DATA STRUCTURES AND ALGORITHMS LECTURE 3

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In Lecture 2...

Algorithm Analysis

Dynamic Array

Iterator

Today

Iterators

2 Binary Heap

Iterator

- An *iterator* is a structure that is used to iterate through the elements of a container.
- Containers can be represented in different ways, using different data structures. Iterators are used to offer a common and generic way of moving through all the elements of a container, independently of the representation of the container.
- Every container that can be iterated, has to contain in the interface an operation called *iterator* that will create and return an iterator over the container.

Iterator

- An iterator usually contains:
 - a reference to the container it iterates over
 - a reference to a *current element* from the container
- Iterating through the elements of the container means actually moving this current element from one element to another until the iterator becomes invalid
- The exact way of representing the current element from the iterator depends on the data structure used for the implementation of the container. If the representation/ implementation of the container changes, we need to change the representation/ implementation of the iterator as well.



Iterator - Interface I

Domain of an Iterator

 $\mathcal{I} = \{ \mathbf{it} | \text{it is an iterator over a container with elements of type TElem } \}$

Iterator - Interface II

• Interface of an Iterator:

Iterator - Interface III

- init(it, c)
 - description: creates a new iterator for a container
 - **pre:** c is a container
 - **post:** $it \in \mathcal{I}$ and it points to the first element in c if c is not empty or it is not valid

Iterator - Interface IV

- getCurrent(it, e)
 - description: returns the current element from the iterator
 - **pre:** $it \in \mathcal{I}$, it is valid
 - post: $e \in TElem$, e is the current element from it

Iterator - Interface V

- next(it)
 - description: moves the current element from the container to the next element or makes the iterator invalid if no elements are left
 - **pre**: $it \in \mathcal{I}$, it is valid
 - **post:** the current element from *it* points to the next element from the container

Iterator - Interface VI

- valid(it)
 - description: verifies if the iterator is valid
 - ullet pre: $it \in \mathcal{I}$
 - post:

 $valid \leftarrow \begin{cases} True, & \text{if it points to a valid element from the container} \\ False & \text{otherwise} \end{cases}$

Types of iterators I

- The interface presented above describes the simplest iterator: *unidirectional* and *read-only*
- A unidirectional iterator can be used to iterate through a container in one direction only (usually forward, but we can define a reverse iterator as well).
- A bidirectional iterator can be used to iterate in both directions. Besides the next operation it has an operation called previous.

Types of iterators II

- A random access iterator can be used to move multiple steps (not just one step forward or one step backward).
- A *read-only* iterator can be used to iterate through the container, but cannot be used to change it.
- A read-write iterator can be used to add/delete elements to/from the container.

Using the iterator

 Since the interface of an iterator is the same, independently of the exact container or its representation, the following subalgorithm can be used to print the elements of any container.

```
subalgorithm printContainer(c) is:
//pre: c is a container
//post: the elements of c were printed
//we create an iterator using the iterator method of the container
  iterator(c, it)
  while valid(it) execute
     //get the current element from the iterator
     getCurrent(it, elem)
     print elem
     //go to the next element
     next(it)
  end-while
end-subalgorithm
```

Iterator for a Dynamic Array

- How can we define an iterator for a Dynamic Array?
- How can we represent that current element from the iterator?

Iterator for a Dynamic Array

- How can we define an iterator for a Dynamic Array?
- How can we represent that *current element* from the iterator?
- In case of a Dynamic Array, the simplest way to represent a current element is to retain the position of the current element.

IteratorDA:

da: DynamicArray current: Integer

 Let's see how the operations of the iterator can be implemented.



Iterator for a Dynamic Array - init

• What do we need to do in the init operation?

