meanshift for circular

November 21, 2021

1 MS algorithm for circular-linear data

#print(values)

In this task, I take the data of theta as direction and the cluster is based only on the r data. The idea of mean shift here is that, 1. Randomly initialize a data as mean, and here we just choose the first unclusterred data. 2. Next, calculate the difference between the dataset and mean, and choose the ones that has a difference less than bandwidth. 3. Then, calculate the new mean based on the chosen data and do the second step again until the mean is smaller than the minimum distance set. A new random mean is draw to perform step 1 to 3 until all data is in one cluster. We do not need to pre-define the mode number in advance, the algorithm will calculate it by itself. However, it depends on the bandwidth that is manually defined, and in thi program, the number of bandwidth is manually tuned. There should be a better way to estimate or dynamically tune it.

In the following part, the data is process by the function defined as "meanShift". This function takes the band width, minimum distance and data as input and output the array after clustering, the cluster result in the original sequencial and the number of mode. The function "plot_result" is for plotting the cluster result, it's mode and print the mean and covriance of each cluster. The last function is "pre_process" that load the data from ".csv" file and map them into [x y] format.

```
[125]: import matplotlib.pyplot as plt
       import numpy as np
       import scipy.stats as stats
[126]: def measure(n):
           "Measurement model, return two coupled measurements."
           m1 = np.random.normal(size=n)
           m2 = np.random.normal(scale=0.5, size=n)
           return m1+m2, m1-m2
       m1, m2 = measure(2000)
       xmin = m1.min()
       xmax = m1.max()
       ymin = m2.min()
       ymax = m2.max()
       X, Y = np.mgrid[xmin:xmax:100j, ymin:ymax:100j]
       positions = np.vstack([X.ravel(), Y.ravel()])
       values = np.vstack([m1, m2])
```

```
kernel = stats.gaussian_kde(values)
       #print(kernel.dataset)
       Z = np.reshape(kernel(positions).T, X.shape)
       print(Z)
      [[5.05487242e-04 6.28196861e-04 7.42172097e-04 ... 1.13525875e-51
        3.57898846e-53 1.03781140e-54]
       [6.05737306e-04 7.80292833e-04 9.46315771e-04 ... 9.30719118e-50
        3.10458928e-51 9.51930881e-53]
       [6.71039059e-04 9.01177016e-04 1.13345193e-03 ... 6.94006063e-48
        2.44854755e-49 7.93719162e-51]
       [2.39841895e-47 5.54130523e-46 1.18615932e-44 ... 2.39038780e-05
        1.27831440e-05 6.50467419e-06]
       [3.17181518e-49 7.76959885e-48 1.76829082e-46 ... 2.04377605e-05
        1.09815391e-05 5.60221891e-06]
       [3.81670931e-51 9.92250509e-50 2.40525774e-48 ... 1.76456576e-05
        9.39772288e-06 4.78247045e-06]]
[127]: #the functio to perform the mean shift clustering
       #input params: band_width
       #
                     min_distance:
                      data_meanshift: the data to process, as we have a 2D data and_
       \rightarrow one would have to
                                      perform as direction, the data shape here is 1D
       #output result: clusterred: the reformed data after clustering
                      cluster_result: cluster result for each point in ndarray
       #
                      current_cluster-1: the number of clusters
       def meanShift(band_width, min_distance, data_meanshift):
           num_points = data_meanshift.size
                                                          # total number of points in_
        \rightarrow one dataset
           cluster_flag = np.zeros(num_points)
                                                          # if each point is classified_
        →into a cluster or not, O refers to not clustered
           cluster_result = np.zeros(num_points)
                                                          # cluster result, for example_
        \hookrightarrow1 refers to cluster NO.1
           num_notclustterd = (cluster_flag == 0).sum() # number of points not in any_
        ⇔cluster yet
           clusterred = []
                                                                # keep track of the
           current_cluster = 1
        \hookrightarrow cluster number
           while num notclustterd:
               index_temp = np.where(cluster_flag == 0)[0][0] # choose the first not_
        →clusterred points randomly as the mean
```

```
current_mean = data_meanshift[index_temp]
        diff_distance = np.Inf
                                                        # initialize the_
 → distance different to be infinity
       while diff_distance > min_distance:
                                                      # stopping criteria for
 \rightarrow one cluster
            distance_temp = data_meanshift - current_mean # calculate the_
\rightarrow difference
            cluster_index = np.where(distance_temp < band_width) # save the_</pre>
→index of data that satisfy the criteria
            cluster_points = data_meanshift[cluster_index[0]] # save data__
→ that satify the criteria
            #print(cluster points)
            new_mean = np.mean(cluster_points)
                                                                 # calculate a
→new mean based on selected data
            #print(new mean)
            diff_distance = np.abs(new_mean - current_mean)
                                                                # calculate
→ the difference to the previous mean
            current mean = new mean
            #print(diff_distance)
       cluster flag[cluster index] = 1
                                                                  # set the
→flag to 1 to those who belong to the current
                                                                  # cluster and
→will not be visited again
       cluster_result[cluster_index] = current_cluster # set the_
⇒cluster number to the data holder
        current_cluster = current_cluster + 1
        data_meanshift[cluster_index] = 1000
                                                                 # naive, set_
→ the number to be large enough so that it
                                                                  # would not
→ be visited; using the clusterflat should
                                                                   # make more
\hookrightarrowsense
       num_notclustterd = (cluster_flag == 0).sum()
                                                                 # check if
\rightarrowall data are processed
        #print(cluster_flag)
        clusterred = [clusterred]
   return clusterred, cluster_result, current_cluster-1
def plot_result(clusterred, cluster_result, current_cluster, data_x, data_y):
```

```
[128]: # for plot
def plot_result(clusterred, cluster_result, current_cluster, data_x, data_y):
    cluster_color = ["b", "g", "r", "c", "m", "y", "b", "g", "r", "c", "m"]
    fig = plt.figure()

# plot different clusters
```

```
for i in range(data_x.size):
               color_temp = cluster_color[int(cluster_result[i])-1]
              plt.plot(data_x[i], data_y[i],".",color=color_temp)
           # plot the mode for each cluster and print out mean and covariance value
           for i in range(current_cluster):
               data_x_cluster = data_x[np.where(cluster_result == i+1)]
               data y cluster = data y[np.where(cluster result == i+1)]
               data_temp=np.stack((data_x_cluster, data_y_cluster))
              mean val = np.mean(data temp,axis=1)
              cov_val = np.cov(data_temp)
              plt.plot(mean_val[0], mean_val[1],__
        →marker='o', markerfacecolor=cluster_color[i], __
        →markeredgecolor="k",markersize=10)
              print ("The mean value of the ", i+1, "clustter is: ", mean_val,"." )
              print ("The covariance value of the ", i+1, "clustter is: ", cov_val,".
        " )
[129]: # to pre-process the circular data into [x,y]
       def pre_process(data_path):
           #read data from csv with one line of names for each col
           data_raw = np.genfromtxt(data_path,names=True, dtype=None, delimiter=',')
           # as the dataset is circular of circular linear, we first remap it to [x y]
           data_theta = np.array(data_raw["theta"])
           data_r = np.array(data_raw["r"])
           data_x = data_r* np.cos(data_theta)
           data_y = data_r* np.sin(data_theta)
           return data_theta, data_r, data_x, data_y
[130]: data_path = './data/data1.csv'
       min_distance = 0.01
       band_width = 1.5
       [data_theta, data_r, data_x, data_y] = pre_process(data_path)
       #visualize data after remapping
       fig = plt.figure()
       plt.plot(data_x, data_y,".")
       # process and visualize
       [clusterred, cluster_result, current_cluster] = meanShift(band_width,__
       →min_distance, data_r)
       plot result(clusterred, cluster result, current cluster, data x, data y)
```

