
LINEAR ALGEBRA

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1 8/21/23 - Mon

1.1 Field and its Properties

Definition (Field). \mathbb{R}, \mathbb{C} k : is a field if k has operations and satisfies

1. k contains 0 & 1
2. $a+0=a, a \cdot 1 = a$
3. $a+b=b+a, (a+b) \cdot c = a \cdot c + b \cdot c$
4. $a \neq 0, a$ has multiplicative inverse i.e. $a \in K, a \cdot a^{-1} = 1, a^{-1} \in K$
5. $\forall a \in k$ has an additive inverse $-a$
6. associativity for $+$ and \cdot

examples that $\mathbb{Q}, \mathbb{R}, \mathbb{C}$ are fields

$\mathbb{Q}(i) = \{a + bi : a, b \in \mathbb{Q}\}$ is a field

$$i^{-1} = -i | (a + bi)^{-1} = \frac{a - bi}{a^2 + b^2}$$

\mathbb{Z} is not a field. Because not all element has a multiplicative inverse

1.2 vector space

Definition (Vector spaces). let K be a field. $K^n = \{(a_1, a_2, a_3 \dots a_n) | a_i \in K\}$ where a is a vector

$$\underbrace{(1, 0, \dots, 0)}_{e_1} \underbrace{(0, 1, \dots, 0)}_{e_2} \dots \underbrace{(0, 0, \dots, 1)}_{e_n}$$

also $\vec{0} \in K$

addition: $(a_1, a_2 \dots a_n) + (b_1, b_2, b_3 \dots b_n) = (a_1 + b_1, a_2 + b_2 \dots a_n + b_n)$

scalar multiplication: $c \in K, c \cdot (a_1, a_2, a_3 \dots a_n) = (ca_1, ca_2, ca_3 \dots ca_n)$ They satisfy the following requirement

1. $\vec{a} + \vec{a} = \vec{a}$
2. $\vec{b} + \vec{a} = \vec{a} + \vec{b}$
3. $c \cdot (\vec{a} + \vec{b}) = c \cdot \vec{a} + c \cdot \vec{b}$
4. $c_1 c_2 \cdot \vec{a} = c_1 \cdot (c_2 \cdot \vec{a})$
5. $(c_1 + c_2) \cdot \vec{a} = c_1 \vec{a} + c_2 \vec{a}$
6. $1 \cdot \vec{a} = \vec{a}$
7. $\vec{a} + -\vec{a} = \vec{0}$
- 8.

9.

with all the prereq, K^n is a vector space over K

Definition (general vector space). *a set V with origin $0 \in V$ together, closed addition and scalar multiplication*

i.e. $\vec{V} + \vec{W} \in V, c \cdot v \in V$ also $c \in K, v, w \in V$ is called vector space over K if all the above holds

any element $v \in V$ is called vectors of V

δ

:

e.g.

1. $\mathbb{R}C(\mathbb{R}) - \{ \text{continuous function on } \mathbb{R} \text{ is a v space over } \mathbb{R} \}$

2. $f + g \in C(\mathbb{R})$

3. $a \in \mathbb{R}$ a $\cdot f$, a function $f \in C(\mathbb{R})$ is a vector

more general X is a set $k(X) = \{ x \rightarrow k \}$ is a v space over $K \forall f, g \in k(x)$

$$(f + g)(x) = f(x) + g(x)$$

$$(c \cdot f)(x) = c \cdot f(x)$$

2 8/23/23 - Wed

2.1 fields

last class recall that V is a vector space over $\underbrace{K}_{\text{field, } k = \mathbb{R} \text{ or } \mathbb{C}}$ note in this class, \mathbb{R}, \mathbb{C} is our field

$$\underbrace{V}_{\text{vector}} \cdot \underbrace{W}_{\text{vector}} \in V$$

$$\text{also } V + W \in V$$

$$0 \in V$$

2.2 subspaces

Definition (subspaces). *V is a vector space over k we say the subset $W \subseteq V$ is a subspace if it is closed under*

- *addition*
- *multiplication*

$$v + w \in W$$

$$v \cdot w \in W$$

$$\forall v, w \in W, a \in K$$

note this definition also implies that $0 \in W$ e.g. $V = k^n$ $W = \{(a_1, a_2, a_3 \dots a_n) \in K^n \mid \sum_{i=1}^n a_i = 0\}$ $W \subseteq V$ subspace

2.3 Linear Combination

we have vectors $v_1, v_2, v_3 \dots v_n \in V$ and scalars $a_1, a_2, a_3 \dots a_n \in K$ and we call $a_1 + v_1, a_2 + v_2, a_3 + v_3$ **linear combination** of $v_1, v_2 \dots$ e.g. we have $e_1(1, 0) \wedge e_2(0, 1) \in k^2$ example

we have $(3, 2) = \underbrace{3}_{\text{scalar}} \underbrace{e_1}_{\text{vector}} + 2e_2$

Proposition 2.1. given $v_1, v_2 \dots v_n$ $W = \text{set of all possible linear combination of } v_1 \dots v_n$ then, W is a subspace of V .

Proof. given $a_1 v_1 \dots a_n v_n$ and $b_1 \dots b_n = (a_1 + b_1)v_1 + (a_2 + b_2)v_2 + \dots (a_n + b_n)v_n$ is also an linear combination

property 2. $c(a_1 v_1 + a_n v_n) = c(a_1)v_1 + c(a_n)v_n$

□

2.4 Dot Product

$\vec{a}(a_1, a_2 \dots a_n) \vec{b}(b_1, b_2 \dots b_n)$

$\vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 \dots a_n b_n$

Remark (properties of dot product).

- $\vec{a} \cdot \vec{b} = \vec{b} \cdot \vec{a}$
- $\vec{a} \cdot (\vec{b} + \vec{c}) = \vec{a} \cdot \vec{b} + \vec{a} \cdot \vec{c}$
- $\underbrace{(c \cdot \vec{a})}_{\text{scalar multiples}} \cdot \vec{b} = c(\vec{a} \cdot \vec{b})$

Definition (orthogonal). we say 2 vectors $\vec{a}, \vec{b} \in k^n$ are **perpendicular** or **orthogonal** if their dot product is 0 in k^n

in notation $e_i \cdot e_j = 0$

hence we write $\vec{a} \perp \vec{b}$

recall $W = \{(a_1, a_2 \dots a_n) | a_1 + a_n = 0 \subseteq k^n \equiv \{\vec{a} | \vec{a} \cdot (1, 1, 1)\}\}$ more generally $\vec{b}(b_1, b_2 \dots b_n)$
 $W\{\vec{a} \in k^n | \vec{a} \cdot \vec{b} = 0\} \subseteq k^n$

give n 2 sub spaces w_1 and w_2 we have 2 operations

1.

$$w_1 \cap w_2$$

2.

$$w_1 + w_2$$

Notice that both of those operations preserves sub spaces.

$$(w_1 + w_2) + (w'_1 + w'_2) = (w_1 + w'_1) + (w_2 + w'_2)$$

2.5 linear independence

Definition (Linear independence). V is a vector space over K , we say that $v_1, v_2 \dots v_n \in V$ are **linearly dependent** over K if there exists $a_1, a_2 \dots a_n$ such that not all of them are zero and $a_1v_1 + a_2v_2 + a_3v_3 + \dots a_nv_n = 0$ otherwise we call it linearly independent

Remark. we have k^2 where as we have $(1,0)(0,1) \in V(2,5)$ such that $= 2e_1 + 3e_2$ hence we know that

$$v - 2e_1 - 3e_2 = 0$$

Thus $e_1 \wedge e_2$ are not linearly independent

Remark. notice that e^t and e^{2t} functions are linearly independent

Proof. suppose that there are linearly dependent then we have a,b such that

$$ae^t + be^{2t} = 0$$

factor out a e^t we have

$$a + be^t = 0$$

taking derivative of both sides we have

$$be^t = 0$$

but $e^t \neq 0$ hence $b=0$ and $a=0$ which we have arrived at a contradiction \nexists

□

Definition (alternative definition of vector space). V is a vector space if

1. $v_1, v_2 \dots v_n$ are linearly independent

2. $v_1, v_2 \dots v_n$ **generates** V

(a) i.e. any vector $v \in V$ is a linear combination of $v_1, v_2 \dots v_n$

(a) e.g. $e_1, e_2, e_3 \dots e_n$ are linearly independent and clearly

i. $e_1, e_2, e_3 \dots e_n$ generates V

3 8/25/23 - Fri

Last class recall V is a vector space over K $v_1, v_2 \dots v_n \in V$

Definition (Linear Combination). $a_1v_1 + a_2v_2 + \dots + a_nv_n \in W = \{\sum a_i v_i | a_i \in K\} \subseteq V$
 $v_1, v_2 \dots v_n$ are linearly dependent if $a_1v_1 + a_2v_2 + \dots + a_nv_n = 0$ for $\forall \neq 0 a_i$
otherwise we call $v_1, v_2 \dots v_n$ are linearly independent

Definition (basis).

$$v_1, v_2 \dots v_n$$

is a **basis** if and only if:

1. $v_1, v_2 \dots v_n$ are linearly independent
2. $v_1, v_2 \dots v_n$ **generates** V

Theorem 3.1. Assume that $v_1, v_2 \dots v_n$ are linearly independent $\in V$ then $a_1v_1 + a_2v_2 + \dots + a_nv_n = b_1v_1 + b_2v_2 + \dots + b_nv_n$ then $a_i = b_i \forall i$ $a_i, b_i \in K$

Proof.

$$\begin{aligned} & (a_1v_1 + a_2v_2 + \dots + a_nv_n) - (b_1v_1 + b_2v_2 + \dots + b_nv_n) \\ &= (a_1 - b_1)v_1 + \dots + (a_n - b_n)v_n \\ &= 0 \end{aligned}$$

□

Note: Linearly independent of $v_1, v_2 \dots v_n \Rightarrow a_i - b_i = 0$
 $\Leftrightarrow a_i = b_i$

uniqueness of a_i . if $v_1, v_2 \dots v_n$ is a basis of V , then $\forall v \in V$
 $V = a_1v_1 + a_2v_2 + \dots + a_nv_n$ for unique $a_i \in K$

Definition (coordinates). if $v_1, v_2 \dots v_n$ is a basis, if $V = a_1v_1 + a_2v_2 + \dots + a_nv_n$
 we call $a_1, a_2 \dots a_n$ the coordinates of v with reference of this basis
 e.g. $\underbrace{(1, 1)}_{v_1}, \underbrace{(1, -1)}_{v_2}$ is a basis of K^2

Proof. 1. linear independence

suppose $\exists a, b$ s.t. $a \cdot (1, 1) + b \cdot (1, -1) = 0, K = \mathbb{R}$ or \mathbb{C}

$$(a + b)(a - b) = 0$$

$$(a + b = 0)$$

$$(a - b = 0)$$

$$(a = 0, b = 0)$$

Contradiction \nmid

2. v_1, v_2 generates K

Given $(a, b) \in K^2$

$$(a, b) = \frac{a+b}{2}(1, 1) + \frac{a-b}{2}(1, -1)$$

□

3.1 finitely generated vspace

Definition (Finitely generated). We say V is **finitely generated** over K if there exists $v_1, v_2 \dots v_n \in V$ which generates to V and its finite

Theorem 3.2. Suppose that $v_1, v_2 \dots v_n$ generates V . Let $\{v_1 \dots v_r\}$ be the maximal subset of linearly independent of vectors in $\{v_1, v_2 \dots v_n\}$ then $v_1 \dots v_r$ form a basis

Proof. By assumption, we know that $v_1, v_2 \dots v_r$ are linearly independent
 $\forall k, k > r$

$v_1, v_2 \dots v_r, v_k$ are linearly dependent

i.e. $a_1 v_1 + \dots + a_r v_r + b v_k = 0$ for some $a, b \neq 0$ in fact $b \neq 0$

$$v_k = -\frac{a_1}{b} v_1 - \dots - \frac{a_r}{b} v_r$$

which implies $v_1, v_2 \dots v_n$ generates V

Hence $v_1, v_2 \dots v_r$ is a basis

□

3.2 dimension of v space

Theorem 3.3 (linearly dependent for $n > m$). Let V be a vector space over K and let $\{v_1 \dots v_m\}$ be a basis of V , let $\{w_1 \dots w_n\}$ be vectors in V , assume $n > m$ then $w_1 \dots w_n$ are linearly dependent

proof by contradiction. Assumes that w_1, w_n are linearly dependent (\star)

For simplicity, let $m=2$ $n > 2$ and assume that $w_i \neq 0 \forall i$

First of all w_1 can be written as

$$w = a_1 v_1 + a_2 v_2$$

Since a_1, a_2 cannot both be 0 WLOG we may assume that $a_1 \neq 0$ then

$$v_1 = \frac{1}{a_1} w_1 - \frac{a_2}{a_1} v_2$$

Because v_1, v_2 generates V by the definition of v space $\rightarrow w_1, v_2$ generates V if we do this repeatedly

Thus

$$w_2 = b_1 w_1 + b_2 v_2$$

where as $b_2 \neq 0$

$$v_2 = \frac{1}{b_2} w_2 - \frac{b_1}{b_2} w_1$$

This means that

$$w_1, w_2 \text{ generates } V \text{ which contradicts } \star$$

⚡

□

Corollary (. 1.2 cardinality of the basis) Any 2 basis of V have the same cardinality

4 8/28/23 - Mon

Last class

Let V be a V space over K

recite the definition of basis lol

Theorem 4.1 (A). and let $v_1, v_2 \dots v_m$ be a basis of V and let $w_1, w_2 \dots w_n$ be any vectors in V and if $n > m$ then $w_1, w_2 \dots w_n$ are linearly independent

