep sampling
- If \widehat{R} close to 1, it is still possible that chains have not converged
 - if starting points were not overdispersed
 - distribution far from normal (especially if infinite variance)
 - just by chance when N is finite



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- Additional \widehat{R} methods to assess convergence
- Split- \hat{R}
 - Examines mixing and stationarity of chains
 - To examine stationarity chains are split to two parts: compare means and variances of the split chains



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- Additional \widehat{R} methods to assess convergence
- Split- \hat{R}
 - Examines mixing and stationarity of chains
 - To examine stationarity chains are split to two parts: compare means and variances of the split chains
- Rank normalized \hat{R}
 - Does not requires that the target distribution has finite mean and variance



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MCMC draws are dependent

Monte Carlo estimates still valid (central limit theorem)

$$E_{p(\theta|y)}[f(\theta)] \approx \frac{1}{S} \sum_{s=1}^{S} f(\theta^{(s)})$$

- Estimation of Monte Carlo error is more difficult
 - evaluation of *effective* sample size, S_{eff} .



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MCMC Autocorrelation

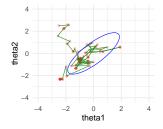
- Auto correlation function
 - describes the correlation given a certain lag
 - can be used to compare efficiency of MCMC methods



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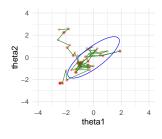
Autocorrelation

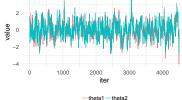




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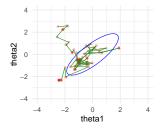


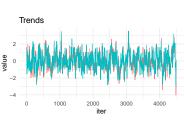
Trends



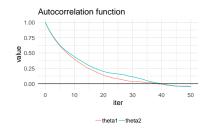
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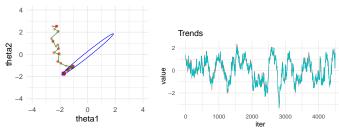




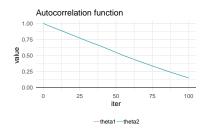


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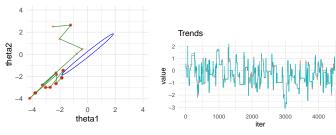




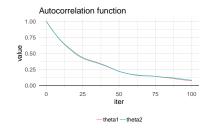


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- The autocorrleation can be used to estimate Monte Carlo error in case of MCMC
- For expectation $\bar{\theta}$

$$\operatorname{Var}[\bar{\theta}] = \frac{\sigma_{\theta}^2}{S_{\text{eff}}}$$

where $S_{\rm eff} = S/ au$, and au is sum of autocorrelations



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 \bullet $\,\tau$ describes how many dependent draws correspond to one independent draw



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- Here S = NM (in BDA3 N = nm and $n_{\text{eff}} = N/\tau$)



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- \bullet $\,\tau$ describes how many dependent draws correspond to one independent draw
- Here S = NM (in BDA3 N = nm and $n_{\text{eff}} = N/\tau$)
- ullet BDA3 focuses on $S_{
 m eff}$ and not the Monte Carlo error directly



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Autocorrelation

• Estimation of the autocorrelation using several chains

$$\hat{\rho}_{n} = 1 - \frac{W - \frac{1}{M} \sum_{m=1}^{M} \hat{\rho}_{n,m}}{2 \hat{\text{var}}^{+}}$$

where $\hat{\rho}_{n,m}$ is autocorrelation at lag n for chain m



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 \bullet BDA3 has slightly different and less accurate equation. The above equation is used in Stan 2.18+



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where $\hat{\rho}_{n,m}$ is autocorrelation at lag n for chain m

- BDA3 has slightly different and less accurate equation.
 The above equation is used in Stan 2.18+
- Compared to a method which computes the autocorrelation from a single chain, the multi-chain estimate has smaller variance



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Estimating τ

• Estimation of τ

$$\tau = 1 + 2\sum_{t=1}^{\infty} \hat{\rho}_t$$

where $\hat{
ho}_t$ is empirical autocorrelation



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- empirical autocorrelation function is noisy
- noise is larger for longer lags (less observations)



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where $\hat{\rho}_t$ is empirical autocorrelation

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- noise is larger for longer lags (less observations)
- less noisy estimate is obtained by truncating

$$\hat{\tau} = 1 + 2\sum_{t=1}^{T} \hat{\rho}_t$$



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Geyer's adaptive window estimator of au

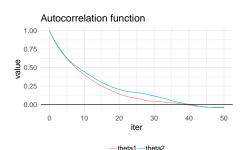
- Truncation T can be decided adaptively
 - for stationary, irreducible, recurrent Markov chain
 - let $\Gamma_m = \rho_{2m} + \rho_{2m+1}$, which is sum of two consequent autocorrelations
 - Γ_m is positive, decreasing and convex function of m



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Geyer's adaptive window estimator of au

- Truncation T can be decided adaptively
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 - let $\Gamma_m = \rho_{2m} + \rho_{2m+1}$, which is sum of two consequent autocorrelations
 - Γ_m is positive, decreasing and convex function of m
- Initial positive sequence estimator (Geyer's IPSE)
 - Choose the largest m so, that all values of the sequence $\hat{\Gamma}_1,\ldots,\hat{\Gamma}_m$ are positive





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Effective sample size, $S_{\rm eff}$

Effective sample size $\mathrm{ESS} = \mathcal{S}_{\mathrm{eff}} pprox \mathcal{S}/\hat{ au}$

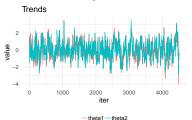


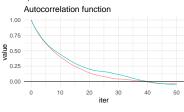
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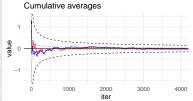
Effective sample size, $S_{\rm eff}$

Effective sample size $ESS = S_{eff} \approx S/\hat{\tau}$





-theta1 -theta2



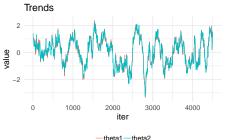
$$\hat{\tau} = 1 + 2 \sum_{t=1}^{T} \hat{\rho}_t$$
 ≈ 24

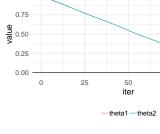


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Effective sample size

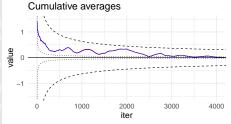
Effective sample size $ESS = S_{eff} \approx S/\hat{\tau}$





Autocorrelation function

1.00



$$\hat{\tau} = 1 + 2 \sum_{t=1}^{T} \hat{\rho}$$

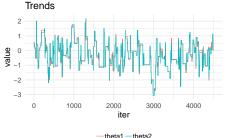
$$\approx 104$$



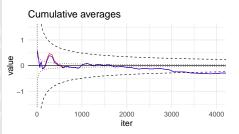
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Effective sample size

Effective sample size $\mathrm{ESS} = \mathcal{S}_{\mathsf{eff}} pprox \mathcal{S}/\hat{ au}$



theta1 —theta2



Autocorrelation function

1.00

0.75

0.50

0.25

0.00

0 25 50

iter

-theta1 -theta2

$$\hat{ au} = 1 + 2 \sum_{t=1}^{T} \hat{
ho}_t$$
 $pprox 63$



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- Nonlinear dependencies
 - optimal proposal depends on location



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- Funnels
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- Multimodal
 - difficult to move from one mode to another



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- Nonlinear dependencies
 - optimal proposal depends on location
- Funnels
 - optimal proposal depends on location
- Multimodal
 - difficult to move from one mode to another
- Long-tailed with non-finite variance and mean
 - central limit theorem for expectations does not hold