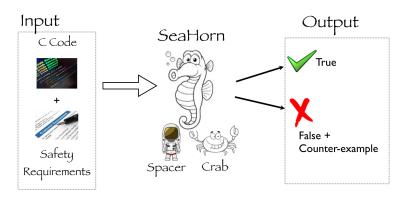
A Context-Sensitive Memory Model for Verification of C/C++ Programs

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Our Motivation



Automatic modular safety proofs on realistic C and C++ programs

Classical Memory Models for C/C++

 Byte-level model: a large array of bytes and every allocation returns a new offset in that array

$$\mathsf{Ptr} = \mathsf{Int} \qquad \mathit{Mem} : \mathsf{Ptr} \to \mathsf{Byte}$$

Untyped Block-level model: a pointer is a pair \(\lambda ref, o \rangle\) where ref
uniquely defines a memory object and o defines the byte in the
object being point to

$$\mathsf{Ptr} = \mathsf{Ref} \times \mathsf{Int}$$
 $Mem : \mathsf{Ptr} \to \mathsf{Ptr}$

 Typed Block-level model: refines the block-level model by having a separate block for each distinct type:

$$\mathsf{Ptr} = \mathsf{Ref} \times \mathsf{Int}$$
 $\mathit{Mem} : \mathsf{Type} \times \mathsf{Ptr} \to \mathsf{Ptr}$

Classical Memory Models for C/C++

 Byte-level model: a large array of bytes and every allocation returns a new offset in that array

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• Untyped Block-level model: a pointer is a pair $\langle ref, o \rangle$ where ref uniquely defines a memory object and o defines the byte in the object being point to

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 Typed Block-level model: refines the block-level model by having a separate block for each distinct type:

$$\mathsf{Ptr} = \mathsf{Ref} \times \mathsf{Int}$$
 $\mathit{Mem} : \mathsf{Type} \times \mathsf{Ptr} \to \mathsf{Ptr}$

From Pointer Analysis to Verification Conditions

- Run a pointer analysis to disambiguate memory
- Produce a side-effect-free encoding by:
 - ullet Replacing each memory object o to a logical array A_o
 - Replacing memory accesses to a pointer p (within object o) to array reads and writes over A_o
 - Each array write on A_o produces a new version of A_o' representing the array after the execution of the memory write
- Logical arrays are unbounded and the "whole array" is updated in its entirety:
 - $A[1] = 5 \rightarrow A_1 = \lambda i : i = 1 ? 5 : A_0$
 - $A[k] = 7 \rightarrow A_2 = \lambda i : i = k ? 7 : A_1$



```
f(p,q) x,y,p,q f(x,y)
```

```
f(r,s)

f(x,y)

x,y,p,q,r,s
```

Verification conditions:

```
 \begin{split} f(x,y,A_{xy},A''_{xy}) \{ \\ A'_{xy} &= \mathtt{store}(A_{xy},x,1) \\ A''_{xy} &= \mathtt{store}(A'_{xy},y,2) \\ \} \\ g(p,q,r,s,A_{pqrs},A''_{pqrs}) \{ \\ f(p,q,A_{pqrs},A'_{pqrs}) \\ f(r,s,A'_{pqrs},A''_{pqrs}) \\ \} \end{split}
```

```
f(r,s) r s

f(x",y") x" y"

f<sub>sum</sub>(x,y) x y
```

Verification conditions:

```
\begin{split} &f(x,y,A_{x},A_{y},A'_{x},A'_{y})\{\\ &A'_{x} = \mathtt{store}(A_{x},x,1)\\ &A'_{y} = \mathtt{store}(A_{y},y,2)\\ \} \\ &g(p,q,r,s,A_{pq},A_{r},A_{s},A'_{pq},A'_{r},A'_{s})\{\\ &f(p,q,A_{pq},A_{pq},A'_{pq},A'_{pq})\\ &f(r,s,A_{r},A_{s},A'_{r},A'_{s})\\ \} \end{split}
```

```
void f(int* x,int* y) {
  *x = 1;
void q(int* p,int* q,
       int* r,int* s) {
  f(p,q);
  f(r,s);
```

Verification conditions:

```
f(x, y, A_x, A_y, A'_x, A'_y){
    A'_{\times} = \text{store}(A_{\times}, x, 1)
    A'_{v} = store(A_{v}, y, 2)
g(p, q, r, s, A_{pq}, A_r, A_s, A'_{pq}, A'_r, A'_s)
    f(p,q,A_{pq},A_{pq},A'_{pq},A'_{pq},A'_{pq})
    f(r,s,A_r,A_s,A'_r,A'_s)
```

A direct VC encoding is unsound:

First call to $f: A'_{pq} = \text{store}(A_{pq}, p, 1)$ and $A'_{pq} = \text{store}(A_{pq}, q, 2)$

The update of p is lost!