Proof. Last we have proven $m=2$

case $m=3$ $\{v_1, v_2, v_3\}$ is a basis for $n > 3$

$$w_1 = a_1 v_1 + a_2 v_2 + a_3 v_3 \Rightarrow v_1 = \frac{1}{a_1} w_1 - \frac{a_2}{a_1} v_2 - \frac{a_3}{a_1} v_3$$

WLOG assume that $a_1 \neq 0 \Rightarrow w_1, v_2, v_3$ generates V

$$w_2 = b_1 w_1 + b_2 v_2 + b_3 v_3$$

WLOG assume that $b_2 \neq 0$

$$v_2 = \frac{1}{b_2} w_2 - \frac{b_1}{b_2} w_1 - \frac{b_3}{b_2} v_3$$

Thus w_1, w_2, v_3 **generates** V

$$w_3 = c_1 w_1 + c_2 w_2 + c_3 v_3$$

which gives us

$$v_3 = \star w_1 + \star w_2 + \star v_3$$

which means that w_1, w_2, w_3 **Generates** v_1

and $w_4 = w_1 + w_2 + w_3 \rightarrow \nexists$

□

This allows us to arrive at an immediate corollary

Corollary i. any 2 basis of V have the same cardinality

Proof. $\#\mathcal{B} = \{v_1, v_2 \dots v_n\}$ be a basis and let

$$\#\mathcal{B}' = \{w_1, w_2 \dots w_n\}$$

by the above theorem, we can immediately conclude that

$$\#\mathcal{B} = \#\mathcal{B}'$$

□

4.1 dimensions & maximal set

Definition (Maximal set). $v_1, v_2 \dots v_n$ are linearly independent $\in V$

we say that $v_1, v_2 \dots v_n$ form a **maximal set** of linearly independent vectors of V .

i.e. $\forall w \in V, w_1 v_1, v_2 \dots v_n$ are linearly dependent

Theorem 4.2 (B). Any maximal set of linearly independent vectors of V is a basis

Proof. let $v_1, v_2 \dots v_n$ be a maximal set of linearly independent vectors of V be a basis
then, for all $w \in v$ are linearly dependent

$w_1 v_1, v_2 \dots v_n$ are linearly dependent

$bw + a_1 v_1 + a_2 v_2 + \dots + a_n v_n \rightarrow w = \star v_1 + \dots + \star v_n$

are linearly independent hence generates V

□

Theorem 4.3 (C). let V be a vspace over K and let $\dim V = n$

let $v_1, v_2 \dots v_n$ be any set of linearly dependent vectors $\in V$ then $v_1, v_2 \dots v_n$ is a basis

Proof. By theorem A, we know that $\{v_1, v_2 \dots v_n\}$ is a maximal set of linearly dependent vectors

Then by theorem B $\{v_1, v_2 \dots v_n\}$ is a basis

□

Note: $\# \text{maximal set} = \dim V$

Corollary K. let W be a subspace of V , if $\dim w = \dim V$ then $V = W$

i.e. Any proper subspace of w has $\dim W < \dim V$

Proof. suppose that $\dim W = \dim V = n$

then $\exists w_1, w_2 \dots w_n$ such that it is a basis of W

$w_1, w_2 \dots w_n$ is also a basis of v so $W = V$

□

Corollary L. suppose that $\dim V = n$ let $v_1 \dots v_r, r < n$ be linearly independent, then we can find vectors $v_{r+1} \dots v_n$ such that $v_1 \dots v_r, v_{r+1} \dots v_n$ forms a basis of V

Proof. $\{v_1 \dots v_r\}$ is NOT a maximal set of linearly independent vectors then $\exists v_{r+1}$ such that v_1, v_r, v_{r+1} are linearly independent if $r + 1 = n$ then we are done

otherwise we can find vectors $v_{r+1} \dots v_n$ such that $v_1, v_2 \dots v_n$ are linearly independent

□

Theorem 4.4 (D). let V be a vspace over K such that $\dim V = n$ and W is a proper subspace of V

Then W has a basis and $\dim w < n$

Proof. if $W=0$, then we are done

Otherwise suppose that $W \neq 0$

There exists a $w_1 \in W \neq 0$

tbc.....

□

5 8/30/23 - Cancelled

6 9/1/23 - Fri

recall: Let V be a finite dimension vector space over K

$\dim V = \#\mathcal{B}, \mathcal{B} = \{v_1, v_2 \dots v_n\}$ is a basis

Theorem 6.1. Any max set of linearly independent vectors is a basis

Theorem 6.2. if $\dim V = n$ and $v_1, v_2 \dots v_n \in V$ are linearly independent then $v_1, v_2 \dots v_n$ is a basis

Corollary i. $\dim v = n, v_1, v_2 \dots v_r$ and $v < n$ are linearly independent, then $\exists v_{r+1} \dots v_n$ such that $v_1 \dots v_r, v_{r+1}, \dots, v_n$ is a basis

Theorem 6.3. $\dim V = n$ and let W be any proper subspace of V , then W has a basis and $\dim W < n$

Proof. suppose W has no max set of linearly independent vectors then \exists vectors $v_1, v_2, v_3 \dots$ such that

$$\{v_1\} \subset \{v_1, v_2\} \subset \{v_1, v_2, v_3\}$$

are linearly independent but this contradicts $\dim V = n$ Thus W has a max set $\{w_1, w_2, \dots w_r\}$ of linearly independent vectors $r \leq n$ which is a basis since $w \subsetneq v$ $w_1, w_2, \dots w_r$ does not generate V

Hence $\{w_1, w_2, \dots w_r\}$ is not a basis of V
in particular $r < n$ □

6.1 sums & direct sums

Let V be a vector space over K , Let W, U be subspaces of V
recall $w + u = \{w + u | w \in W, u \in U\}$

Definition (direct sum). let W, U be subspaces of V , we say V is a direct sum of W and U if

1. $V = W + U$
2. $\forall v \in V$ can be written as a sum of $w = w + u$ in a **unique** way

we denote this $V = W \oplus U$

Theorem 6.4. let W, U be subspaces of V , if $V = W + U$ and $W \cap U = 0$ then $V = W \oplus U$

Proof. $V = u_1 + w_1 = u_2 + w_2 \rightarrow w_1 - w_2 = u_1 - u_2 \wedge w \cap u = 0 \rightarrow w_1 = w_2, u_1 = u_2$
This is a uniqueness proof □

Theorem 6.5. let V be a vector space, for any subspace $W \subseteq V$ there exists a **Compliment** U of W such that $V = W \oplus U$

Proof. By previous theorem \exists a basis $\{w_1, w_2, \dots w_r\}$ of W which can be extended to a basis $\{w_1, w_2, \dots w_r, w_{r+1} \dots w_n\}$ of V such that $U = \text{span}\{w_{r+1} \dots w_n\}$ Then, $V = W \oplus U$ □

Note: The author omitted a step that needed to prove that $U \cap W = 0$ because the instructor's handwriting is unreadable ☹

Theorem 6.6 (Dimensions of Direct sum v spaces). If $V = W \oplus U$ then $\dim V = \dim U + \dim W$

Proof. Choose a basis $\{u_1, u_2 \dots u_s\}$ of U and a basis $\{w_1, w_2, \dots w_t\}$ of W . Then $\{u_1, u_2 \dots, u_s, w_1, w_2 \dots, w_t\}$ forms a basis for V □

Remark. Given subspaces $w_1, w_2, w_k \subseteq V$

$w_1, w_2 + \dots w_k = \{w_1 + w_2 + \dots + w_k | w_i \in w, 1 \leq i \leq k\}$ is a subspace of V

Definition. We say that V is a direct sum of $w_1, \dots w_k$. If $\forall v \in V$ The summation $V = w_1 + \dots + w_k$ is unique

We write $V = w_1 \dot{+} w_2 \dot{+} w_3 \dot{+} \dots \dot{+} w_k$ $| w_i \in w_i$

e.g.

$$\mathbb{R}^3 = \underbrace{l_x}_{\mathbb{R}_{e_1}} |$$

$$l_{y\mathbb{R}_{e_2}} |$$

$$l_{z\mathbb{R}_{e_3}}$$

Theorem 6.7. $w_1 \dots w_k$ be subspaces of V if $V = w_1 + \dots w_k$ and $w_i \cap (\sum_{j \neq i} w_j) = 0$ then $V = w_1 \dot{+} \dots \dot{+} w_k$

Proof. $k=3$

$$V = w_1 + w_2 + w_3 = w'_1 + w'_2 + w'_3$$

$$\rightarrow w_1 - w'_1 = w_2 - w'_2 = w_3 - w'_3$$

□

Lemma *. $w_1 \cap (w_2 + w_3) = 0$

then $v = w_1 = w_2 + w_3$

7 9/6/23 - Wed

recall: direct sum $W, U, \subseteq V$ $V = W \dot{+} U$ if

\exists a unique $w \in W, u \in U$ s.t.

$V = w + u$ and $w \cap u = 0$

Given 2 vectors w, u

Let $w \times u$ be a direct product

$$w \times u = \{(w, u) | w \in W, u \in U\}$$

$W \times U$ can be endowed w/ a vector space structures

Additives $(w, u) + (w' + u') = (w + w', u + u')$

scalar multiplication $a(w, u) = (aw, au)$

$W \times U$ is a vector space over K

ex : $\dim W \times U \{w_1, w_2 \dots w_n\}$ be a basis of W

$\{u_1, u_2 \dots u_m\}$ be a basis of U

$$\{(w_1, 0) \dots (w_n, 0)(0, u_1 \dots (0, u_m))\}$$

is a basis of $W \times U$

in fact W can be identified w/ $\{(w, 0) | w \in W\} \subseteq W \times U$

U can be identified w/ $\{(0, u) | u \in U\} \subseteq W \times U$

under such identification $W \times U = W \amalg U$

$$W \subseteq W \times U$$

$$W \rightarrow (W, 0)$$

Remark. Given $v_1, v_2 \dots v_n$ we can define their produce $V_1 \times V_2 \times V_3 \dots \times V_n$ to be a vector space

7.1 Matricies

we call matricies

$$\begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

This is a $m \times n$ matrix over a field $K(\mathbb{R}, \mathbb{C}, \mathbb{Q} \dots)$

Where a row vectors are

$$a_1 = (a_{11}, a_{12} \dots a_{1n})$$

\dots

$$a_m = a_{m1}, a_{m2}, \dots, a_{mn}$$

Where column vectors are

$$a^1 = \begin{bmatrix} a_{11} \\ a_{21} \\ \dots \\ a_{n1} \end{bmatrix}$$

\dots

$$a^n = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \dots \\ a_{mn} \end{bmatrix}$$

Definition (square matrix). if $m=n$ then A is a square matrix

Definition (zero matrix). $A_{ij} = 0 \forall i, j$ Then a is a zero matrix

Definition (diagonal matrix). the square matrix A is called diagonal if

$$A = \begin{bmatrix} x & & & \\ & \dots & & \\ & & \dots & \\ & & & x \end{bmatrix}$$

Definition (Upper triangular matrix). *The square matrix A is upper triangular iff*

$$A = \begin{bmatrix} x & x & x & x \\ & x & x & x \\ & & x & x \\ & & & x \end{bmatrix}$$

Definition (Lower triangular matrix). *The square matrix A is lower triangular iff*

$$A = \begin{bmatrix} x & & & \\ x & x & & \\ x & x & x & \\ x & x & x & x \end{bmatrix}$$

A $m \times n$ matrix is transposed when

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & \dots & a_{2n} \\ \dots & \dots & \dots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \sim A^t = \begin{bmatrix} a_{11} & \dots & a_{m1} \\ \dots & \dots & \dots \\ a_{1n} & \dots & a_{mn} \end{bmatrix}$$

we denote this $a^t \equiv a \equiv A^T \dots$

Let $\mathcal{M}_{m \times n}(K) = \{m \times n \text{ matrices over } K\}$

Addition of scalar multiplication, on $\mathcal{M}_{m \times n}(K)$

$A + B (A = a_{ij}, B = b_{ij})$

$= a_{ij} + b_{ij} \forall c \in K, c \cdot A = (ca_{ij})$

Zero matrix $\mathcal{O} \in \mathcal{M}_{m \times n}(K)$

A $m \times n$ matrix A is called symmetri iff $A = A^t$

7.2 sys. of Linear Eqns

Given $a_{11}x_1 + \dots + a_{1n}x_n = b_1$

...

$a_{m1}x_1 + \dots + a_{mn}x_n = b_m$

if $\forall b_i = 0$ we call this system homogeneous

which can be written as

$$(\star)x_1 \begin{bmatrix} a_{11} \\ a_{12} \\ \dots \\ a_{m1} \end{bmatrix} + x_2 \begin{bmatrix} a_{12} \\ a_{22} \\ \dots \\ a_{m2} \end{bmatrix} + \dots + x_n \begin{bmatrix} a_{1n} \\ a_{2n} \\ \dots \\ a_{mn} \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_m \end{bmatrix}$$

To find a solution of such eqn is equiv to express $\begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_m \end{bmatrix}$ as a linear combination of

$$A' = \begin{bmatrix} a_{11} \\ a_{21} \\ \dots \\ a_{m1} \end{bmatrix} \dots \begin{bmatrix} a_{1m} \\ a_{2m} \\ \dots \\ a_{mn} \end{bmatrix}$$

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Theorem 8.1 (Linear independence of solns). In a linear system \star , assume that $m=n$, and A^1, A^2, \dots, A^n are linearly independent then, \star has a unique solution.

