INTRODUCTION TO MICRO CONTROLLERS WITH ARDUINO

Most of us know what a computer looks like. It usually has a keyboard, monitor, CPU (Central Processing Unit), printer, and a mouse. These types of computers, like the Mac or PC, are primarily designed to communicate (or "interface") with humans.

But did you know that there are computers all around us, running program and quietly doing calculations, not interacting with humans at all? These computers are in your car, on the Space Shuttle, in your kid brother's toy, and maybe even inside your hairdryer.

We call these devices "microcontrollers". Micro because they re small, and controller because they "control" machines, gadgets, whatever.

They're cool because, you can build a machine or device, write programs to control it and then let it work for you automatically.

There is an infinite number of applications for microcontrollers. Your imagination is the only limiting factor!





WHAT IS ARDUINO:

Arduino is an open source physical computing platform based on a simple input/output (I/O) board and a development environment that implements the Processing language (www.processing.org).

Arduino can be used to develop standalone interactive objects or can be connected to software on your computer (such as Flash, Processing, NodeJS or Max/MSP).

PHYSICAL COMPUTING?:

Physical Computing uses electronics to prototype new materials for designers and artists.

It involves the design of interactive objects that can communicate with humans using sensors and actuators controlled by a behavior implemented as software running inside a microcontroller (a small computer on a single chip).

PHYSICAL COMPUTING?:

In the past, using electronics meant having to deal with engineers, and building circuits one small component at a time. These issues kept creative people from experimenting with the medium directly. In recent years, microcontrollers have become cheaper and easier to use.

PHYSICAL COMPUTING?:

The progress that has been made with Arduino has been to bring these tools one step closer to the non expert allowing people to start building things after only two or three days of a workshop.

With Arduino, a designer or artist can get to know the basics of electronics and sensors very quickly and can start building prototypes with very little investment.

SOME EXAMPLES

http://www.jimcampbell.tv/portfolio/installations/shadow_for_heisenberg/

http://www.snibbe.com/index.php/projects/interactive/blowup/

http://www.smoothware.com/danny/woodenmirrormov.html

THE ARDUINO PLATFORM

Arduino is composed of two major parts:

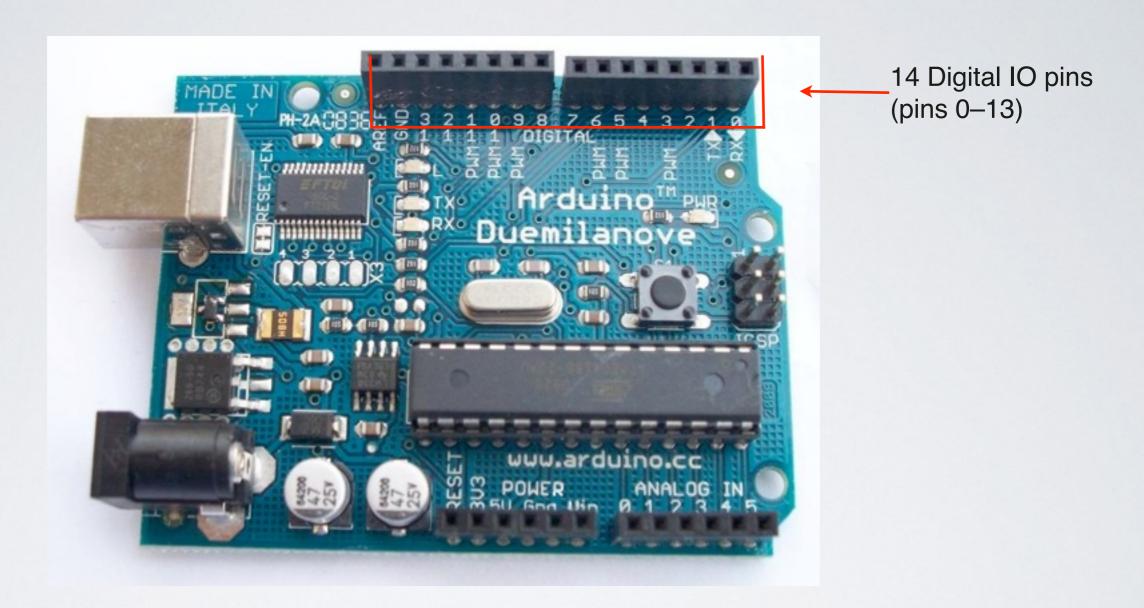
- -The Arduino board, which is the piece of hardware you program to control your projects.
- -The Arduino IDE, the piece of software you run on your computer. You use the IDE to create a sketch(a program) that you upload to the Arduino board. The sketch tells the board what to do.

ARDUINO TERMS

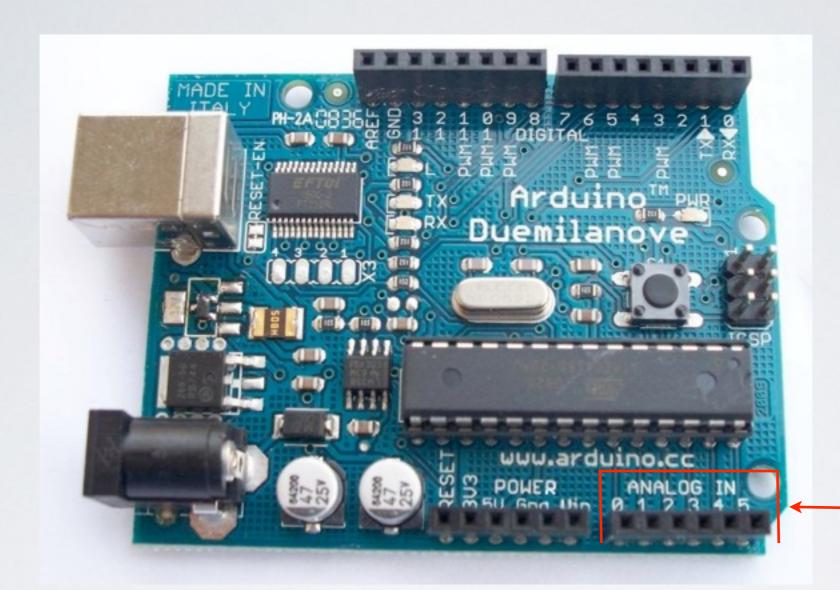
- "sketch" a program you write to run on an Arduino board
- "pin" an input or output connected to something. e.g. output to an LED, input from a knob.
- "digital" value is either HIGH or LOW. (aka on/off, one/zero) e.g. switch state
 - "analog" value ranges, usually from 0-255. e.g. LED brightness, motor speed, etc.

The Arduino board is a microcontroller board, which is a small circuit (the board) that contains a whole computer on a small chip (the micro- controller). This computer is at least a thousand times less powerful than the MacBook I'm using to write this, but it's a lot cheaper and very useful to build interesting devices.

The Arduino design team have placed on this board all of the components that are required for this micro controller to work properly and to communicate with your computer. There are many versions of this board; the one we'll use throughout this book is the Arduino Uno, which is the simplest one to use and the best one for learning on.

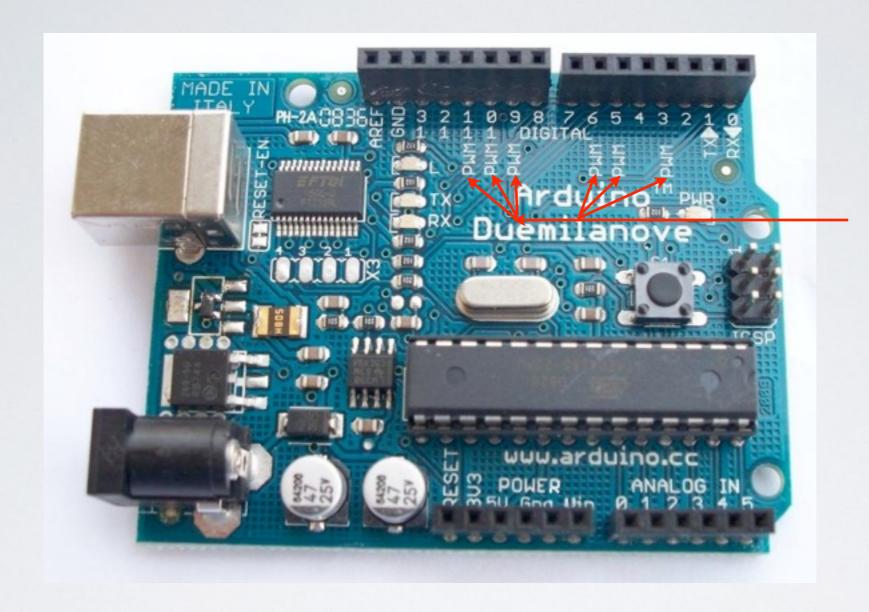


These can be inputs or outputs, which is specified by the sketch you create in the IDE.



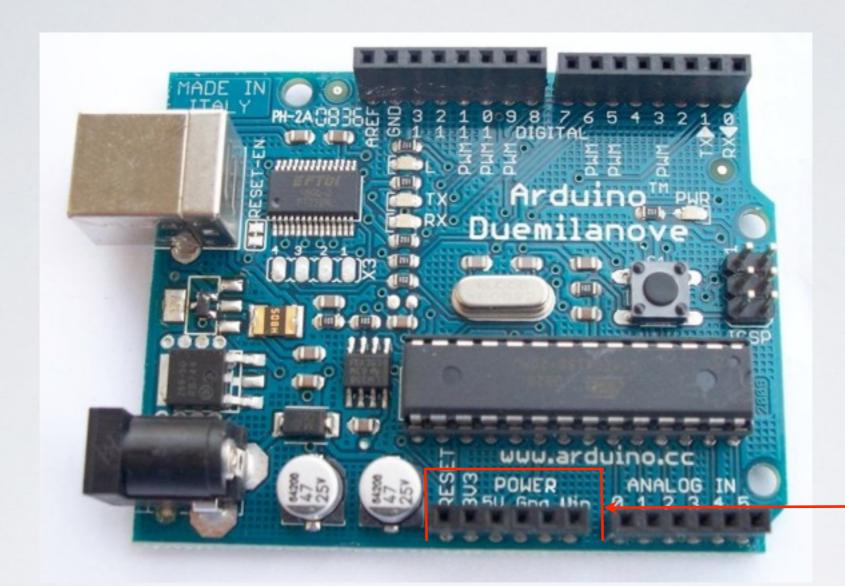
Analogue In pins (pins 0–5)

These dedicated analogue input pins take analog values (i.e., voltage readings from a sensor) and convert them into a number between 0 and 1023 we'll look at this Thursday



Analogue Out pins (pins 3, 5, 6, 9, 10, and 11)