Ensuring Sound VCs using a CS Pointer Analysis

- Arbitrary CS pointer analysis cannot be directly leveraged for modular verification
- They must satisfy this Correctness Condition (CC): "No two disjoint memory objects modified in a function can be aliased at any particular call site "
- Observed by Reynolds'78, Moy's PhD thesis'09, and many others
- Proposed solutions:
 - ignore context-sensitivity: SMACK and Cascade
 - generate contracts that ensure CC holds, otherwise reject programs: Frama-C + Jessie plugin

```
f(r,s) r s

f(x",y") x",y"

f<sub>sum</sub>(x,y) x,y
```

```
f(r,s) r,s

f(x",y") x",y"

f<sub>sum</sub>(x,y) x,y
```

Sound verification conditions:

```
\begin{array}{l} f(x,y,A_{xy},A_{xy}'') \{ \\ A_{xy}' = \mathtt{store}(A_{xy},x,1) \\ A_{xy}'' = \mathtt{store}(A_{xy}',y,2) \\ \} \\ g(p,q,r,s,A_{pq},A_{rs},A_{pq}',A_{rs}') \{ \\ f(p,q,A_{pq},A_{rs}',A_{rs}') \\ f(r,s,A_{rs},A_{rs}') \\ \} \end{array}
```

```
void f(int* x,int* y) {
  *x = 1;
  *y = 2;
void q(int* p,int* q,
       int* r,int* s) {
  f(p,q);
  f(r,s);
```

Sound verification conditions:

```
f(x, y, A_{xy}, A_{xy}^{"})
     A'_{xy} = \mathtt{store}(A_{xy}, x, 1)
    A_{xv}^{"} = \mathtt{store}(A_{xv}^{"}, y, 2)
g(p,q,r,s,A_{pq},A_{rs},A_{na}^{\prime},A_{rs}^{\prime})\{
     f(p, q, A_{pq}, A'_{pq})
     f(r, s, A_{rs}, A'_{rc})
```

Good compromise:

context-sensitive: calls to f do not merge $\{p,q\}$ and $\{r,s\}$ ensure that CC holds!

Field- and Array-Sensitive Pointer Analysis

```
typedef struct list{
  struct list *n;
  int e;
} 11;
11* mkList(int s,int e){
 if (s <= 0)
   return NULL;
 11*p=malloc(sizeof(11));
 p->e=e;
 p\rightarrow n=mkList(s-1,e);
 return p;
void main(){
 11* a[N];
 int i;
 for (i=0; i<N; ++i)
   a[i] = mkList(M, 0);
```

Our pointer analysis infers:

- ① &a[0] points to an object O_A which has > 1 elements of size of a pointer
- $Q O_A$ points to another object O₁ with 0 and 4 offsets

Similar pointer analyses do not distinguish O_A from O_I

Our contributions

We present a new pointer analysis for verification of C/C++ that:

- 1 is context-, field-, and array-sensitive
- a has been implemented and publicly available https://github.com/seahorn/sea-dsa
- has been evaluated on flight control components written in C++ and SV-COMP benchmarks in C

Concrete Semantics

- A concrete cell is a pair of an object reference and offset
- A concrete points-to graph $g \in \mathcal{G}_{\mathbb{C}}$ is a triple $\langle V, E, \sigma \rangle$:

$$V \subseteq \mathcal{C}_{\mathbb{C}} \quad E \subseteq \mathcal{C}_{\mathbb{C}} \times \mathcal{C}_{\mathbb{C}} \quad \sigma : \mathcal{V}_{\mathcal{P}} \mapsto \mathcal{C}_{\mathbb{C}}$$

• A concrete state is a triple $\langle g, \pi, pc \rangle$ where

$$g \in \mathcal{G}_{\mathbb{C}}$$
 $\pi: \mathcal{V}_{\mathcal{I}} \mapsto \mathbb{Z}$ $pc \in \mathbb{L}$

malloc returns a fresh memory object

Concrete Semantics: Assumptions

• Freed memory is not reused:

```
int *p = (int*) malloc(..);
int *q = p;
free(p);
int *r = (int*) malloc(...)
```

it assumes that r cannot alias with q

It does not distinguish between valid and invalid pointers:

```
int *p = (int*) malloc(..);
free(p);
int *q = (int*) malloc(..);
if (p == q) *p=0;
```