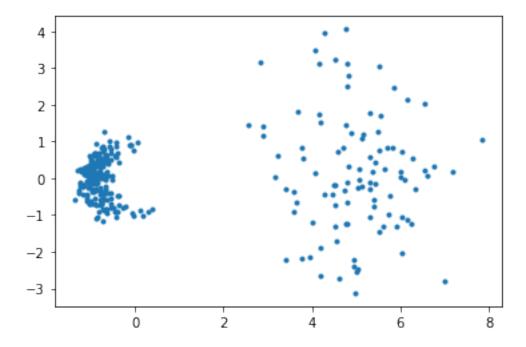
The mean value of the 1 cluster is: [-0.78622952 -0.01037369]. The covariance value of the 1 cluster is: [[0.09377495 -0.00879855]]

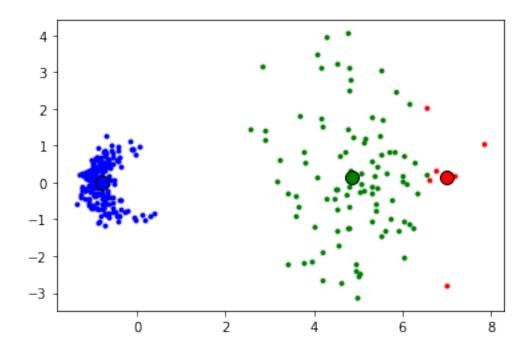
[-0.00879855 0.30504982]] .