Iterator for a Dynamic Array - init

• What do we need to do in the init operation?

```
\begin{array}{l} \textbf{subalgorithm} \  \, \text{init(it, da)} \ \textit{is:} \\ \textit{//it is an IteratorDA, da is a Dynamic Array} \\ \text{it.da} \leftarrow \text{da} \\ \text{it.current} \leftarrow 1 \\ \textbf{end-subalgorithm} \end{array}
```

Complexity:

Iterator for a Dynamic Array - init

• What do we need to do in the init operation?

```
\begin{array}{l} \textbf{subalgorithm} \  \, \text{init(it, da)} \ \textit{is:} \\ \textit{//it is an IteratorDA, da is a Dynamic Array} \\ \text{it.da} \leftarrow \text{da} \\ \text{it.current} \leftarrow 1 \\ \textbf{end-subalgorithm} \end{array}
```

Complexity: Θ(1)

Iterator for a Dynamic Array - getCurrent

• What do we need to do in the getCurrent operation?

Iterator for a Dynamic Array - getCurrent

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Complexity:

Iterator for a Dynamic Array - getCurrent

• What do we need to do in the getCurrent operation?

```
\begin{array}{l} \textbf{subalgorithm} \ \ \text{getCurrent(it, e)} \ \textit{is:} \\ e \leftarrow \text{it.da.elems[it.current]} \\ \textbf{end-subalgorithm} \end{array}
```

• Complexity: $\Theta(1)$

Iterator for a Dynamic Array - next

• What do we need to do in the *next* operation?

Iterator for a Dynamic Array - next

• What do we need to do in the next operation?

```
\begin{array}{l} \textbf{subalgorithm} \ \ \text{next(it)} \ \textit{is:} \\ \ \ \text{it.current} \ \leftarrow \ \text{it.current} \ + \ 1 \\ \textbf{end-subalgorithm} \end{array}
```

Complexity:

Iterator for a Dynamic Array - next

• What do we need to do in the next operation?

```
\begin{array}{l} \textbf{subalgorithm} \ \ \text{next(it)} \ \textit{is:} \\ \ \ \text{it.current} \leftarrow \ \text{it.current} + 1 \\ \textbf{end-subalgorithm} \end{array}
```

• Complexity: $\Theta(1)$

Iterator for a Dynamic Array - valid

• What do we need to do in the *valid* operation?

Iterator for a Dynamic Array - valid

• What do we need to do in the valid operation?

```
function valid(it) is:

if it.current <= it.da.len then

valid ← True

else

valid ← False

end-if

end-function
```

Complexity:

Iterator for a Dynamic Array - valid

• What do we need to do in the valid operation?

```
function valid(it) is:

if it.current <= it.da.len then

valid ← True

else

valid ← False

end-if

end-function
```

• Complexity: $\Theta(1)$

Iterator for a Dynamic Array

- We can print the content of a Dynamic Array in two ways:
 - Using an iterator (as present above for a container)
 - Using the positions (indexes) of elements

```
subalgorithm printDA(da) is:
//pre: da is a Dynamic Array
//post: the elements of da were printed
for i ← 1, size(da) execute
getElement(da, i, elem)
print elem
end-for
end-subalgorithm
```

Iterator for a Dynamic Array

- In case of a Dynamic Array both printing algorithms have $\Theta(n)$ complexity
- For other data structures/containers we need iterator because
 - there are no positions in the data structure/container (for example for the Bag ADT)
 - the time complexity of iterating through all the elements is smaller

Binary Heap

- A binary heap is a data structure that can be used as an efficient representation for Priority Queues (will be discussed later).
- A binary heap is a kind of hybrid between a dynamic array and a binary tree.
- The elements of the heap are actually stored in the dynamic array, but the array is visualized as a binary tree.
- **Note:** There are several heap data structures (Binary Heap, Binominal Heap, Fibonacci Heap, etc.) in the following we are going to use the term *heap* to represent a binary heap.



