

The Bures-Wasserstein Distance for Machine Learning

Boris Muzellec

*Based joint work with **Marco Cuturi***



Outline

- 1. A (quick) intro to OT**
- 2. The Bures-Wasserstein distance**
- 3. Optimization with Bures distances**
- 4. Applications**

I. An intro to OT

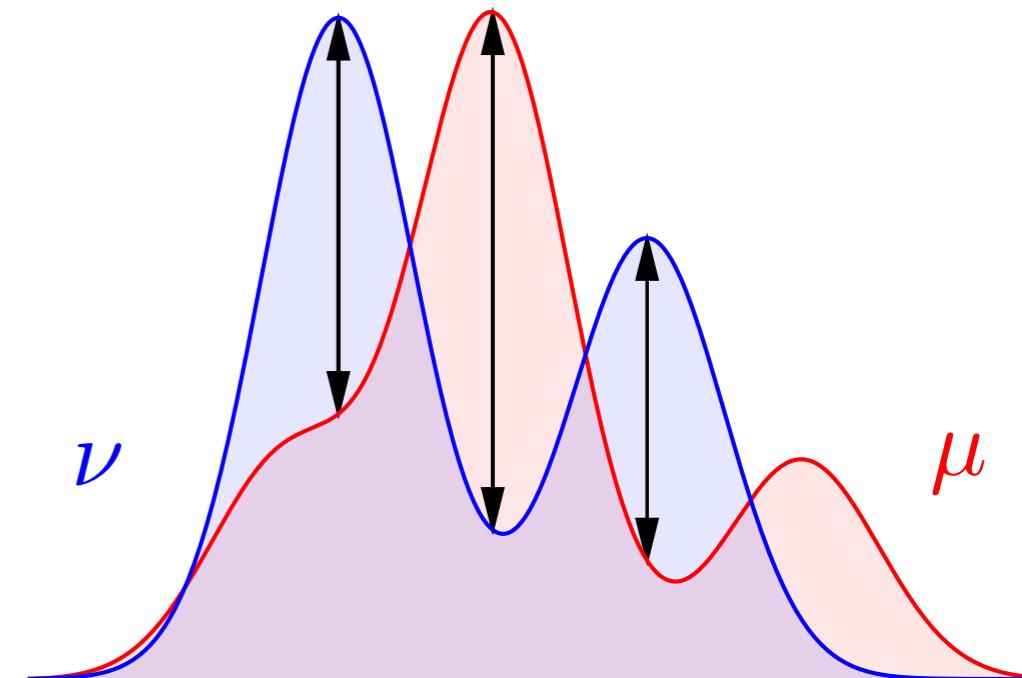
How to compare distributions?

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1. “Vertically”:

- Look at differences between densities:

$$|p(x) - q(x)| \quad \text{or} \quad \frac{p(x)}{q(x)}$$

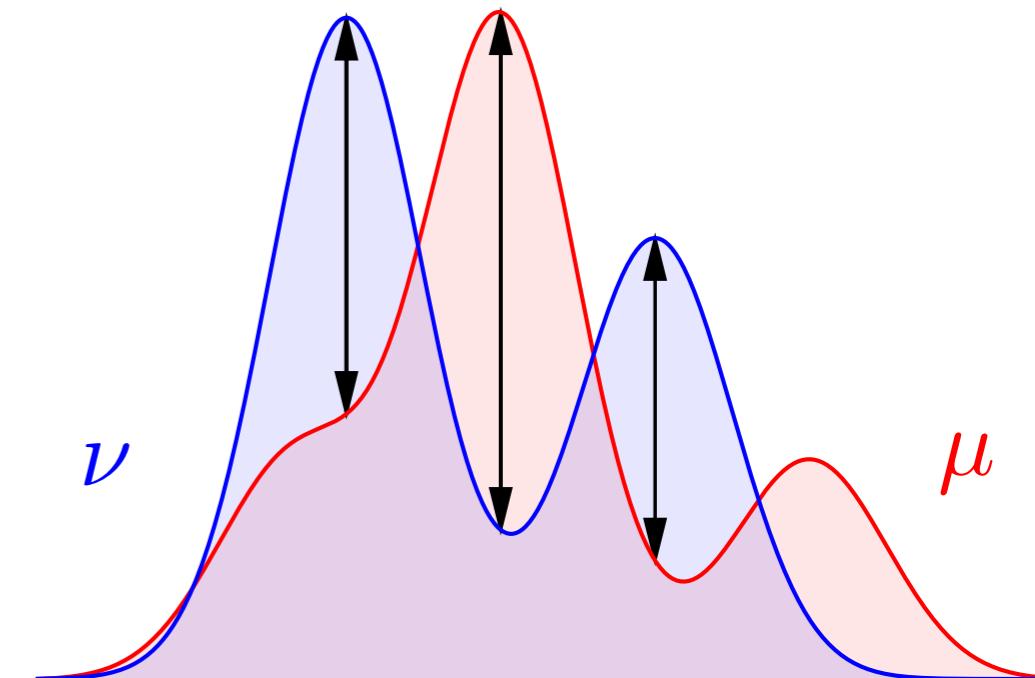


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- Make something useful out of them:

$$\text{TV}(\mu, \nu) = \sup_{A \in \mathcal{B}} \left| \int \mathbb{1}_A(x) p(x) dx - \int \mathbb{1}_A(x) q(x) dx \right| \quad \text{(Total variation)}$$

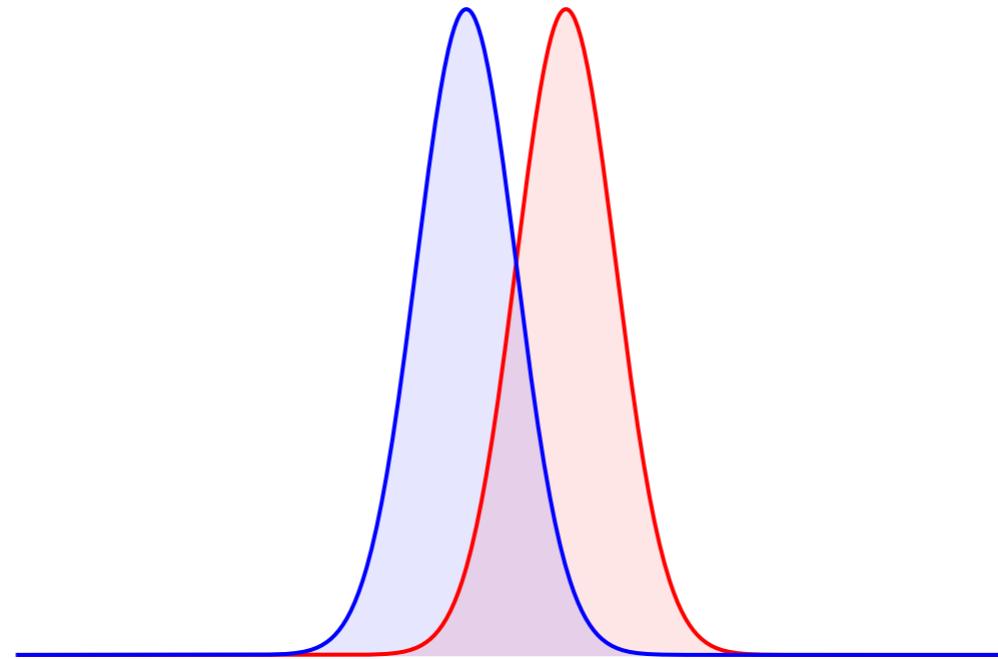
$$D_{\text{KL}}(\mu, \nu) = \int \log \frac{p(x)}{q(x)} p(x) dx \quad \text{(Kullback-Leibler)}$$

$$D_f(\mu, \nu) = \int f \left(\frac{p(x)}{q(x)} \right) q(x) dx \quad \text{(f-divergences)}$$

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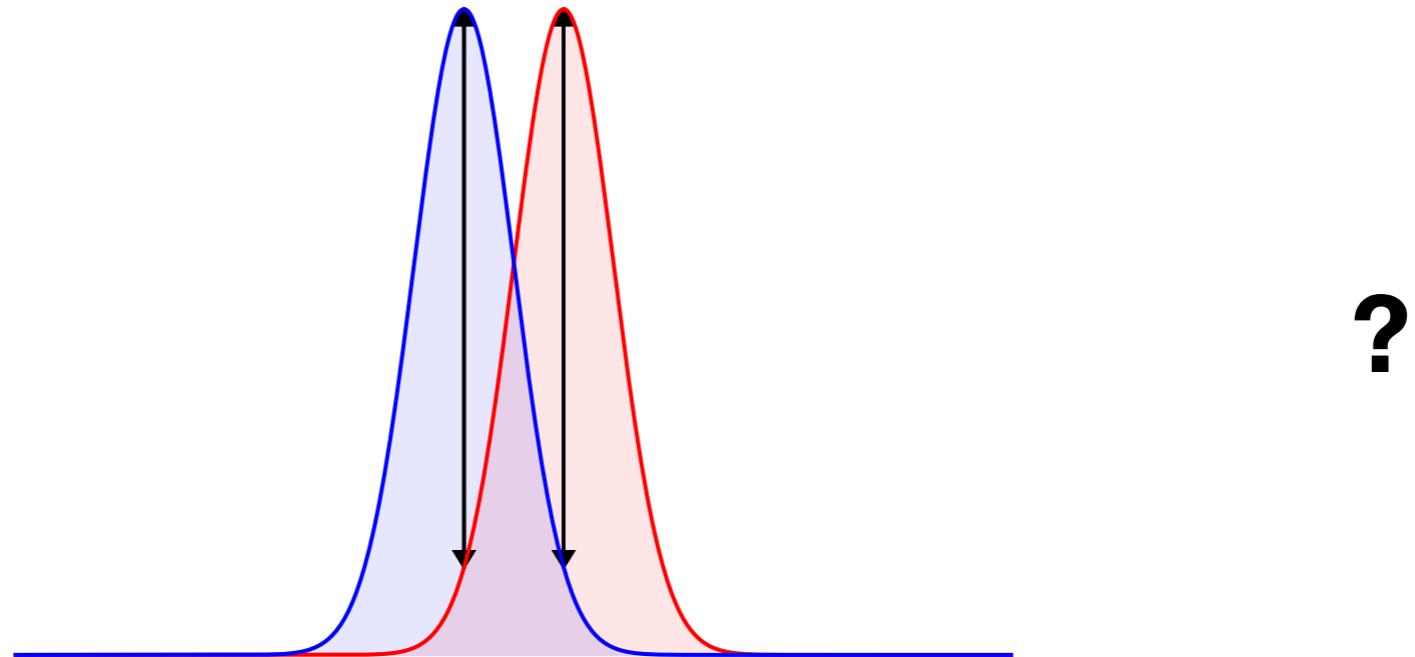
What about

?



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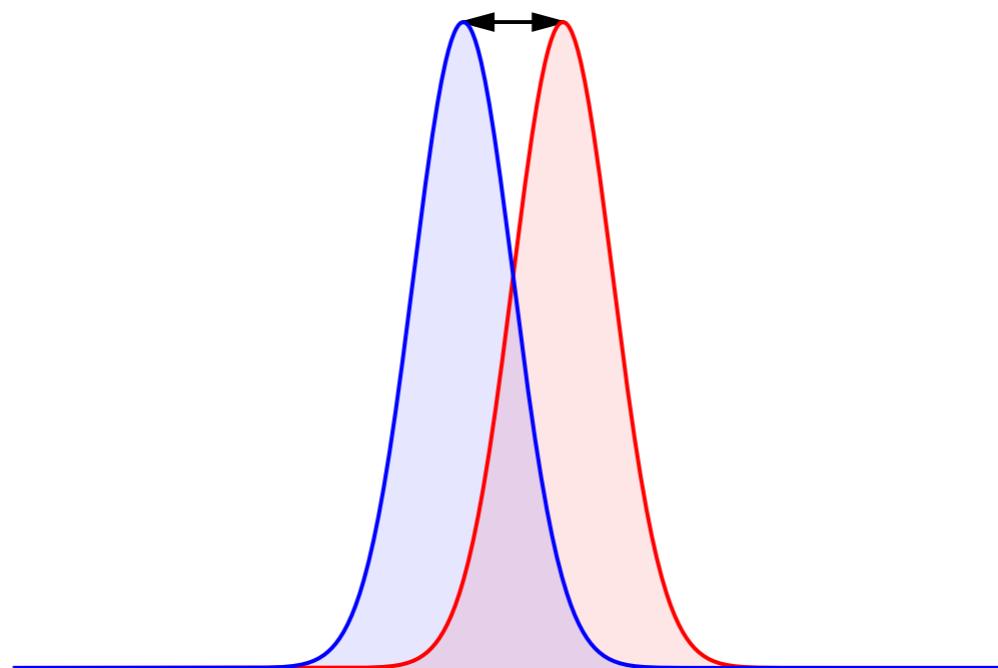


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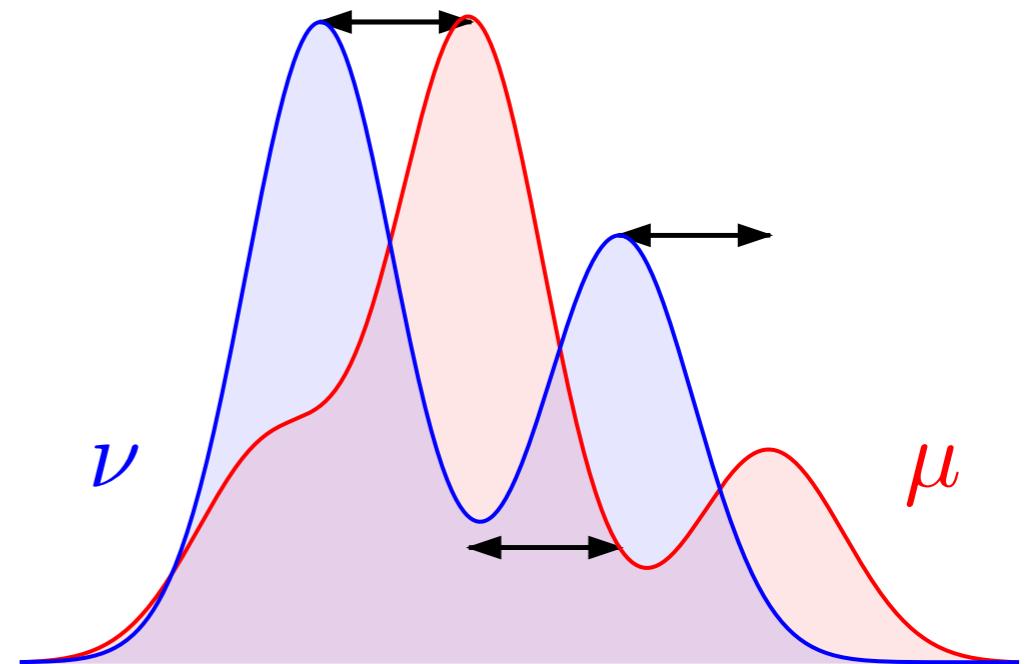


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- Look at distances on the supports:

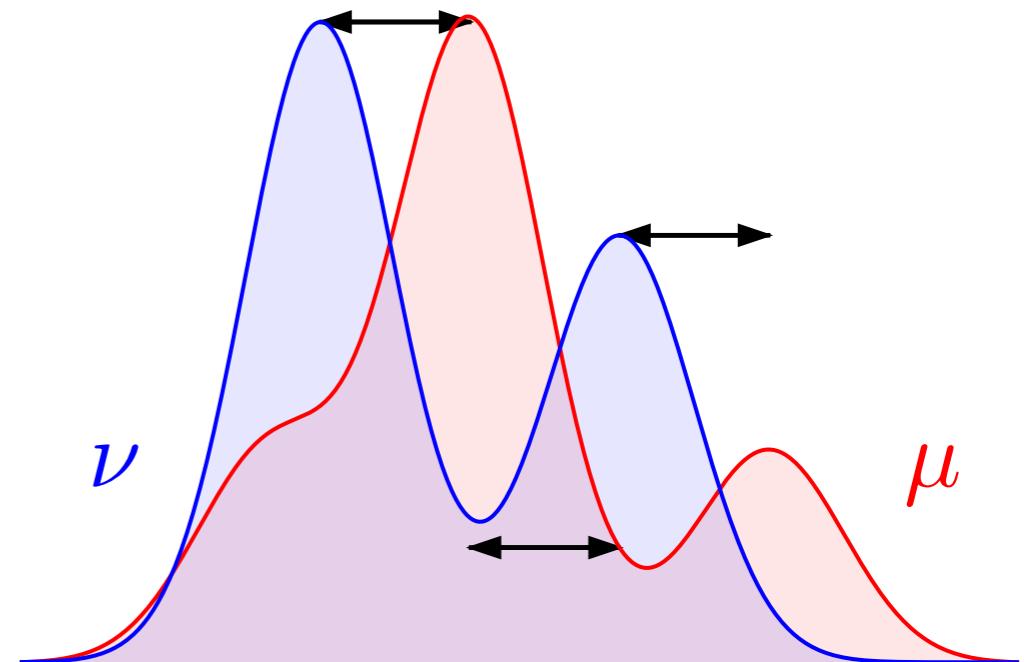


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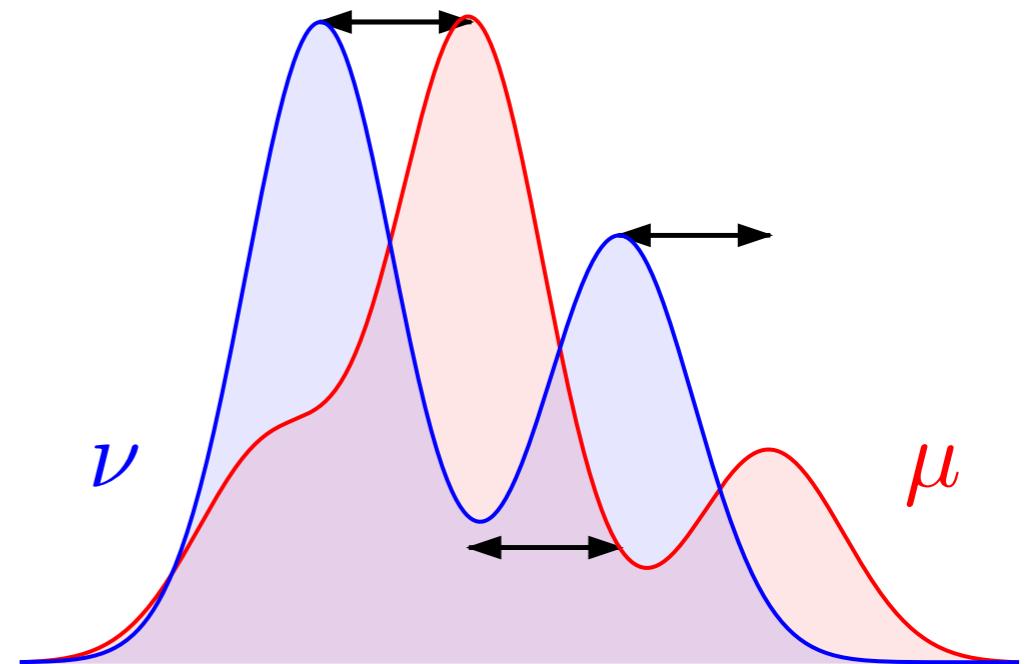
$$\int \int \|x - y\|^2 d\mu(x) d\nu(y) ?$$



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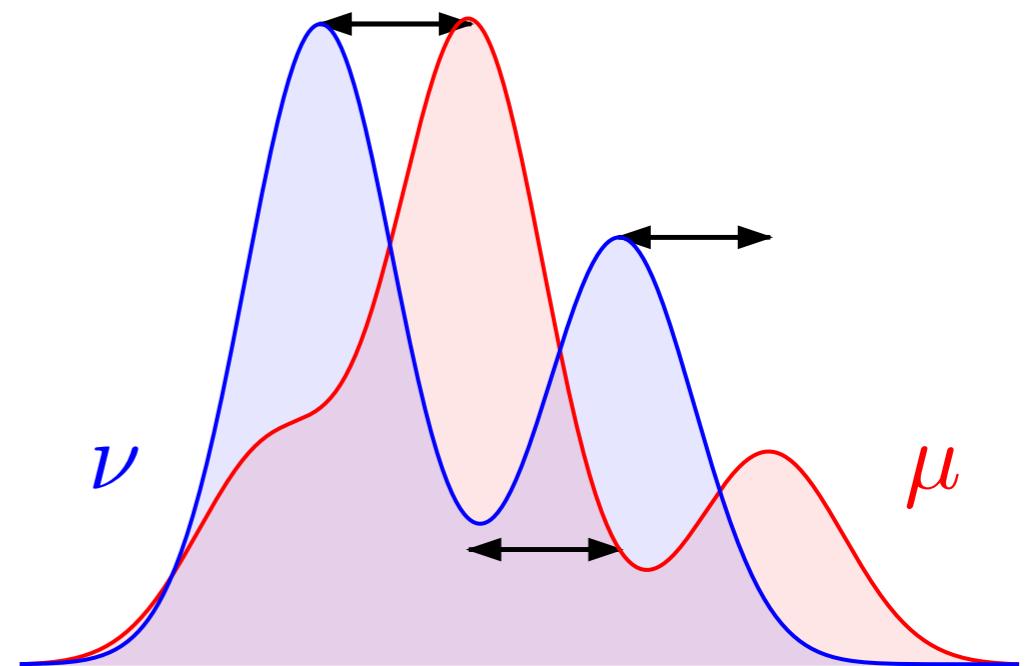


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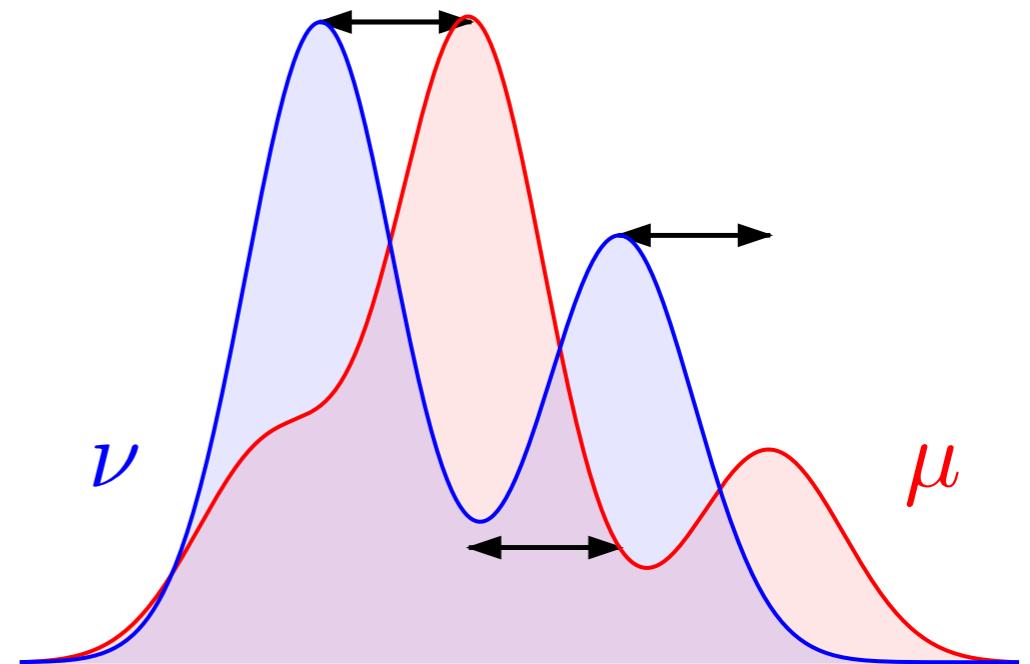
$$\inf_T \int \|x - T(x)\|^2 d\mu(x)$$



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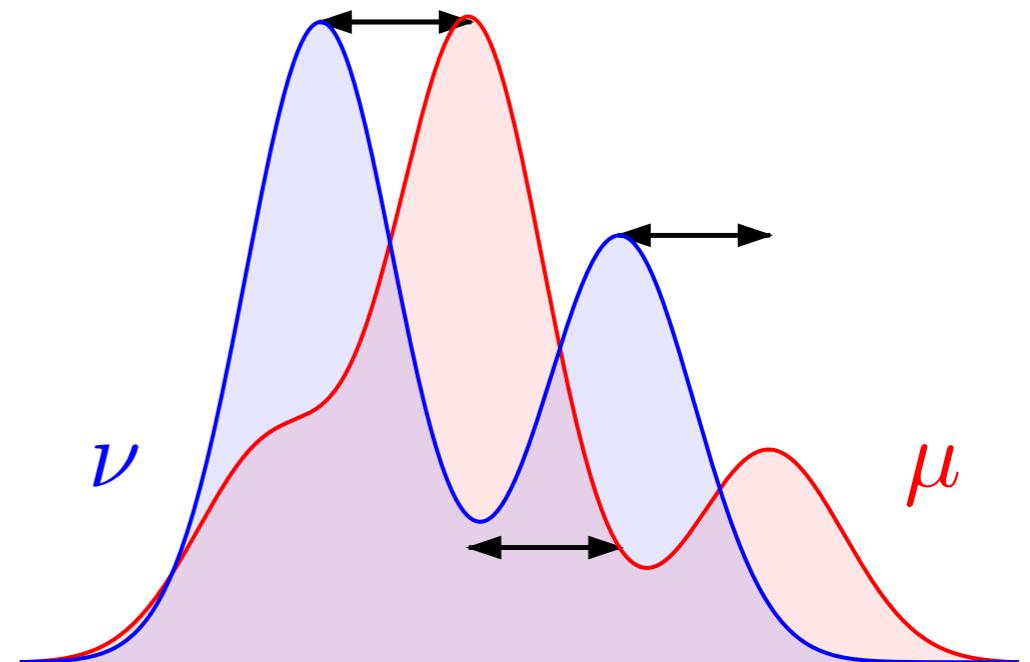


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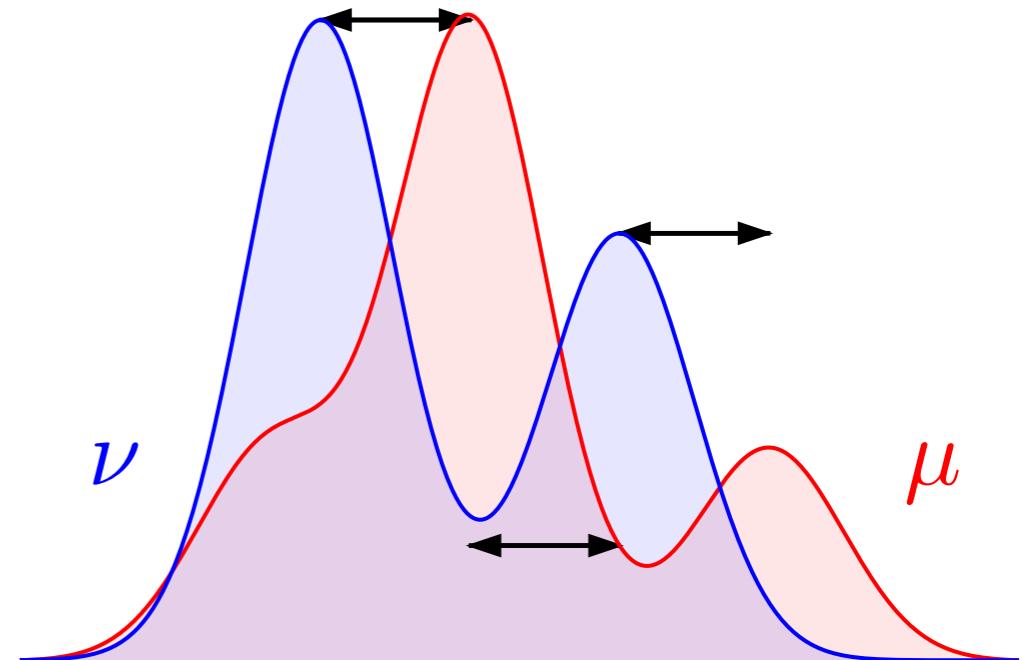
$$T_{\sharp} \mu = \nu \quad \text{iff} \quad X \sim \mu \implies T(X) \sim \nu$$

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“ T pushes forward μ to ν ”

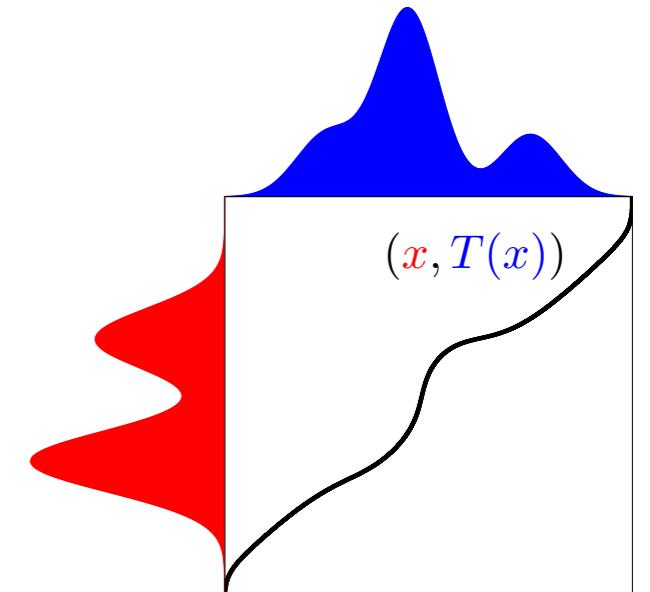
“ T is a Monge map from μ to ν ”

(2-)Wasserstein Distances

- Monge version

Prop. When a Monge map T exists,

$$W_2^2(\mu, \nu) = \inf_{T \# \mu = \nu} \int_{\Omega} \|x - T(x)\|^2 \mu(dx)$$

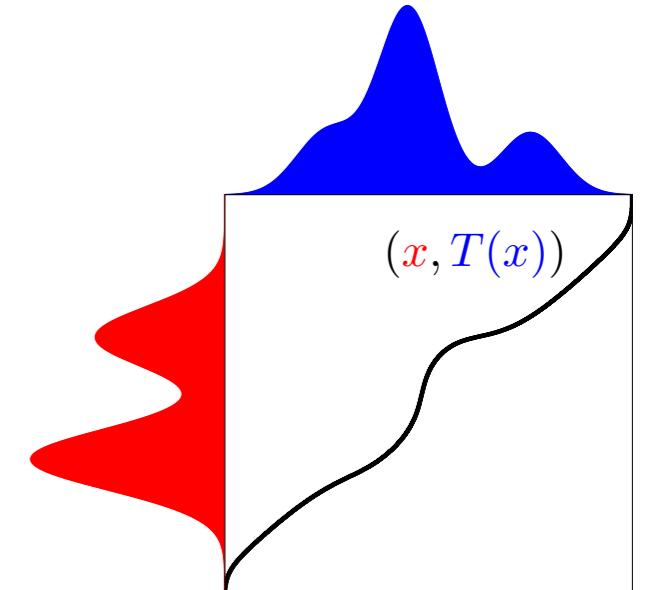


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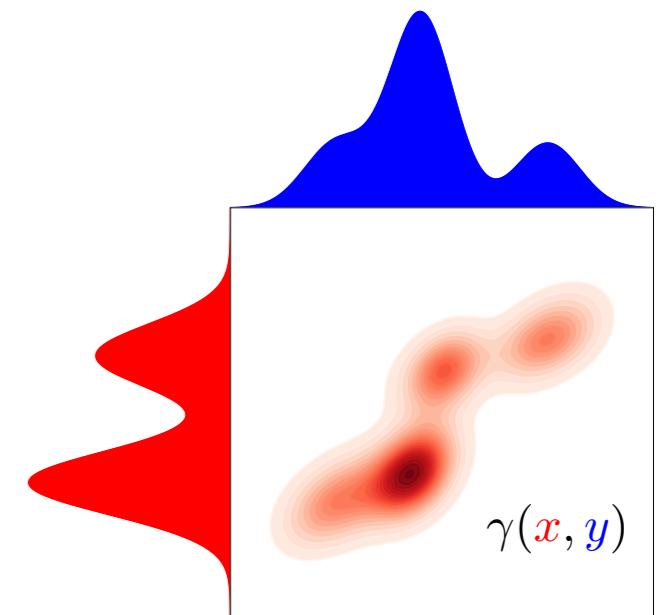
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- Kantorovich version

Def. The 2-Wasserstein distance between $\mu, \nu \in P(\Omega)$ is

$$W_2^2(\mu, \nu) \stackrel{\text{def}}{=} \inf_{\gamma \in \Pi(\mu, \nu)} \int_{\Omega} \|x - y\|^2 d\gamma(x, y)$$



$$\begin{aligned} \Pi(\mu, \nu) &\stackrel{\text{def}}{=} \{P \in \mathcal{P}(\Omega \times \Omega) \mid \forall A, B \subset \Omega, \\ &P(A \times \Omega) = \mu(A), P(\Omega \times B) = \nu(B)\} \end{aligned}$$

“Couplings”

“Kantorovich / transportation plans”

Monge maps: existence

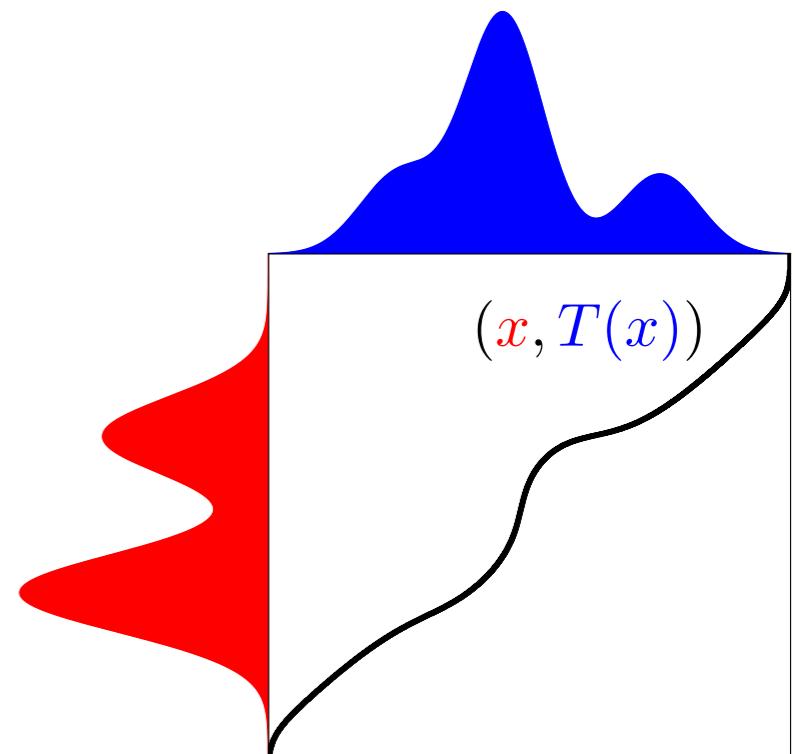
Prop. For “well behaved” costs c , if μ has a density then an *optimal* Monge map T^* between μ and ν must exist.

Monge maps: existence

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- Link between Monge maps and Kantorovitch plans:

$$\gamma^* = (\text{Id}, T^*) \sharp \mu$$



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- Discrete/Discrete:
 - LP with $O(n^3 \log n)$ complexity using network simplex
 - Better with (entropic) regularization [Cuturi'13, Genevay et al.'16, Altschuler et al.'17...]

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- Continuous/Continuous: ?
 - Closed form: elliptical distributions (next slides)

II. The Wasserstein-Bures Distance

Elliptical Distributions

« Def. » Probability measures with densities

$$f(\mathbf{x}) = \frac{1}{\sqrt{|\mathbf{C}|}} h((\mathbf{x} - \mathbf{m})^\top \mathbf{C}^{-1} (\mathbf{x} - \mathbf{m}))$$

where $\int_{\mathbb{R}^d} h(\|\mathbf{x}\|^2) d\mathbf{x} = 1, \quad \mathbf{C} \in S_n^+$

Examples:

- Multivariate normal distributions
- Elliptical uniform distributions
- (Multivariate) t-Student...

OT for Elliptical Distributions

[Gelbrich'90]

Prop. If $\alpha, \beta \in P(\mathbb{R}^d)$ are elliptical distributions (from the same family), then

$$W_2^2(\alpha, \beta) = \|\mathbf{m}_\alpha - \mathbf{m}_\beta\|_2^2 + \mathfrak{B}^2(\text{cov}\alpha, \text{cov}\beta)$$

$\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) \stackrel{\text{def}}{=} \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}}$ is the (squared) **Bures** distance

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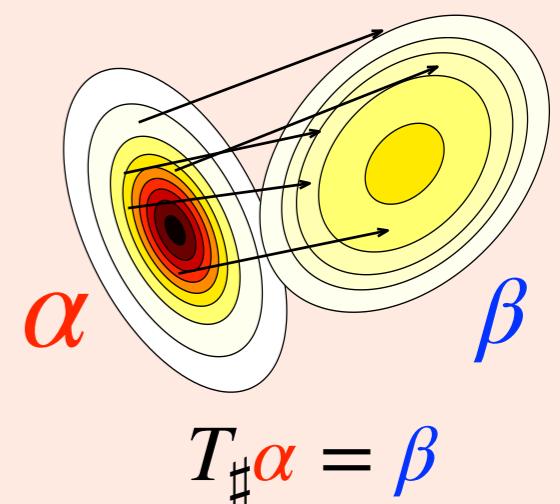
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Prop. If $\alpha, \beta \in P(\mathbb{R}^d)$ are elliptical distributions with $\text{cov}\alpha = \mathbf{A}$, $\text{cov}\beta = \mathbf{B}$, then

$T(\mathbf{x}) = \mathbf{m}_\beta + \mathbf{T}^{\mathbf{AB}}(\mathbf{x} - \mathbf{m}_\alpha)$ is the optimal Monge map

where $\mathbf{T}^{\mathbf{AB}} \stackrel{\text{def}}{=} \mathbf{A}^{-\frac{1}{2}}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}}\mathbf{A}^{-\frac{1}{2}}$ is s.t. $\mathbf{T}^{\mathbf{AB}}\mathbf{A}\mathbf{T}^{\mathbf{AB}} = \mathbf{B}$



A lower bound

- **What if α, β are not elliptical?**

A lower bound

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Prop. Wasserstein-Bures is a lower bound of Wasserstein.

$$W_2^2(\alpha, \beta) \geq \|\mathbf{m}_\alpha - \mathbf{m}_\beta\|_2^2 + \mathfrak{B}^2(\text{cov}\alpha, \text{cov}\beta)$$

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A Lemma

$$\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) \stackrel{\text{def}}{=} \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}}$$

Lemma. [Bhatia et al.'17]

$$\begin{aligned} F(\mathbf{A}, \mathbf{B}) &\stackrel{\text{def}}{=} \text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \\ &= \max\{\text{tr}\mathbf{X} : \begin{pmatrix} \mathbf{A} & \mathbf{X} \\ \mathbf{X}^T & \mathbf{B} \end{pmatrix} \geq 0\} \end{aligned}$$

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Proof.
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$$\begin{aligned} W_2^2(\mu, \nu) &\stackrel{\text{def}}{=} \min_{\gamma \in \Pi(\mu, \nu)} \mathbb{E}_{(X, Y) \sim \gamma} [\|X - Y\|^2] \\ &= \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2 \max_{\gamma \in \Pi(\mu, \nu)} \text{Tr}[Cov_\gamma(X, Y)] \end{aligned}$$

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But $\gamma \in \Pi(\mu, \nu) \implies \text{cov}(\gamma) = \begin{pmatrix} \mathbf{A} & Cov_\gamma(X, Y) \\ Cov_\gamma(X, Y)^T & \mathbf{B} \end{pmatrix} \geq 0$

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Hence $\forall \gamma \in \Pi(\mu, \nu), \quad \text{Tr}[Cov_\gamma(X, Y)] \leq F(\mathbf{A}, \mathbf{B}) \quad \blacksquare$

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- **Q: Is there an equality case?**
- **Q: (Matching) upper bound?**

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- Q: Is there an equality case?
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- Q: (Matching) upper bound?
 - A: ... (independent coupling)

$$W_2^2(\mu, \nu) \leq \|\mathbf{m}_\mu - \mathbf{m}_\nu\|_2^2 + \text{Tr} \mathbf{A} + \text{Tr} \mathbf{B}$$

Equality Case

Lemma. [Bhatia et al.'17]

$$\arg \max \{ \text{tr} \mathbf{X} : \begin{pmatrix} \mathbf{A} & \mathbf{X} \\ \mathbf{x}^T & \mathbf{B} \end{pmatrix} \geq 0 \} = (\mathbf{AB})^{\frac{1}{2}} = \mathbf{A} \mathbf{T}^{\mathbf{AB}}$$

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- e.g. μ, ν are from the same *elliptical family*.

Elliptical Distributions

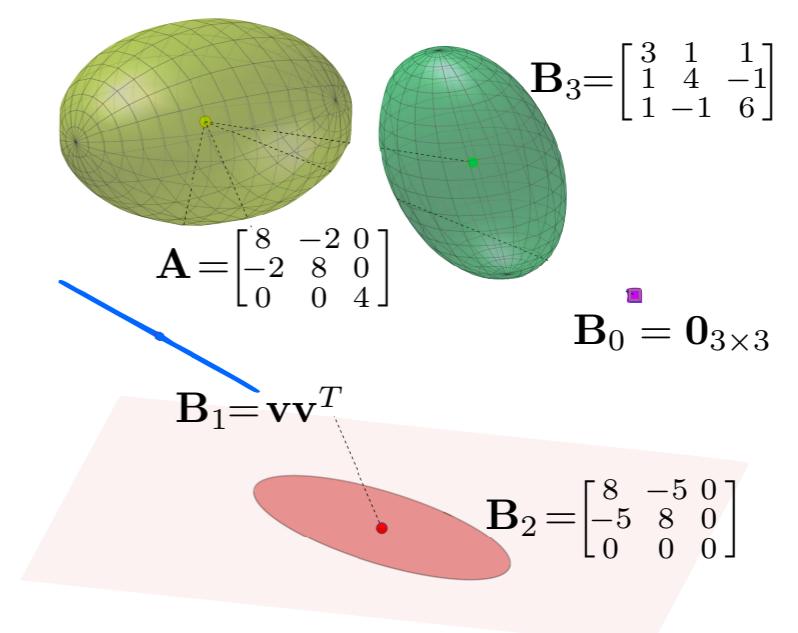
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where $\int_{\mathbb{R}^d} h(\|\mathbf{x}\|^2) d\mathbf{x} = 1, \quad \mathbf{C} \in S_n^+$

Examples:

- Multivariate normal distributions
- Elliptical uniform distributions
- (Multivariate) t-Student...



III. Working with the Bures distance

Issues

$$\begin{aligned}\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) &\stackrel{\text{def}}{=} \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \\ &= \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{AB})^{\frac{1}{2}}\end{aligned}$$

- 1. How to compute matrix roots (in a scalable way)?**
- 2. How to compute gradients?**
- 3. Can I avoid projections on the PSD cone?**

How (not) to compute roots?

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- **Option 1: SVD**
 - $O(n^3)$ complexity
 - Batched version?

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- Option 2: Iterations? e.g.

- Babylonian algorithm $\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \mathbf{X}_k^{-1}\mathbf{A}), \quad \mathbf{X}_0 = \mathbf{A}$

$$\lim_{k \rightarrow \infty} \mathbf{X}_k = \mathbf{A}^{\frac{1}{2}} \quad (\text{if } \max_{ij} \frac{1}{2}|1 - \lambda_i^{1/2}\lambda_j^{-1/2}| < 1)$$

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- Denman-Beavers $\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \mathbf{Y}_k^{-1}), \quad \mathbf{X}_0 = \mathbf{A}$

$$\mathbf{Y}_{k+1} = \frac{1}{2}(\mathbf{Y}_k + \mathbf{X}_k^{-1}), \quad \mathbf{Y}_0 = \mathbf{I}$$

$$\lim_{k \rightarrow \infty} \mathbf{X}_k = \mathbf{A}^{\frac{1}{2}}, \quad \lim_{k \rightarrow \infty} \mathbf{Y}_k = \mathbf{A}^{-\frac{1}{2}}$$

From DB to Newton-Schulz

- Denman-Beavers

$$\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \mathbf{Y}_k^{-1}), \quad \mathbf{X}_0 = \mathbf{A}$$

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From DB to Newton-Schulz

- **Denman-Beavers**
$$\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \mathbf{Y}_k^{-1}), \quad \mathbf{X}_0 = \mathbf{A}$$
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- **Inverse is costly. However, we expect $\mathbf{Y}_k^{-1} \simeq \mathbf{X}_k$**

From DB to Newton-Schulz

- **Denman-Beavers** $\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \mathbf{Y}_k^{-1}), \quad \mathbf{X}_0 = \mathbf{A}$
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- **Inverse is costly. However, we expect $\mathbf{Y}_k^{-1} \simeq \mathbf{X}_k$**
 - **Approximate \mathbf{Y}_k^{-1} using one Newton iteration for the inverse:**

$$\mathbf{Y}_k^{-1} \simeq 2\mathbf{X}_k - \mathbf{X}_k \mathbf{Y}_k \mathbf{X}_k$$

$$(f(x) = 1/x - y, \quad x_{n+1} = x_n - f(x)/f'(x) = x_n - \frac{1/x_n - y}{-1/x_n^2} = 2x_n - x_n^2 y)$$

From DB to Newton-Schulz

- Denman-Beavers $\mathbf{X}_{k+1} = \frac{1}{2}(\mathbf{X}_k + \boxed{\mathbf{Y}_k^{-1}}), \quad \mathbf{X}_0 = \mathbf{A}$

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From DB to Newton-Schulz

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- Do the same thing with $\mathbf{X}_k^{-1} \simeq \mathbf{Y}_k$: Newton-Schulz algorithm (next slide).

How to compute roots

- **Newton-Schulz square root iterations:**

$$\mathbf{X}_{k+1} = \frac{1}{2}\mathbf{X}_k(3\mathbf{I} - \mathbf{Y}_k\mathbf{X}_k), \quad \mathbf{X}_0 = \mathbf{A}$$

$$\mathbf{Y}_{k+1} = \frac{1}{2}(3\mathbf{I} - \mathbf{Y}_k\mathbf{X}_k)\mathbf{Y}_k, \quad \mathbf{Y}_0 = \mathbf{I}$$

How to compute roots

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$$\mathbf{X}_{k+1} = \frac{1}{2}\mathbf{X}_k(3\mathbf{I} - \mathbf{Y}_k\mathbf{X}_k), \quad \mathbf{X}_0 = \mathbf{A}$$

$$\mathbf{Y}_{k+1} = \frac{1}{2}(3\mathbf{I} - \mathbf{Y}_k\mathbf{X}_k)\mathbf{Y}_k, \quad \mathbf{Y}_0 = \mathbf{I}$$

Prop. [Higham'08]

If $\|\mathbf{I} - \mathbf{A}\| < 1$, $\lim_{k \rightarrow \infty} \mathbf{X}_k = \mathbf{A}^{\frac{1}{2}}, \quad \lim_{k \rightarrow \infty} \mathbf{Y}_k = \mathbf{A}^{-\frac{1}{2}}$

with *quadratic convergence*.

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$$\mathbf{Y}_{k+1} = \frac{1}{2}(3\mathbf{I} - \mathbf{Y}_k\mathbf{X}_k)\mathbf{Y}_k, \quad \mathbf{Y}_0 = \mathbf{I}$$

Prop. [Higham'08]

If $\|\mathbf{I} - \mathbf{A}\| < 1$, $\lim_{k \rightarrow \infty} \mathbf{X}_k = \mathbf{A}^{\frac{1}{2}}, \quad \lim_{k \rightarrow \infty} \mathbf{Y}_k = \mathbf{A}^{-\frac{1}{2}}$

with *quadratic convergence*.

- **GPU friendly (batch matrix-matrix multiplications)**
- *Gives simultaneously the square root and its inverse*

Issues

$$\begin{aligned}\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) &\stackrel{\text{def}}{=} \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \\ &= \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{AB})^{\frac{1}{2}}\end{aligned}$$

- 1. How to compute matrix roots (in a scalable way)?**
- 2. How to compute gradients?**
- 3. Can I avoid projections on the PSD cone?**

How to compute the Bures Gradient?

How to compute the Bures Gradient?

Option 1: Automatic differentiation

- Has the same cost as computing $\mathfrak{B}^2(\textcolor{red}{A}, \textcolor{blue}{B})$
- Gives the exact gradient of the *approximated* distance

How to compute the Bures Gradient?

How to compute the Bures Gradient?

$$\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}, \quad \mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} \left(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}} \right)^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$$

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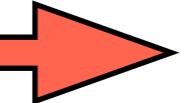
In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

How to compute the Bures Gradient?

$$\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}, \quad \mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} \left(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}} \right)^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$$

In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

Option 2: Closed form & a nice hack

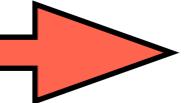
- $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}$  we need $\mathbf{T}^{\mathbf{AB}}$ and $\mathbf{T}^{\mathbf{BA}}$

How to compute the Bures Gradient?

$$\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}, \quad \mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$$

In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

Option 2: Closed form & a nice hack

- $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}$  we need $\mathbf{T}^{\mathbf{AB}}$ and $\mathbf{T}^{\mathbf{BA}}$

The naive way: $\mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$, $\mathbf{T}^{\mathbf{BA}} = \mathbf{B}^{-\frac{1}{2}} (\mathbf{B}^{\frac{1}{2}} \mathbf{A} \mathbf{B}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{B}^{-\frac{1}{2}}$

We need: $\{\mathbf{A}^{\frac{1}{2}}, \mathbf{A}^{-\frac{1}{2}}\}$, $\{\mathbf{B}^{\frac{1}{2}}, \mathbf{B}^{-\frac{1}{2}}\}$, $\{(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}}\}$, $\{(\mathbf{B}^{\frac{1}{2}} \mathbf{A} \mathbf{B}^{\frac{1}{2}})^{\frac{1}{2}}\}$

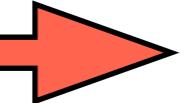
4 runs of Newton-Schulz

How to compute the Bures Gradient?

$$\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}, \quad \mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} \left(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}} \right)^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$$

In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

Option 2: Closed form & a nice hack

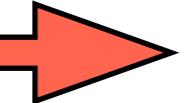
- $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}$  we need $\mathbf{T}^{\mathbf{AB}}$ and $\mathbf{T}^{\mathbf{BA}}$

How to compute the Bures Gradient?

$$\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}, \quad \mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$$

In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

Option 2: Closed form & a nice hack

- $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) = \mathbf{I} - \mathbf{T}^{\mathbf{AB}}$  we need $\mathbf{T}^{\mathbf{AB}}$ and $\mathbf{T}^{\mathbf{BA}}$

Prop.

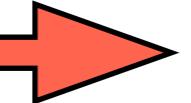
$$\begin{aligned}\mathbf{T}^{\mathbf{AB}} &= \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}} \\ &= \mathbf{B}^{\frac{1}{2}} (\mathbf{B}^{\frac{1}{2}} \mathbf{A} \mathbf{B}^{\frac{1}{2}})^{-\frac{1}{2}} \mathbf{B}^{\frac{1}{2}}\end{aligned}$$

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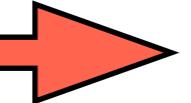
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The **better way**: $\mathbf{T}^{\mathbf{AB}} = \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$, $\mathbf{T}^{\mathbf{BA}} = \mathbf{A}^{\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{-\frac{1}{2}} \mathbf{A}^{\frac{1}{2}} = (\mathbf{T}^{\mathbf{AB}})^{-1}$

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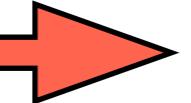
2 runs of Newton-Schulz

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0 if we computed $\mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ earlier

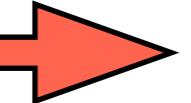
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- [BM&Cuturi'18]

In most applications, we need both $\nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ and $\nabla_{\mathbf{B}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$

Option 2: Closed form & a nice hack

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Issues

$$\begin{aligned}\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) &\stackrel{\text{def}}{=} \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{A}^{\frac{1}{2}}\mathbf{B}\mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \\ &= \text{Tr}\mathbf{A} + \text{Tr}\mathbf{B} - 2\text{Tr}(\mathbf{AB})^{\frac{1}{2}}\end{aligned}$$

- 1. How to compute matrix roots (in a scalable way)?**
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Can we avoid projections?

- $\mathbf{A} - t \nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ is not necessarily PSD.

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- Classic workaround: $\mathbf{A} = \Pi(\mathbf{L}_{\mathbf{A}}) \stackrel{\text{def}}{=} \mathbf{L}_{\mathbf{A}} \mathbf{L}_{\mathbf{A}}^T$. Effect on gradient methods?

$$\nabla_{\mathbf{L}_{\mathbf{A}}} \frac{1}{2} \mathfrak{B}^2(\mathbf{L}_{\mathbf{A}} \mathbf{L}_{\mathbf{A}}^T, \mathbf{B}) = (\mathbf{I} - \mathbf{T}^{\mathbf{A}\mathbf{B}}) \mathbf{L}_{\mathbf{A}}$$

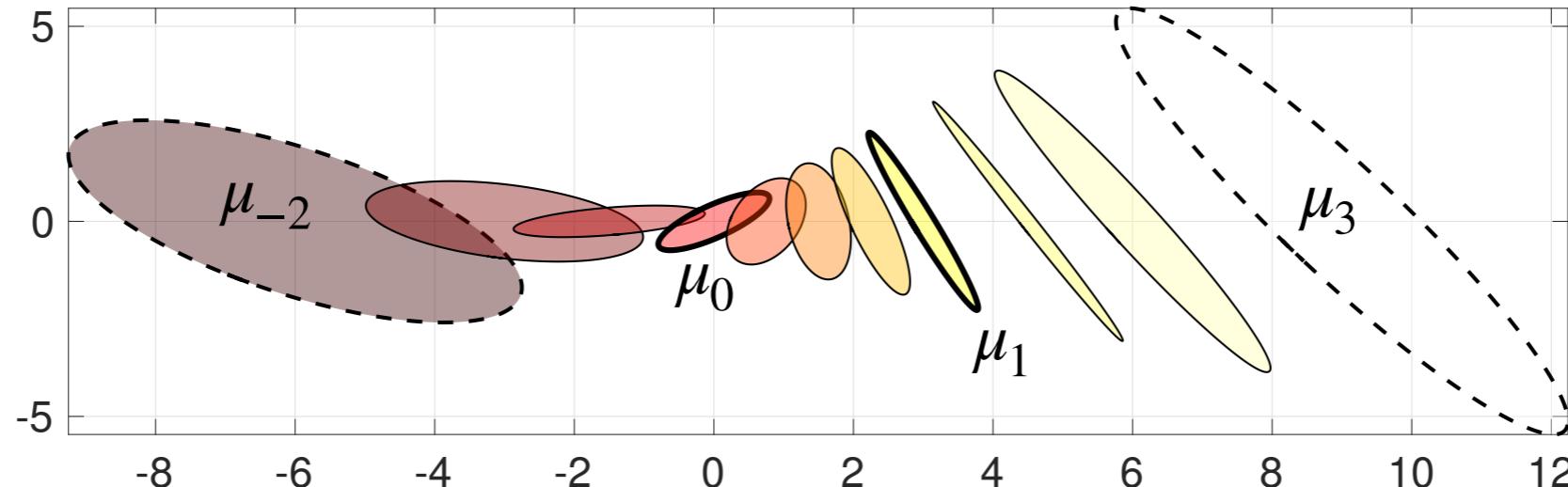
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- Riemannian geodesics: $\mathbf{C}_{\mathbf{AB}}(t) = [(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]\mathbf{A}[(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]$

W_2 geodesic $(\mu_t)_t$ from μ_0 to μ_1 ($t \in [0, 1]$) and extrapolation



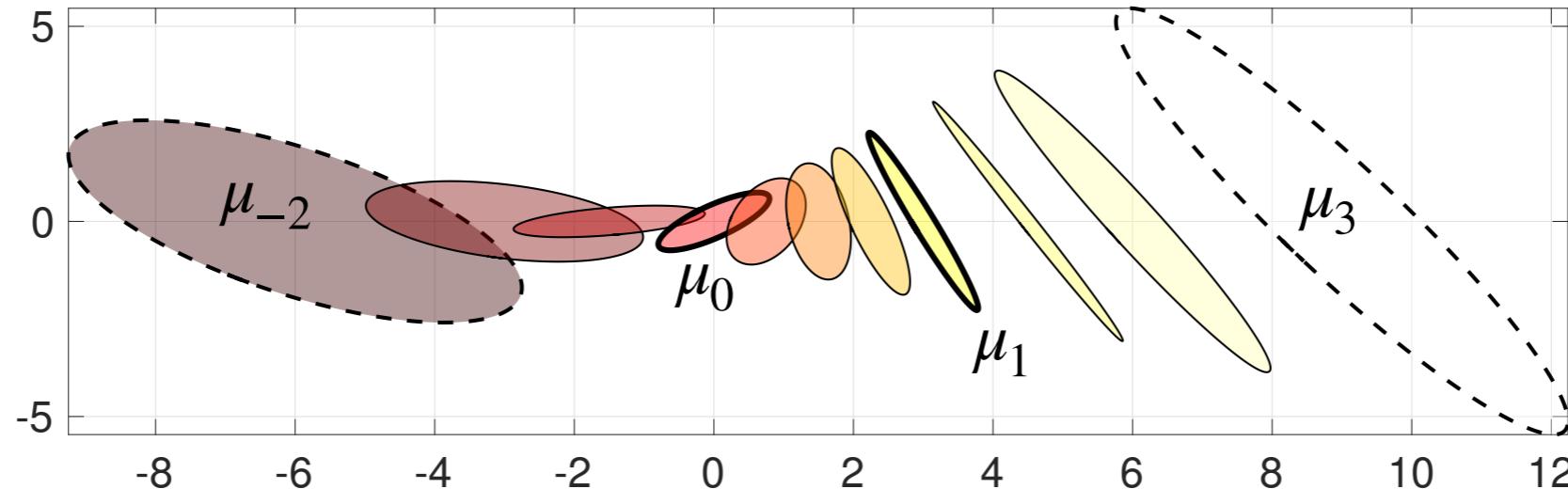
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W_2 geodesic $(\mu_t)_t$ from μ_0 to μ_1 ($t \in [0, 1]$) and extrapolation

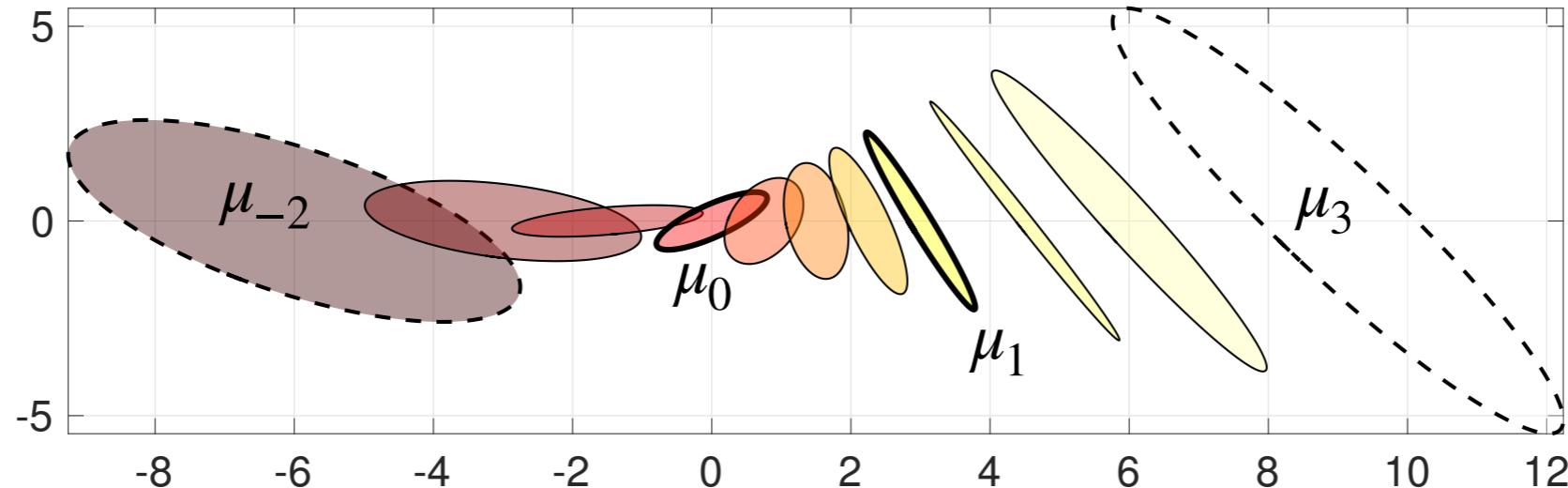


- “ $\Pi(\cdot)$ makes \mathfrak{B}^2 flat”: $\mathbf{L}_{\mathbf{A}} - t \nabla_{\mathbf{L}_{\mathbf{A}}} \frac{1}{2} \mathfrak{B}^2(\mathbf{A}, \mathbf{B}) \in \Pi^{-1}\{\mathbf{C}_{\mathbf{AB}}(t)\}$

Can we avoid projections?

- $\mathbf{A} - t \nabla_{\mathbf{A}} \mathfrak{B}^2(\mathbf{A}, \mathbf{B})$ is not necessarily PSD.
- Classic workaround: $\mathbf{A} = \Pi(\mathbf{L}_{\mathbf{A}}) \stackrel{\text{def}}{=} \mathbf{L}_{\mathbf{A}} \mathbf{L}_{\mathbf{A}}^T$. Effect on gradient methods?
$$\nabla_{\mathbf{L}_{\mathbf{A}}} \frac{1}{2} \mathfrak{B}^2(\mathbf{L}_{\mathbf{A}} \mathbf{L}_{\mathbf{A}}^T, \mathbf{B}) = (\mathbf{I} - \mathbf{T}^{\mathbf{AB}}) \mathbf{L}_{\mathbf{A}}$$
- Riemannian geodesics: $\mathbf{C}_{\mathbf{AB}}(t) = [(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]\mathbf{A}[(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]$

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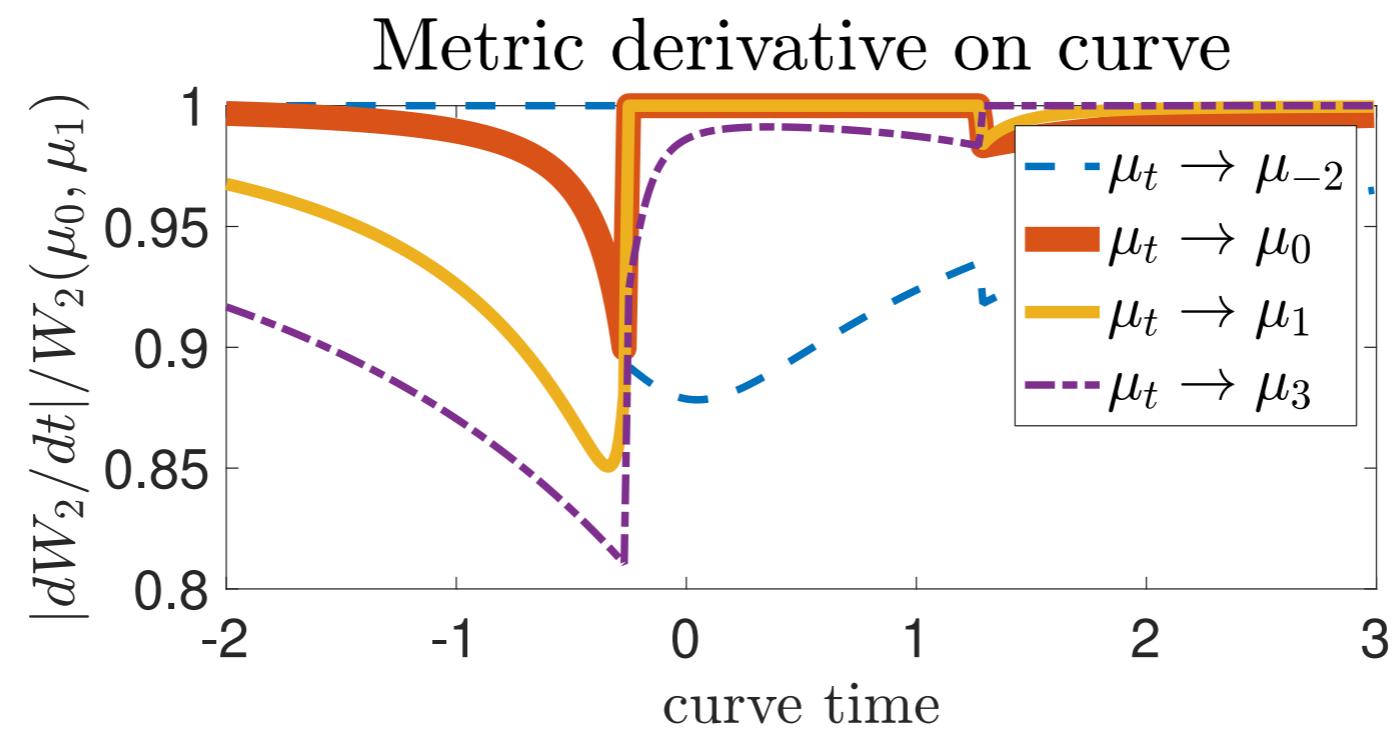
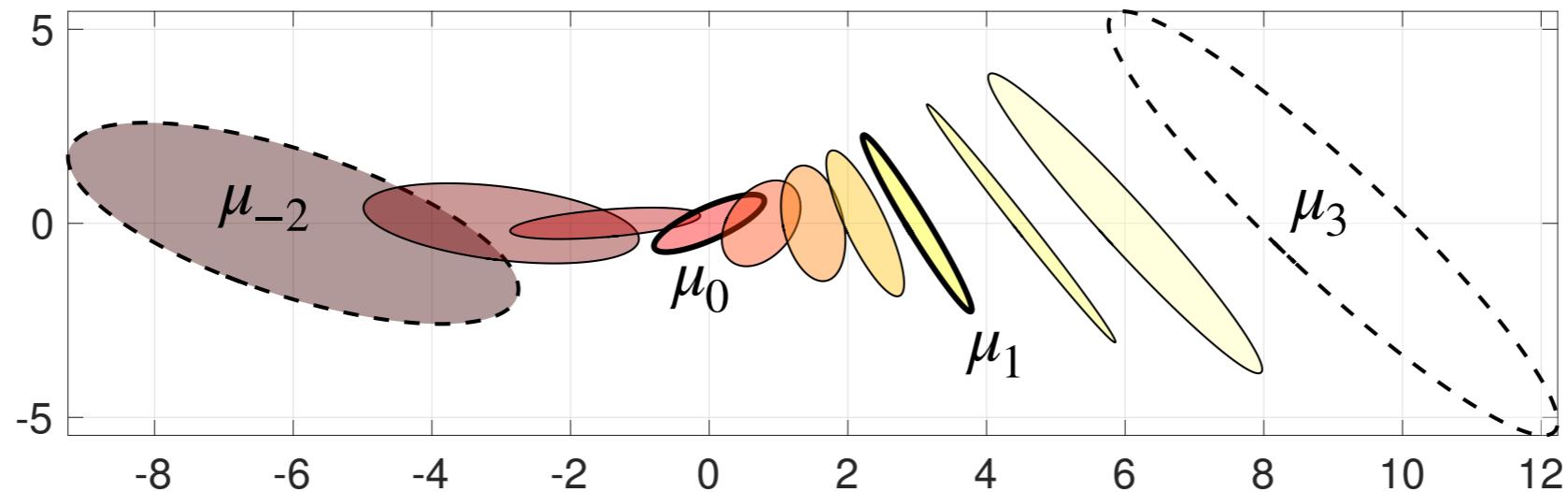


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Extrapolation

- **Riemannian geodesics:** $\mathbf{C}_{\mathbf{AB}}(t) = [(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]\mathbf{A}[(1-t)\mathbf{I} - t\mathbf{T}^{\mathbf{AB}}]$

W_2 geodesic $(\mu_t)_t$ from μ_0 to μ_1 ($t \in [0, 1]$) and extrapolation



IV. Applications

Elliptical Word Embeddings

- [BM&Cuturi'18]

« Skipgram-like » model :

