DIAGNOSIS ON EMBEDDED SYSTEMS

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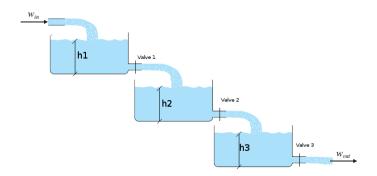
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THREE TANKS

Diagnosis of errors in high-fidelity models using a data-driven approach



THREE TANKS

Differential equation:
$$\delta(h_i) = \frac{in_i - out_i}{h_{max}}$$

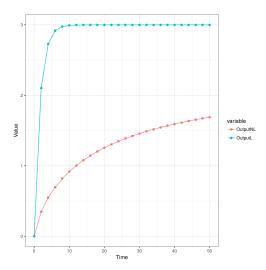
NON LINEAR MODEL:

$$out_i = \mathsf{Valve}_i \cdot \sqrt{\max(0, 2 \cdot g \cdot h_{max} \cdot (h_i - h_{i+1}))}$$

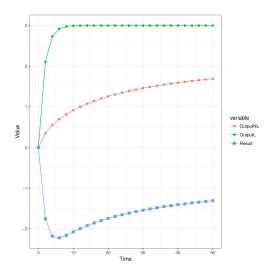
LINEAR MODEL:

$$out_i = \mathsf{Valve}_i \cdot \max(0, 2 \cdot g \cdot h_{max} \cdot (h_i - h_{i+1}))$$

THREE TANKS SIMULATION



CORRECTION FUNCTION



Types of problems

- Valve problems

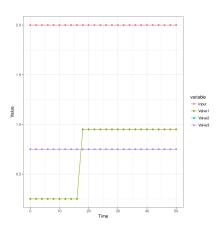
Types of problems

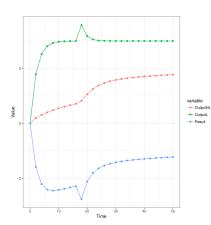
- Valve problems
- Different type of inputs

Types of problems

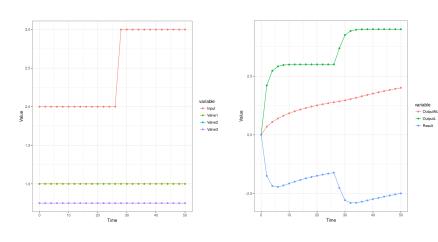
- Valve problems
- Different type of inputs
- Combinations of the above

VALVE PROBLEMS

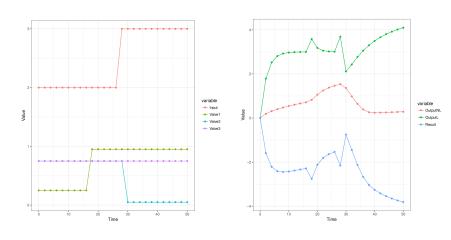




DIFFERENT INPUTS



COMBINATIONS OF ISSUES



BEST CORRECTIVE FUNCTION

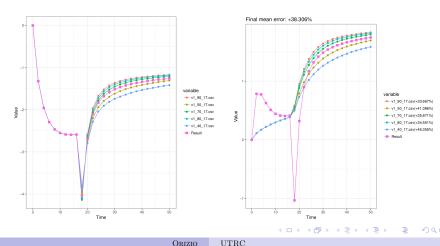
Can we find the best corrective function for our linear model?

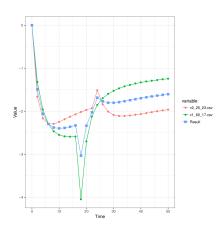
BEST CORRECTIVE FUNCTION

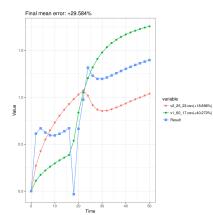
Can we find the best corrective function for our linear model?

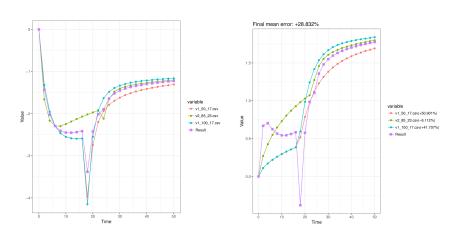
We are looking for a corrective function that could work in anytime for anything

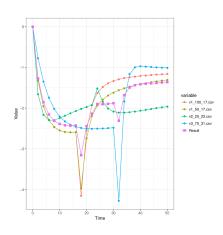
Combine different corrective function and find the optimal between them

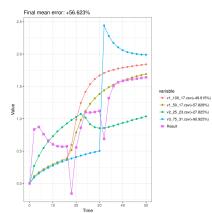












OBSERVATIONS

- Multi issues independent

OBSERVATIONS

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- Initial adapting time

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- Multi issues independent
- Initial adapting time
- Require smoothing on spikes

DIAGNOSIS

Reversing the process and try to understand which issue has arisen knowing how the surrogate model behaved in that scenario

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SERIES OF SVM : train an SVM for each known problem and use it to identify it when it occurs

NEURAL NETWORK