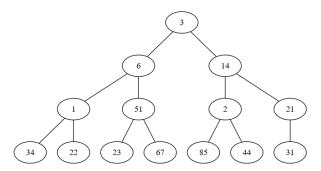
Неар

• Assume that we have the following array (upper row contains positions, lower row contains elements):

1	2	3	4	5	6	7	8	9	10	11	12	13	14
3	6	14	1	51	2	21	34	22	23	67	85	44	31

Heap

 We can visualize this array as a binary tree, in which each node has exactly 2 children, except for the last two rows, but there the children of the nodes are completed from left to right.



Heap

- If the elements of the array are: $a_1, a_2, a_3, ..., a_n$, we know that:
 - a₁ is the root of the heap
 - for an element from position i, its children are on positions 2 * i and 2 * i + 1 (if 2 * i and 2 * i + 1 is less than or equal to n)
 - for an element from position i (i > 1), the parent of the element is on position [i/2] (integer part of i/2)

Heap

- A binary heap is an array that can be visualized as a binary tree having a heap structure and a heap property.
 - Heap structure: in the binary tree every node has exactly 2 children, except for the last two levels, where children are completed from left to right.
 - Heap property: $a_i \ge a_{2*i}$ (if $2*i \le n$) and $a_i \ge a_{2*i+1}$ (if $2*i+1 \le n$)
 - ullet The \geq relation between a node and both its descendants can be generalized (other relations can be used as well).



Heap - Notes

- If we use the \geq relation, we will have a MAX-HEAP.
- If we use the ≤ relation, we will have a MIN-HEAP.
- The height of a heap with n elements is log₂n, so the operations performed on the heap have O(log₂n) complexity.

Heap - operations

- A heap can be used as representation for a Priority Queue and it has two specific operations:
 - add a new element in the heap (in such a way that we keep both the heap structure and the heap property).
 - remove (we always remove the root of the heap no other element can be removed).

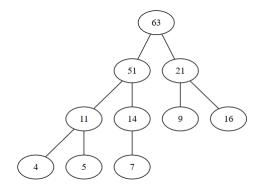
Heap - representation

Heap:

cap: Integer len: Integer elems: TElem[]

 For the implementation we will assume that we have a MAX-HEAP.

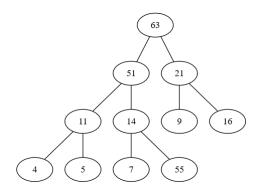
• Consider the following (MAX) heap:



• Let's add the number 55 to the heap.

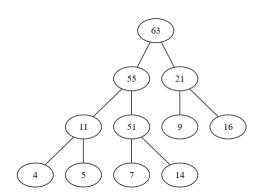


 In order to keep the heap structure, we will add the new node as the right child of the node 14 (and as the last element of the array in which the elements are kept).



- Heap property is not kept: 14 has as child node 55 (since it is a MAX-heap, each node has to be greater than or equal to its descendants).
- In order to restore the heap property, we will start a bubble-up process: we will keep swapping the value of the new node with the value of its parent node, until it gets to its final place. No other node from the heap is changed.

• When bubble-up ends:



Heap - add

```
subalgorithm add(heap, e) is:
//heap - a heap
//e - the element to be added
  if heap.len = heap.cap then
     @ resize
  end-if
  heap.elems[heap.len+1] \leftarrow e
  heap.len \leftarrow heap.len + 1
  bubble-up(heap, heap.len)
end-subalgorithm
```

Heap - add

```
subalgorithm bubble-up (heap, p) is:
//heap - a heap
//p - position from which we bubble the new node up
   poz \leftarrow p
   elem \leftarrow heap.elems[p]
   parent \leftarrow p / 2
   while poz > 1 and elem > heap.elems[parent] execute
      //move parent down
      heap.elems[poz] ← heap.elems[parent]
      poz ← parent
      parent \leftarrow poz / 2
   end-while
   heap.elems[poz] \leftarrow elem
end-subalgorithm
```