Proof. Let $A^1, A^2, \dots, A^n \in \mathbb{K}^n$ and they are linearly independent. Thus they form a basis $\rightarrow B = c_1 A^1 + \dots + c_n A^n$ for unique numbers
i.e. (c_1, c_2, \dots, c_n) is a unique solution. □

8.1 Matrix multiplications

Let

$$A = a_1, a_2 \dots a_n \in \mathbb{K}^n$$

$$B = b_1, b_2 \dots b_n \in \mathbb{K}^n$$

recall their dot product $A \cdot B = a_1 b_1 + a_2 b_2 + \dots + a_n b_n$

They have some nice properties

1. $A \cdot B = B \cdot A$
2. $c \in \mathbb{K}, (cA)B = c(AB) = A(cB)$

Definition (Matrix multiplication). Given 2 matrices

$A = a_{ij} m \times n$ matrix

$B = b_{ij} n \times k$ matrix

We define a matrix multiplication AB as

$$AB = \begin{bmatrix} A_1 B^1 & A_1 B^2 & \dots & A_1 B^k \\ A_2 B^1 & A_2 B^2 & \dots & A_2 B^k \\ \dots & \dots & \dots & \dots \\ A_m B^1 & A_m B^2 & \dots & A_m B^k \end{bmatrix}$$

$$e.g. \ a = \begin{bmatrix} 2 & 1 & 5 \\ 1 & 3 & 2 \end{bmatrix} \ b = \begin{bmatrix} 3 & 4 \\ -1 & 2 \\ 2 & 1 \end{bmatrix}$$

$$ab = \begin{bmatrix} 15 & 15 \\ 4 & 12 \end{bmatrix}$$

In general let $A : m \times n, B : n \times k \rightarrow AB : m \times k$

Let $A = a_{ij}$ be a $m \times n$ matrix

let $B = \begin{bmatrix} b_1 \\ b_2 \\ \dots \\ b_n \end{bmatrix}$ which is a column vector $n \times 1$ matrix

Their product AB is a $\begin{bmatrix} A^1 B \\ A^2 B \\ \dots \\ A^n B \end{bmatrix}$ col vector

A system of linear equation \star can be written as

$$Ax = B$$

where

$$X = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix}$$

Where as $c : (c_1, c_2, \dots, c_m)$ is a row vector

$cA = (cA^1, cA^2, \dots, cA^n)$ has a $\# = n$

can be alternatively written as the product of

$$(c_1, c_2, \dots, c_m) \cdot \begin{bmatrix} a_{11} & a_{12} & \dots \\ a_{21} & a_{22} & \dots \\ \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots \end{bmatrix} \equiv \begin{bmatrix} A^1 & A^2 & \dots & A^m \end{bmatrix}$$

Theorem 8.2. A $m \times n$ matrix B $n \times k$ matrix A $A(B+C) = AB + AC$

Notation A matrix $\rightsquigarrow A_{ij} = ij$ entries of A

if $A = a_{ij}$ then $(AB)_{ij} = A_i B_j$

Proof. $(A(B + C))_{ij}$

$$= A_i (B + C)^j$$

$$= A_i (B^j + C^j)$$

$$= A_i B^j + A_i C^j$$

$$= (AB)_{ij} + (AC)_{ij} = (AB + AC)_{ij}$$

□

Theorem 8.3 (commutativity of scalar multiplication). let $c \in \mathbb{K}$

$$(cA)B = A(cB)$$

Assume $A, B = m \times n$ matrix and let $C = n \times k$ matrix then $(A + B)C = AC + BC$

Theorem 8.4 (commutativity of matrix multiplication). let ABC be mutually manipulable matrices then $(AB)C = A(BC)$

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Recall $A = (a_{ij})$ be a $m \times n$ matrix $B = b_{ij}$ be a $n \times k$ matrix
 $AB = (c_{ij})$ of a matrix

$$(AB)_{ij} = A_i B^j = (a_1, a_2, \dots, a_n) \cdot \begin{bmatrix} b_{1j} \\ b_{2j} \\ \dots \\ b_{nj} \end{bmatrix}$$

Theorem 9.1. $A: m \times n$ matrix $B: n \times k$ matrix $C: k \times l$ matrix
 $(AB)C = A(BC)$ (assoc.)

Proof. $A = a_{ij}$ $B = b_{ij}$ $C = c_{ij}$

$$AB_{ij} = \sum_{s=1}^n a_{is} b_{sj} \quad ((AB)C)_{ij} = \sum_{t=1}^k (AB)_{it} C_{tj} = \sum_{t=1}^k \left(\sum_{s=1}^n a_{is} b_{st} \right) c_{tj} = \sum_{t=1}^k \sum_{s=1}^n a_{is} b_{st} c_{tj}$$

similarly

$$(A(BC))_{ij} = \sum_{s=1}^n a_{is} (BC)_{sj} = \sum_{s=1}^n a_{is} \left(\sum_{t=1}^k b_{st} c_{tj} \right)$$

$$= \sum_{s=1}^n \sum_{t=1}^k a_{is} b_{st} c_{tj} \quad \text{The summation can be switched}$$

□

let $A = a_{ij}$ be a $m \times n$ matrix

$ijA^t = a_{ji}$ then $A^t = n \times m$ matrix

$B = n \times k$ matrix

$B^t = k \times n$ matrix

Theorem 9.2. $(AB)^t = B^t A^t$

Proof. $ij(AB)^t = (AB)_{ji} = \sum_{s=1}^n a_{js} b_{si}$

$$ij(B^t A^t) = \sum_{s=1}^n (B^t)_{is} (A^t)_{sj} = \sum_{s=1}^n b_{si} a_{js}$$

□

9.1 Linear maps

Definition (Linear maps). Let v, w , be vector spaces over K , a map $F: V \rightarrow W$ is called linear if

1. $F(V + U) = F(U) + F(V) \forall v, u \in V$
2. $F(av) = aF(v), \forall a \in K, v \in V \equiv F(au + bv) = aF(u) + bF(v)$

Remark. $F(0) = 0$

e.g. let $P: K^3 \rightarrow K^2$

$$1. (x, y, z) \mapsto (x, y)$$

$$2. \mathbb{C}^\infty(\mathbb{R}) \rightarrow \mathbb{C}^\infty(\mathbb{R})$$

$$f \mapsto \frac{df}{dx}$$

$$3. A = (a, b, c) \in K^3$$

$$F_A: K^3 \rightarrow K \text{ given by } F_A(x, y, z) = ax + by + cz = A \cdot (x, y, z)$$

hence F_A is linear

let $A = (a_{ij})$ be a $m \times n$ matrix

we define a map $F_A : \underbrace{K^n \rightarrow K^m}_{\text{which is linear}}$

$$x \mapsto AX = \begin{bmatrix} A_1 \cdot x \\ A_2 \cdot x \\ \vdots \\ A_m \cdot x \end{bmatrix}$$

Let V be a vector space over K

Identity map $V \rightarrow V$ 0 map $V \rightarrow V, V \rightarrow 0$ they are all linear

Given a basis $\mathcal{B} : \{v_1, v_2 \dots v_n\}$ of V

$F_{\mathcal{B}} : V \rightarrow K^n$

$v \mapsto (x_1, x_2 \dots x_n)$ where $v = x_1 v_1 + \dots + x_n v_n$

and we know $F_{\mathcal{B}}$ is linear

$v = \sum x_i v_i, w = \sum y_i v_i, v + w = \sum (x_i + y_i) v_i$

hence $F_{\mathcal{B}}(w) = F_{\mathcal{B}}(V)$

see pic Given V, W such that they are vector spaces over K

$L(V, W) = \{\text{Linear maps from } V \text{ to } W\}$

Then $L(V, W)$ is a vector space over K

So we have fcn's $F, G, (F + G)(v) = F(v) + G(v)$

$(aF)(v) = aF(v)$

$0 \in L(V, W)$

$0 : v \mapsto w$

$v \mapsto 0$

Theorem 9.3. v, w , as arb. and let $\mathcal{B} = \{v_1, v_2 \dots v_n\}$ be a basis of V , and let $\{w_1, w_2 \dots w_n\}$ be a arb set of vectors in W .

There exists a unique linear map $F : V \rightarrow W$ such that $F(v_1) = w_1, f(v_2) = w_2 \dots f(v_n) = w_n$

Proof. $F(v) = a_1 w_1 + \dots + a_n w_n$

where $v = a_1 v_1 + a_2 v_2 + \dots + a_n v_n$ Then one way check F is linear

□

see pic

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Recall: A linear map $F : V \rightarrow W, V, W/K$

$F(au + bv) = aF(u) + bF(v), a, b \in K, u, v \in V$

$L(V, W) = \{\text{Linear maps from } V \rightarrow W\}$

vector spaces over K

10.1 Kernel and image of linear maps

Let $F : V \rightarrow W$ Linear

Definition (kernel). $\ker F = \{v \in V \mid f(v) = 0\} \subseteq V$

Lemma . $\ker F$ is a subspace of V

Proof. Given $u, v \in \ker F$, $\forall a, b \in K$ $F(au+bv) = aF(u)+bF(v) = 0 \rightarrow au+bv \in \ker F$ \square

Lemma . $F : V \rightarrow W$ is injective if and only if $\ker F = 0$

Proof. \rightarrow suppose F is injective, then the only element that maps to 0 is 0

\leftarrow

$\forall u, v \in V$ suppose $F(u) = F(v)$ then by injectivity of $F(u - v) = 0$

since $\ker F = 0$, $u - v = 0 \rightarrow u = v$ \square

e.g. $A = (2, 1, -1) \in K^3$

$F_A : K^3 \rightarrow K$

$(x, y, z) \mapsto (2x + y - z)$

$\ker F_A = \{(x, y, z) \in K^3 \mid 2x + y - z = 0\}$

similarly $A = ija : m \times n$ matrix

$F_A : K^m \rightarrow K^n$

X : col vector

$X \mapsto AX$

$\ker F_A = \{X \in K^n \mid A \cdot X = 0\}$

$= \{\text{solution of } \begin{bmatrix} a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ \dots \\ a_{m1}x_1 + \dots + a_{mn}x_n = 0 \end{bmatrix}\}$ call it $\star \ker F_A = 0 \iff \star$ has trivial solution \iff

F_A is injective \iff col vectors are linearly independent

Theorem 10.1. $F : V \rightarrow W$ linear s.t. $\ker F = 0$

if $v_1, v_2 \dots v_n \in V$ are linearly independent then $F(v_1), F(v_2) \dots, F(v_n)$ are also linearly independent

Proof. by contradiction suppose we have $a_1f(v_1) + \dots + a_nf(v_n) = 0$

by linearity we have $f(a_1v_1 + a_2v_2 + \dots + a_nv_n) = 0$ then $a_1v_1 + a_2v_2 + \dots + a_nv_n = 0$

hence $a_1 = \dots = a_n = 0$ \square

10.2 image

$F : V \rightarrow W$ linear

$\text{Im} F = F(V) = \{f(v) \mid v \in V\}$

Lemma I. $\text{Im} F$ is a subspace of W

Proof. $\forall F(v), F(u) \in \text{im} F, \forall a, b \in K$
 $aF(u) + bF(v) = F(au + bv) \in \text{im} F$

□

Given $v_1, v_2 \dots v_n \in V$
 $F : K^n \rightarrow V$
 $(a_1, a_2 \dots a_n) \mapsto a_1v_1 + a_2v_2 + \dots + a_nv_n$
 $\text{im} F = \{\text{linear combinations of } v_1, v_2 \dots v_n\}$
 $= \text{span}\{v_1, v_2 \dots v_n\}$
 $F_A : k^n \rightarrow k^m$
 $X = \begin{bmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{bmatrix} \mapsto A \cdot X$ note that $A \cdot X = \star\star$ or a lin comb of the col vectors

$\text{im} F_A = \text{span}\{\text{column of vectors}\}$

Given $A = \begin{bmatrix} 2 & 1 & -1 \end{bmatrix}$

$K^3 \rightarrow k$

$(x, y, z) \mapsto 2x + y - z$

$\dim \ker F_A = 2$

$\text{Im } F_A = k \dim \text{Im } F_A = 1$

Theorem 10.2. $F : v \rightarrow w$ linear
 $\dim \ker F + \dim \text{Im } F = \dim V$

Proof. Choose a basis $\{w_1, w_2 \dots w_n\}$ of $\text{Im } F$ also a basis $v_1, v_2 \dots v_n$ of $\ker F$ Choose There exists $u_1, u_2 \dots u_m \in V$

s.t. $F(u_1) = w_1 \dots f(u_m) = w_m$

we claim that $\{u_1, u_2, \dots u_m, v_1 \dots v_n\}$ is a basis of V

1. it generates V

$\forall v \in V, f(v) \in \text{im } F$

$F(v) = a_1w_1 + \dots + a_mw_n$

$= a_1f(u_1) + \dots + a_mF(u_m)$

$= F(a_1u_1 + \dots a_mu_m) \rightarrow v - \sum a_iu_i \in \ker F \rightarrow v - \sum a_iu_i = \sum b_jv_j$

2. $\{v_1, v_2 \dots v_n, u_1 \dots, u_m\}$ is linearly independent

suppose $\sum a_iv_i + \sum b_ju_j = 0$

we apply F hence $F(b_ju_j) = 0$

$= \sum b_jF(u_j)$

$= \sum b_jw_j = 0$

by linearly independent of $\{w_j\}, b_j = 0 \forall j \rightarrow \sum a_iv_i = 0, a_i = 0 \forall i$

□

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$A = a_{ij} : m \times n$ matrix $F_A : K^n \rightarrow K^m$

$X \mapsto AX$

$\ker F_A = \{\text{sols of } AX=0\}$

$\text{Im } F = \text{span}\{\text{sol vectors}\} \rightarrow n = \dim\{\text{sols of } AX=0\} + \dim \text{span}\{\text{col of } A\}$

Let $n = m$ $AX=0$ has only trivial sol \iff cols of A is a basis of K^n

Theorem 11.1. $F : V \rightarrow W$: Linear Map
assume $\dim V = \dim W$ if $\ker F = 0$ or $\text{Im } F = W$ then F is a bijection.

