

Lecture 6. Subspaces, Bases, and Projections in Machine Learning

Recall geometric view of least squares

Given (x_i, y_i) for $i=1, \dots, n$

Labels $\underline{y} \in \mathbb{R}^p$ for n training samples

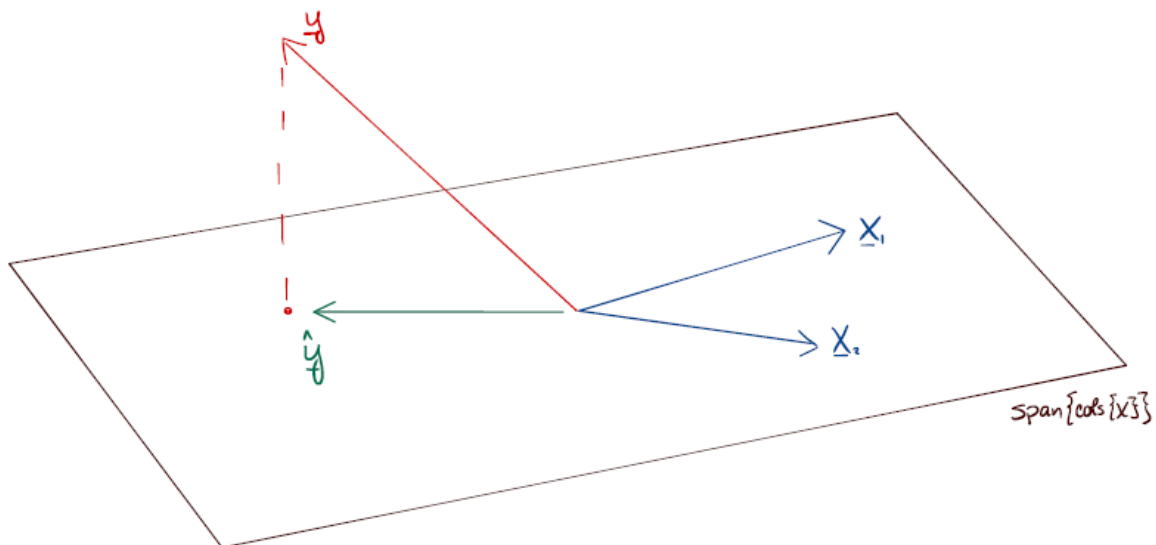
Features $X \in \mathbb{R}^{n \times p}$ (p features)

$$\underline{y} = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}, X = \begin{bmatrix} \dots & \underline{x}_1^T & \dots \\ \dots & \underline{x}_2^T & \dots \\ \dots & \underline{x}_n^T & \dots \end{bmatrix} \in \mathbb{R}^{n \times p}$$

We want to find $\hat{\underline{y}} = X\underline{w}$ such that $\|\hat{\underline{y}} - \underline{y}\|_2^2$ is as small as possible

Let $X_1, X_2, \dots, X_p = p$ columns of X .

Then, $\hat{\underline{y}} = w_1 X_1 + w_2 X_2 + \dots + w_p X_p$



The hyperplane $\text{span}\{\text{cols}(X)\}$ is called a **subspace**

If the columns of X are linearly independent, then they form a basis for \mathcal{X} .

$\hat{\underline{y}}$ is the **orthogonal projection** of \underline{y} onto the subspace.

The 2 columns of X in the image above **span** the subspace.

We will use this notion of least squares with a motivating example.

Subspaces

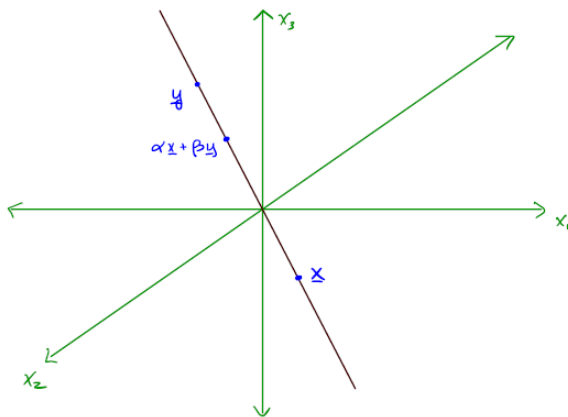
Consider all points $\underline{x} \in \mathbb{R}^n$. A subspace is a subset of these points that satisfies a few key properties: Specifically, let \mathcal{S} be a subspace and let \underline{x} and \underline{y} be any two points in the subspace. Then for any scalars α and β , the weighted sum $\alpha \underline{x} + \beta \underline{y}$ must also be in the subspace.