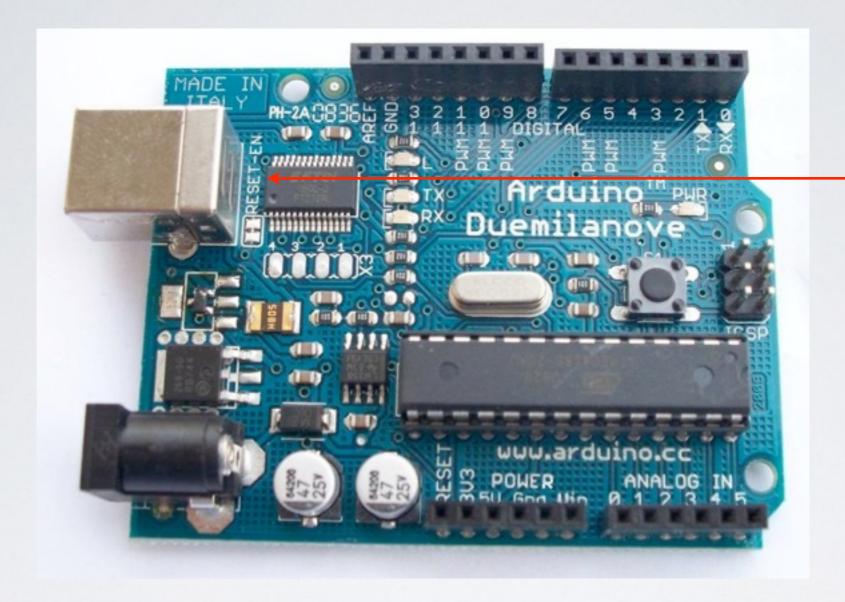
These are actually six of the digital pins that can be reprogrammed for analog output we'll look at this Thursday



Power Pins

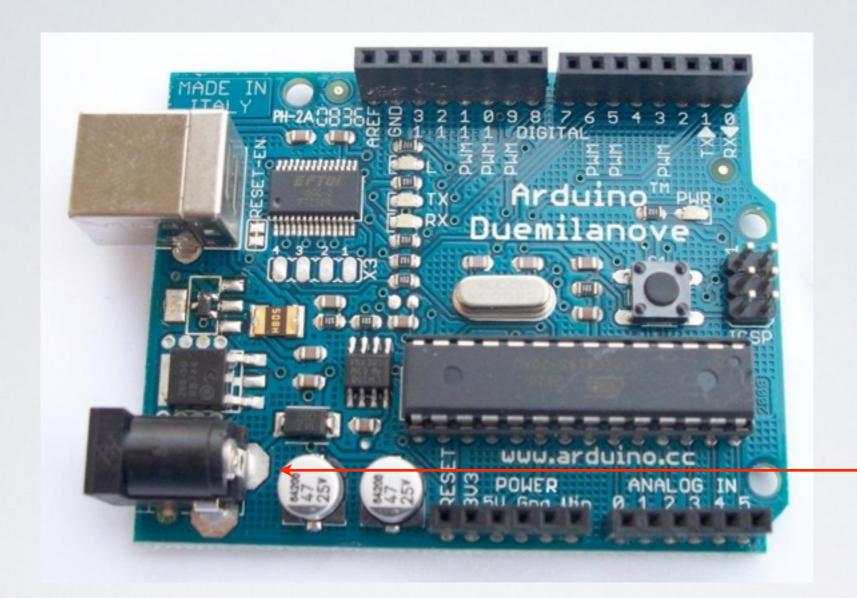
These power pins are capable or providing 5.5 volts or 3.3 volts of power. Also there are two pins that are capable of providing ground any components that you attach to the controller.

*We'll cover Power, Ground and Voltage in just a bit.



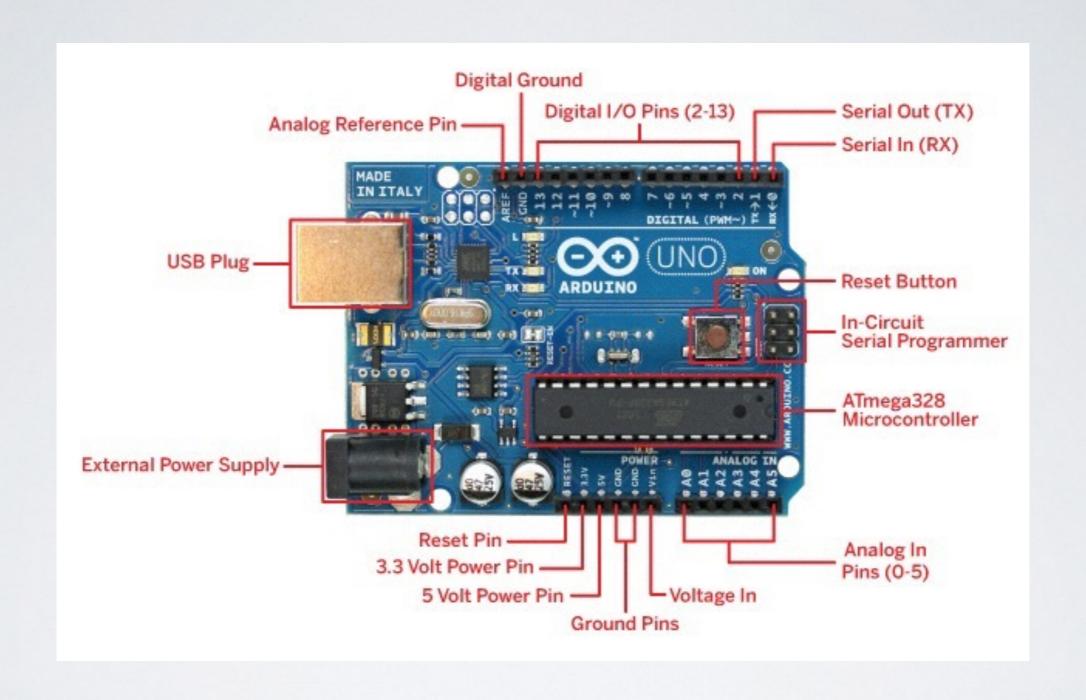
USB Connector

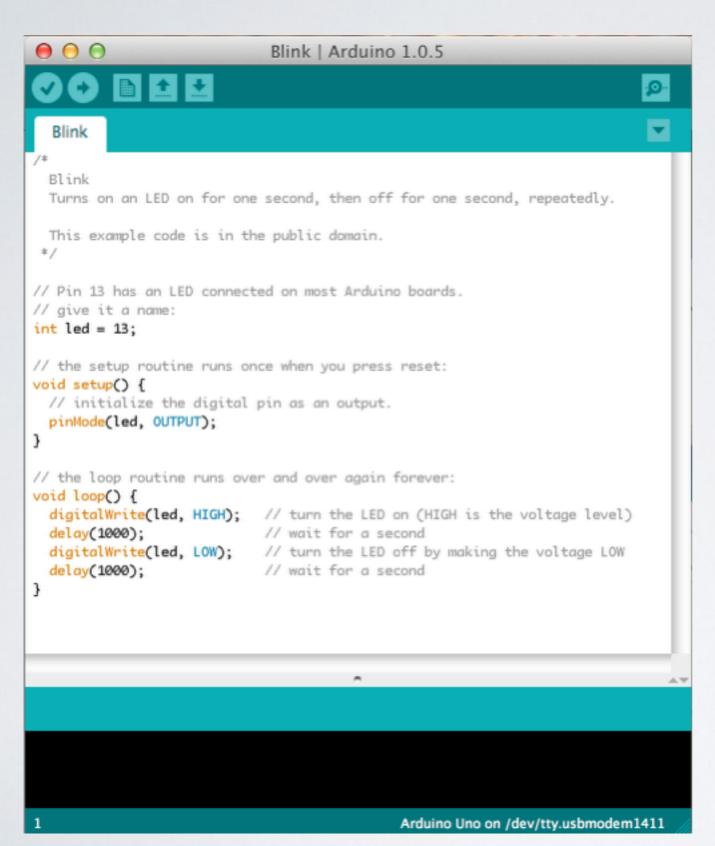
The USB connector connects the controller to you computer allowing you to program it. The USB connection also provides power.



Power Connector

The power connector allows you to power your controller independently either with a battery or a power supply.





- -Like a text editor
- -View/write/edit sketches
- -But then you program them into hardware

The IDE (Integrated Development Environment) is a program running on your computer that allows you to write sketches for the Arduino board in a simple language modeled after the Processing (www.processing.org) language.

The magic happens when you press the button that uploads the sketch to the board: the code that you have written is translated into the C language (which is generally quite hard for a beginner to use), and is compiled into a language that the micro controller understands.

This last step is quite important, because it's where Arduino makes your life easy by hiding away as much as possible of the complexities of programming microcontrollers.

The programming cycle on Arduino is basically as follows:

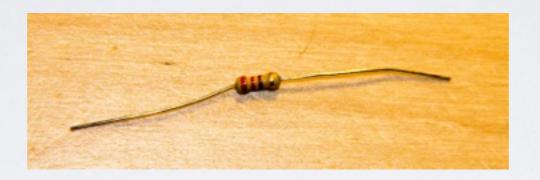
- » Plug your board into a USB port on your computer.
 - » Write a sketch that will bring the board to life.
- » Upload this sketch to the board through the USB connection and wait a couple of seconds for the board to restart.
 - » The board executes the sketch that you wrote.

LESSON I - BASIC HOUSEKEEPING

This first lesson won't really teach programming the Arduino. It's meant to introduce you to building a basic electrical circuit.

It will also get us prepped for building the rest of the exercises throughout the class.

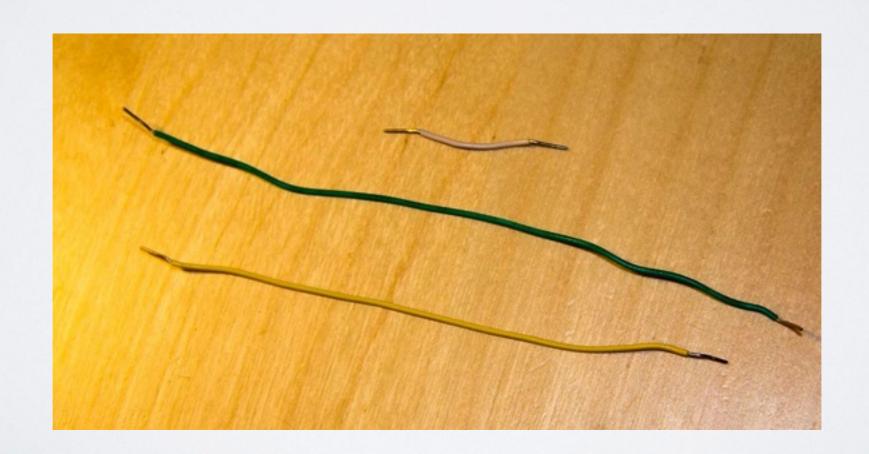
I 220 ohm resistor (bands are red,red,violet, gold)