Proof. Let $\underbrace{\ker F = 0}_{F \text{ is injective}}$ by thm $\iff \dim \text{Im } F = \underbrace{\dim V = \dim W}_{\text{By assumptions}}$

$\iff \text{Im } F = W$

i.e. F is injective $\iff F$ is surjective

□

11.1 Composition of linear maps

Theorem 11.2. Given 2 linear maps $F: U \rightarrow V$ $G: V \rightarrow W$ Their composition $G \circ F : U \rightarrow W$ is linear

Proof. $\forall u_1, u_2 \in U, a_1, a_2 \in K$

$G \circ F(a_1 u_1 + a_2 u_2)$

$= G(F(a_1 u_1 + a_2 u_2))$

$= G(a_1 F(u_1) + a_2 F(u_2))$

$= a_1 G(F(u_1)) + a_2 G(F(u_2))$

$= a_1 (G \circ F)(u_1) + a_2 (G \circ F)(u_2)$

hence $G \circ F$ is linear

□

Theorem 11.3. $F : V \rightarrow W$ linear and bijective then its inverse $G : W \rightarrow V$ is also linear

Proof. $\forall w_1, w_2 \in W, a_1, a_2 \in K$

$G(a_1 w_1 + a_2 w_2)$ want to prove $= a_1 G(w_1) + a_2 G(w_2)$

we apply $F, F(G(a_1 w_1 + a_2 w_2)) \equiv a_1 w_1 + a_2 w_2$

where as $a_1 G(w_1) + a_2 G(w_2)$ apply $F, F(a_1 G(w_1) + a_2 G(w_2)) = a_1 F(G(w_1)) + a_2 F(G(w_2)) =$

$a_1 w_1 + a_2 w_2$

since F is bijective we are done

□

e.g. $K^2 \xrightarrow{F} K^2$

$(x, y) \mapsto (2x - y, x + y)$

is that a bijection?

$$\begin{bmatrix} x \\ y \end{bmatrix} \rightarrow \begin{bmatrix} 2x - y \\ x + y \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

1. $\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ are linearly independent $\rightarrow F$ is bijective

2. Only trivial solution = $\ker F = 0$ hence F is bijective

Definition (isomorphism). A linear map F is called isomorphism or invertible if F is also a bijection

ie F : invertible $\rightarrow F^{-1}$ is linear

$A \in \mathcal{M}_{m \times n}(k) \rightsquigarrow F_A \in \mathcal{L}(k^n, k^m)$
 $\mathcal{M}_{m \times n}(k) \rightarrow \mathcal{L}(k^n, k^m)$
 linear

Theorem 11.4. $\mathcal{M}_{m \times n}(k) \rightarrow \mathcal{L}(k^n, k^m)$
 is injective i.e. $F_A = F_B \rightarrow A = B \forall A, B \in \mathcal{M}_{m \times n}(k)$

Proof. since F is linear it is sufficient to show that $F_A = 0 \rightarrow A = 0$

$$F_A(X) = AX = \begin{bmatrix} A_1 \cdot X \\ A_2 \cdot X \\ \vdots \\ A_n \cdot X \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \forall X \in K^n$$

$x \in k^n$ for each $i = 1 \dots m \rightarrow A_i X = 0, \forall X \in k^n \rightarrow A_i = 0$

□

Lemma . If $a_1 x_1 + \dots a_n x_n = 0$

$\forall x_i \in K$

then $a_i = \dots = a_n = 0$

Theorem 11.5. $F : \mathcal{M}_{m \times n}(k) \rightarrow \mathcal{L}(k^n, k^m)$
 $A \mapsto F_A$ is surjective
 ie for any linear map $Q : k^n \rightarrow k^m$ $Q = F_A$ for some A .

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$F : V \rightarrow W, G : W \rightarrow U$ be linear maps

Composition $G \circ F : V \rightarrow U$

1. $G \circ F$ is linear

$$2. G \circ (a_1 F_1 + a_2 F_2) = a_1 G \circ F_1 + a_2 G \circ F_2$$

$$(b_1 G_1 + b_2 G_2) \circ F = b_1 G_1 \circ F + b_2 G_2 \circ F$$

$$\mathcal{M}_{m \times n}(k) \xrightarrow{\varphi} \mathcal{L}(k^n, k^m)$$

$$A \mapsto F_A$$

$$\text{e.g. } A = \begin{bmatrix} 2 & 1 \\ -1 & 5 \\ 1 & 0 \end{bmatrix} \rightsquigarrow F_A : k^2 \rightarrow k^3$$

$$F_A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

$$F_A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ 0 \end{bmatrix}$$

In general

Given $A = (a_{ij}) : m \times n$ matrix

$F_A(e_i)$ = ith column of A

$$\text{e.g. } e_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Theorem 12.1. $\varphi : \mathcal{M}_{m \times n}(k) \rightarrow \mathcal{L}(k^n, k^m)$ is injective i.e. $F_A = F_B \forall A, B \in \mathcal{M}_{m \times n}(k)$

Theorem 12.2. φ is onto i.e. \forall linear maps $F : k^n \rightarrow k^m$ there exists a $m \times n$ matrix A such that $F = F_A$

Lemma . Given a linear map $F : k^n \rightarrow k$

$$F = \underbrace{A \cdot X}_{\text{dot product}} \text{ where } A = F(e_1), F(e_2), \dots, F(e_n) \in k^n$$

$$\text{e.g. } F : k^n \rightarrow k$$

$$F(x_1 \dots x_n) = a_1 v_1 + a_2 v_2 + \dots + a_n v_n$$

$$F(e_1) = a_1, F(e_2) = a_2 \dots$$

Proof. We can write $X = x_1 e_1 + \dots + x_n e_n$

$$F(x) = x_1 F(e_1) + \dots + x_n F(e_n)$$

$$= F(e_1) \cdot x_1 + \dots + F(e_n) \cdot x_n$$

□

proof of theorem

Proof. Let $F : k^n \rightarrow k^m$ be a linear map

Let $P : k^m \rightarrow k$ be the i th projection

$$p_i \cdot \begin{bmatrix} y_1 \\ \dots \\ y_n \end{bmatrix} = y_i$$

Then $p_i \circ F : k^n \rightarrow k$ is linear, by the lemma $p_i \circ F(X) = A_i \cdot X_i$ for some $A_i \in k^n$

$$\text{In fact } F(x) = \begin{bmatrix} A_1 \cdot X \\ A_2 \cdot X \\ A_3 \cdot X \\ \vdots \\ A_m \cdot X \end{bmatrix} = AX, A = \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_m \end{bmatrix} \quad \square$$

$$\begin{aligned} & a_1, \dots, a_n \in k^n \\ A &= \begin{bmatrix} A_1 \\ A_2 \\ \vdots \\ A_m \end{bmatrix} : m \times n \text{ matrix} \\ A_1 & \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \end{bmatrix} \in k^n \\ A_2 & \begin{bmatrix} a_{21} & a_{22} & \dots & a_{2n} \end{bmatrix} \in k^n \\ & \dots \end{aligned}$$

Theorem 12.3 (A+B). let $\Phi : \mathcal{M}_{m \times n}(k) \rightarrow \mathcal{L}(k^n, k^m)$
 is an isomorphism of vector spaces over k
 for any $F \in \mathcal{L}(k^n, k^m)$
 there exists a unique $m \times n$ matrix A
 such that $F = F_A$ we call A to be associated matrix of F

e.g. $F : k^3 \rightarrow k^2$

$(x, y, z) \mapsto (x + y, z)$

find the associated matrix of F

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} : 2 \times 3$$

$$F\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad F\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad F\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

In general $F : k^n \rightarrow k^m$

$$F = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n \end{bmatrix} \quad \text{e.g. } L_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

a rotation by θ counter-clockly

what is the matrix A ?

$$A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

e.g. $R(\frac{\pi}{2}) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

Lemma . Let A $m \times n$ matrix and B $n \times l$ matrix

$$F_A : k^n \rightarrow k^m, F_B : k^l \rightarrow k^n$$

$$\text{then } F_A \circ F_B = F_{AB}$$

Proof. for every $x \in k^n$ $F_{AB} = (AB)X = A(BX) = (F_A \circ F_B)(x)$ □

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warning: Midterm 9/27 chap I-IV

recall $\mathcal{M}_{m \times n}(k) \xrightarrow{\sim} L(k^n, k^m)$

$$\text{hence } A \mapsto^\varphi F_A$$

$$F_{AB} = F_A \circ F_B$$

let $n=m$, F_A is invertible iff A is invertible

Proof. \rightarrow

$$F_A : K^n \rightarrow K^n \text{ invertible}$$

there exists $G : k^n \rightarrow k^n$ such that $F_A \circ G = Id, G \circ F_A = Id$ $G = F_A^{-1}$ for a unique matrix B

$$\text{then } F_A \circ F_B = F_{AB} = Id = F_I$$

$$F_B \circ F_A = F_{BA} = Id = F_I$$

□

Theorem 13.1. $A : n \times n$ matrix and let A^i be the i th col of A , then A is invertible iff $A^1 \dots A^n$ are linearly independent

Proof. consider the associated linear map

$$F_A : K^n \rightarrow K^n, X \mapsto AX$$

$$F_A(e_i) = A^i$$

As explained previously A is invertible iff F_A is invertible. F_A is invertible then $A^1 \dots A^n$ are linearly independent

$$\text{suppose we have } c_1 A^1 + \dots + c_n A^n = 0$$

$$\text{then we know that } c_1 F_A(e_1) + \dots + c_n F_A(e_n) = 0 \iff F_A(c_1 e_1 + \dots + c_n e_n) = 0 \iff$$

$$c_1 e_1 + \dots + c_n e_n = 0 \iff c_1 = \dots = c_n = 0$$

\leftarrow suppose $A^1 \dots A^n$ are linearly independent then they form a basis of k^n . There exists a linear map $G : k^n \rightarrow k^n$ s.t.

$$G(A^1) = e_1 \dots G(A^n) = e_n$$

clearly $F_A \circ G = I \quad G \circ F_A = I$

□

e.g. $\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$ is invertible since A^1, A^2, A^3 are linearly independent

$$\text{e.g. } F(x, y, z) = (x - 2y, y - z, 2z), F_A = \begin{bmatrix} 1 & -2 & 0 \\ 0 & -1 & -1 \\ 0 & 0 & 2 \end{bmatrix}$$

This matrix is invertible because $\dim \mathbb{R}^3 = \dim \mathbb{R}^3 \rightarrow$ dimension is the same also $\ker F = \mathcal{O} \rightarrow$ this is injective hence this is bijective and A is invertible

13.1 Bases, matrices and linear maps

V is a vector space over K and let \mathcal{B} be a basis $\{v_1, v_2 \dots v_n\}$

$k^n \xrightarrow{\varphi} V$ is an isomorphism iff $(a_1, a_2 \dots a_n) \mapsto a_1 v_1 + a_2 v_2 + \dots + a_n v_n$ that $\{v_1, v_2 \dots v_n\}$ is a basis

Proof. φ is injective $\iff v_1, v_2 \dots v_n$ are linearly independent

φ is surjective $\iff v_1, v_2 \dots v_n$ generates v.