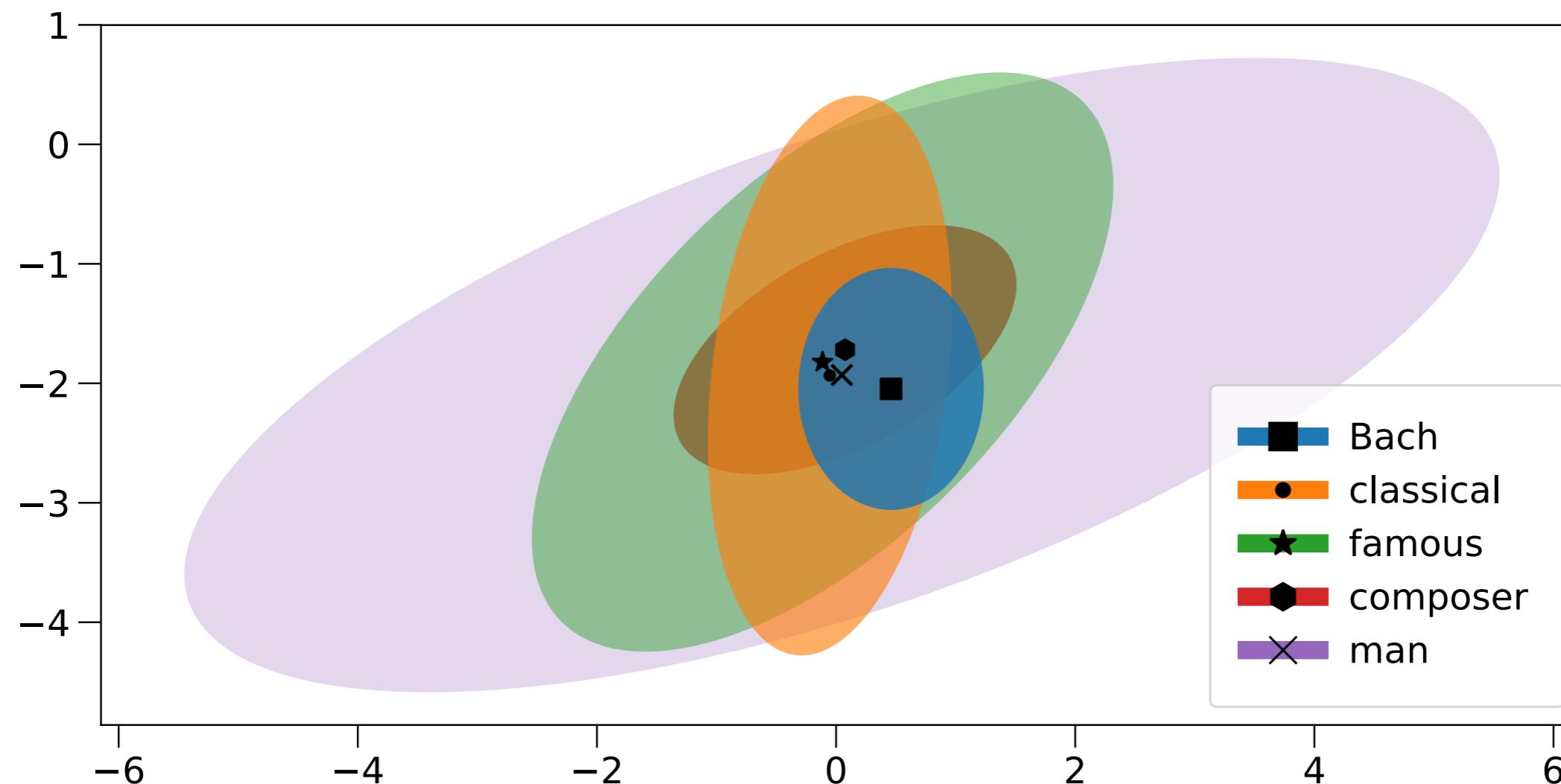
- Sliding window of size 10, extract positive pairs $(w, c) \in \mathcal{R}$
- Sample negative pairs $(w, c') \notin \mathcal{R}$
- Optimize

$$\min \sum_{(w,c) \in \mathcal{R}} \left[M - ([\mu_w, \mu_c]_{\mathfrak{B}} - [\mu_w, \mu_{c'}]_{\mathfrak{B}}) \right]_+$$

where $[\alpha, \beta]_{\mathfrak{B}} := \langle \mathbf{a}, \mathbf{b} \rangle + \text{Tr} \left(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}} \right)^{\frac{1}{2}}$ is a Bures generalization of the dot product

- Trained over *Wackypedia* + *UkWac* : 3 billion tokens

Word Embeddings: visualization



Word Embeddings: Similarity Evaluation

Dataset	W2G/45/C	Ell/12/BC
SimLex	33.28	24.09
WordSim	62.52	66.02
WordSim-R	69.37	71.07
WordSim-S	57.56	60.58
MEN	61.5	65.58
MC	79.5	65.95
RG	67.61	65.58
YP	20.86	25.14
MT-287	61.71	59.53
MT-771	58.11	56.78
RW	30.62	29.04

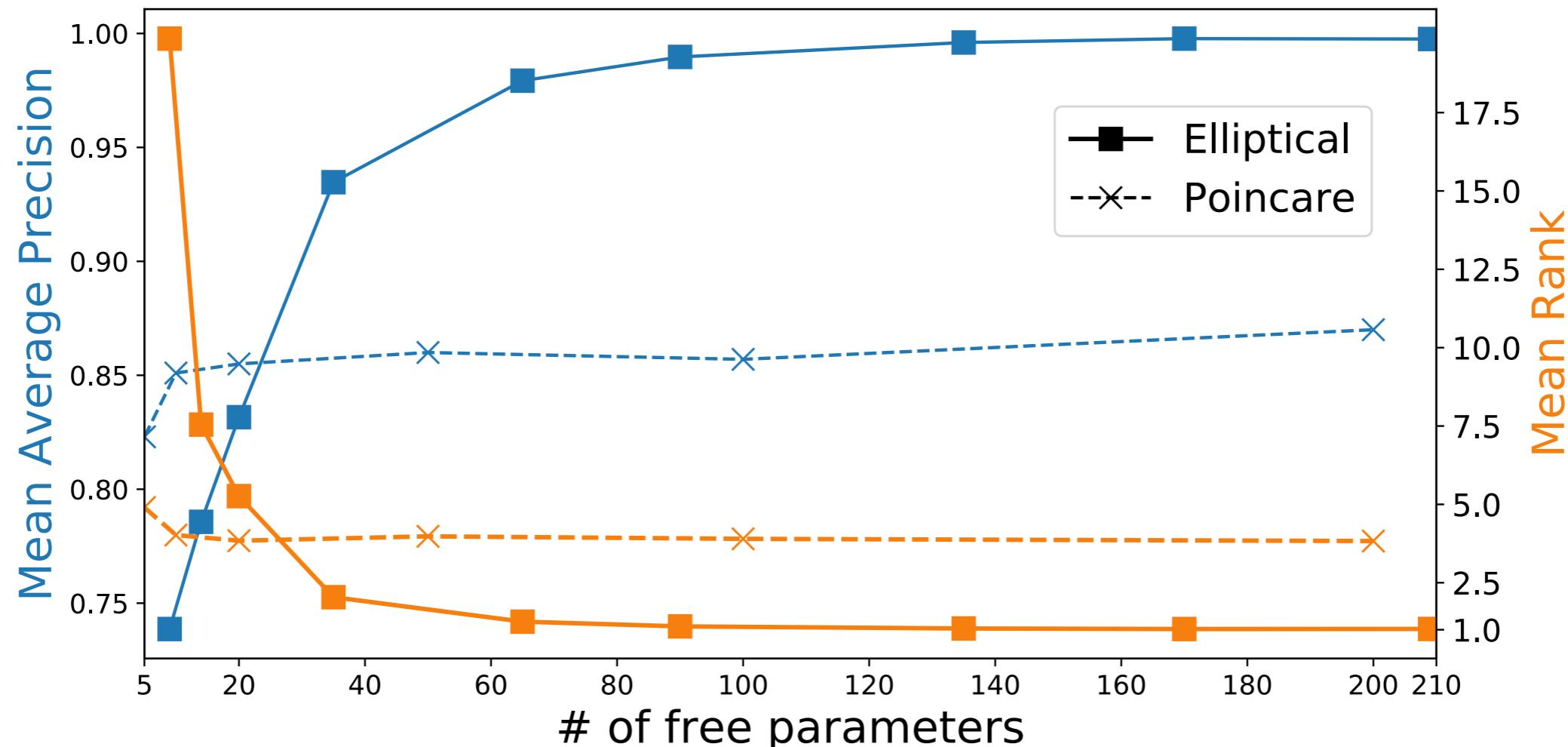
Spearman rank correlation with human scores

Comparison with [Vilnis & McCallum'15]

Hypernymy embeddings

A is a *hypernym* of B if every B is an A

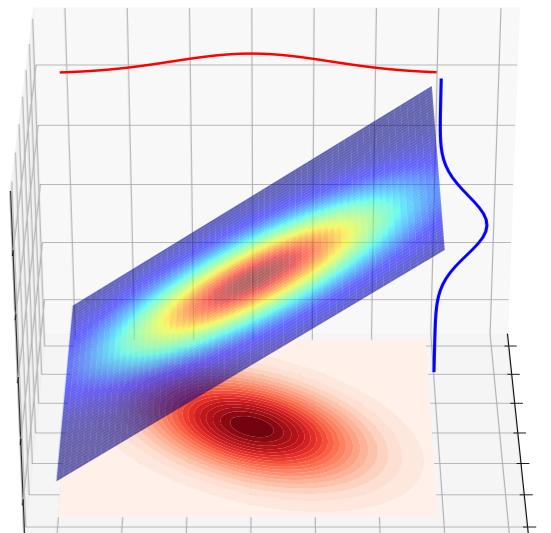
- Ex: ‘*mammal*’ > ‘*dog*’
- WordNet Dataset: 743,251 relations, 82,115 distinct nouns



Comparison with [Nickel & Kiela'17]

Other applications

- Robust (min/max) estimation of inverse covariance matrices [Nguyen et al.'18]
- Distributionally robust Kalman filtering [Abadeh et al.'18]
- GANs: Fréchet Inception Distance (FID) [Heusel et al.'17]
- Extension to the subspace constraints: [BM&Cuturi'19]



Extensions

Subspace-Optimal Transport

Let E a subspace, $s : E \rightarrow E$ an (optimal) transport on E

Def. The class of E -optimal transport plans from μ to ν is

$$\Pi_E(\mu, \nu) \stackrel{def}{=} \{\gamma \in \Pi(\mu, \nu) : \gamma_E = (\text{Id}_E, s)_\sharp \mu_E\}$$

where $\mu_E \stackrel{def}{=} (p_E)_\sharp(\mu)$, $\nu_E \stackrel{def}{=} (p_E)_\sharp(\nu)$, $\gamma_E \stackrel{def}{=} (p_E, p_E)_\sharp(\gamma)$

A quick reminder

Def. Disintegration of μ on E : $(\mu_{x_E})_{x_E \in E}$ **s.t.**

$\forall g \in C_b(E), x_E \rightarrow \int_{E^\perp} g \mu_{x_E}$ **is Borel-measurable**