The mean value of the 2 clustter is: $[4.84509599 \ 0.13390095]$.

The covariance value of the 2 cluster is: [[0.81410628 -0.145365] [-0.145365 2.63740948]].

The mean value of the 3 clustter is: $[6.98759948\ 0.1380465\]$. The covariance value of the 3 clustter is: $[[\ 0.22831137\ -0.03171087]$ $[-0.03171087\ 2.61853101]]$.





The mean value of the 1 clustter is: [3.09921957 2.07437343] .

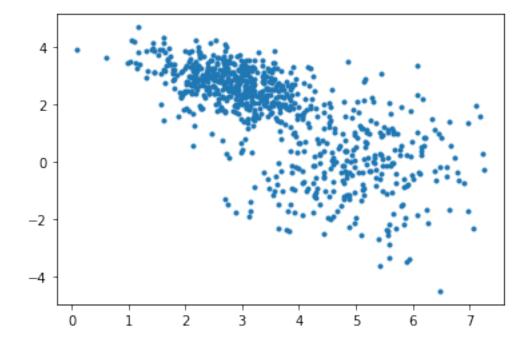
The covariance value of the 1 clustter is: [[0.77630374 -0.84254689] [-0.84254689 2.02948843]] .

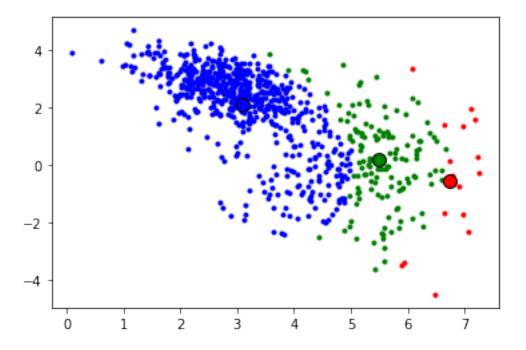
The mean value of the 2 clustter is: [5.49903107 0.18559261] .

The covariance value of the 2 clustter is: [[0.29149229 -0.23558854] [-0.23558854 2.36983521]] .

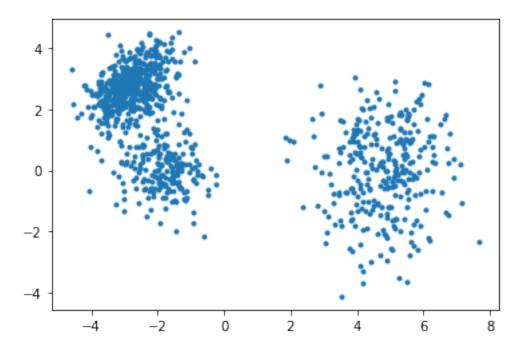
The mean value of the 3 clustter is: [6.7433964 -0.53601131] .

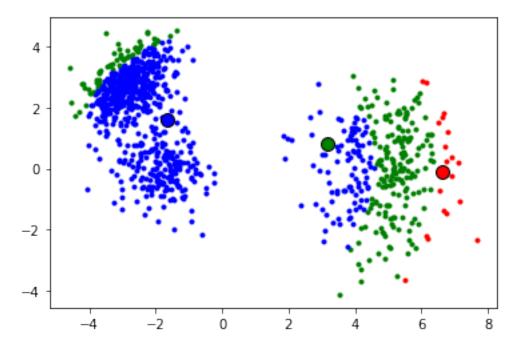
The covariance value of the 3 clustter is: [[0.18728468 0.32213428] [0.32213428 4.55630992]] .