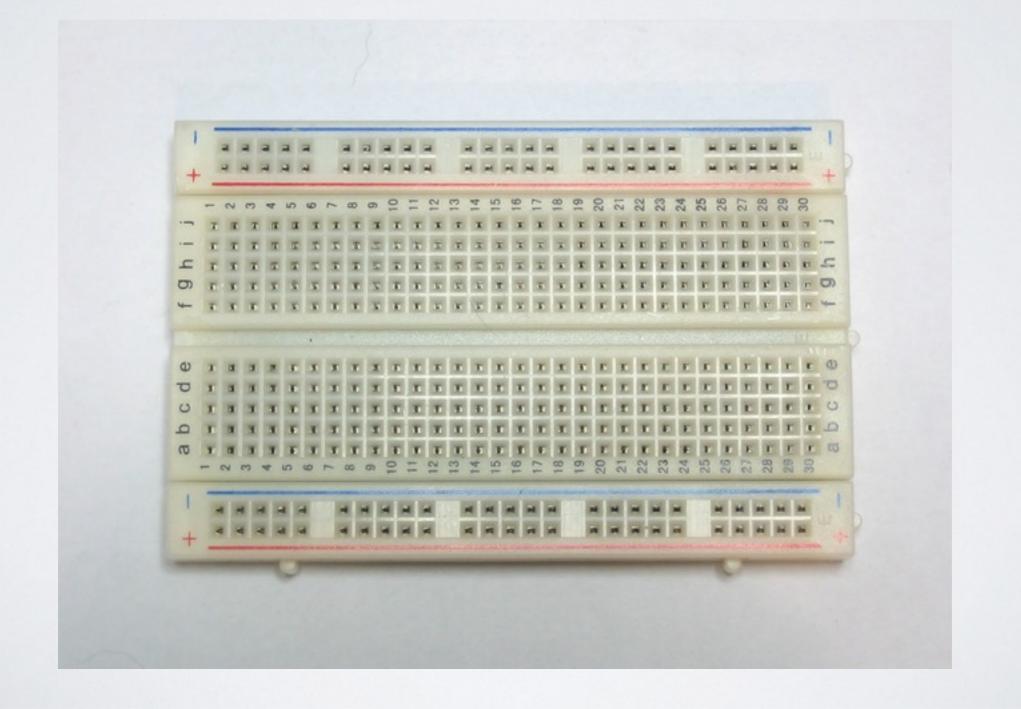
I red Light Emitting Diode(LED)



I long yellow wire
I long green wire
I short white wire



I breadboard



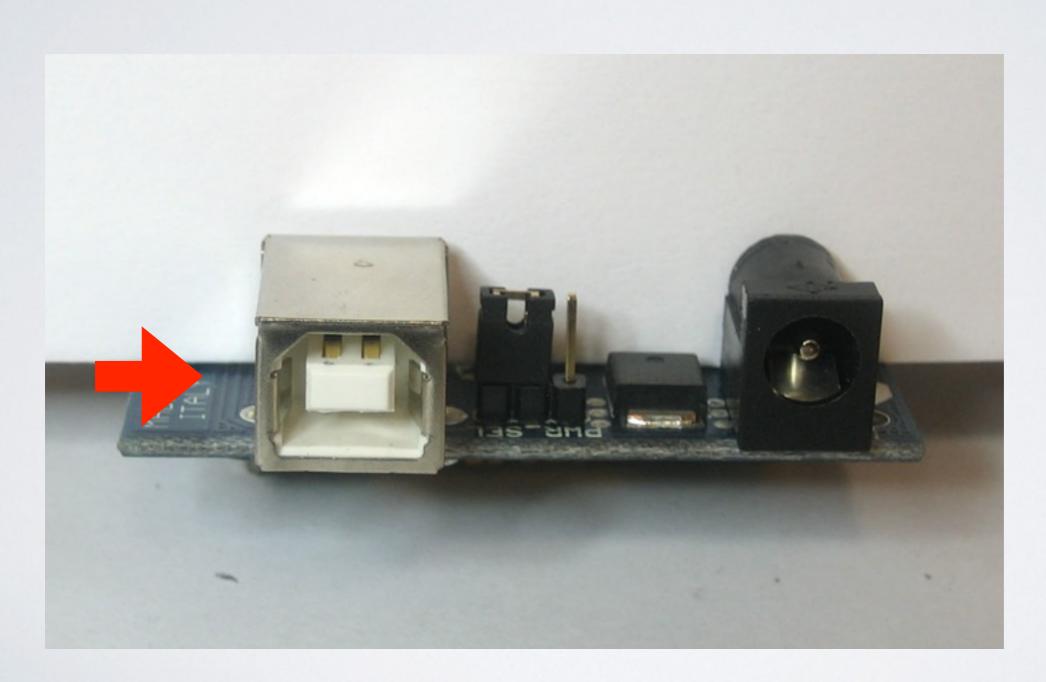
LESSON I - GATHER THE PARTS I USB cable



I Arduino



CONNECTING TO YOUR COMPUTER



USB Port

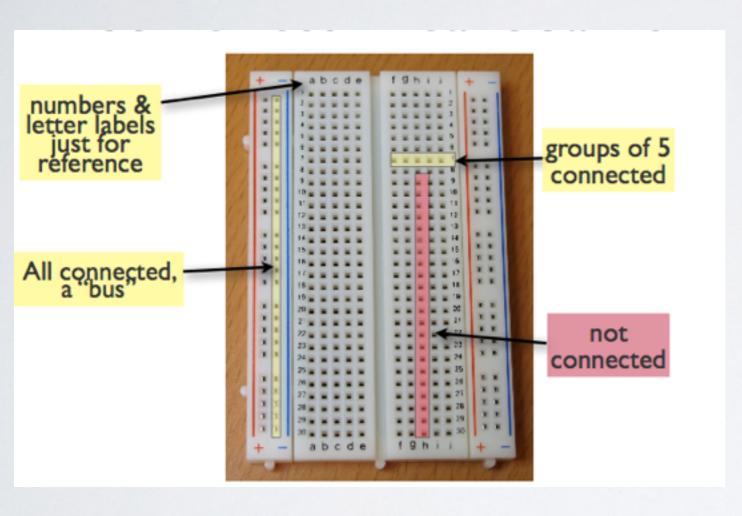
CONNECTING TO YOUR COMPUTER

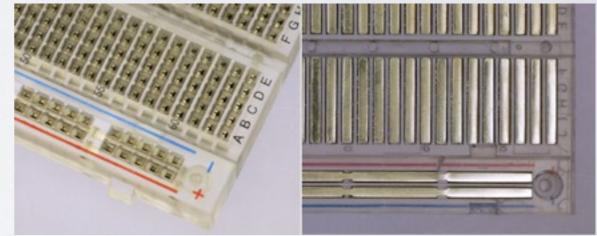
Connect the flat end of the USB cable to your computer, and the square end to the Arduino. A green led on the right should come on.



LET MAKE SOME CIRCUITS!

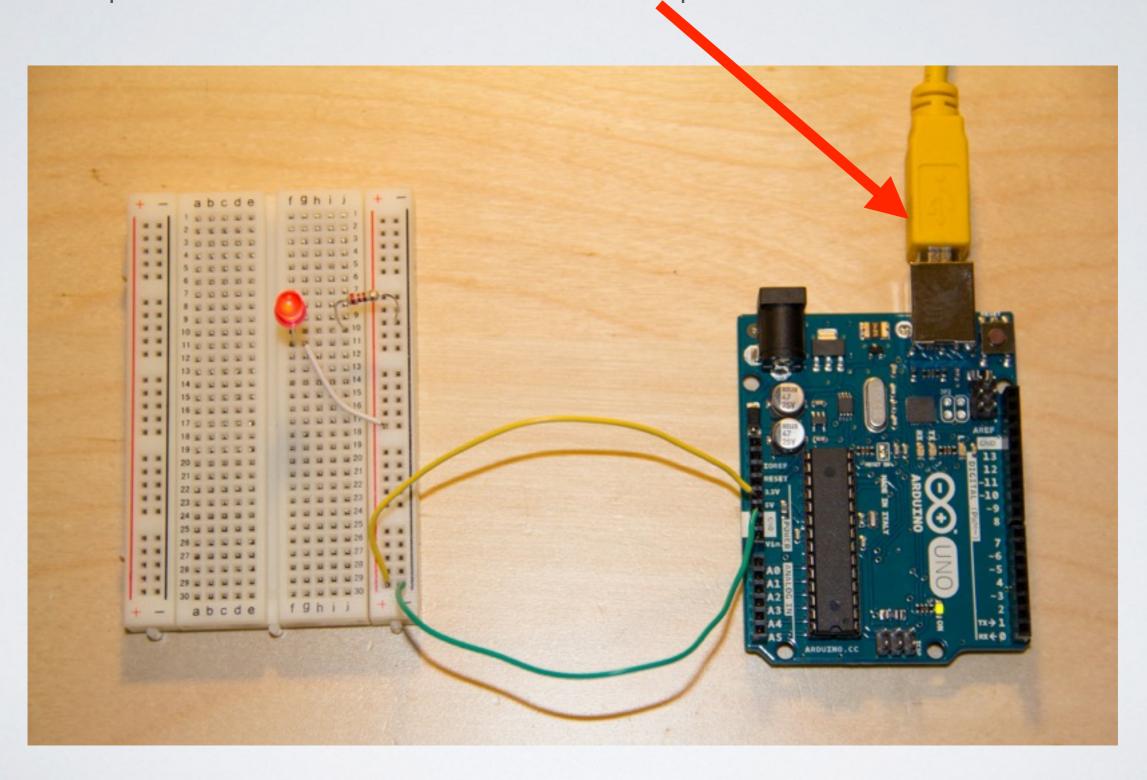
Solderless Breadboard





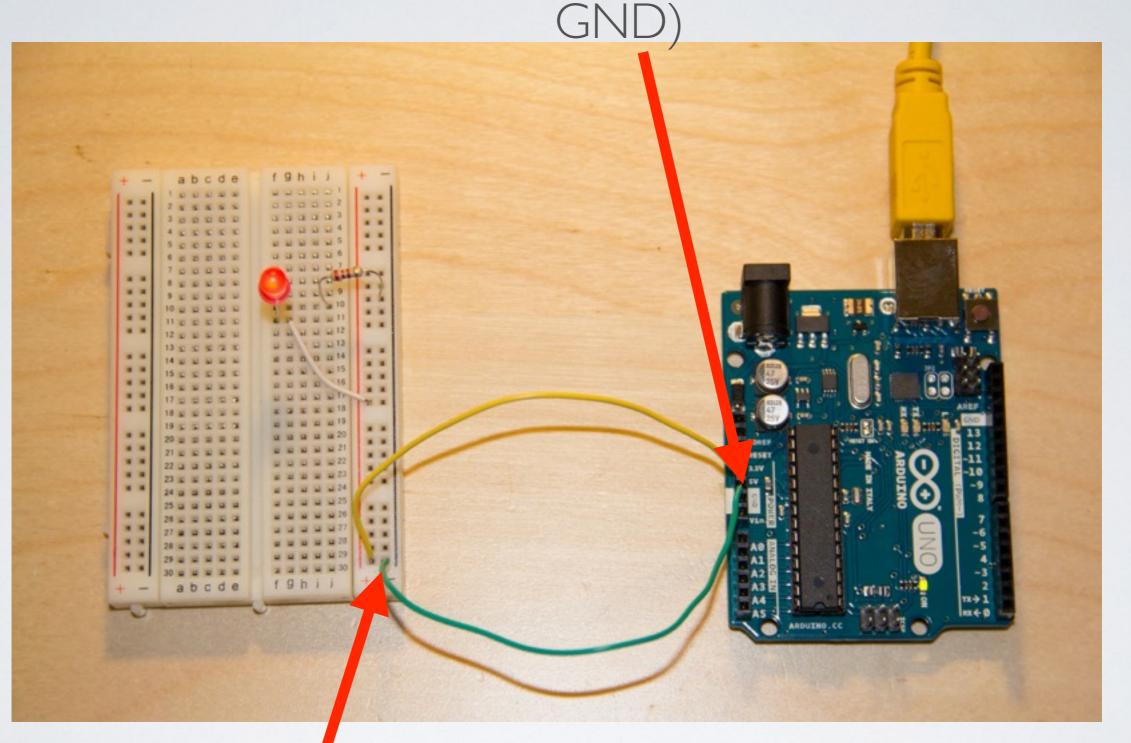
LETS MAKE SOME CIRCUITS!