□

Given a linear map $F : V \rightarrow W$

Let \mathcal{B} be a basis of V, \mathcal{B}' be a basis of W

Let $\dim V = n \quad \dim W = m$

$$V \xrightarrow{F} W$$

$k^n \xrightarrow{F_{\mathcal{B}'}} k^m$ Let $M_{\mathcal{B}'}^{\mathcal{B}}(F)$ be a matrix associated to $F_{\mathcal{B}'}$

Definition. $M_{\mathcal{B}'}^{\mathcal{B}}(F)$ is the matrix associated to F with respect to $\mathcal{B}, \mathcal{B}'$

Exercise . $V \subseteq k^3, V = \{(x, y, z) | x + y + z = 0\}$ $F : k^3 \rightarrow V$

$F(x, y, z) = (x - y, y - z, z - x)$ we have standard basis $e_1 = (1, 0, 0), e_2 = (0, 1, 0), e_3 = (0, 0, 1)$

$v_1 = (1, -1, 0), v_2 = (0, -1, 1)$ clearly forms a basis of V. $F(1, 0, 0) = (1, 0, -1) = v_1 - v_2$

$F(0, 1, 0) = (-1, 1, 0) = -v_1$

$F(0, 0, 1) = (0, -1, 1) = v_2$

we claim that $M_{\mathcal{B}'}^{\mathcal{B}}(F) = \begin{bmatrix} 1 & -1 & 0 \\ -1 & 0 & 1 \end{bmatrix}$

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V: a vector space over K

$\mathcal{B} = \{v_1, v_2 \dots v_n\}$

$v \in V, v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n$

$X_{\mathcal{B}} = (x_1, \dots, x_n)$ coordinates of v w.r. to \mathcal{B}
 e.g. $k^2 \{v_1(1, 1), v_2(1, -1)\}$ a basis $= \mathcal{B}$ $v(1, 0) = \frac{1}{2}v_1 + \frac{1}{2}v_2$ $X_{\mathcal{B}} = (\frac{1}{2}, \frac{1}{2})$
 Given a linear map $F : V \rightarrow W$
 $\mathcal{B} = \{v_1, v_2 \dots v_n\}$ a basis of V
 $\mathcal{B}' = \{w_1, w_2 \dots w_m\}$ a basis of W
 then $\exists \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}$ $m \times n$ matrix associated to F and $\mathcal{B}, \mathcal{B}'$

$$F : \underbrace{V}_{k^n} \xrightarrow{\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F)} \underbrace{W}_{k^m}$$

Theorem 14.1. $\forall v \in V$

$$X_{\mathcal{B}'}(F(v)) = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F)X_{\mathcal{B}}(v)$$

Proof. By linearity it suffices to check for $v_1, v_2 \dots v_n$ we write

$$F(v_1) = a_{11}w_1 + \dots a_{m1}w_m$$

...

$$F(v_n) = a_{m1}w_1 + \dots a_{mn}w_m$$

$$X_{\mathcal{B}'}F(v_1) = (a_{11}, a_{21} \dots a_{m1})$$

$$X_{\mathcal{B}'}F(v_i) = (a_{1i}, a_{2i} \dots a_{mi}), 1 \leq i \leq n$$

Hence

$$X_{\mathcal{B}}(v_i) = (0, 0, \underbrace{1}_{i\text{-th}}, 0, \dots, 0)$$

$$\text{In fact } \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F) = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Thus

$$X_{\mathcal{B}'}F(v) = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F)X_{\mathcal{B}}(v)$$

□

e.g. In k^2 we have an identity map $k^2 \rightarrow k^2$ $\mathcal{B} = \{e_1(1, 0), e_2(0, 1)\}$
 $\mathcal{B}' = \{(1, 1)(0, 1)\}$ determine $\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id)$

$$(1, 0) = (1, 1) - (0, 1)$$

$$(0, 1) = (0, 1)$$

then we know that $\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}id = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix}$ transition matrix from $\mathcal{B} \rightarrow \mathcal{B}'$

In general let $\mathcal{B}, \mathcal{B}'$ to be 2 bases of V $\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id)$ is called transition matrix from $\mathcal{B} \rightarrow \mathcal{B}'$ e.g.

$$F : k^3 \rightarrow k^3$$

$$(x, y, z) \mapsto (z, x)$$

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\} \quad \mathcal{B}' = \left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} \text{ determine } \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}} F$$

$$F(1, 1, 0) = (0, 1) = 0(1, -1) + (0, 1)$$

$$F(0, 1, 1) = (1, 0) = 1(1, -1) - 1(0, -1)$$

$$F(0, 0, 1) = (1, 0) = 1(1, -1) - 1(0, -1)$$

$$\text{Hence matrix } \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}} = \begin{bmatrix} 0 & 1 & 1 \\ 1 & -1 & -1 \end{bmatrix}$$

14.1 Properties

$$F : G : V(\mathcal{B}) \rightarrow W(\mathcal{B}')$$

$$\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(aF + bG) = a\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F) + b\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(G)$$

$$\begin{aligned} \text{Proof. } \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(aF + bG) &= \forall v \in V X_{\mathcal{B}}(v) \text{ then } X_{\mathcal{B}'}(aF + bG)(v) = X_{\mathcal{B}'}(aF(v)) + vG(v) \\ &= aX_{\mathcal{B}'}F(v) + bX_{\mathcal{B}'}G(v) \end{aligned}$$

see pic

□

Theorem 14.2. Given linear maps

$$V \xrightarrow{F} W \xrightarrow{G} U$$

and let \mathcal{B} be a basis of V

\mathcal{B}' be a basis of W

\mathcal{B}'' be a basis of U

$$\dim V = n, \dim W = m, \dim U = l$$

$$\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F) \sim m \times n, \mathcal{M}_{\mathcal{B}''}^{\mathcal{B}'}(G) \sim l \times m, \mathcal{M}_{\mathcal{B}''}^{\mathcal{B}'}(G \circ F) \sim l \times n$$

then

$$\mathcal{M}_{\mathcal{B}''}^{\mathcal{B}'}(G) \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F) = \mathcal{M}_{\mathcal{B}''}^{\mathcal{B}}(G \circ F)$$

$$\text{Proof. } \forall v \in V \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(G \circ F)X_{\mathcal{B}}(v)$$

then for $G \circ F$

$$= X_{\mathcal{B}''}(G \circ F)(v)$$

$$= X_{\mathcal{B}''}G(F(v)) = \mathcal{M}_{\mathcal{B}''}^{\mathcal{B}'}GX_{\mathcal{B}'}F(v)$$

□

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Last class $F : V \rightarrow W$ be a linear map

$\mathcal{B} = \{v_1, v_2 \dots v_n\}$ a basis for V

$\mathcal{B}' = \{w_1, w_2 \dots w_n\}$ a basis for W

Then $F(v_1) = a_1w_1 + a_{21}w_2 + \dots + a_{m1}w_m$

$$\textbf{Theorem 15.1. } \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(F) = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Proof. Let $W = Id \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id)$ = transformation matrix from $\mathcal{B} \rightarrow \mathcal{B}'$ $V = W$ then
 $\mathcal{B}' = \mathcal{B} = \{v_1, v_2 \dots v_n\}$
 $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)$

$$F(v_1) = a_{11}v_1 + \dots + a_{n1}v_n$$

$$\vdots$$

$$F(v_n) = a_{1n}v_1 + \dots + a_{nn}v_n$$

$$\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F) = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{n1} & \dots & a_{nn} \end{bmatrix}$$

Which is the matrix associated F and \mathcal{B} □

e.g. $F : k^2 \rightarrow k^2$

$$F(x, y) = (x + y)(y - x)$$

$\mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\}$ compute $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}F$

$$\text{since } F\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} F\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ -2 \end{pmatrix} = -\begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} \text{ Hence matrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

recall let

$$V \xrightarrow{F} V' \xrightarrow{G} V''$$

Let $\mathcal{B} \rightarrow V, \mathcal{B}' \rightarrow V' \mathcal{B}'' \rightarrow V''$ Hence $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}G \circ F = \mathcal{M}_{\mathcal{B}''}^{\mathcal{B}'}(G)\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)$

Corollary . Let $V \xrightarrow{Id} V \xrightarrow{Id} V \mathcal{B} \rightarrow \mathcal{B}' \rightarrow \mathcal{B}$

Then $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id)\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id) = I_n$

$$\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(id)\mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id) = I_n \text{ ie } \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id) = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id)^{-1}$$

Let $\mathcal{B}\mathcal{B}'$ be 2 basis

Theorem 15.2 (change of basis). $\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}'}(F) = N^{-1}\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)N$, where $N = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id)$

Proof. $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id)\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}'}(F)\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(Id) = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(F)\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}}(id) = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)$ Thus $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(F) = N^{-1}\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)N$ □

In the prev example we want to verify

$$\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F) = N^{-1}\mathcal{M}_{\mathcal{B}_0}^{\mathcal{B}_0}(F)N$$

$$N = \mathcal{M}_{\mathcal{B}_{st}}^{\mathcal{B}}(Id) = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}, N^{-1} = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}_{st}}(Id) = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \text{ We verify}$$

$$\begin{aligned}
\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix} & \stackrel{?}{=} \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix} \\
& = Id \cdot \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \\
& = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}
\end{aligned}$$

Definition (diagonizability of a matrix). *A linear map $F : V \rightarrow V$ is called diagonizable if there exists a basis $\mathcal{B} = \{v_1, v_2 \dots v_n\}$ $\mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F)$ is a diagonal matrix*

i.e. $F(v_1) = c_1 v_1$

$F(v_2) = c_2 v_2$

$F(v_n) = c_n v_n$

for some $c_1 \dots c_n \in K$

e.g.

$F : k^2 \rightarrow k^2$ $F(x, y) = (y, x)$ in this case $F \sim \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ can we find a basis such that F

can be diagonalized. $\begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$ $F\begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, $F\begin{pmatrix} 1 \\ -1 \end{pmatrix} = -\begin{pmatrix} 1 \\ -1 \end{pmatrix}$

$\{\begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}\}$ diagonalizes F

Let \mathcal{B} be stand basis and let $\mathcal{B}' = \{\begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix}\}$

then we can see that

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}^{-1} \underbrace{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}}_{\text{standard basis}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$N = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id) = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

e.g. $F : k^2 \rightarrow k^2$

we claim tht $F(x, y) = (0, x)$ is not diagable

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Theorem 16.1. $F : V \rightarrow V$ and let $\mathcal{B}, \mathcal{B}'$ be basis. we know that $\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}'}(F)$
 $N^{-1} \mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F) N$ where as $N = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'}(Id)$

$$\text{e.g. we have } V = k^n, \mathcal{B} = \left\{ \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} \right\}, \mathcal{B}' = \{v_1 = \begin{bmatrix} g_{11} \\ \vdots \\ g_{n1} \end{bmatrix}, \dots, v_n = \begin{bmatrix} g_{1n} \\ \vdots \\ g_{nn} \end{bmatrix}\}$$

$F : k^n \rightarrow k^n$

$$F = F_A \iff F(X) = AX$$

$$\text{where as } A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{n1} & \dots & a_{nn} \end{bmatrix} \quad F(v_1) = b_{11}v_1 + b_{21}v_2 + \dots + v_{n1}v_n$$

\vdots

$$F(v_n) = b_{1n}v_1 + b_{2n}v_2 + \dots + v_{nn}v_n \quad B = b_{ij}$$

$$\text{where } \mathcal{M}_B^B(F) = A \mathcal{M}_{B'}^B(F) = B \quad N = \mathcal{M}_B^B(Id) = \begin{bmatrix} g_{11} & g_{12} & \dots & g_{1n} \\ g_{21} & g_{22} & \dots & g_{2n} \\ \dots & \dots & \dots & \dots \\ g_{n1} & g_{n2} & \dots & g_{nn} \end{bmatrix} \quad B = N^{-1}AN$$

16.1 Scalar product and orthogonality

Let V be as vector space over K such as $\mathbb{R}, \mathbb{C}, \mathbb{Q}$

Definition. A scalar product of a vector space V is a binary operation $\langle, \rangle: V \times V \rightarrow K$ such that

$$1. \quad \langle av_1 + bv_2, w \rangle = a \langle v_1, w \rangle + b \langle v_2, w \rangle$$

$$v, w = w, v$$

the scalar product \langle, \rangle is k degenerate if and only if TFAE: $\langle v, w \rangle = 0$ for any $w \in V \rightarrow v = \mathcal{O} \quad \forall v \neq \mathcal{O} \in V \exists w \in V \text{ s.t. } \langle v, w \rangle \neq \mathcal{O}$

$$\text{e.g. } 1. \quad V = k^n \quad x = (x_1, \dots, x_n), y = (y_1, \dots, y_n)$$

$$X \cdot Y = \langle X, Y \rangle = x_1y_1 + x_2y_2 + \dots + x_ny_n \quad \forall x = (x_1, x_2, \dots, x_n) \neq 0$$

$x \cdot e_i = s_i \neq 0$ if $X_i \neq 0$ then \langle, \rangle is nondegenerate 2. $v = k^2 \langle x, y \rangle = x_1y_2x = (0, 1) \langle x, y \rangle = 0 \forall Y$ degenerative!

3. Let \mathcal{S} to be any finite set

$$K(\mathcal{S}) = \{\text{functions on } \mathcal{S}\}$$

$$\langle f, g \rangle = \sum_{s \in \mathcal{S}} f(s)g(s) \text{ is a scalar product } \langle f, 1 \rangle = \sum_{t \in \mathcal{S}} f(t)1_s(t)$$

$f(s) \neq 0 \rightarrow \langle, \rangle$ is not degenerative

Definition. let V be a vector space with a scalar product we say $v, w \in V$ are perpendicular /orthogonal if $\langle v, w \rangle = \mathcal{O}$ denoted by $v \perp w$

$$S \subset V, S^\perp = \{v \in V | v \perp w \forall w \in S\} \text{ e.g. } S = v_1, v_2, \dots, v_n \quad S^\perp = \{v \in V | v \perp v_1, \dots, v_n\}$$

claim S^\perp is a subspace in V

Fact: Let U be the span of S then

$$S^\perp = U^\perp$$

we use bilinearity of scalar products

let

$$a_{11}x_1 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + \dots + a_{2n}x_n = 0$$

\vdots

$$a_{n1}x_1 + \cdots + a_{mn}x_n = 0$$

In fact solution to this homogeneous linear eqn $\{x \in k^n | x \cdot A_1 = x \cdot A_2 \dots x \cdot A_n = 0\} = \{A_1 \dots A_n\}$

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recall $FV \rightarrow V$ and let $\mathcal{B}, \mathcal{B}'$ be 2 basis of V

$$\mathcal{M}_{\mathcal{B}'}^{\mathcal{B}'}(F) = N^{-1} \mathcal{M}_{\mathcal{B}}^{\mathcal{B}}(F) N \text{ where } N = \mathcal{M}_{\mathcal{B}}^{\mathcal{B}'} ID$$

$$\text{recall } v \in V \quad X_{\mathcal{B}'} F(v_1) = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}} F(X) X_{\mathcal{B}}(V)$$

Take $F = \text{Id}$

$$\rightarrow X_{\mathcal{B}'}(V) = \mathcal{M}_{\mathcal{B}'}^{\mathcal{B}} ID X_{\mathcal{B}}(V)$$

$$\text{e.g. } V = k^2 \mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}, \mathcal{B}' = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right\} \quad V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \right\}$$

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} X_{\mathcal{B}}(v)$$

$$a_{11}x_1 + \dots + a_{1n}x_n = 0$$

$$\vdots$$

$$a_{n1}x_1 + \dots + a_{nn}x_n = 0$$

$$\updownarrow$$

$$Ax = 0, x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

$$\updownarrow$$

$$X \cdot A_1 = X \cdot A_2 = \dots = X \cdot A_n = 0$$

where as

$$X \in \{A_1 \dots A_n\}^\perp = \text{span}\{A_1 \dots A_n\}^\perp$$

If columns of A are linearly independent then this sys of eqns has only trivial soluns

$\iff \text{span}\{A_1 \dots A_n\}^\perp = \{0\}$ Further If $A_1 \dots A_n$ are linearly independent then $\text{span}\{A_1 \dots A_n\} = k^n = V$

$V^\perp = \{0\}$ scalar product is non-degenerative

For now on we will define $K = \mathbb{R}$

Definition (orthogonality). Let $\mathcal{B} = \{v_1, v_2 \dots v_n\}$ be as basis of V we say that \mathcal{B} is an orthogonal basis iff $\langle v_i, v_j \rangle = 0$ for $i \neq j$

Definition (positive definite). A Scalar product on V/\mathbb{R} is called positive definite iff $\langle v, v \rangle > 0 \forall v \neq 0 \in V$

e.g. $X = (x_1 \dots x_n) \neq 0 \cdot c = x_1^2 + \dots x_n^2 > 0$ their dot product on \mathbb{R} is positive definite.