Ex 1. $n=3$, $\mathcal{S} = \{\underline{x} \in \mathbb{R}^3: x_1 = x_2 = -x_3\}$

$$\underline{x} \in \mathcal{S}$$

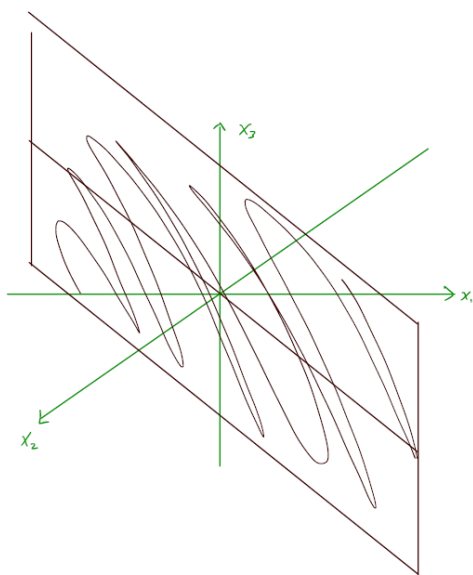
$$\underline{x} = a \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} \text{ for some } a$$

$$x_1 = a, x_2 = a, x_3 = -a$$



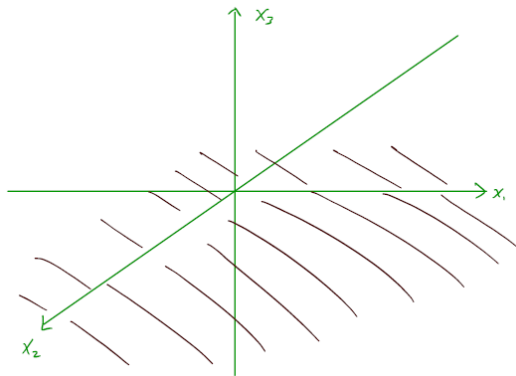
Ex 2. $n=3$, $\mathcal{S} = \{\underline{x} \in \mathbb{R}^3: x_1 = x_2\}$

Vertical plane along diagonal



Ex 3. $n=3$, $S=\{\underline{x} \in \mathbb{R}^3: x_3 = 0\}$

Horizontal plane



Ex 4, recommender system

$$\begin{array}{c}
 \text{X} = \begin{bmatrix} \text{ } \\ \text{ } \\ \text{ } \end{bmatrix} \\
 \text{n} \times \text{p}
 \end{array}
 \begin{array}{c}
 \text{customer} \\
 \text{movie}
 \end{array}
 = \begin{array}{c}
 \text{U} \\
 \text{n} \times \text{r}
 \end{array}
 \begin{array}{c}
 \text{V} \\
 \text{r} \times \text{p}
 \end{array}$$

$= r$ representative taste profiles
 r weights for each user

X_{ij} = rating of i^{th} movie by j^{th} customer (user)

The span of columns of U is a subspace.
 All columns of X lie in that subspace.

For example, for one column of X , we can think about this column as **a weighted sum** of the columns of U and the j^{th} column of V that tells us what those **weights** are. So every column of X is a weighted sum of the columns of U for some sort of weights (V) here and this again coincides with our notion of subspaces because the subspace corresponding to the span of the columns of U .

How to represent a subspace?