Step I connect Ardunio to computer with USB cable



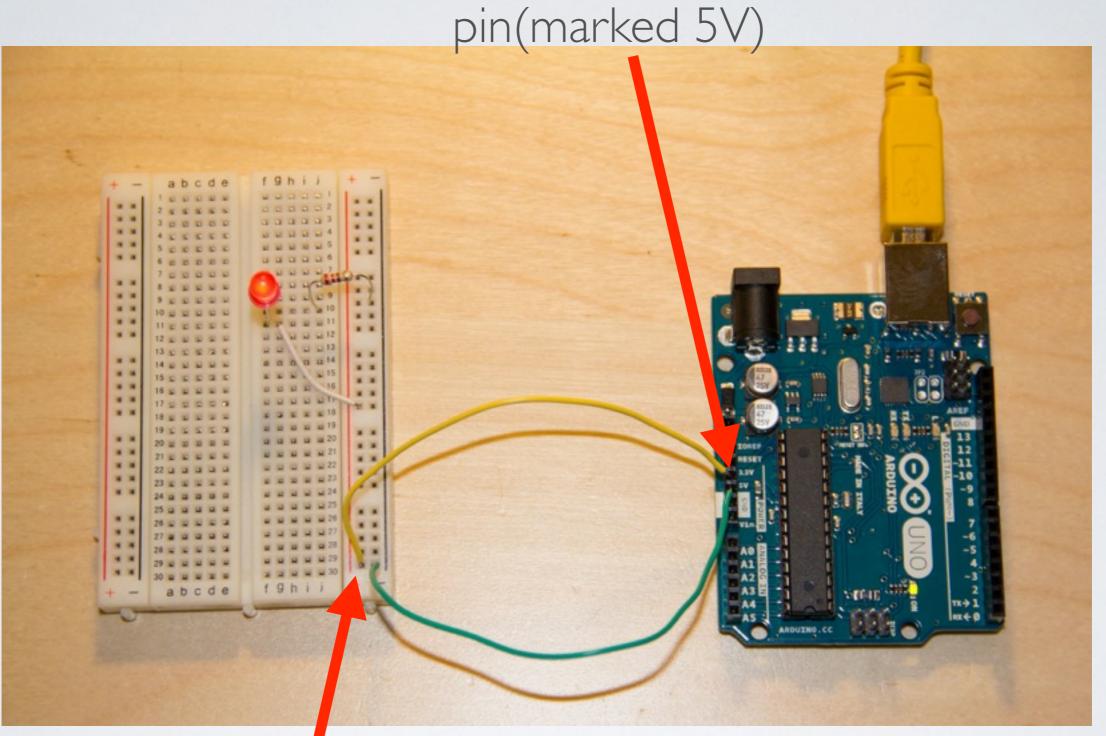
LETS MAKE SOME CIRCUITS!

Step 2 connect one side green wire to the ground pin(marked



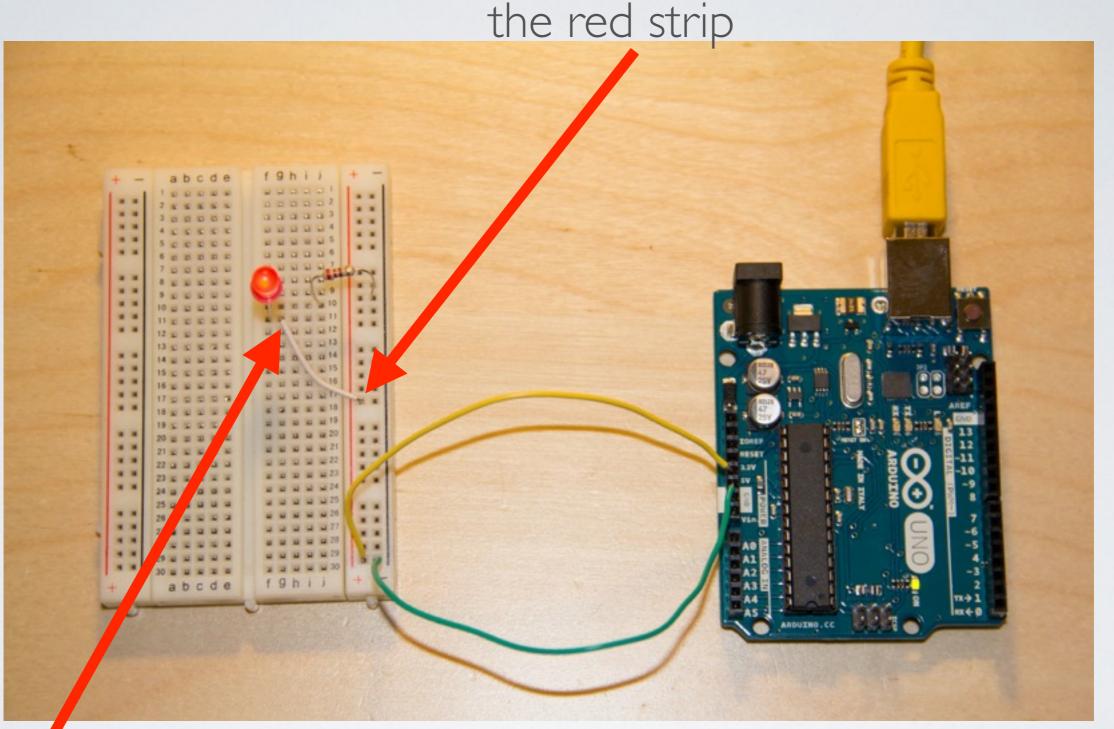
Connect the other side of the green wire to the ground strip on the breadboard market with a minus sign -

LETS MAKE SOME CIRCUITS!
Step 3 connect one side of the yellow wire to the 5 volt



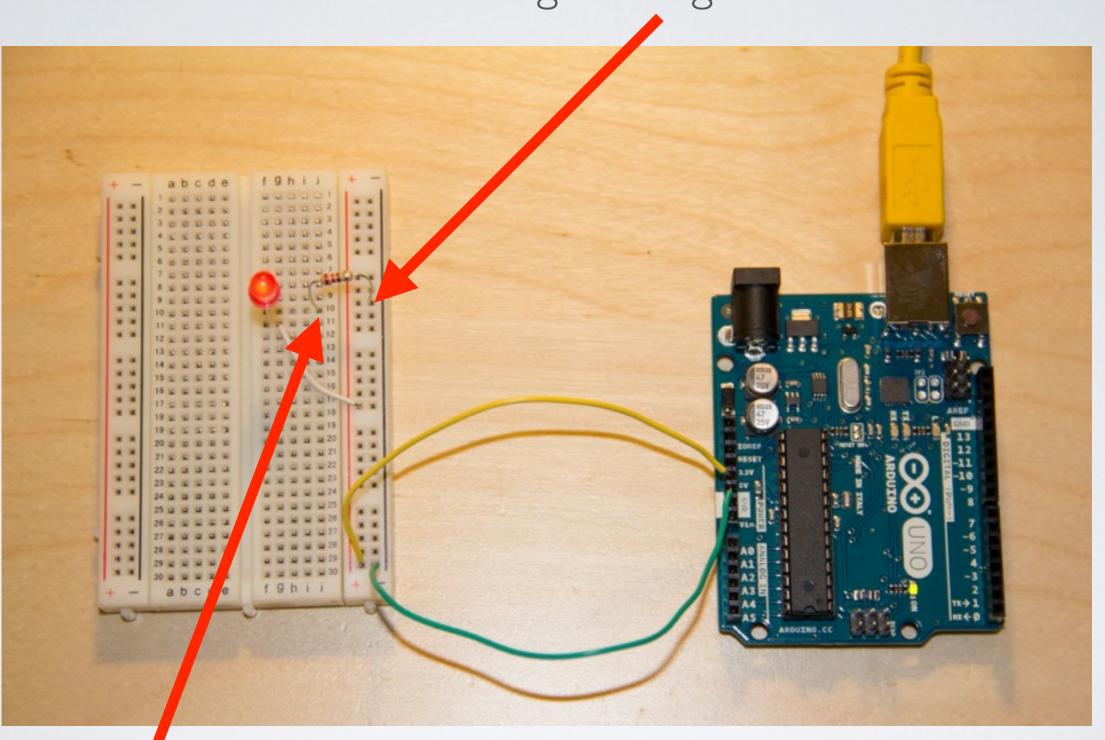
Connect the other side of the green wire to the ground strip on the breadboard market with a plus sign +

LETS MAKE SOME CIRCUITS!
Step 4 connect one side of the short white to any socket along



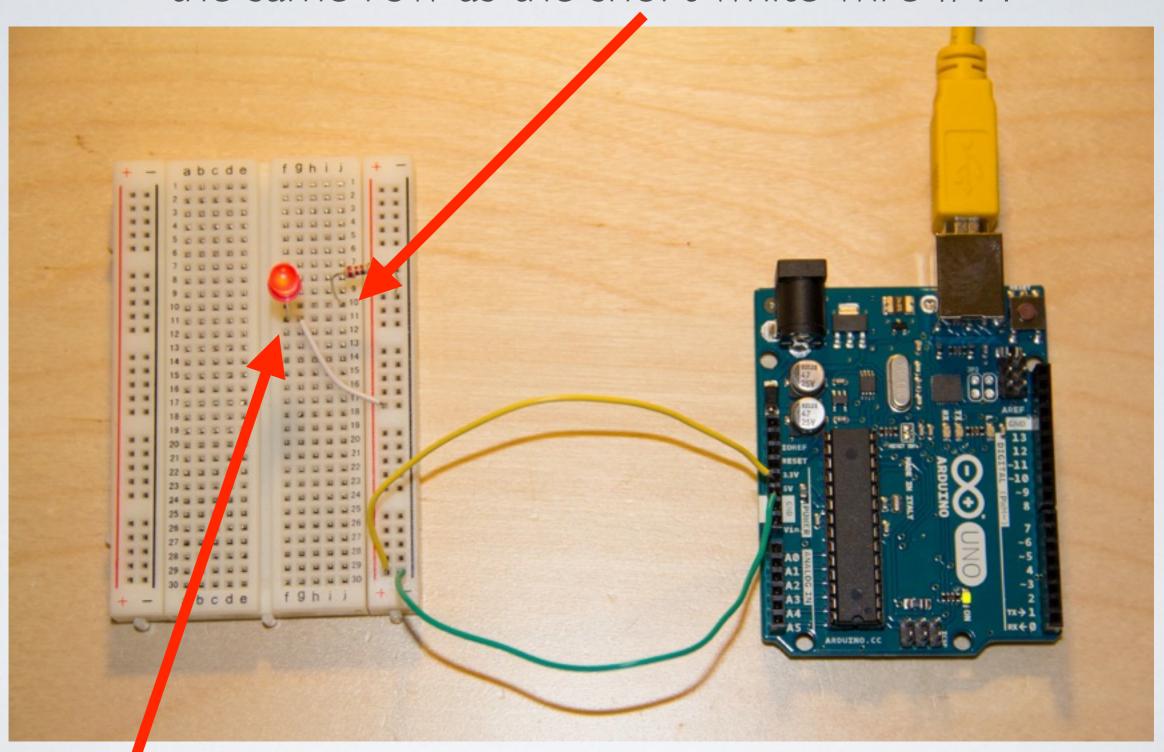
Connect the other side of the short wire to any socket in the row numbered 11