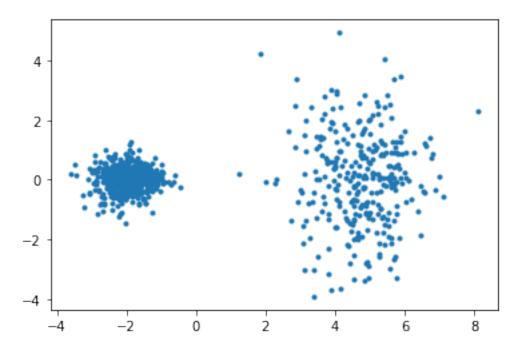
The mean value of the 1 clustter is: $[-1.66613629 \ 1.59808349]$. The covariance value of the 1 clustter is: $[[\ 4.9100343 \ -1.60623006]$ $[-1.60623006 \ 2.18647159]]$. The mean value of the 2 clustter is: $[\ 3.1543514 \ 0.83191976]$. The covariance value of the 2 clustter is: $[[\ 13.25288152 \ -5.09195641]$ $[-5.09195641 \ 4.08903679]]$. The mean value of the 3 clustter is: $[\ 6.62110745 \ -0.10171635]$. The covariance value of the 3 clustter is: $[[\ 0.22474723 \ 0.01503337]$ $[\ 0.01503337 \ 3.41252714]]$.

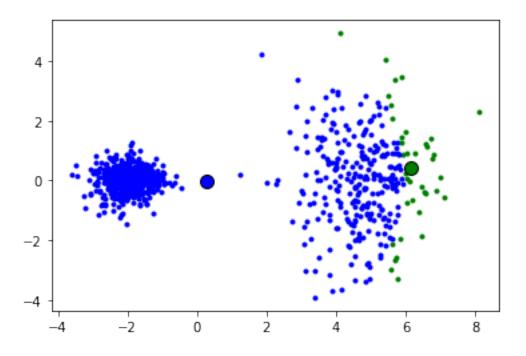




```
[133]: data_path = './data/data4.csv'
band_width = 3
[data_theta, data_r, data_x, data_y] = pre_process(data_path)
```

The mean value of the 1 clustter is: [0.27654806 - 0.01010758]. The covariance value of the 1 clustter is: [[9.90654716 - 0.13341212] $[-0.13341212 \ 0.84798305]]$. The mean value of the 2 clustter is: $[6.13740911 \ 0.43402557]$. The covariance value of the 2 clustter is: [[0.42431322 - 0.22674841] $[-0.22674841 \ 3.88199975]]$.





```
[134]: data_path = './data/data5.csv'
band_width = 0.6
  [data_theta, data_r, data_x, data_y] = pre_process(data_path)

#visualize data after remapping
fig = plt.figure()
plt.plot(data_x, data_y,".")

# process and visualize
[clusterred, cluster_result, current_cluster] = meanShift(band_width,__
____min_distance, data_r)
plot_result(clusterred, cluster_result, current_cluster, data_x, data_y)
```

The mean value of the 1 clustter is: [3.23164181 1.69162243] .

The covariance value of the 1 clustter is: [[0.29420742 -0.3055209] [-0.3055209 1.24321106]] .

The mean value of the 2 clustter is: [4.24367711 1.32099938] .

The covariance value of the 2 clustter is: [[0.41882992 -0.83180361] [-0.83180361 3.28020024]] .

The mean value of the 3 clustter is: [5.56064948 -0.26452857] .

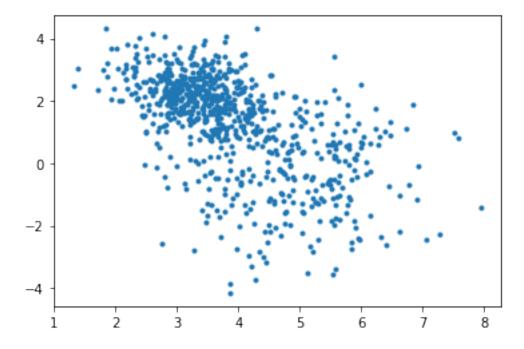
The covariance value of the 3 clustter is: [[0.23525097 0.14797426] [0.14797426 2.64446548]] .

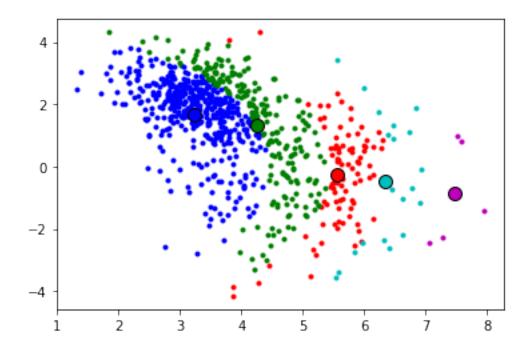
The mean value of the 4 clustter is: [6.33520031 -0.45119078] .