- (a) Represent \mathcal{S} as the span of a set of vectors
- (b) Represent \mathcal{S} as the span of a set of linearly independent vectors (called subspace **basis**)
- (c) Represent \mathcal{S} as the span of a set of orthonormal vectors (called subspace **orthonormal basis**)

Recall

$n=3$, $\mathcal{S}=\{\underline{x} \in \mathbb{R}^3: x_3 = 0\} \rightarrow$ horizontal plane

$$(a) \mathcal{S} = \text{span}\left\{\begin{pmatrix} 1/2 \\ 1/2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1/2 \\ -1/2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right\}$$

$$(b) \mathcal{S} = \text{span}\left\{\begin{pmatrix} 1/2 \\ 1/2 \\ 0 \end{pmatrix}, \begin{pmatrix} 1/2 \\ -1/2 \\ 0 \end{pmatrix}\right\}$$

$$(c) \mathcal{S} = \text{span}\left\{\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right\}$$

Two vectors \underline{u}_1 and \underline{u}_2 are orthogonal if $\langle \underline{u}_1, \underline{u}_2 \rangle = \underline{u}_1^T \underline{u}_2 = \underline{u}_2^T \underline{u}_1 = 0$

A vector \underline{u} is normal if $\|\underline{u}\|_2 = \|\underline{u}\|_2^2 = \langle \underline{u}, \underline{u} \rangle = \underline{u}^T \underline{u} = 1$

A set of vectors $\underline{u}_1, \underline{u}_2, \dots, \underline{u}_p$ is orthonormal if

$$\langle \underline{u}_i, \underline{u}_j \rangle = 1 \quad \text{if } i=j$$

$$\langle \underline{u}_i, \underline{u}_j \rangle = 0 \quad \text{if } i \neq j$$

Properties of the orthonormal basis matrix

If $\mathcal{S} = \text{span}\{\underline{u}_1, \underline{u}_2, \dots, \underline{u}_p\}$ where the vectors are orthonormal, then

$$U = \begin{bmatrix} \vdots & \vdots & & \vdots \\ u_1 & u_2 & \dots & u_p \\ \vdots & \vdots & & \vdots \end{bmatrix} \text{ is a (orthogonal) basis matrix}$$

U is an orthogonal matrix

$$C = U^T U \rightarrow C_{ij} = \langle \underline{u}_i, \underline{u}_j \rangle$$

$$\langle \underline{u}_i, \underline{u}_j \rangle = 1 \quad \text{if } i=j$$

$$\langle \underline{u}_i, \underline{u}_j \rangle = 0 \quad \text{if } i \neq j$$

$$C = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = I$$

U is (squared) length preserving

Let $\underline{v} \in \mathbb{R}^p$ Consider Uv

$$\|Uv\|_2^2 = (Uv)^T (Uv) = v^T U^T U v = v^T v = \|v\|_2^2$$

Dimension of subspace

$\dim(\mathcal{S}) = \text{number of vectors in subspace basis}$

If $\mathcal{S} = \text{span}(\text{cols}(X))$, then $\dim(\mathcal{S}) = \text{rank}(X)$

$$X \in \mathbb{R}^{n \times p}$$

Projection

The projection of a point \underline{y} onto a set is the point in the set closest to \underline{y} .

$$\hat{\underline{y}} = \text{projection of } \underline{y} \text{ onto set } \mathcal{X} = P_{\mathcal{X}} \underline{y} = \underset{\underline{x} \in \mathcal{X}}{\operatorname{argmin}} \left\| \underline{y} - \underline{x} \right\|_2^2$$

If \mathcal{X} is a subspace spanned by columns of $X \in \mathbb{R}^{n \times p}$ with LI columns, any point in \mathcal{X} has form $\hat{\underline{y}} = w_1 \underline{x}_1 + w_2 \underline{x}_2 + \dots + w_p \underline{x}_p$.

$$\text{Let } \hat{\underline{w}} = \underset{\underline{w}}{\operatorname{argmin}} \left\| \underline{y} - X \underline{w} \right\|_2^2 \text{ and } \hat{\underline{y}} = X \hat{\underline{w}}$$