LETS MAKE SOME CIRCUITS!
Step 5:Place the resistor on one socket in the strip marked with a negative sign -



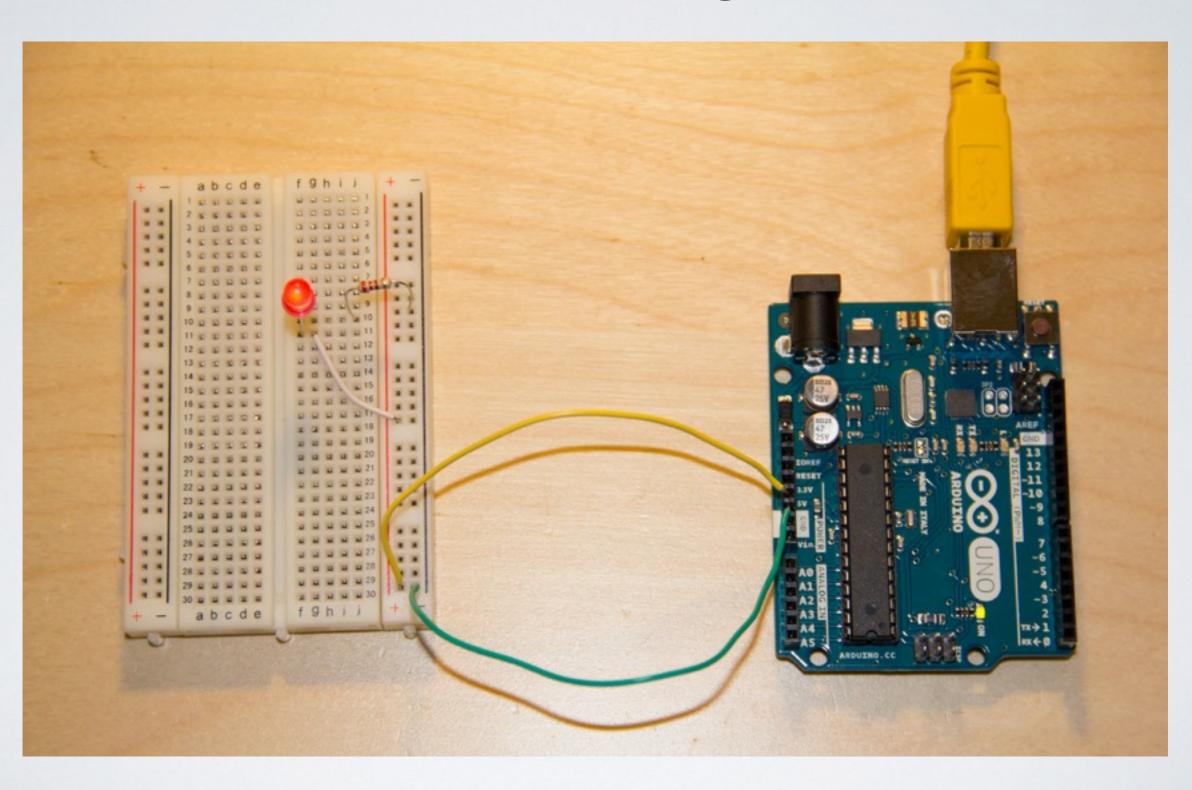
Place the other end of the resistor in row I I

Step 6: The LED has a long wire and a short wire place that in the same row as the short white wire #11

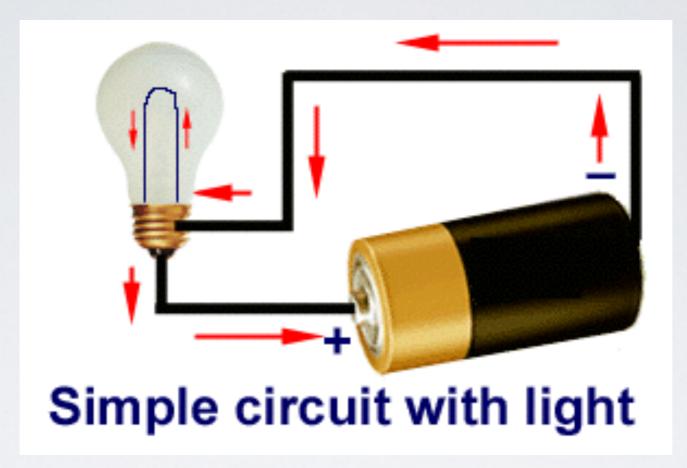


Place short end of the LED in the same row as the resistor #10

You should have Light!



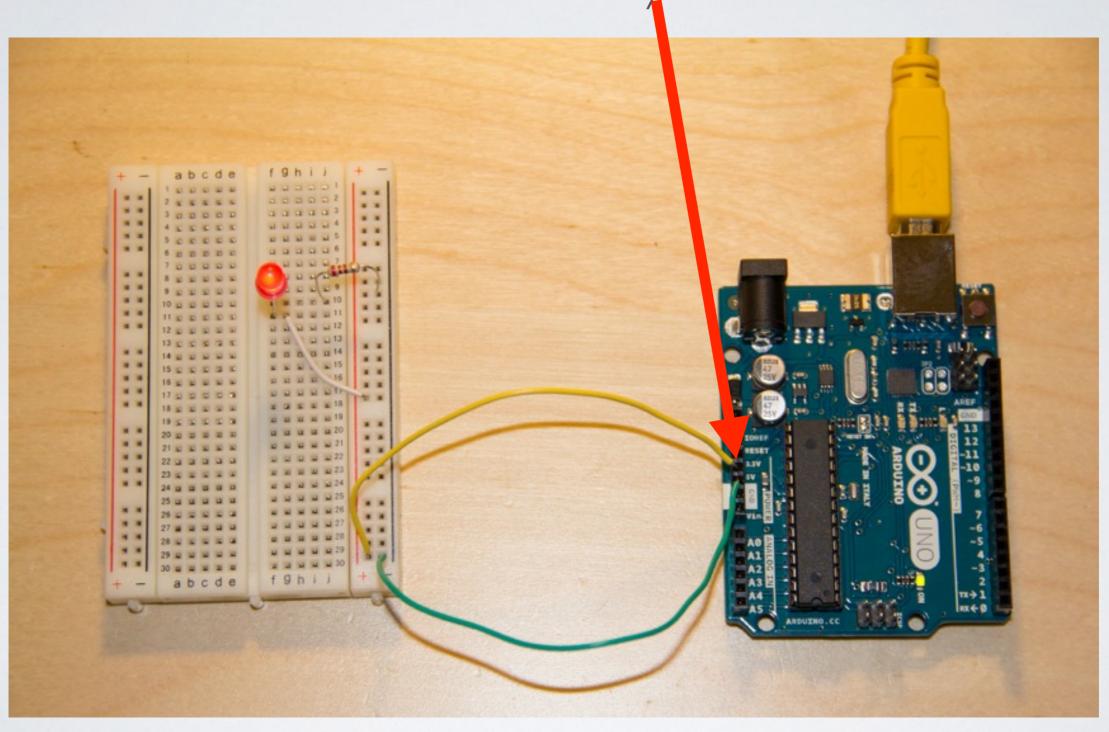
What's going on here?



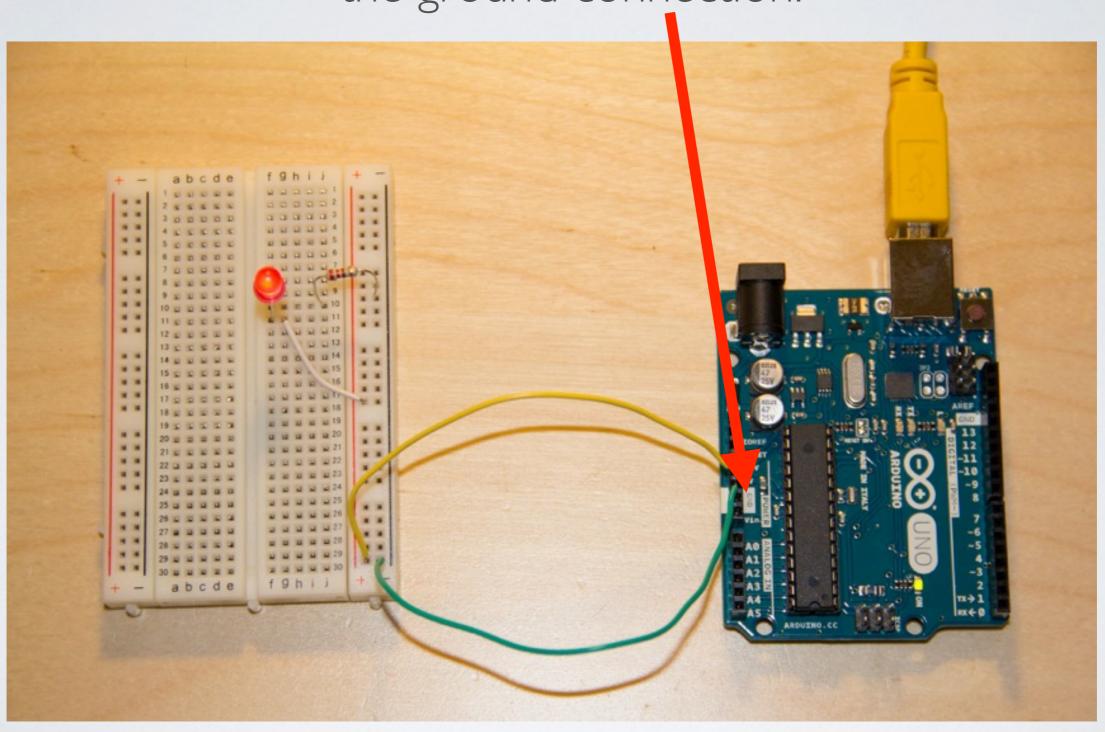
An electric circuit is a closed loop where electric current can flow. Electricity flows like water from Ground to Positive.

As the current passes though a component such as an LED it causes it to light up.

The Arduino is acting as our battery providing 5 volts of electricity.



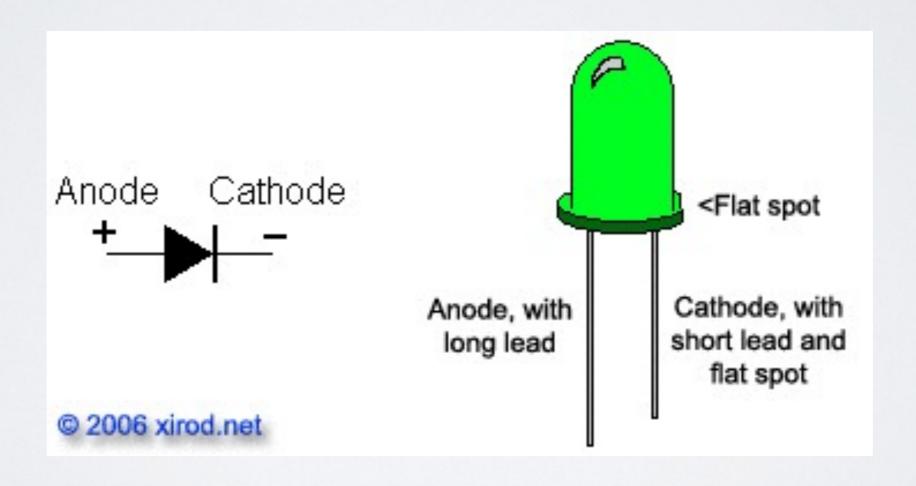
The Arduino is acting as our battery and is closing the loop with the ground connection.