it assumes no null dereference

Abstract Semantics

- An abstract cell is a pair of an abstract object and byte offset
- An abstract object has an identifier and:
 - is_sequence: unknown sequence of consecutive bytes
 - is_collapsed: all outgoing cells have been merged
 - 3 size in bytes (see paper for details)
- An abstract points-to graph $\mathcal{G}_{\mathbb{A}}$ is a triple $\langle V, E, \sigma \rangle$:

$$V \subseteq \mathcal{C}_{\mathbb{A}} \quad E \subseteq \mathcal{C}_{\mathbb{A}} \times \mathcal{C}_{\mathbb{A}} \quad \sigma : \mathcal{V}_{\mathcal{P}} \mapsto \mathcal{C}_{\mathbb{A}}$$

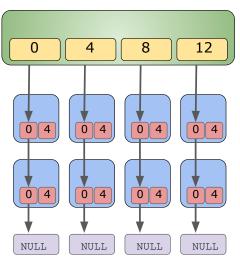
The number of abstract objects is finite

- An abstract state is represented by an abstract points-to graph
 - it does not keep track of an environment for integer variables
 - it is flow-insensitive

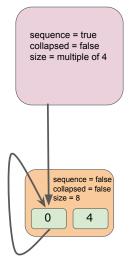


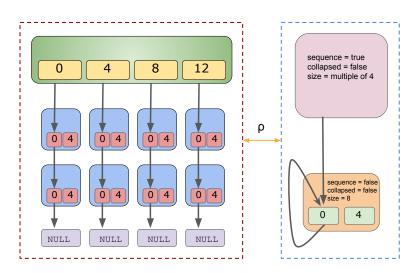
Concrete vs Abstract points-to Graphs

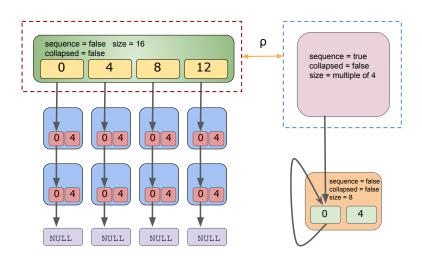
Concrete points-to graph

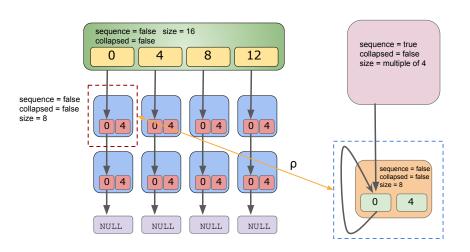


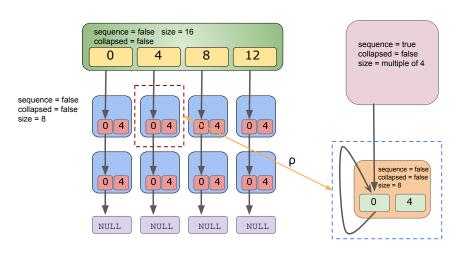
Abstract points-to graph

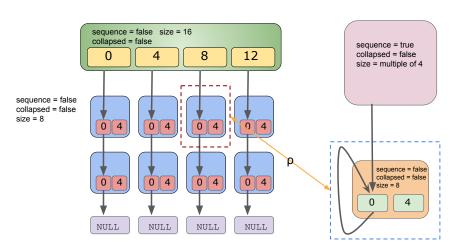


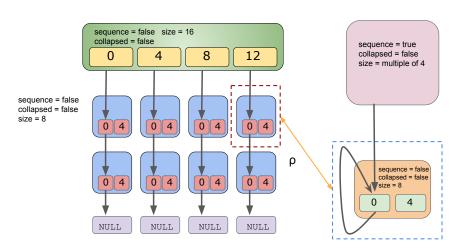


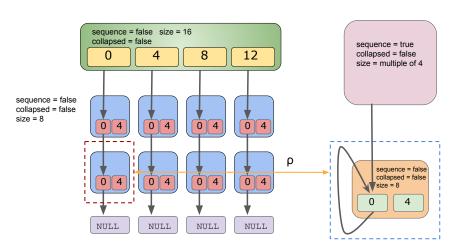


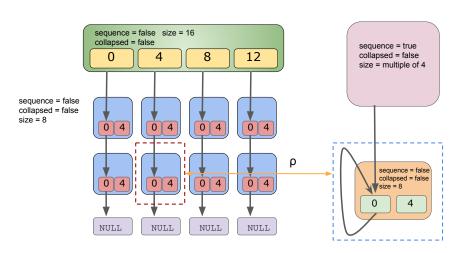


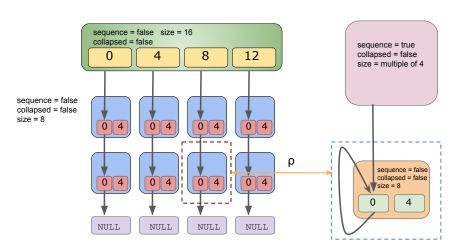


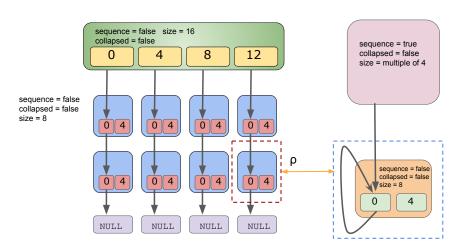


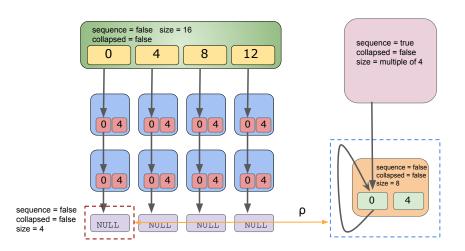


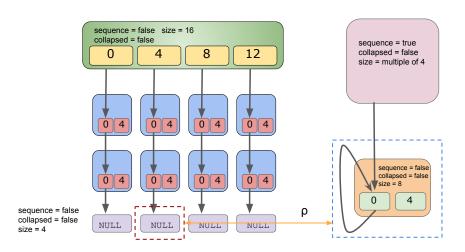


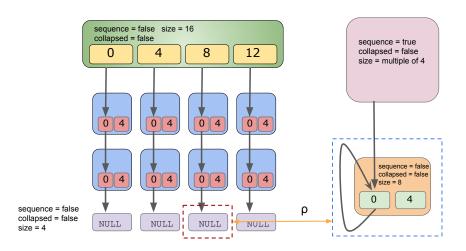


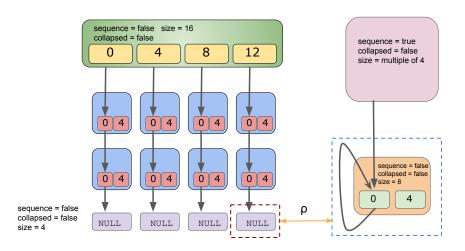












