

TPDP, WPES and CCS talks

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Abstract

Summaries of talks we attended.

1 Invited talk TPDP: Composition, Verification, and Differential Privacy

Speaker: Justin Hsu

After introducing differential privacy in general, we see a few well-known composition results. Post-processing is seen as an instantiation of sequential composition of an (ϵ, δ) -DP mechanism with a $(0, 0)$ -DP mechanism, which is kind of nice. Similarly, local DP is presented as an instantiation of parallel composition.

1.1 Formally verifying privacy

Our goals here are twofold: we want to have *dynamic* verification, i.e., raise errors if DP is violated and *static* verification, i.e., checking DP on all possible inputs. As a side-note, we want to simplify verification by using composition results; composition allows verification techniques to have much better automation.

The Fuzz family of languages allows for describing each type with a metric and, using group privacy ($(\epsilon, 0)$ -DP for $\Delta_f = 1$ implies $(k \cdot \epsilon, 0)$ -DP for $\Delta_f = k$). The description allows for an immediate static analysis that can use both sequential and parallel composition. These languages, so far, cannot deal well with ADP, but the speaker is currently working on that.

Privacy as an approximate coupling Idea: verify privacy by game hops. We somehow relate pairs of sampling instructions to show properties of a pair of inputs, but I'm not sure how exactly we do that. This static-analysis technique seems to be related to how Tim and me modeled differential indistinguishability, i.e., as a property of a pair of programs/machines. They, so far, cannot automatically generate proofs, but can check them.

1.2 Advanced composition

They analyze the old “advanced composition theorem” by Dwork, Rothblum and Vadhan. The speaker says that the analysis is more complicated, since the composition theorem needs to be applied “as a block”, instead of on small units of the program. The speaker then mentions that novel approaches (e.g., by Mironov on RDP) makes formal verification easier, as it allows to analyze a program step-by-step. I think that using our privacy buckets approach, such an analysis could be improved even more and made flexible as well.

1.3 Modularity

The verification approach aims at being able to modularly compose differential privacy mechanisms. Their approach does not solve a fundamental problem that black-box composition of DP mechanisms have: after black-box composition there is potentially too many points where noise is added. So, a more thorough

approach would divide DP mechanisms into summarizing data (e.g., via statistical queries) and adding noise. Then, composition would compose the summarization operations and then only add noise once. Such an approach would deteriorate utility much less.

2 Invited Talk TPDP 2: Deploying Differential Privacy for Learning on Sensitive Data

Speaker: Ulfar Erlingsson

The speaker mentions problems with RAPPOR, mostly that for the quantities of data they require, the privacy guarantees are deteriorating too fast. The main problem seems to be that they have to use local DP mechanisms.

The aim of their Prochlo realization is to combine the local differential privacy mechanisms with some central DP approach.

They notice that if they don't need correlations between data points from the same user, anonymous communication can help them. As a result, they have a partially central approach. They group data based on useful features.

Their approach combines three aspects of uncertainty: the uncertainty introduced by the local DP mechanism (via randomized response), the uncertainty introduced by the combination (anonymity and random shuffling) and the uncertainty applied to the results afterwards (in a centralized DP manner).

2.1 Private neural networks

The speaker identifies the problem of machine learning models, e.g., NNs, memorize the training data. This confirms known results on adversarial ML and works by Dawn Song and Vitaly Shmatikov.

Specifically, they introduce canaries, i.e., specific numbers, and want to check whether the NN is surprised to see this canary or not. In other words, they check whether the NN learnt this canary. Their experiments show that NNs indeed learn such canaries. Learning the canaries seems to reach its worst case early, with the convergence of the model.

The speaker emphasizes that this memoization is different from overfitting, because in spite of memoization generalization works well.

The speaker emphasizes that there are edge cases that the NNs seemingly have to memorize exceptions, because there does not seem to be a rule to characterize these edge cases. These exceptions are not necessarily important for the final model, as they contradict the general paradigm of machine learning: to learn general properties of samples and not exceptions. This makes differential privacy a natural fit for ML.

We now get an introduction into the privacy-preserving stochastic gradient descent (SGD) [?] work and the PATE paper [?].

In their case study, they use prior knowledge and use a strong bayesian prior.

3 Local differential privacy for evolving data

Speaker: Matthew Joseph, collaboration with Aaron Roth, Jonathan Ullman and Bo Waggoner

Paper: <https://arxiv.org/pdf/1802.07128.pdf>

The main difficulty they tackle is evolving data, i.e., data that can change over time. The simplest solution in terms of differential privacy would be to simply have a randomized response for every user in every round. While this is very simple, privacy deteriorates over time. To moderately improve it, you can apply subsampling, i.e., ask different subsets of users every time. This is better in terms of privacy, but the error is still large. Local sparse vectors (?) would allow for nice privacy guarantees, but require an exponentially larger number of samples.

The solution lets users “vote” to change statistics, i.e., they construct an adaptive mechanism.

In each epoch t , each user creates a localized bit, then generates a vote for or against updating and then depending on the average vote the analyst decides whether or not the estimate should be updated (requiring more interaction) or not.

Each user can guess whether or not the global estimate has changed significantly. We aren't completely sure on the maths here, but apparently each user locally simulates what the estimate should be (in the current round) and compare that to the previous global estimate. If these don't differ much, the user is content; if they do differ significantly, the user votes for a change.

If a change occurred, the analyst collects the changed estimates from the users to update the global estimate. Otherwise the analyst just keeps the previous estimate.

I'm not completely convinced yet by the proof intuition for why their mechanism satisfies differential privacy; a closer look into their paper ¹ might be in order to understand what exactly they are doing and why that is privacy-preserving, particularly towards the data analyst that collects the votes and combines the estimates.

¹available online: <https://arxiv.org/pdf/1802.07128.pdf>