What's going on here?

An led is a directional component.

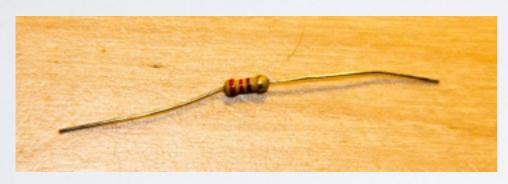
- -The long Lead is called the Anode is connected to the +5Volts
- -The short lead is called the Cathode and is connected to ground
- -As the electrical current passes through the LED produces light.

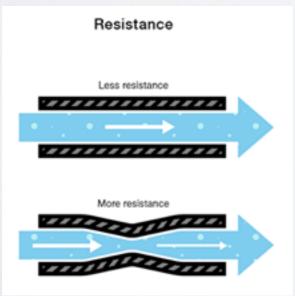


What's going on here?

But, 5 Volts is too much electricity for the LED and will burn it out!

So before we send electricity to it we need to place a resistor in front of it to limit the electrical current.

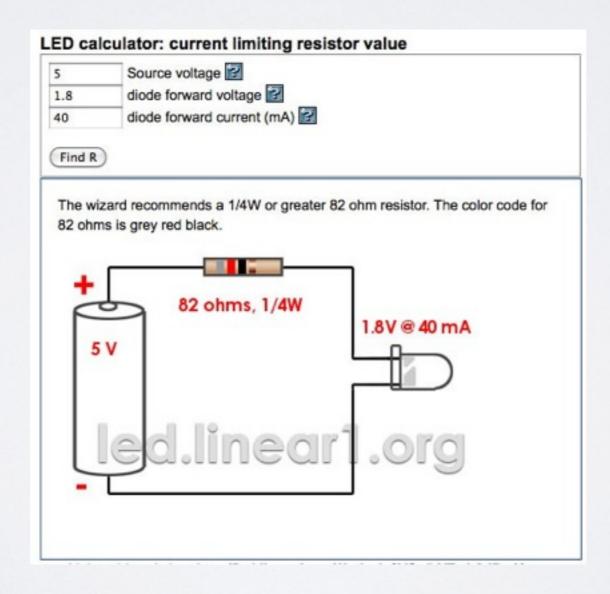






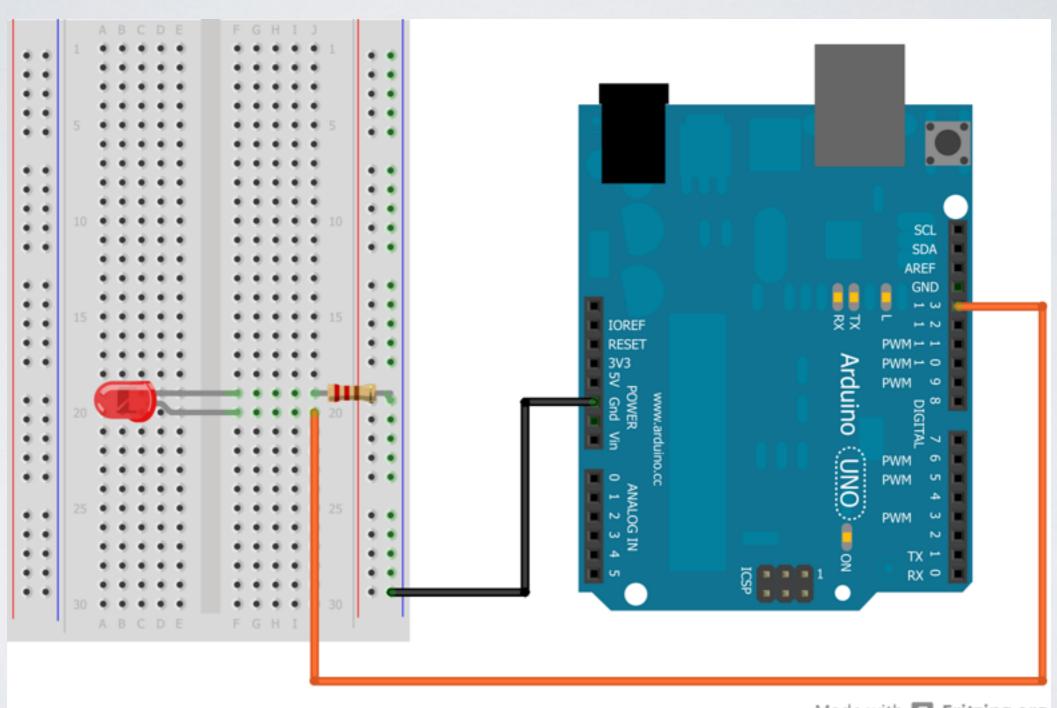
More on basic electrical theory here: https://learn.sparkfun.com/tutorials/voltage-current-resistanceand-ohms-law

LED Resistor calculator: http://led.linearl.org/lled.wiz



LESSON 2 -REALLY GETTING STARTED WITH ARDUINO

This lesson will basically get you up and running using the Arduino software and uploading a sketch to the Arduino board. Once you've completed this step we can continue to the really interesting stuff, which is when we start writing our own sketches!



Made with Fritzing.org

Parts:

I long green wire

I long yellow wire

I Led(your choice of color)

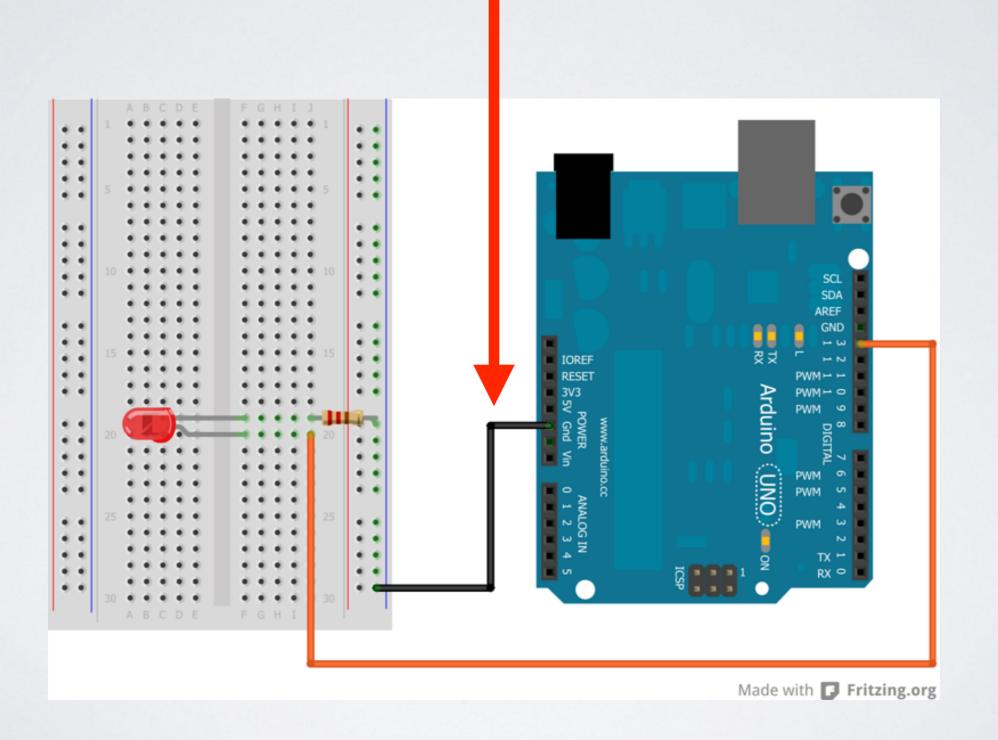
I resistor (bands are red, red, violet, gold)

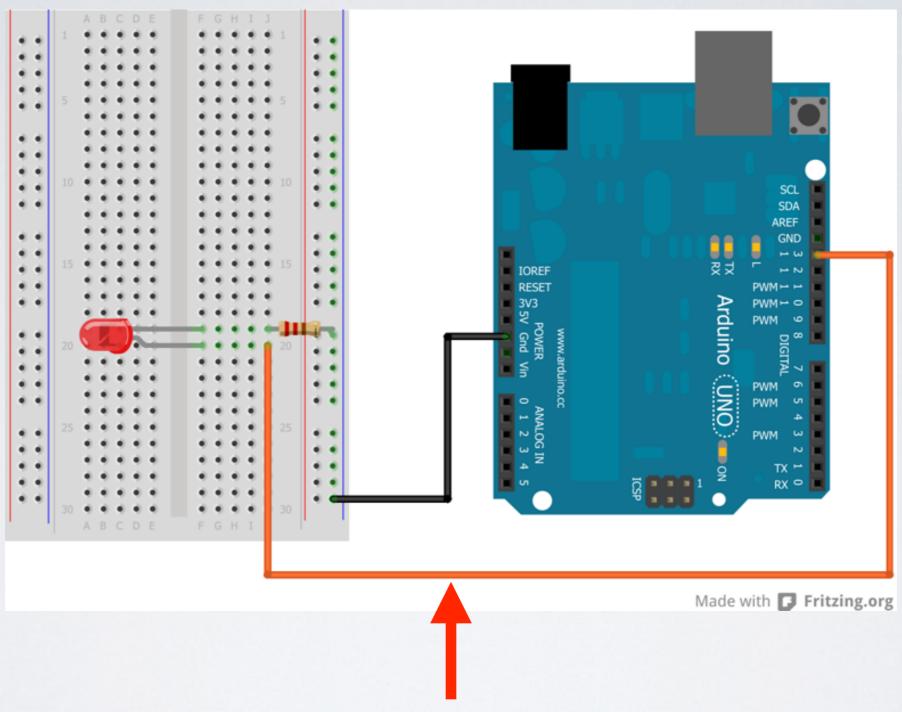
I Breadboard

I Arduino and USB cable

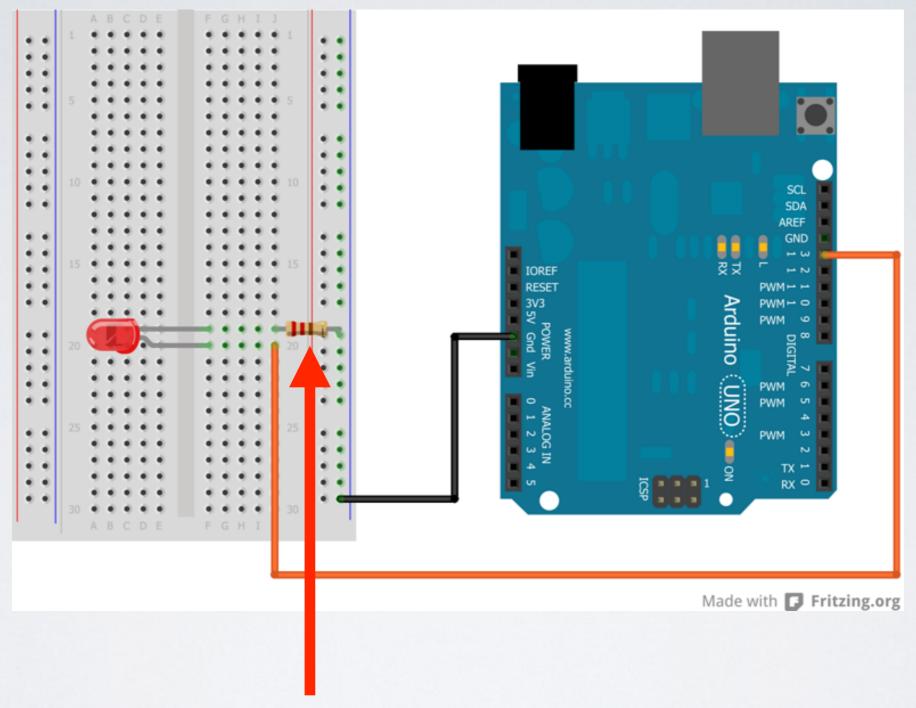
*Most of the parts from exercise I

I Connect GND on the arduino to the ground terminal on the breadboard





2 Connect Pin 13 on the to the same row as the long lead of the LED on the breadboard



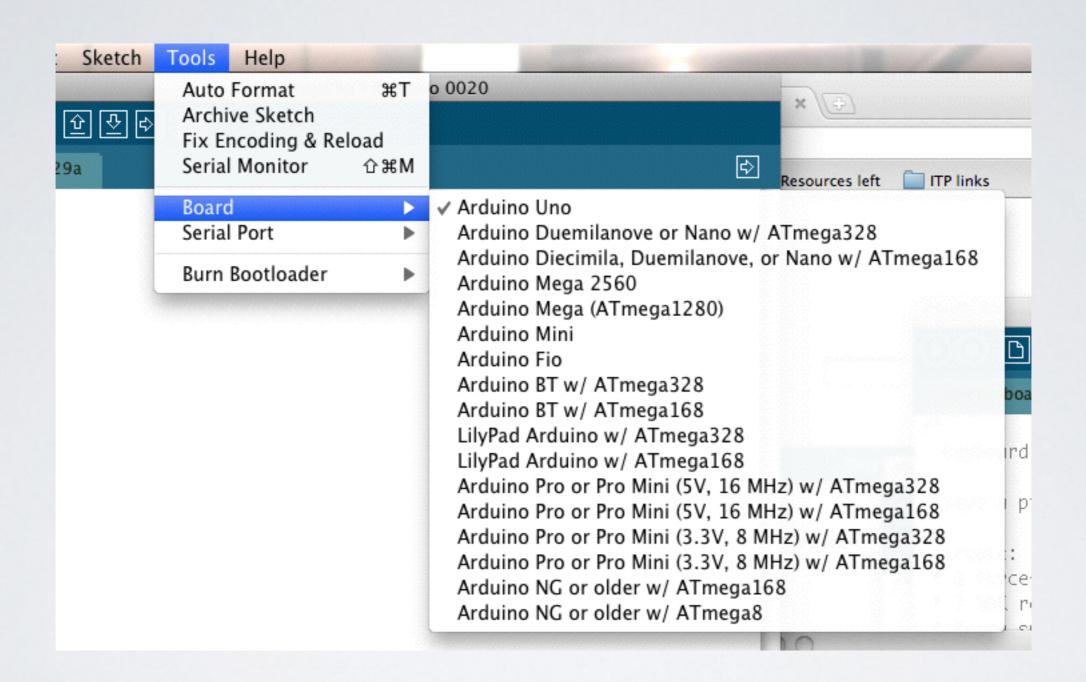
3 Make a connection between the ground strip and the short lead of the LED using the resistor.

Once the LED is connected, you need to tell Arduino what to do. This is done through code - that is, a list of instructions that we give the micro- controller to make it do what we want.

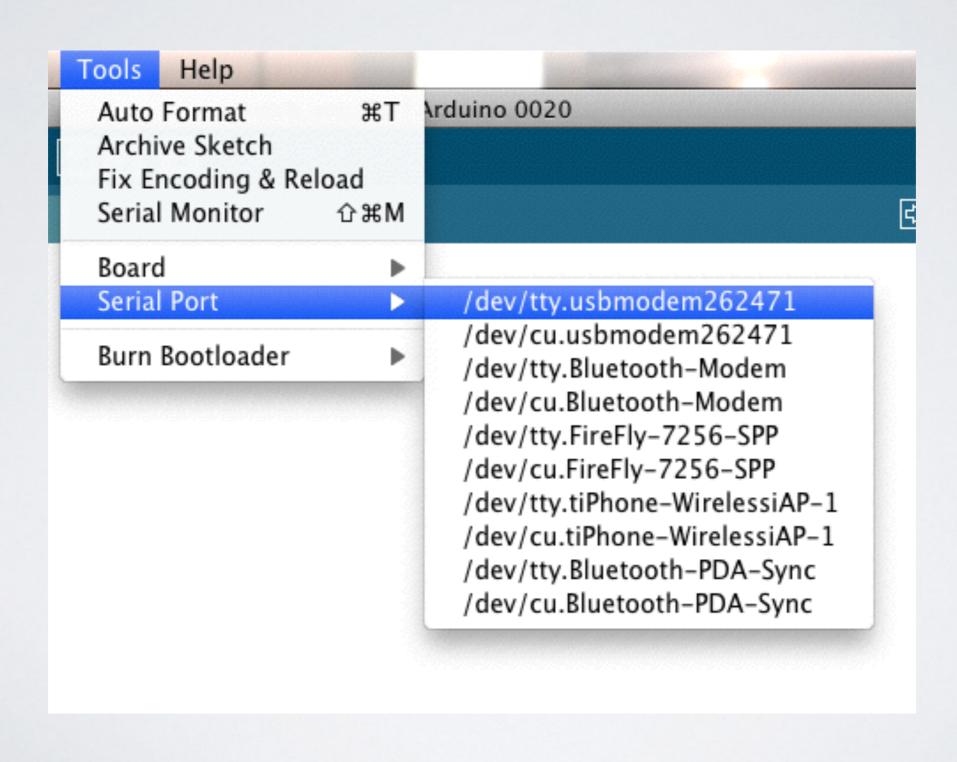


Fire up the Arduino IDE from the Applications folder.

From the tools menu -> Board->Arduino Uno



From the tools menu -> Serial Port >tty.usbmodem####



Upload code to board

Check code for errors

```
Blinking Led Random Delay | Arduino 1.0.5
  Blinking_Led_Random_Delay
// Example 01 : Blinking LED
int LED = 13; // LED connected to// digital pin 13
int i; // Variable to hold our random value
void setup()
 pinHode(LED, OUTPUT); // sets the digital pin as output
void loop()
 i = random(1, 1000); // generate a random value every loop cycle
 digitalWrite(LED, HIGH); // turns the LED on
 delay(i);
               // pause for the duration of i
 digitalWrite(LED, LOW); // turns the LED off
 delay(i); // waits for a second the duration of i
Done Saving.
Binary sketch size: 1,748 bytes (of a 32,256 byte maximum)
                                          Arduino Uno on /dev/tty.usbmodem1421
```

The Arduino IDE with your first sketch loaded

```
// Example 01 : Blinking LED
int LED = 13; // LED connected to digital pin 13
void setup()
pinMode(LED, OUTPUT); // sets the digital
                // pin as output
void loop()
 digitalWrite(LED, HIGH); // turns the LED on
 delay(1000); // waits for a second
 digitalWrite(LED, LOW); // turns the LED off
 delay(1000); // waits for a second
```

USING ARDUINO

- -Write your sketch
- -Press Compile button (to check for errors)
- -Press Upload button to program Arduino board with your sketch

```
void setup() (
 pinMode(ledPin, OUTPUT);
                               // sets 1
void loop() {
 digitalWrite(ledPin, HIGH);
                               // sets t
 delay(1000);
                               // vaits
 digitalWrite(ledPin, LOW);
                               // sets t
  delay(1800);
                               // vaits
                        compile
        Done compiling.
                         upload
                           TX/RX flash
                            sketch runs
```

Arduino expects two functions to exists—one called setup() and one called loop().

setup() is where you put all the code that you want to execute once at the beginning of your program

loop() contains the core of your program, which is executed over and over again.

When you power up the board, the code runs; when you want to stop, you just turn it off.

// Example 01 : Blinking LED

A comment is a useful way for us to write little notes. The preceding title comment just reminds us that this program, Example 01, blinks an LED.

int LED = 13; // LED connected to // digital pin 13

We are defining a integer variable called LED as Arduino pin 13.

void setup()

This line tells Arduino that the next function will be called setup().

```
void setup()
{
pinMode(LED, OUTPUT); // sets the digital // pin as output
}
```

pinMode tells Arduino how to configure a certain pin. Digital pins can be used either as INPUT or OUTPUT.

In this case, we need an output pin to control our LED, so we place the number of the pin and its mode inside the parentheses.

pinMode is a function, and the words (or numbers) specified inside the parentheses are arguments. INPUT and OUTPUT are constants in the Arduino language.

```
void loop()
{
```

loop() is where you specify the main behavior of your interactive device. It will be repeated over and over again until you switch the board off.

digitalWrite(LED, HIGH); // turns the LED on

As the comment says, digitalWrite() is able to turn on (or off) any pin that has been configured as an OUTPUT.

The first argument (in this case, LED) specifies which pin should be turned on or off (remember that LED is a constant value that refers to pin 13, so this is the pin that's switched).

The second argument can turn the pin on (HIGH) or off (LOW).

Imagine that every output pin is a tiny power socket, like the ones you have on the walls of your apartment. American ones are 110 V, and Arduino works at a more modest 5 V.

The magic here is when software becomes hardware. When you write digitalWrite(LED, HIGH), it turns the output pin to 5 V, and if you connect an LED, it will light up.

So at this point in your code, an instruction in software makes something happen in the physical world by controlling the flow of electricity to the pin. Turning on and off the pin at will now let us translate these into something more visible for a human being; the LED is our actuator.

delay(1000); // wait for a second

Arduino has a very basic structure. Therefore, if you want things to happen with a certain regularity, you tell it to sit quietly and do nothing until it is time to go to the next step. delay() basically makes the processor sit there and do nothing for the amount of milliseconds that you pass as an argument. Milliseconds are thousands of seconds; therefore, 1000 milliseconds equals I second. So the LED stays on for one second here.

digitalWrite(LED, LOW); // turns the LED off

This instruction now turns off the LED that we previously turned on. Why do we use HIGH and LOW? Well, it's an old convention in digital electronics. HIGH means that the pin is on, and in the case of Arduino, it will be set at 5 V. LOW means 0 V. You can also replace these arguments mentally with ON and OFF.

delay(1000); // wait for a second

Here, we delay for another second. The LED will be off for one second.

This closing curly bracket marks end of the loop function.

To sum up, this program does this:

- Turns pin 13 into an output (just once at the beginning)
- Enters a loop
- Switches on the LED connected to pin 13
- Waits for a second
- Switches off the LED connected to pin 13
- Waits for a second
- Goes back to beginning of the loop

CODE:STEP BY STEP

Before we move on to the next section, I want you to play with the code. For example, reduce the amount of delay, using different numbers for the on and off pulses so that you can see different blinking patterns.

In particular, you should see what happens when you make the delays very small, but use different delays for on and off ... there is a moment when something strange happens; this "something" will be very useful when you learn about pulse-width modulation on Thursday.