 \bullet $\gamma: \mathcal{G}_{\mathbb{A}} \mapsto 2^{\mathcal{G}_{\mathbb{C}}}$ defined as

$$\gamma(g_a) = \{g_c \in \mathcal{G}_\mathbb{C} \mid g_c \text{ simulated by } g_a\}$$

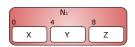
- It defines also an ordering between abstract graphs $g,g'\in\mathcal{G}_{\mathbb{A}}$ $g\sqsubseteq_{\mathcal{G}_{\mathbb{A}}} g' \text{ if and only if } g \text{ is simulated by } g'$
- It will play an essential role during the context-sensitive analysis (later in this talk)

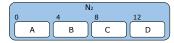
Intra-Procedural Pointer Analysis

- Based on field-sensitive Steensgaard's
- Key operation: cell unification
- Ensure $c_1 = (n_1, o_1)$ and $c_2 = (n_2, o_2)$ are the same address
- If $o_1 < o_2$ then (other case symmetric) map $(n_1, 0)$ to $(n_2, o_2 - o_1)$ $(n_1, o_1) = (n_2, o_2 - o_1 + o_1) = (n_2, o_2)$ unify each (n_1, o_k) with $(n_2, o_2 - o_1 + o_k)$

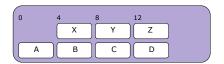
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unifv(Y,C) = unifv((N₁,4),(N₂,8))



Array-Sensitivity

```
typedef struct list{
  struct list *n;
  int e;
} 11;
11* mkList(int s,int e){
 if (s <= 0)
   return NULL;
 11*p=malloc(sizeof(11));
p->e=e;
 p->n=mkList(s-1,e);
 return p;
#define N 4
void main(){
 11* a[N];
 int i;
 for (i=0; i<N; ++i)</pre>
   a[i] = mkList(M, 0);
```

```
sequence = false collapsed = false size = 16

0 4 8 12
```

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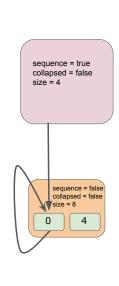
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 int i;
 for (i=0; i<N; ++i)</pre>
   a[i] = mkList(M, 0);
```