The covariance value of the 4 clustter is: [[0.20035758 0.18473899] [0.18473899 4.41574648]] .

The mean value of the 5 clustter is: [7.4726589 -0.87346052] .

The covariance value of the $\,$ 5 clustter is: [[0.1129651 0.24539714] [0.24539714 2.74521871]] .





The mean value of the 1 clustter is: [1.8544436 1.2187651] .

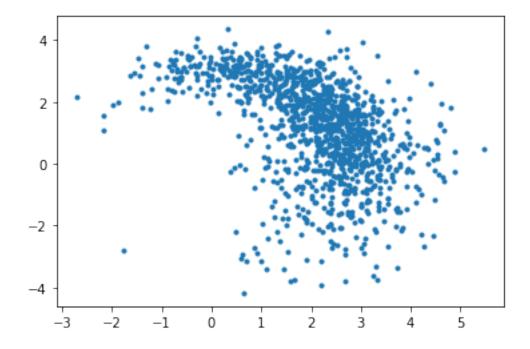
The covariance value of the 1 clustter is: [[1.15252815 -0.74748841] [-0.74748841 2.02037773]] .

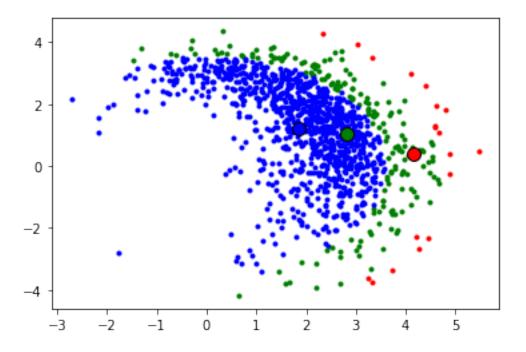
The mean value of the 2 clustter is: [2.80797793 1.05868803] .

The covariance value of the 2 clustter is: [[1.63040149 -1.42017465] [-1.42017465 5.02267257]] .

The mean value of the 3 clustter is: [4.15402558 0.38336721] .

The covariance value of the 3 clustter is: [[0.61682047 -0.19835895] [-0.19835895 7.07217604]] .





```
[136]: data_path = './data/data7.csv'
band_width = 0.8
  [data_theta, data_r, data_x, data_y] = pre_process(data_path)

#visualize data after remapping
fig = plt.figure()
plt.plot(data_x, data_y,".")

# process and visualize
[clusterred, cluster_result, current_cluster] = meanShift(band_width,__
____min_distance, data_r)
plot_result(clusterred, cluster_result, current_cluster, data_x, data_y)
```

The mean value of the 1 clustter is: [0.01169898 2.43486164].

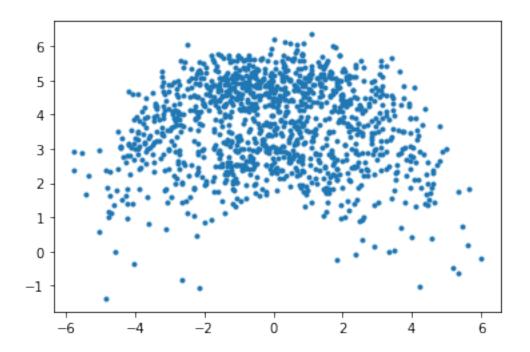
The covariance value of the 1 clustter is: [[2.11723578 -0.07404559] [-0.07404559 0.58011483]].

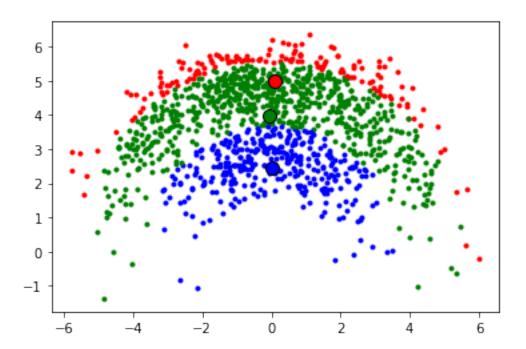
The mean value of the 2 clustter is: [-0.06568609 3.98044095].

The covariance value of the 2 clustter is: [[5.73663738 -0.06815426] [-0.06815426 1.15101721]].

The mean value of the 3 clustter is: [0.10731107 4.97217675].

The covariance value of the 3 clustter is: [[8.1656813 -0.24131626] [-0.24131626 1.17038314]].





[]: