

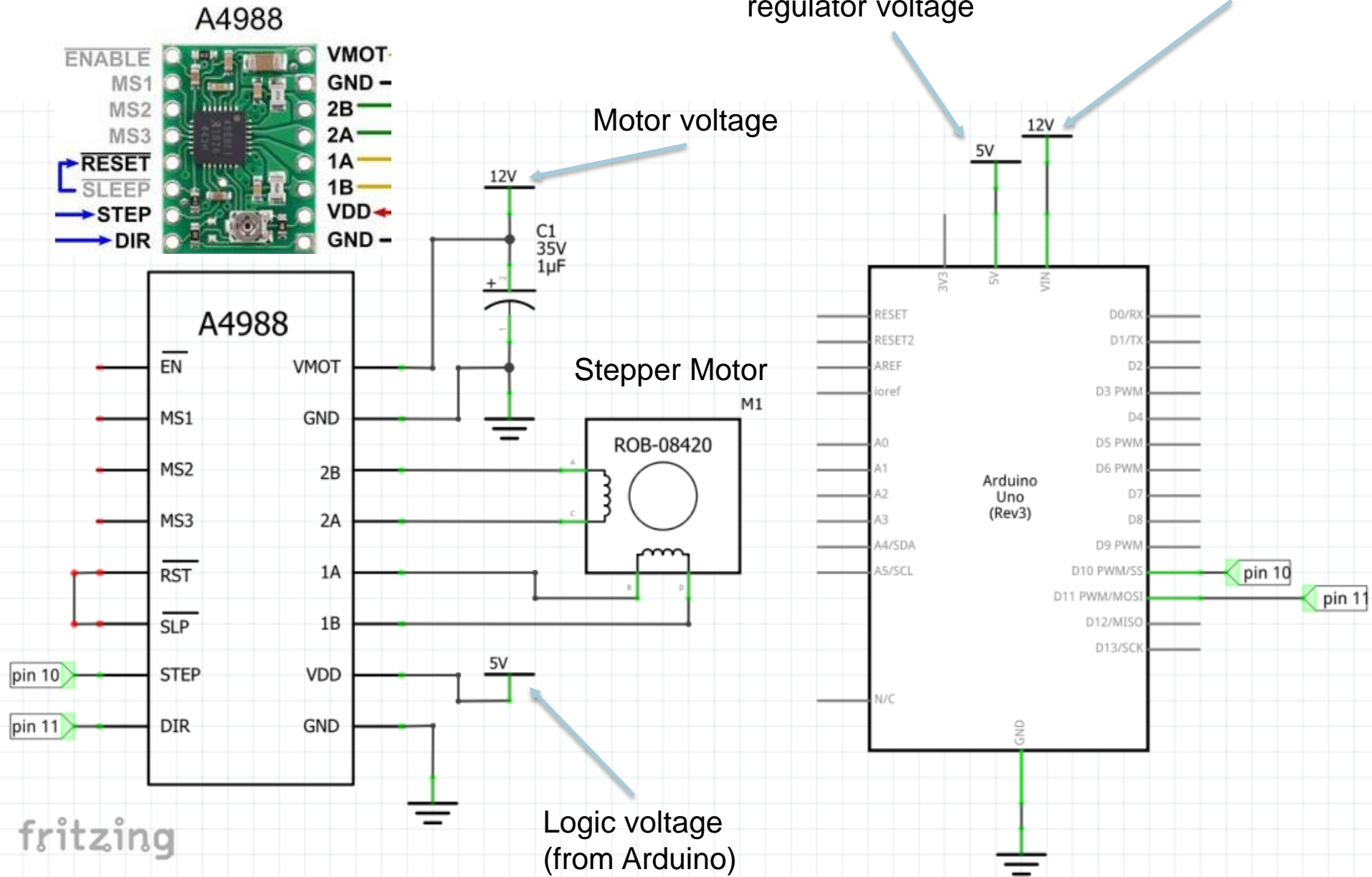
# Pololu stepper drivers

Arduino generates  
5V with a voltage  
regulator voltage

Motor voltage to Vin  
to power Arduino

Motor voltage

Logic voltage  
(from Arduino)



fritzing

# Stepper driver – Take care

Put a large (at least 47  $\mu\text{F}$ ) electrolytic capacitor across motor power (VMOT) and ground somewhere close to the board.

Electrolytic capacitors can explode if they are connected wrong: longer leg = positive; check “-” marking

Connecting or disconnecting a stepper motor while the driver is powered can destroy the driver.

Set the current of the motor – adjust the potentiometer on the Pololu stepper driver

<https://www.youtube.com/watch?v=89BHS9hfSUK>

## Exercise #2 - Moving stepper motors

Try to move the motor using switches or an arduino

**dir**

**0V -> forward**

**5V -> backward**

**step**

**1 pulse = 1 step**

**1 pulse = 0V->5V->0V**

Advanced:

Try to use a library (provides speed profiles)

[https://www.pjrc.com/teensy/td\\_libs\\_AccelStepper.html](https://www.pjrc.com/teensy/td_libs_AccelStepper.html)

<https://github.com/laurb9/StepperDriver>