RANDOM DELAY

```
//Random Delay
//
int LED = 13; // LED connected to// digital pin 13
int i; // Variable to hold our random value
void setup()
 pinMode(LED, OUTPUT); // sets the digital pin as
output
void loop()
 i = random(I, 1000); // generate a random value every
loop cycle
 digitalWrite(LED, HIGH); // turns the LED on
 delay(i);
                  // pause for the duration of variable i
 digitalWrite(LED, LOW); // turns the LED off
 delay(i); // waits for a second the duration of
variable i
```

ITERATIVE DELAY

```
/// Blink with for loop
//
int LED = 13; // LED connected to digital pin 13
       // Variable to hold our random value
void setup()
 pinMode(LED, OUTPUT); // sets the digital
// pin as output
void loop()
 // set I to I; while i is less that I00 increment i by one
 for(int i = 1; i \le 100; i++){
 digitalWrite(LED, HIGH); // turns the LED on
 delay(i); // set delay based on the value of i
 digitalWrite(LED, LOW); // turns the LED off
 delay(i); // set delay based on the value of i
```

I MADE AN LED BLINK?

- -Most actuators are switched on and off with a digital output
- -The digitalWrite() command is the software portion of being able to control just about anything
- -LEDs are easy, motors come in a bit
- -Arduino has up to 13 digital outputs, and you easily can add more with helper chips

I MADE AN LED BLINK?

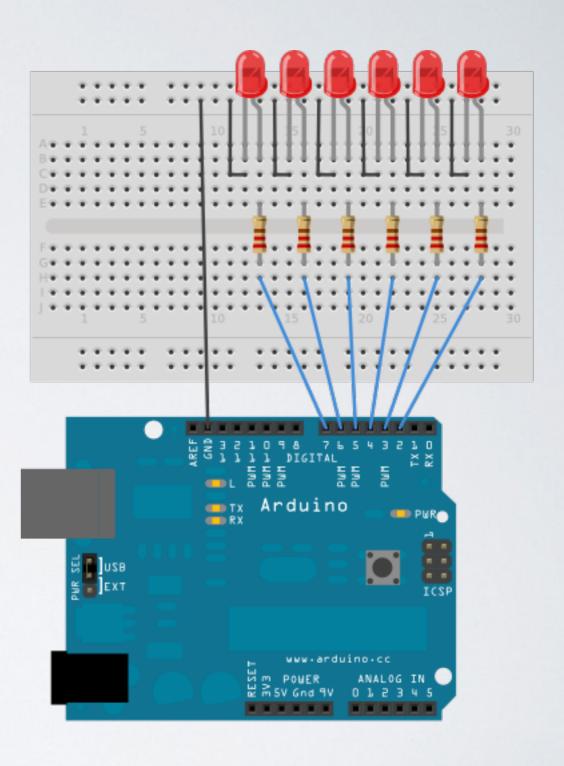
Cool Example!

http://vimeo.com/8196236

KNIGHT RIDER





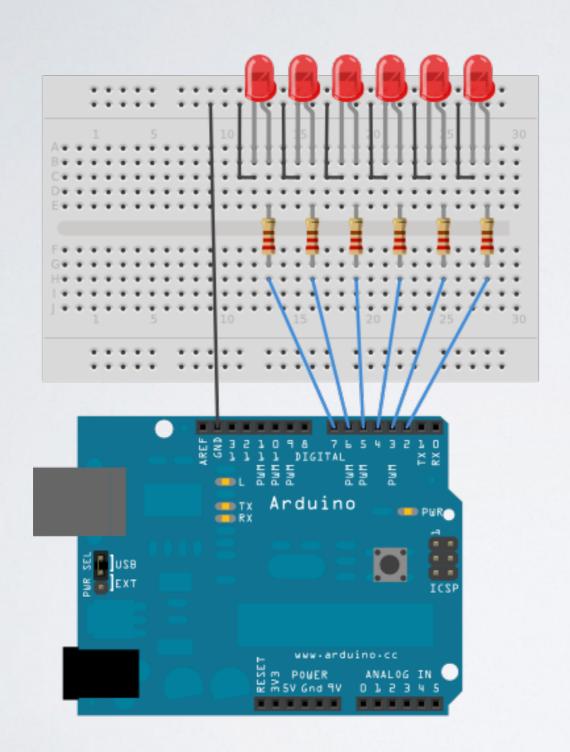


KNIGHT RIDER

Parts for this project

- Solderless Breadboard
- 13 x Flexible Wire Jumpers
- 6 x LEDs (any color)
- 6 x 220 Ohm Resistors
- Arduino Duo board
- USB Cable

KNIGHT RIDER



Steps

-Connect the cathode of each LED to Ground

-Put a resistor in series with the Anode of each LED

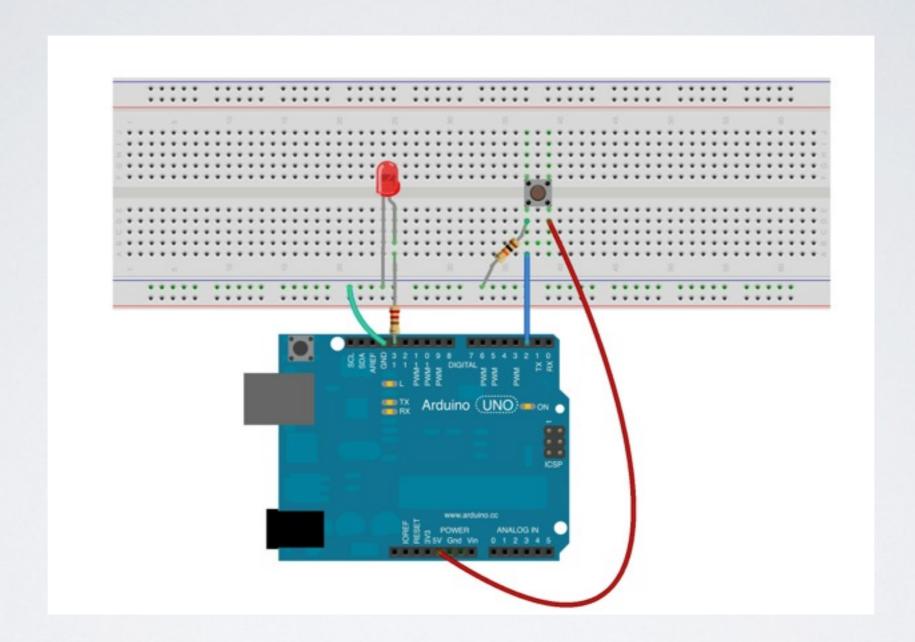
-Connect the each resistor to pins 2-7

KNIGHT RIDER I

```
/* Knight Rider I
int pin2 = 2;
int pin3 = 3;
int pin4 = 4;
int pin5 = 5;
int pin6 = 6;
int pin7 = 7;
int timer = 100;
void setup(){
pinMode(pin2, OUTPUT);
 pinMode(pin3, OUTPUT);
 pinMode(pin4, OUTPUT);
 pinMode(pin5, OUTPUT);
 pinMode(pin6, OUTPUT);
pinMode(pin7, OUTPUT);
void loop() {
  digitalWrite(pin2, HIGH);
 delay(timer);
 digitalWrite(pin2, LOW);
 delay(timer);
 digitalWrite(pin3, HIGH);
 delay(timer);
  digitalWrite(pin3, LOW);
  delay(timer);
 digitalWrite(pin4, HIGH);
 delay(timer);
 digitalWrite(pin4, LOW);
 delay(timer);
 digitalWrite(pin5, HIGH);
 delay(timer);
 digitalWrite(pin5, LOW);
  delay(timer);
 digitalWrite(pin6, HIGH);
 delay(timer);
 digitalWrite(pin6, LOW);
 delay(timer);
 digitalWrite(pin7, HIGH);
 delay(timer);
  digitalWrite(pin7, LOW);
  delay(timer);
 digitalWrite(pin6, HIGH);
 delay(timer);
  digitalWrite(pin6, LOW);
 delay(timer);
 digitalWrite(pin5, HIGH);
 delay(timer);
  digitalWrite(pin5, LOW);
  delay(timer);
  digitalWrite(pin4, HIGH);
  delay(timer);
  digitalWrite(pin4, LOW);
  delay(timer);
```

KNIGHT RIDER WITH A FOR LOOP

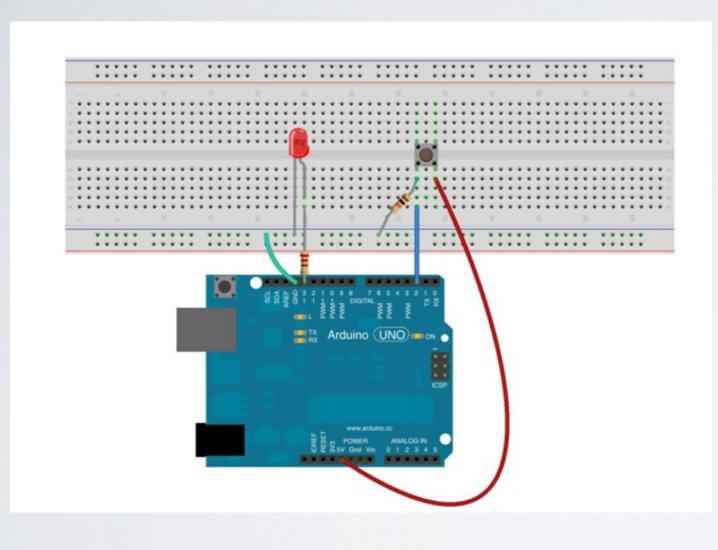
```
/* Knight Rider 2
int pinArray[] = {2, 3, 4, 5, 6, 7};
int count = 0;
int timer = 100;
void setup(){
 // we make all the declarations at once
 for (count=0;count<6;count++) {</pre>
  pinMode(pinArray[count], OUTPUT);
void loop() {
 for (count=0;count<6;count++) {</pre>
  digitalWrite(pinArray[count], HIGH);
  delay(timer);
  digitalWrite(pinArray[count], LOW);
  delay(timer);
 for (count=5;count>=0;count--) {
  digitalWrite(pinArray[count], HIGH);
  delay(timer);
  digitalWrite(pinArray[count], LOW);
  delay(timer);
```



Parts for this project

- Solderless Breadboard
- 3 x Flexible Wire Jumpers
- I x LEDs (any color)
- 2 x 220 Ohm Resistors (bands are red,red,violet, gold)
- Arduino Duo board
- USB Cable





- Connect one side of the button to 5V
- On the other side of the button put a resistor to ground. In the same row connect a wire to pin 2
- Connect the cathode of the LED to ground.
- Connect the Anode of the LED to pin 13 in series with a resistor

```
// constants won't change. They're used here to
// set pin numbers:
const int buttonPin = 2; // the number of the pushbutton pin
const int ledPin = 13; // the number of the LED pin
// variables will change:
int buttonState = 0;
                         // variable for reading the pushbutton status
void setup() {
 // initialize the LED pin as an output:
 pinMode(ledPin, OUTPUT);
 // initialize the pushbutton pin as an input:
 pinMode(buttonPin, INPUT);
void loop(){
 // read the state of the pushbutton value:
 buttonState = digitalRead(buttonPin);
 // check if the pushbutton is pressed.
 // if it is, the buttonState is HIGH:
 if (buttonState == HIGH) {
  // turn LED on:
  digitalWrite(ledPin, HIGH);
 else {
  // turn LED off:
  digitalWrite(ledPin, LOW);
```