Definition (norm). The norm of V/\mathbb{R} $\|v\| = \sqrt{\langle v, v \rangle}$

In previous example $\|x\| = \sqrt{x_1^2 + x_2^2 + x_3^2}$ let $c \in \mathbb{R}$ we have $\|cv\| = \|c\| \cdot \|v\|$ $\|v - w\| =$ distance from w to v unit vector

Theorem 17.1 (pythagorams thm). If $v \perp w$ we have $\|v - w\|^2 = \|v + w\|^2 = \|v\|^2 + \|w\|^2$

Proof. $\|v + w\|^2 = \langle v + w, v + w \rangle$
 $= \langle v, v \rangle + 2\langle v, w \rangle + \langle w, w \rangle$
 since $v \perp w \langle v, w \rangle = 0$

$$\begin{aligned} \text{hence } &= \langle v, v \rangle + \langle w, w \rangle \\ &= \|v\|^2 + \|w\|^2 \end{aligned}$$

□

17.1 Projection

We can project v onto W denote $\text{proj}_w(v) = cw$

$$\langle v - \text{proj}_w(v), v - \text{proj}_w(v) \rangle = 0$$

$$= \langle v - \langle w, w \rangle^{-1} \langle v, w \rangle w, v - \langle w, w \rangle^{-1} \langle v, w \rangle w \rangle = 0$$

$$\text{hence } C = \frac{\langle v, w \rangle}{\langle w, w \rangle}$$

Definition. $\frac{\langle v, w \rangle}{\langle w, w \rangle}$ is the projection component of V along w and $\text{proj}_w(v) = \frac{\langle v, w \rangle}{\langle w, w \rangle} w$ is the projection of v along w

$$\text{e.g. } v = (2, 1)w = (1, 1), \frac{\langle v, w \rangle}{\langle w, w \rangle} = \frac{3}{2}$$

Theorem 17.2. v/\mathbb{R} is non-degenerative scalar product if $\{v_1, v_2 \dots v_n\}$ are orthogonal along w for $w \in V$

$$w_1 = a_1 v_1 + \dots + a_n v_n$$

$$a_i = \frac{\langle w, v_i \rangle}{\langle v_i, v_i \rangle} \text{ where as } a_i v_i = \text{proj}_{v_i} w$$

Proof. $\langle w, v_i \rangle$

$$\langle a_1 v_1 + \dots + a_n v_n, v_i \rangle$$

$$= \langle a_i v_i, v_i \rangle$$

$$= a_i \langle v_i, v_i \rangle$$

$$a_i = \frac{\langle w, v_i \rangle}{\langle v_i, v_i \rangle}$$

□

Theorem 17.3 (Schwartz Inequality). $\forall v, w \in V$ we have $|\langle v, w \rangle| \leq \|v\| \cdot \|w\|$

Proof. by cases: case 1 $w = 0$ trivial

case 2 w is the unit vector $\langle w, w \rangle = 1$ then $\text{proj}_w(v) = \langle v, w \rangle w$

Then we apply the pythagoram thm $\|v\|^2 = \|\text{proj}_w(v)\|^2 + \|v - \text{proj}_w(v)\|^2$

case 3 $w \neq 0$ then we know that $\frac{w}{\|w\|}$ is the unit vector by case 2

$$|\langle \frac{w}{\|w\|}, v \rangle| \leq \|v\|$$

$$= \frac{|\langle w, v \rangle|}{\|w\|} \leq \|v\| \iff |\langle v, w \rangle| \leq \|v\| \|w\|$$

□

Definition. $\frac{\langle v, w \rangle}{\langle w, w \rangle}$ is the projection component of V along w and $\text{proj}_w(v) = \frac{\langle v, w \rangle}{\langle w, w \rangle} w$ is the projection of v along w

$$\text{e.g. } v = (2, 1)w = (1, 1), \frac{\langle v, w \rangle}{\langle w, w \rangle} = \frac{3}{2}$$

Theorem 17.4. v/\mathbb{R} is non-degenerative scalar product if $\{v_1, v_2 \dots v_n\}$ are orthogonal along w for $w \in V$

$$w_1 = a_1 v_1 + \dots + a_n v_n$$

$$a_i = \frac{\langle w, v_i \rangle}{\langle v_i, v_i \rangle} \text{ where as } a_i v_i = \text{proj}_{a_i} w$$

Proof. $\langle w, v_i \rangle$

$$\langle a_1 v_1 + \dots + a_n v_n, v_i \rangle$$

$$= \langle a_i v_i, v_i \rangle$$

$$= a_i \langle v_i, v_i \rangle$$

$$a_i = \frac{\langle w, v_i \rangle}{\langle v_i, v_i \rangle}$$

□

Theorem 17.5 (Schwartz Inequality). $\forall v, w \in V$ we have $|\langle v, w \rangle| \leq \|v\| \cdot \|w\|$

Proof. by cases:

case 1 $w = 0$ trivial

case 2 w is the unit vector $\langle w, w \rangle = 1$ then $\text{proj}_w(v) = \langle v, w \rangle w$

Then we apply the pythagoram thm $\|v\|^2 = \|\text{proj}_w(v)\|^2 + \|v - \text{proj}_w(v)\|^2$

case 3 $w \neq 0$ then we know that $\frac{w}{\|w\|}$ is the unit vector by case 2

$$|\langle \frac{w}{\|w\|}, v \rangle| \leq \|v\|$$

$$= \frac{|\langle w, v \rangle|}{\|w\|} \leq \|v\|$$

$$\iff |\langle v, w \rangle| \leq \|v\| \|w\| \quad (1)$$

□

we know that the projection matrix

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Recall: last class, \langle, \rangle is positive definite scalar product on V

$$\text{proj}_w(v) = \frac{\langle v, w \rangle}{\langle w, w \rangle} \cdot w$$

$v_1, v_2 \in V$ are linearly independent, $v_1 \perp v_2$

$$\text{proj}_w \left(\underbrace{\frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle}}_{\text{proj}_{v_1}(v)} + \underbrace{\frac{\langle v, v_2 \rangle}{\langle v_2, v_2 \rangle}}_{\text{proj}_{v_2}(v)} \right)$$

we claim that $u_i = v - \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} \cdot v_1 - \frac{\langle v, v_2 \rangle}{\langle v_2, v_2 \rangle} \cdot v_2$ is perpendicular to v_1 and v_2

Proof. $\langle u, v_1 \rangle = \langle v, v_1 \rangle - \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} \cdot \langle v_1, v_1 \rangle - 0 = 0$ similarly $\langle u, v_2 \rangle = 0$

□

Corollary . v_1, v_2, u is an orthogonal basis of $\text{span } v_1, v_2, v$ whereas $u = v - \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle v, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2$ This is called the gram smidt procedure

e.g. in \mathbb{R}^3 $v_1 = (1, 1, 0), v_2 = (0, 1, 1), v_3 = (1, 0, 1)$

Goal: construct an orthogonal basis w_1, w_2, w_3 out of v_1, v_2, v_3

$$u_1 = v_1 = (1, 1, 0) u_2 = v_2 - \frac{\langle v_2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 = (0, 1, 1) - \frac{1}{2} \langle 1, 1, 0 \rangle = (-\frac{1}{2}, \frac{1}{2}, 1)$$

(2)

$$w_3 = v_3 - \frac{\langle v_3, u_1 \rangle}{\langle u_1, u_1 \rangle} u_1 - \frac{\langle v_3, u_2 \rangle}{\langle u_2, u_2 \rangle} u_2 = (1, 0, 1) - \frac{1}{2}(1, 1, 0) - \frac{\frac{1}{2}}{\frac{3}{2}} = (\frac{1}{2}, \frac{1}{2}, 1)$$

$$(1, 0, 1) - (\frac{1}{2}, \frac{1}{2}, 0) - \langle -\frac{1}{6}, \frac{1}{6}, \frac{1}{3} \rangle$$

$$= (1 - \frac{1}{2} + \frac{1}{6}, -\frac{1}{2} - \frac{1}{6}, 1 - \frac{1}{3})$$

$$\frac{2}{3}, -\frac{2}{3}, \frac{2}{3}$$

$$\rightarrow (1, 1, 0), (-\frac{1}{2}, \frac{1}{2}, 1)(\frac{2}{3}, \frac{-2}{3}, \frac{2}{3}) \text{ are the orthogonal basis}$$

Lemma . suppose that we have v_1, v_2, v_k are mutually orthogonal vectors in V , then v_1, v_2, v_k are linearly independent

Proof. if we have $a_1 v_1 + a_2 v_2 + \dots a_k v_k = 0$ then we know that $\langle a_1 v_1 + a_2 v_2 + \dots a_k v_k, v_i \rangle = 0$
 $a_i \langle v_i, v_i \rangle = a_i = 0$ □

Theorem 18.1. V/\mathbb{R} be a vector space with a positive definite scalar product with $W \subseteq V$ subspace and let $\{w_1, w_2, \dots w_m\}$ be an orthogonal basis of W . Then there exists $w_{m+1} \dots w_n$ such that $\{w_1, w_2, \dots w_m, w_{m+1}, \dots, w_n\}$ is an orthogonal basis

Proof. By a theorem we have proven earlier there exists vectors $v_{m+1}, \dots v_n$ such that $\{w_1 \dots w_m, v_{m+1}, v_n\}$ is a basis of V

By gram schmidt, we have

$$w_{m+1} = v_{m+1} - \frac{\langle v_{m+1}, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1 - \dots - \frac{\langle v_{m+1}, w_m \rangle}{\langle w_m, w_m \rangle} w_m$$

we have $w_{m+1} \perp w_1, w_2, \dots w_m$

we use induction to find another vector

□

Corollary F. or vector space v/\mathbb{R} with positive-definite scalar products there always exists an orthogonal basis.

Definition (orthonormal basis). *An orthogonal basis $\{v_1, v_2 \dots v_n\}$ is called orthonormal if $\|v_i\| = 1 \forall i$*

for example $\{v_1, v_2 \dots v_n\}$ be a basis of V

then v_1, v_2, v_3 are linearly independent

$$u_1 = v_1$$

$$u_2 = v_2 - \frac{\langle v_2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1$$

$$u_3 = v_3$$

$$\begin{array}{l} \text{hence step 1} \quad \begin{bmatrix} 1 & \star & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \text{step 2: } w_1 = u_1 \\ w_2 = u_2 \\ w_3 = u_3 - \star u_2 - \star u_1 \rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & \star \\ 0 & 0 & 1 \end{bmatrix} \end{array}$$

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Gram schmidt orthogonalities where \langle, \rangle are positive definite
say that We have $v_1, v_2 \dots v_n$ are orthogonal are linearly independent
Then we can find vectors that

$$v_{n+1} - \text{proj}_{v_1}(v_{n+1}) - \text{proj}_{v_2}(v_{n+1}) - \dots - \text{proj}_{v_n}(v_{n+1})$$

see pic

Theorem 19.1 (orthogonality implies linearly independent). Any mutually orthogonal nonzero vectors $v_1, v_2 \dots v_k \in V$ can be extended to an orthogonal basis $\{v_1, v_2 \dots v_n\}$

let (v, \langle, \rangle) be positive definite
let $\mathcal{B} = \{v_1, v_2 \dots v_n\}$ be an orthogonal basis
 $\forall v \in V v = x_1 v_1 + x_2 v_2 + \dots + x_n v_n$
 $\forall w \in v = y_1 v_1 + y_2 v_2 + \dots + y_n v_n$
 $\langle v, w \rangle = x_1 y_1 \langle v_1, v_1 \rangle + x_2 y_2 \langle v_2, v_2 \rangle + \dots + x_n y_n \langle v_n, v_n \rangle$
 $= x_1 y_1 + \dots + x_n y_n$
if \mathcal{B} is orthonormal

Theorem 19.2. Let V be a vector space over \mathbb{R} with positive definite scalar product \langle, \rangle of $\dim v = n$ let $w \in v$ be a subspace of dimension r , then $\dim w^\perp = n - r$

Remark. (w, \langle, \rangle)
if

$$\langle, \rangle$$

is positive definite \rightarrow non degenerative then $\langle, \rangle|_w$ is also positive definite (in particular non-degenerative)

