RESEARCH ARTICLE

Title

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ARTICLE HISTORY
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ABSTRACT
This is the abstract.

KEYWORDS
Keyword; keyword; keyword

1. Utils

1.1. *Lists*

1.1.1. Itemize

- item 1;
- item 2.

1.1.2. Enumerate

(1) item 1;
(2) item 2.

1.2. *Mathematics*

1.2.1. Formula

$$\hat{\theta}_{w_i} = \hat{\theta}(s(t, \mathcal{U}_{w_i})) \tag{1}$$

1.2.2. Environment

This is the γ.

1.3. *References*

This is a citation (Ding *et al.* 2022).

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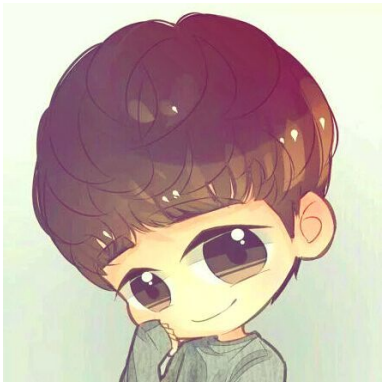
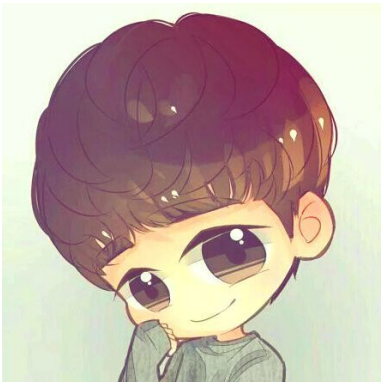


(a) sub-caption.



(b) sub-caption.

Figure 1. Caption.

Table 1. XXX.

	Type					
Class	One	Two	Three	Four	Five	Six
Alpha[a]	A1	A2	A3	A4	A5	A6
Beta	B2	B2	B3	B4	B5	B6
Gamma	C2	C2	C3	C4	C5	C6

[a]XXX.

1.4. *Figures*

1.5. *Tables*

Acknowledgement(s)

This is the acknowledgement(s).

Disclosure statement

This is the disclosure statement.

Funding

This is the funding.

Notes on contributor(s)

This is the notes on contributor(s).

Notes

This is the notes.

References

Ding, G., *et al.*, 2022. A coarse-to-fine boundary localization method for naturalistic driving action recognition. *In*: *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR) Workshops*, June. 3234–3241.

Appendix A. XXX