```
sequence = false collapsed = false size = 16
                       sequence = false
                       collapsed = false
                       size = 8
```

Array-Sensitivity

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typedef struct list{
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 for (i=0; i<N; ++i)</pre>
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```



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```
void g(...) {
  f(p1,p2,p3);
void h(...) {
  f(r1,r2,r3);
void f(int*q1,int*q2,int*q3) {
  . . .
```

```
p1,p2
            p3
            q3
q1
      q2
```

```
void g(...) {
  f(p1,p2,p3);
void h(...) {
  f(r1,r2,r3);
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```

```
p1,p2
             p3
q1,q2
             q3
                   top-down
```

```
void g(...) {
  f(p1,p2,p3);
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  . . .
```

```
p1,p2
             p3
r1,r2
                    bottom-up
q1,q2
              q3
                    top-down
```

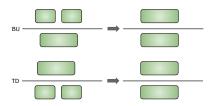
```
void q(...) {
                                             p1,p2
                                                        p3
  f(p1,p2,p3);
void h(...) {
                                             r1,r2
                                                             bottom-up
  f(r1,r2,r3);
void f(int*q1,int*q2,int*q3) {
                                             q1,q2
                                                        q3
                                                             top-down
  . . .
```

 Next, h's callsites and callsites where h is called must be re-analyzed, and so on

```
void q(...) {
                                             p1,p2
                                                        p3
  f(p1,p2,p3);
void h(...) {
                                             r1,r2
                                                             bottom-up
  f(r1,r2,r3);
void f(int*q1,int*q2,int*q3) {
                                             q1,q2
                                                        q3
                                                             top-down
  . . .
```

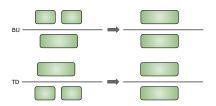
- Next. h's callsites and callsites where h is called must be re-analyzed, and so on
- In general, after an unification we need to re-analyze:
 - if top-down: callsites with same callee and callsites within the callee
 - if bottom-up: callsites with same caller and callsites within the caller
- However, no need to re-analyze the whole function!
- Fixpoint over all callsites until no more bottom-up or top-down unifications

Bottom-Up and Top-Down Unifications



Q: How to decide whether BU, TD or no more unifications?

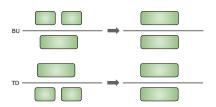
Bottom-Up and Top-Down Unifications



Q: How to decide whether BU, TD or no more unifications?

A: Simulation relation!

Bottom-Up and Top-Down Unifications



Q: How to decide whether BU, TD or no more unifications?

A: Simulation relation!

Build a simulation relation ρ between callee and caller graphs:

- if ρ is not a function then BU
- \circ else if ρ is a function but not injective then TD
- \odot else ρ is an injective function then do nothing



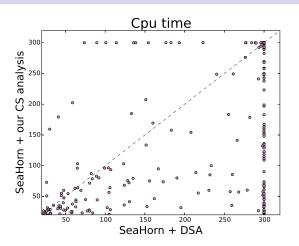
Context-Sensitive Pointer Analysis: All Pieces Together

- for each function in reverse topological order of the call graph compute summary
- for each callsite clone callee's summary into the caller graph and unify formal/actual cells
- apply BU and TD unifications until CC holds for all callsites

Experiments

- Integrated the pointer analysis in SeaHorn
- The pointer analysis is used during VC generation
- Compared SeaHorn verification time using:
 - (CI) DSA Pointer analysis from LLVM PoolAlloc project
 - Our pointer analysis

Experiments on SV-COMP C Programs



- 2000 benchmarks from SV-COMP DeviceDrivers64 category
- Verification time with timeout of 5m and 4GB memory limit
- With our analysis SeaHorn proved 81 more programs

(Ongoing) C++ Case Study

Goal:

Verify absence of buffer overflows on the flight control system of the Core Autonomous Safety Software (CASS) of an Autonomous Flight Safety System

- 13,640 LOC (excluding blanks/comments) written in C++ using standard C++ 2011 and following MISRA C++ 2008
- It follows an object-oriented style and makes heavy use of dynamic arrays and singly-linked lists

	#Objects	#Collapsed	Max. Density	% Proven
Sea + DSA	258	49%	80%	13
Sea + our CS	12,789	4%	13%	21

Conclusions

- Modular proofs require context-sensitive heap reasoning
- We adopted a very high-level memory model that can still express low-level C/C++ features such as:
 - pointer arithmetic, pointer casts and type unions
- We presented a scalable field-,array-,context-sensitive pointer analysis tailored for VC generation
 - A simulation relation between points-to graphs plays a major role in the analysis of function calls
- It can produce a finer-grained partition of memory that often results in faster verification times

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