Least squares

$$\hat{\underline{w}} = (X^T X)^{-1} X^T \underline{y}$$

Projection matrix

$$\begin{aligned} \hat{\underline{y}} &= X(X^T X)^{-1} X^T \underline{y} \\ &= P_X \underline{y} \end{aligned}$$

P_X is squares

$$P_X = P_X^2 \underline{y} = P_X P_X$$

If $\hat{\underline{y}} \in \mathcal{X}$, then $P_X \hat{\underline{y}} = \hat{\underline{y}}$

Orthogonal Subspace Bases and Least Squares

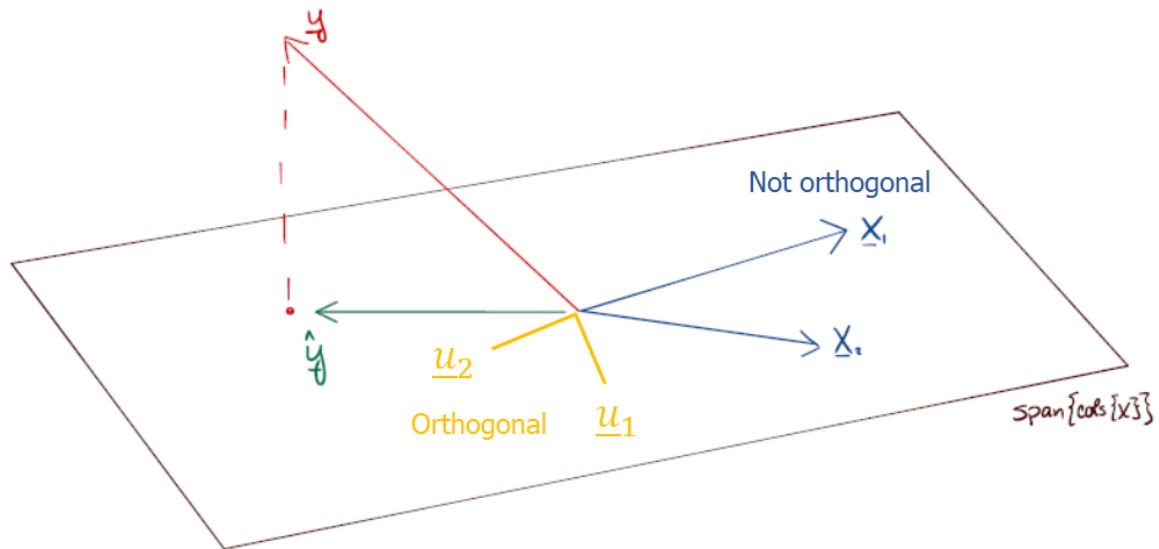
Let $X \in \mathbb{R}^{n \times p}$, $y \in \mathbb{R}^n$

Let U be orthonormal basis matrix for subspace spanned by columns of X
 $\text{span}(\text{cols}(U)) = \text{span}(\text{cols}(X))$

$\hat{\underline{y}} = X\hat{\underline{w}} = U\tilde{\underline{w}}$ for any $\hat{\underline{y}} \in \mathcal{X}$, there are both $\hat{\underline{w}}, \tilde{\underline{w}}$ so that $\hat{\underline{y}} = X\hat{\underline{w}} = U\tilde{\underline{w}}$

We can write any point in the space as

$$w_1 \underline{x}_1 + w_2 \underline{x}_2 = \tilde{w}_1 \underline{u}_1 + \tilde{w}_2 \underline{u}_2$$



Use least squares to find \tilde{w}

$$\underline{\tilde{w}} = \underset{w}{\operatorname{argmin}} \left\| \underline{y} - U\underline{w} \right\|_2^2$$

$$=(U^T U)^{-1} U^T y$$

$$\hat{\underline{y}} = \underline{U}(\underline{U}^T \underline{U})^{-1} \underline{U}^T \underline{y} = \underline{X}(\underline{X}^T \underline{X})^{-1} \underline{X}^T \underline{y}$$

Projection onto span(cols(U)) = Projection onto span(cols(X))

$$U(U^T U)^{-1} U^T$$

$$UU^T = UU^T$$