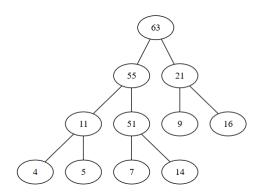
Complexity:

Heap - add

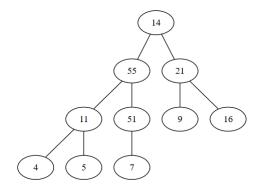
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subalgorithm bubble-up (heap, p) is:
//heap - a heap
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   poz \leftarrow p
   elem \leftarrow heap.elems[p]
   parent \leftarrow p / 2
   while poz > 1 and elem > heap.elems[parent] execute
      //move parent down
      heap.elems[poz] ← heap.elems[parent]
      poz ← parent
      parent \leftarrow poz / 2
   end-while
   heap.elems[poz] \leftarrow elem
end-subalgorithm
```

- Complexity: O(log₂ n)
- Can you give an example when the complexity of the algorithm is less than log_2n (best case scenario)?

• From a heap we can only remove the root element.

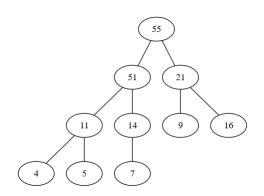


 In order to keep the heap structure, when we remove the root, we are going to move the last element from the array to be the root.



- Heap property is not kept: the root is no longer the maximum element.
- In order to restore the heap property, we will start a bubble-down process, where the new node will be swapped with its maximum child, until it becomes a leaf, or until it will be greater than both children.

• When the bubble-down process ends:



```
function remove(heap, deletedElem) is:
//heap - is a heap
//deletedElem - is an output parameter, the removed element
  if heap.len = 0 then
     @ error - empty heap
   end-if
  deletedElem \leftarrow heap.elems[1]
  heap.elems[1] \leftarrow heap.elems[heap.len]
  heap.len \leftarrow heap.len - 1
  bubble-down(heap, 1)
  remove \leftarrow deletedElem
end-function
```

```
subalgorithm bubble-down(heap, p) is:
//heap - is a heap
//p - position from which we move down the element
   poz \leftarrow p
   elem \leftarrow heap.elems[p]
   while poz ≤ heap.len execute
      maxChild \leftarrow -1
      if poz * 2 \le \text{heap.len then}
      //it has a left child, assume it is the maximum
         maxChild \leftarrow poz*2
      end-if
      if poz^*2+1 \le heap.len and heap.elems[2*poz+1] > heap.elems[2*poz] th
      //it has two children and the right is greater
         maxChild \leftarrow poz*2 + 1
      end-if
//continued on the next slide...
```

```
if maxChild \neq -1 and heap.elems[maxChild] > elem then
        heap.elems[poz] ← heap.elems[maxChild]
        poz \leftarrow maxChild
     else
        heap.elems[poz] \leftarrow elem
        poz \leftarrow heap.len + 1
       //to stop the while loop
     end-if
  end-while
end-subalgorithm
```

Complexity:

```
if maxChild \neq -1 and heap.elems[maxChild] > elem then
        heap.elems[poz] ← heap.elems[maxChild]
        poz \leftarrow maxChild
     else
        heap.elems[poz] \leftarrow elem
        poz \leftarrow heap.len + 1
       //to stop the while loop
     end-if
  end-while
end-subalgorithm
```

- Complexity: $O(log_2 n)$
- Can you give an example when the complexity of the algorithm is less than log_2n (best case scenario)?



Questions

- In a max-heap where can we find the:
 - maximum element of the array?

Questions

- In a max-heap where can we find the:
 - maximum element of the array?
 - minimum element of the array?

Questions

- In a max-heap where can we find the:
 - maximum element of the array?
 - minimum element of the array?
- Assume you have a MAX-HEAP and you need to add an operation that returns the minimum element of the heap.
 How would you implements this operation, using constant time and space? (Note: we only want to return the minimum, we do not want to be able to remove it).