Proof. give (w, \langle, \rangle) is also positive definite, there exists an orthogonal basis v_1, v_2, \dots, v_r
These vectors can be extended to an orthogonal basis of V $v_1, v_2, \dots, v_r, v_{r+1}, \dots, v_n$ we
claim that $w^\perp = \text{span}\{v_{r+1}, \dots, v_n\}$
proof of claim:

It is clear that $v_{r+1}, \dots, v_n \in W^\perp$

$\forall u \in W^\perp$

we write that $u = a_1 u_1 + \dots + a_r u_r + a_{r+1} u_{r+1} + \dots + a_n v_n$

since $1 \leq i \leq r \langle u, v_i \rangle = a_i \langle v_i, v_i \rangle = \mathcal{O} \rightarrow a_i = \mathcal{O}, 1 \leq i \leq r$

i.e. $u = a_{r+1} u_{r+1} + \dots + a_n v_n \in \text{span} \{v_{r+1}, v_n\}$

□

19.1 application in Complex numbers: Hertian product

example $z = a + bi \in \mathbb{C}$

we have $z \cdot z = a^2 - b^2 + 2abi$

$z \cdot \bar{z} = (a + bi)(a - bi) = (a^2 + b^2) > 0$ if $z \neq 0$

Definition (Hertian product). let $V = \mathbb{C}^n = (y_1, y_2, \dots, y_n)$ then we know that $\langle (x_1, x_2, \dots, x_n), (y_1, y_2, \dots, y_n) \rangle = x_1 \bar{y}_1 + \dots + x_n \bar{y}_n = \|x_1\|^2 + \|x_2\|^2 + \dots$ if $x_i = y_i \forall i$

example we have \mathbb{C}^2

$$\langle (x_1, y_2), (y_1, y_2) \rangle = \frac{x_1 \bar{y}_1 + x_2 \bar{y}_2}{\langle (y_1, y_2), (x_1, x_2) \rangle}$$

$$\langle (x_1, x_2) + (x'_1, y'_2), (y_1, y_2) \rangle$$

$$= \langle (x_1 + x'_1, y_2 + y'_2), (y_1, y_2) \rangle$$

$$= (x_1 + x'_1) \bar{y}_1 + (y_2 + y'_2) \bar{y}_2$$

$$= \langle (x_1, x_2), (y_1, y_2) \rangle + \langle (x'_1, y'_2), (y_1, y_2) \rangle$$

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Last class reminder we know that the hermitian product on $V : \text{vspace}/C \langle, \rangle V \times V \rightarrow \mathbb{C}$

- $\langle u, v \rangle = \overline{\langle v, u \rangle}$
- $\langle au, v \rangle = a \langle u, v \rangle$
- $\langle u_1 + u_2, v \rangle = \langle u_1, v \rangle + \langle u_2, v \rangle$

Definition. The hermitian product \langle, \rangle on V is positive definite if $\langle u, v \rangle = 0 \forall v \neq 0$

$\forall u, v \in V$ if $\langle u, v \rangle = 0$ then we say that $u \perp v$

$$\|v\| = \sqrt{\langle v, v \rangle}$$

Pythagorean theorem if $v \perp w$ then $\|v + w\|^2 = \|v\|^2 + \|w\|^2$

the Schwarz inequality $|\langle v, w \rangle| \leq \|v\| \cdot \|w\|$

This also suggests that we have the Gram-Schmidt process for positive definite hermitian product

e.g. we have \mathbb{C}^2

$\langle (x, y), (x', y') \rangle = x \bar{x}' + y \bar{y}'$ is positive definite

$v_1 = (1, 1 + i), v_2 = (1, i)$ they are not orthogonal

another example we have $w_1 = v_1 = (1, 1 + i)$

$$\begin{aligned}
 w_2 - v_2 - \frac{\langle v_2, v_1 \rangle}{\langle v_1, v_1 \rangle} \cdot v_1 \\
 &= (1, i) - \frac{1+i(1-i)}{1+(1+1)}(1, 1 + i) \\
 &= (1, i) - \frac{2+i}{3}(1, 1 + i) \\
 &= (1, 1) - \left(\frac{2+i}{3}, \frac{1+3i}{3}\right) \\
 &= \left(\frac{1}{3}, -\frac{1}{3}, -\frac{1}{3}\right)
 \end{aligned}$$

Theorem 20.1. Let V/\mathbb{C} be a vector space with hermition product \langle, \rangle given non zero mutually othogonal vectors $v_1, v_2, \dots v_k$ then v_1, v_2, v_k can be etendedinto an orthogonal basis $\{v_1, v_2 \dots v_n\}$

Corollary 1. . V has an orthongonal basis

2. $W \subseteq VW^\perp = \{v \in V | v \perp W\}$

20.1 application to sysm. equation

we have $a_{11}x_1 + \dots + a_{1n}x_n = 0$

\vdots

$$a_{m1}x_1 + \dots + a_{mn}x_n = 0$$

we claim that $\{\text{soln of}(\star)\} + \dim \text{span of column} = n$ $F_A : k^n \rightarrow k^m$

Definition (Ranks). *column rank (A)=dim of span of column vectors*
row rank of (A)=dim of span of row vectors

e.g.

$$A = \begin{bmatrix} 0 & 1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}.$$

we have col rank $A = 2$ row rank $A = 2$

Theorem 20.2 (column · rank (A)). we have col rank = row rank

Proof. Null space of (A) = $\{(x_1, x_2, x_3) | x_1 A^1 + \dots + x_n A^n = 0\}$

solution of space = $\{(x_1, x_2, \dots x_n) | X \cdot A_1 = X \cdot A_2 = \dots = X \cdot A_m = 0\}$

Null (A) = $\{A_1, A_2 \dots A_m\}^\perp = \text{span}\{A_1 \dots A_m\}^\perp$ when $k = \mathbb{R}$ recall $\mathbb{R}^n = W_{\text{row}} \oplus W_{\text{row}}^\perp$
 $\rightarrow \mathbb{R}^n = W_{\text{row}} \oplus \text{Null}(A) \rightarrow n = \text{rowrank}(A) + \text{null}(A)$ rewrite \star

we have $n = \text{colrank}(A) + \text{null}(A) \rightarrow \text{row rank (A)} = \text{col rank(A)}$

□

rank for general k the theorem holds

Theorem 20.3. v/K \langle, \rangle scalar product be non degenerative then $\dim w + \dim w^\perp = \dim V$

reminder $A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_n \\ \dots & \dots & \dots & \dots \\ a_{m_1} & a_{m_2} & \dots & a_{mn} \end{bmatrix}$ and $\text{colrank } A = \dim \text{span of sol vectors} \subseteq k^m$
 and $\text{rowrank } A = \dim \text{span of rows vectors} \subseteq k^n$

Theorem 20.4. $\text{Col rank } A = \text{Rowrank}(A)$

$\text{rank } A = \text{col rank } A = \text{row rank } A$

last time we proven that theorem for $k = \mathbb{R}$ we have a theorem that generalize this to any field.

Theorem 20.5. let $V/K, \langle, \rangle$ be a scalar product $w \subseteq V$ subspace then we know that $\dim w + \dim w^\perp = \dim V$

e.g. $k = \mathbb{C}$ dotproduct, given that $v = \mathbb{C}^2, W = \mathbb{C}(1, i)$

$W^\perp = \mathbb{C}(1, i)^\perp = W.V \neq W + W^\perp$

we still see that $\dim w + \dim W^\perp = 2(1, i) \cdot (1, i) = 0$

20.2 standard hermition product

$$W^\perp = \mathbb{C}(1, -i), V = W \oplus W^\perp$$

20.3 Bilinearmaps

recall: Given a $m \times n$ matrix A , we can associate a linear map $F_A : k^n \rightarrow k^m$

$X \mapsto AX$

Recall: V/K vector space with \langle, \rangle scalar product $\langle, \rangle : V \times V \rightarrow K$

Definition (bilinear maps). Let U, V, W be Vector spaces on k , A map $g : U \times V \rightarrow W$ is bi linear map if and only if $\forall u \in U, g(u, \cdot) : V \rightarrow W$ is linear and $\forall v \in V, g(\cdot, v) : U \rightarrow W$ is linear.

$$w = k, g : U \times V \rightarrow K$$

\mapsto

$$U = V, g : V \times V \rightarrow K$$

e.g. a $m \times n$ matrix

\mapsto

$$g_A = k^m \times k^n \rightarrow K$$

and let $(X, Y) \mapsto XAY = (x_1, x_2, \dots, x_n) \begin{bmatrix} a_{11} & \dots & a_{1n} \\ a_{21} & \dots & a_{2n} \\ \dots & \dots & \dots \\ a_{m1} & a_{m2} \dots & a_{mn} \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}$ e.g.

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix}$$

$$\begin{aligned} g_A : k^2 &\rightarrow k^3 \rightarrow k \\ ((x_1, x_2), \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix}) &\mapsto (x_1, y_2) \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = X \cdot F_A(Y) = (x_1 x_2 2x_1 + y_2) \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \\ &= x_1 y_1 + x_2 y_2 + 2x_1 y_3 + x_2 y_3 \end{aligned}$$

In general:

$$g_A(X, Y) = \sum a_{ij} x_i y_j \forall 1 \leq i \leq m, 1 \leq j \leq n$$

In k^n we have standard basis e_1, e_2, \dots, e_n $e_1 = (1, \dots, 0)$ $e_2 = (0, 1, \dots, 0) \dots$ in k^n we have

$$f_1, f_2, f_n \text{ where } f_1 = \begin{bmatrix} 1 \\ 0 \\ \dots \\ 0 \end{bmatrix} f_2 = \begin{bmatrix} 0 \\ 1 \\ \dots \\ 0 \end{bmatrix} \dots \text{ what is } g_A(e_i, f_j) = a_{ij}$$

$$g_A(X, Y) = g_A(\sum x_i e_i, \sum y_j f_j)$$

bi linearity $\sum_{ij} g_A(e_i f_j) x_i y_j = \sum ij x_i y_j$

Theorem 20.6. Given any bilinear map $g : k^m \times k^n \rightarrow k$ there exists a unique matrix $m \times n$ A such that $g = g_A$

Proof. set $A = (g(e_i, f_j)) \forall 1 \leq i \leq m, 1 \leq j \leq n : m \times n$ matrix

we claim that $g = g_A$

since $g(e_i, f_j) = g_A(e_i f_j) \forall i, j$

by bi linearity $g = g_A$ uniqueness: suppose $g_a = g_b$

$$g_A(e_i, f_j) = a_{ij}$$

$$g_b(e_i, f_j) = b_{ij}$$

$$g_A = g_B \Rightarrow a_{ij} = b_{ij} \forall i, j \iff A = B$$

□

by the above theorem we immediately get

all $m \times n$ matrices are bijective with bilinear maps $k^m \times k^n \rightarrow k$ and linear maps $k^n \rightarrow k^m$

whereas $F \mapsto G(X, Y) = X \cdot F(Y)$

$$A = m11 - 31$$

$$g_a : k^2 \times k^2 \rightarrow k$$

$$g_a((x_1, x_2), \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}) = x_1 y_2 + 2x_1 y_2 - 3x_2 y_2 + x_2 y_2$$

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Given any $m \times n$ matrix $A = a_{ij}$

$$\text{we have } g_A(X, Y) = X^t A Y = (x_1, x_2 \dots x_n) \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \dots & \dots & \dots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{bmatrix}$$

If A is Symmetric Then, bi linear map $g_A: k^n \times k^n \rightarrow k$

then g_A is a linear product \iff symmetric bilinear map

$$x^t A Y$$

$$g_A(X, Y) = x^t A Y$$

$$\text{recall } (AB)^t = B^t A^t$$

$$\text{e.g. } A = \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix}$$

$$g_A = \left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right) \\ = x_1 y_1 + 2x_1 y_2 + 2y_2 y_1 - x_2 y_2$$

21.1 General Orthogonal basis

Given a scalar product on $V/K \langle, \rangle : V \times V \rightarrow K$

Question . can we find an orthogonal basis with respect to \langle, \rangle

we know that if the scalar product is positive definite on VR we have proven the existence by gram-schmidt

e.g. $V = k^2$

$$\left\langle \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right\rangle = x_1 y_1 - x_2 y_2 \text{ since this scalar product came from an symmetric metric}$$

$$\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

since $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ is an orthogonal basis

when $k = \mathbb{R}$ we claim its not positive definite because $\left\langle \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\rangle < 0$

$$2. v = k^2, \left\langle \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \cdot \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right\rangle = x_1 y_1$$

$$\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

is orthogonal.

Definition (scalar product). A scalar product \langle, \rangle on V is called null if $\langle v, v \rangle = 0 \forall v \in V$ and V with this \langle, \rangle is called null space.

Remark. if \langle, \rangle is null then $\langle v, w \rangle = 0 \forall v, w \in V$

Proof.

$$\begin{aligned}\langle v - u, v - u \rangle &= 0 = \langle v, v \rangle + \langle u, u \rangle - 2\langle v, u \rangle \\ \langle v, u \rangle &= \frac{\langle v, v \rangle + \langle u, u \rangle}{2} = 0\end{aligned}$$

□

Theorem 21.1. For any scalar product \langle, \rangle on V $V \neq 0$ there always exists an orthogonal basis

Proof. we will use induction on $\dim V = n$

when $\dim = 1$ This is trivial

suppose that $\dim V \geq 2$ if V is a null space then any basis is orthogonal

Otherwise there exists non zero vector $v_1 \in V$ s.t. $\langle v_1, v_1 \rangle \neq 0$

$$P: V \rightarrow V, P(v_1) = \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1$$

$$v \mapsto \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1$$

P is a linear map. $\ker P = \{v \mid \langle v, v_1 \rangle = 0\} := V_1^\perp$

Hence P is surjective

$$\rightarrow \dim V_1^\perp = n - 1$$

we claim that

$$\begin{aligned}V &= V_1 \oplus V_1^\perp \\ v &= \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 \in V_1 + \left(v - \frac{\langle v, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1\right) \in V_1^\perp\end{aligned}$$

By induction V_1^\perp has an orthogonal basis $\{v_2, v_3, \dots, v_n\}$, Then $\{v_1, v_2, \dots, v_n\}$ is an orthogonal basis

□

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recall V : space over K

$V^* = L(V, K) = \{\varphi: V \rightarrow K\}$ Given a basis $\mathcal{B} = \{v_1, v_2, \dots, v_n\}$ of V

A dual basis called $\mathcal{B} = \{\varphi_1, \varphi_2, \dots, \varphi_n\}$ a basis of V^*

Given $W \subseteq V$ a subspace

Definition (peep). $W^\perp = \{\varphi \in V^* \mid \varphi(w) = 0 \forall w \in W\}$

Theorem 22.1. $\dim W + \dim W^\perp = \dim V$

for example $V = k^3$, $v_1 = (1, 1, 0)$, $v_2 = (0, 1, 1)$, $v_3 = (0, 0, 1)$ and let $\{e_1, e_2, e_3\}$ be standard basis then we have $\{\varphi_1, \varphi_2, \varphi_3\}$ be a dual basis of V^*

and let $W = \text{span}\{v_1, v_2\} \subseteq V$ be 2 dim and we have $W^\perp = \{\varphi \in V^* \mid \varphi(v_1) = 0 \wedge \varphi(v_2) = 0\} \subseteq V^*$

$$\varphi = a_1\varphi_1 + a_2\varphi_2 + a_3\varphi_3$$

$$\varphi(v_1) = \varphi(e_1) + \varphi(e_2) = a_1 + a_2 = 0$$

$$\varphi(v_2) = a_2 + a_3 = 0$$

Let $\{\psi_1, \psi_2, \psi_3\}$ be dual basis of $\{v_1, v_2, v_3\}$ can you find a transition matrix M that takes $\{\varphi_1, \varphi_2, \varphi_3\} \rightarrow \{\psi_1, \psi_2, \psi_3\}$?

Let \langle, \rangle be non degenerative scalar product on V recall that $W^\perp = \{v \in V \mid \langle v, W \rangle = 0\}$

Theorem 22.2. $\dim W + \dim W^\perp = \dim V$

Proof.

$$V \rightarrow V^*$$

$v \mapsto L_v(u) = \langle v, u \rangle$ $W^\perp \rightarrow W^\perp^* \rightarrow W^*$ we claim $L : W^\perp \rightarrow W^*$ $\forall v \in W^\perp, L_v \in W^*$

since $L_v(w) = \langle v, w \rangle = 0$ if suffices to check that $L(w^\perp) = W^*$ for any $\varphi \in W^* \subseteq V^*$

$$\varphi = L_v \text{ for some } v \in V$$

$$\varphi \in W^\perp^* \iff \varphi(w) = 0 \iff L_v(W) = 0 \iff \langle v, W \rangle = 0 \iff v \in W^\perp$$

□

Corollary A. $\text{row rank} = \text{col rank} = \text{rank } A$

Proof. null space $(A) = \ker(F_A)$, $F_A = k^n \rightarrow k^m \iff \{X \mid AX = A_m X = 0\}$

$$\iff \text{span}\{A_1, \dots, A_m\} \iff W_{\text{row}}^\perp \text{ hence } \dim \ker(F_A) = n - \text{col rank}$$

$$\dim W^\perp = n - \text{row rank}$$

□

22.1 Quadratic Form

e.g. $Q : k^2 \rightarrow k$

$$(x, y) \mapsto (x^2 - 4xy + y^2)$$

$$x^2 \pm y^2$$

Definition (Quadratic form). V a v space over K a function $Q : V \rightarrow k$ is a quadratic form if there exists a scalar product \langle, \rangle on V such that $Q(v) = \langle v, v \rangle$

$$\text{e.g. } k^2 \left\langle \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} \right\rangle = (x_1, x_2) \cdot \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$Q\left(\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}\right) = (x_1, x_2) \begin{bmatrix} a & b \\ b & c \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = ax_1^2 + 2bx_1x_2 + cx_2^2 \text{ if } a = 1, c = 2, b = 0$$

we get $Q(x_1, x_2) = x_1^2 - x_2^2$ on K^n all quadratic forms can be described as

$$Q()$$

$$= x^t A X \text{ where } A \text{ is a symmetric matrix } X = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = a_{ij}, a_{ij} = a_{ji}$$

$$= \sum_i 1^n a_{ii} x_i^2 + \sum_{i < j} 2a_{ij} x_i x_j$$

Proposition 22.3. Any scalar product \langle, \rangle arise from a quadratic form Q on V s.t.
 $Q(v) = \langle v, v \rangle$

Proof. Let $Q(v) = \langle v, v \rangle$

$$\text{Then } \langle v, w \rangle = \frac{1}{2}(\langle v+w, v+w \rangle - \langle v, v \rangle - \langle w, w \rangle) = \frac{1}{2}Q(v+w) - Q(v) - Q(w)$$

□

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Recall $Q : V \rightarrow K$ is a quadratic form if $Q(v) = \langle v, v \rangle$ for some scalar product $\langle, \rangle \in V$

If $V = K^n$

{ scalar products on K^n } \sim { symbolic matrix } hence $Q \in \{ \text{quadratic forms on } K^n \}$

$$\langle v, w \rangle = \frac{1}{2}(Q(v+w) - Q(v) - Q(w))$$

Let A be a symmetric matrix

$$Q = (x_1 \dots x_n) = X^t A X$$

$$= \sum_{i=1}^n a_{ii} x_i^2 + 2 \sum a_{ij} x_i x_j$$

$$\text{e.g. } Q(x, y) = x^2 - 3xy + 2y^2$$

$$\text{we have } A = \begin{bmatrix} 1 & -\frac{3}{2} \\ -\frac{3}{2} & 2 \end{bmatrix}$$

Let V be a vector space over K \langle, \rangle is a scalar product

$\{v_1, v_2 \dots v_n\}$ be a basis of V

we know that $(\langle v_i, v_j \rangle)$ is a symmetric matrix

In particular we proved that there exists basis orthogonal product $\{v_1, v_2 \dots v_n\}$ such that

$(\langle v_i, v_j \rangle)$ is diagonal

e.g.

For now we assume $k = \mathbb{R}$

$$\text{Let } A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\langle X, Y \rangle = x_1 y_2 + x_2 y_1 \text{ on } k^2$$

question so is $\begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ an orthogonal basis is orthogonal basis. so $\langle \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rangle = -2$

$$\langle \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \rangle = 2$$

$$2. \text{ Let } A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

we already know that $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ are orthogonal

$$\langle e_1, e_1 \rangle = 1 > 0, \langle e_2, e_2 \rangle = 1 > 0$$

$$3. A = \begin{bmatrix} -1 & 1 \\ 1 & -1 \end{bmatrix}$$

let $\langle x, y \rangle = x_1y_1 + x_1y_2 + x_2y_1 - x_2y_2$

indeed $v_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is an orthogonal basis.

$$\langle v_1, v_1 \rangle = -1, \langle v_2, v_2 \rangle = 0$$

Another basis for this would be $w_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, w_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$\langle w_1, w_2 \rangle = 0, \langle w_1, w_1 \rangle = -1, \langle w_2, w_2 \rangle = 0$$

Theorem 23.1 (Sylvester's theorem). Let V be a vector space over \mathbb{R} with scalar product. Let v_1, v_2, \dots, v_n be orthogonal basis and then

$$n^+ = \#\{v_i | \langle v_i, v_i \rangle > 0\}$$

$$n^0 = \#\{v_i | \langle v_i, v_i \rangle = 0\}$$

$$n^- = \#\{v_i | \langle v_i, v_i \rangle < 0\}$$

we call then positive, nullity index and negativity index they do not depend on the choice of orthogonal basis.

e.g. $Q = (x, y, z) = 2x^2 - y^2$

lets determine n^+, n^0, n^-

In this case the associated matrix is

$$A = \begin{bmatrix} 2 & & \\ & -1 & \\ & & 0 \end{bmatrix}$$

we see that $\langle e_1, e_1 \rangle = 2$

$$\langle e_2, e_2 \rangle = -1, \langle e_3, e_3 \rangle = 0$$

$$\text{hence } n^+ = n^- = n^0 = 1$$

note that anytime we have daag matrix then standard matrices are orthogonal basis

Observe we see that $n^+ + n^0 + n^- = n$ so we only need to prove 2 of them.

Proposition 23.2. 1. Let $V_0 = \{v \in V | \langle v, w \rangle = 0 \forall w \in W\}$

let $\{v_1, v_2, \dots, v_n\}$ be an orthogonal basis then $n^0 = \dim V_0$

Proof. Suppose that $\{v_1, v_2, \dots, v_n\} = \{v_1, \dots, v_s, v_{s+1}, \dots, v_n\}$ is ordered so that $\langle v_i, v_i \rangle \neq 0$ $1 \leq i \leq s$

$\langle v, v_i \rangle = 0$ $s < i \leq n$ then we see that $v_{s+1}, \dots, v_n \in V_0$

we claim that $V_0 = \text{span}\{v_{s+1}, \dots, v_n\} \forall v \in V_0$ we write $v = a_1v_1 + \dots + a_s v_s + a_{s+1}v_{s+1} + \dots + a_nv_n$

$$0 = \langle v, v_i \rangle = a_i \langle v_i, v_i \rangle \rightarrow a_i = 0$$

□

Theorem 23.3 (hairy ball). theorem hence we alternatively i see is
 thathence $\mathcal{M}_{\mathbb{B}'}^{\mathbb{B}'}$, which gives us that

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We prove that $n+1$ is inde. Of orthogonal basis. Suppose we are given $n+1$ two orthogonal basis.

$$\{v_1, v_2 \dots v_n\}$$

$$w_1, w_2 \dots w_n\}$$

Those basis can be ordered such that

$$\langle v_i, v_i \rangle > 0 \quad 1 \leq i \leq r$$

$$\langle v_i, v_i \rangle < 0 \quad r+1 \leq i \leq s$$

$$\langle v_i, v_i \rangle = 0 \quad s+1 \leq i \leq n$$

$$\langle w_i, w_i \rangle > 0 \quad 1 \leq i \leq r'$$

$$\langle w_i, w_i \rangle < 0 \quad r'+1 \leq i \leq s'$$

$$\langle w_i, w_i \rangle = 0 \quad s'+1 \leq i \leq n$$

we only need to prove that $r=r'$

we claim that $v_1, v_2, \dots, v_r, w_{r+1}, \dots, w_n$ are linearly independent.

suppose there is a linearly dependent

$$a_1 v_1 + \dots + a_r v_r + b_{r+1} w_{r+1} + \dots + b_n w_n = 0$$

$$\rightarrow a_1 v_1 + \dots + a_r v_r = -(b_{r+1} w_{r+1} + \dots + b_n w_n)$$

the rest see pic

$$\text{if } \exists a_i > 0, 1 \leq i \leq r$$

$$\text{then } \leq 0$$

but $\text{rhs} \leq 0$ this is a contradiction.

$$\text{Thus } a_1 = a_2 = \dots = a_r = 0 \rightarrow b_{r+1} = \dots = b_n = 0$$

$$\text{Therefore } r + (n - r') \leq n \rightarrow r \leq r'$$

$$\text{similarly } r' \leq r \rightarrow r = r'$$

24.1 application of Sylvester's thm

Let $Q(x_1 \dots x_n) = x^t A x$ Let A be a symmetric matrix and $\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

then the scalar product: $\langle X, Y \rangle = x^t A y$

There exists an orthogonal basis

$v_1, v_2 \dots v_n \in \mathbb{R}^n$ such that $\langle v_i, v_j \rangle = 0, i \neq j$
 $\langle v_i, v_i \rangle = d_i$

$$A = \begin{bmatrix} d_1 & & & \\ & d_2 & & \\ & & \dots & \\ & & & d_n \end{bmatrix} P$$

$\langle v_i, v_j \rangle = v_i^t A v_j = e_i^t P^t A P e_j = \text{ij entry of } P^t A P$
 $P e_j = v_j$

$$\begin{bmatrix} p_{11} & \dots & p_{1n} \end{bmatrix} \dots \dots \dots p_{n1} \dots p_{nn} \cdot e_i = v_i$$

claim: A is symmetric $n \times n$ real matrix then exists a matrix P such that $P^t A P =$

$$\begin{bmatrix} d_1 & & & \\ & d_2 & & \\ & & \dots & \\ & & & d_n \end{bmatrix} \quad p = (\text{Orthogonal basis})$$

we can find orthonormal basis i.e. $\langle v_i, v_i \rangle = 1, -1, 0$

Given orthogonal basis $\{v_i\}$

$$\tilde{v}_i = \begin{cases} v_i & \langle v_i, v_i \rangle = 0 \\ \frac{v_i}{\sqrt{\langle v_i, v_i \rangle}} & \langle v_i, v_i \rangle > 0 \\ \frac{v_i}{\sqrt{-\langle v_i, v_i \rangle}} & \langle \rangle \end{cases} \quad \text{Thus } \exists P \text{ s.t. } P^t A P = \text{a matrix with } 1, 0, -1 \text{ in the diagonal}$$

24.2 determinat

$$\text{Let } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det(A) = ad - bc$$

Then $\det k^2 \times k^2 \rightarrow K$

we claim that det is bilinear

proof of distributivity and homogeneity

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