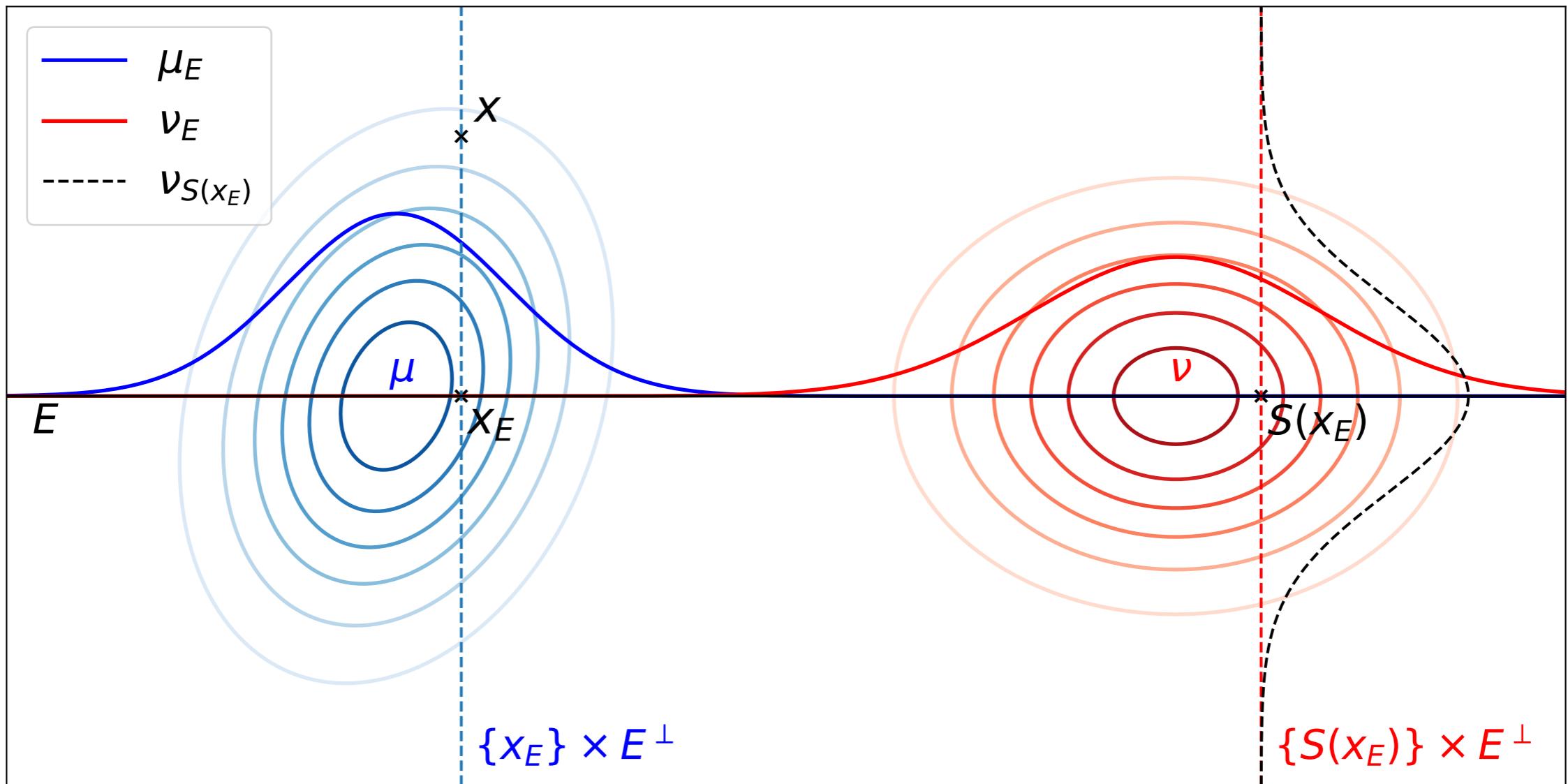
$\forall x_E \in E, \mu_{x_E}$ **is supported on** $\{x_E\} \times E^\perp$

$\forall f \in C_b(\mathbb{R}^d), \int f d\mu = \int \left(\int f(x_E, x_{E^\perp}) d\mu_{x_E}(x_{E^\perp}) \right) d\mu_E(x_E)$

Notation: $\mu = \mu_{x_E} \otimes \mu_E$

Degrees of freedom in $\Pi_E(\mu, \nu)$?

- γ_E is supported on $\mathcal{G}(S) \stackrel{\text{def}}{=} \{(x_E, S(x_E)) : x_E \in E\}$
- $\implies \gamma$ is fully characterised by its disintegrations $\gamma_{(x_E, S(x_E))}, x_E \in E$



Monge-Independent Transport



Extend γ_E with independent couplings $\mu_{x_E} \otimes \nu_{S(x_E)}$

Monge-Independent Transport



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Def. Monge-Independent (MI) transport plan:

$$\pi_{\mathbf{MI}}(\mu, \nu) \stackrel{\text{def}}{=} (\mu_{x_E} \otimes \nu_{S(x_E)}) \otimes (\text{Id}_E, S)_\sharp \mu_E$$

where $\mu_E \stackrel{\text{def}}{=} (p_E)_\sharp(\mu)$, $\nu_E \stackrel{\text{def}}{=} (p_E)_\sharp(\nu)$, **S Monge map from μ_E to ν_E** , $\gamma_E = (\text{Id}_E, S)_\sharp \mu_E$

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Prop. Let $\mu, \nu \in P(\mathbb{R}^d)$ be a.c. and compactly supported,

$\mu_n, \nu_n, n \geq 0$ uniform over n i.i.d samples, $\pi_n \in \Pi_E(\mu_n, \nu_n), n \geq 0$

Then $\pi_n \rightharpoonup \pi_{\mathbf{MI}}$

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MI is naturally obtained as the limit of discrete sampling.

Monge-Knothe Transport



Extend γ_E with optimal couplings between μ_{x_E} and $\nu_{S(x_E)}$

Let $\forall x_E \in \hat{T}(x_E; \cdot) : E^\perp \rightarrow E^\perp$ be the Monge map from μ_{x_E} to $\nu_{S(x_E)}$

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Def. Monge-Knothe (MK) transport map:

$$T_{\mathbf{MK}}(x_E, x_{E^\perp}) \stackrel{\text{def}}{=} (S(x_E), \hat{T}(x_E; x_{E^\perp})) \in E \oplus E^\perp$$

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Prop. The Monge-Knothe plan is optimal in $\Pi_E(\mu, \nu)$, namely

$$\pi_{\mathbf{MK}} \in \arg \min_{\gamma \in \Pi_E(\mu, \nu)} \mathbb{E}_{(\mathbf{X}, \mathbf{Y}) \sim \gamma} [\|\mathbf{X} - \mathbf{Y}\|^2]$$

where, $\pi_{\mathbf{MK}} \stackrel{\text{def}}{=} (\text{Id}_{\mathbb{R}^d}, T_{\mathbf{MK}})_\# \mu$

OT for Gaussian Distributions

[Gelbrich'90]

Prop. If $\alpha, \beta \in P(\mathbb{R}^d)$ are elliptical distributions, then

$$W_2^2(\alpha, \beta) = \|\mathbf{m}_\alpha - \mathbf{m}_\beta\|_2^2 + \mathfrak{B}^2(\text{var}\alpha, \text{var}\beta)$$

$\mathfrak{B}^2(\mathbf{A}, \mathbf{B}) \stackrel{\text{def}}{=} \text{Tr}(\mathbf{A} + \mathbf{B} - 2(\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}})$ is the (squared) *Bures* distance

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Prop. If $\alpha, \beta \in P(\mathbb{R}^d)$ are elliptical distributions with $\text{var}\alpha = \mathbf{A}$, $\text{var}\beta = \mathbf{B}$, then

$T(\mathbf{x}) = \mathbf{m}_\beta + \mathbf{T}^{\mathbf{AB}}(\mathbf{x} - \mathbf{m}_\alpha)$ is the optimal Monge map

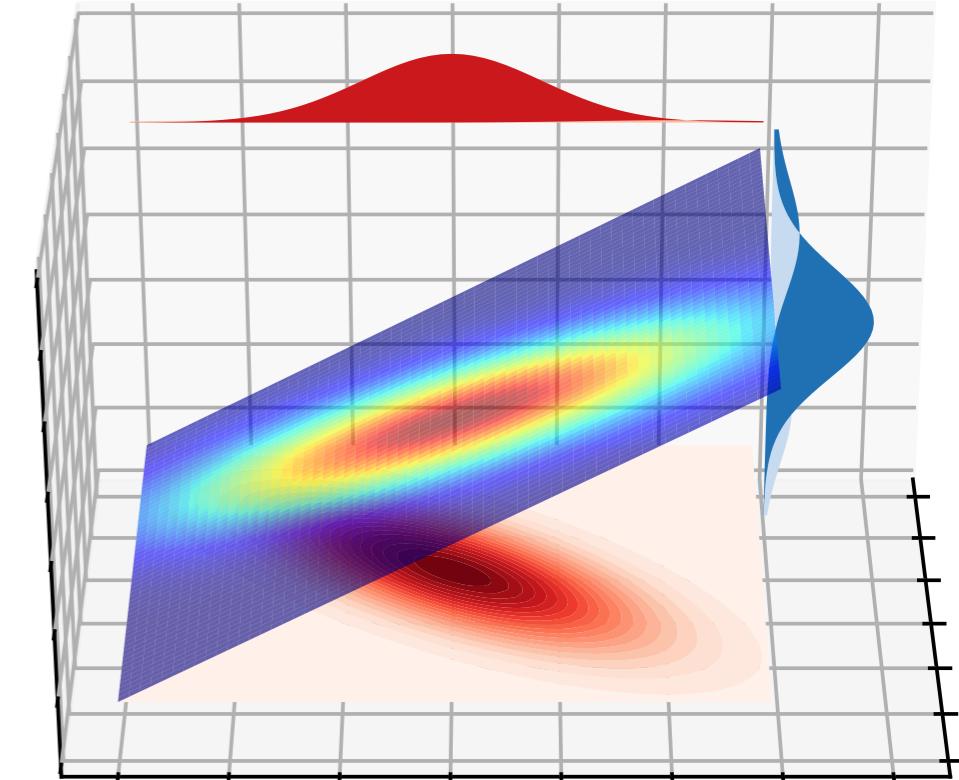
where $\mathbf{T}^{\mathbf{AB}} \stackrel{\text{def}}{=} \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$ is such that $\mathbf{T}^{\mathbf{AB}} \mathbf{A} \mathbf{T}^{\mathbf{AB}} = \mathbf{B}$ and $\mathbf{T}^{\mathbf{AB}} \in \text{PSD}$

Monge-Independent: Gaussian Distributions

From now on: $\mu = \mathcal{N}(0_d, \mathbf{A})$, $\nu = \mathcal{N}(0_d, \mathbf{B})$

$$\mathbf{A} = \begin{pmatrix} \mathbf{A}_E & \mathbf{A}_{EE^\perp} \\ \mathbf{A}_{EE^\perp}^\top & \mathbf{A}_{E^\perp} \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} \mathbf{B}_E & \mathbf{B}_{EE^\perp} \\ \mathbf{B}_{EE^\perp}^\top & \mathbf{B}_{E^\perp} \end{pmatrix}$$

$(\mathbf{V}_E \ \mathbf{V}_{E^\perp})$ orthonormal basis of $E \oplus E^\perp$



Prop. Let $\mathbf{C} \stackrel{\text{def}}{=} (\mathbf{V}_E \mathbf{A}_E + \mathbf{V}_{E^\perp} \mathbf{A}_{EE^\perp}^\top) \mathbf{T}^{\mathbf{A}_E \mathbf{B}_E} (\mathbf{V}_{E^\top} + (\mathbf{B}_E)^{-1} \mathbf{B}_{EE^\perp} \mathbf{V}_{E^\perp}^\top)$ and $\Sigma \stackrel{\text{def}}{=} \begin{pmatrix} \mathbf{A} & \mathbf{C} \\ \mathbf{C}^\top & \mathbf{B} \end{pmatrix}$

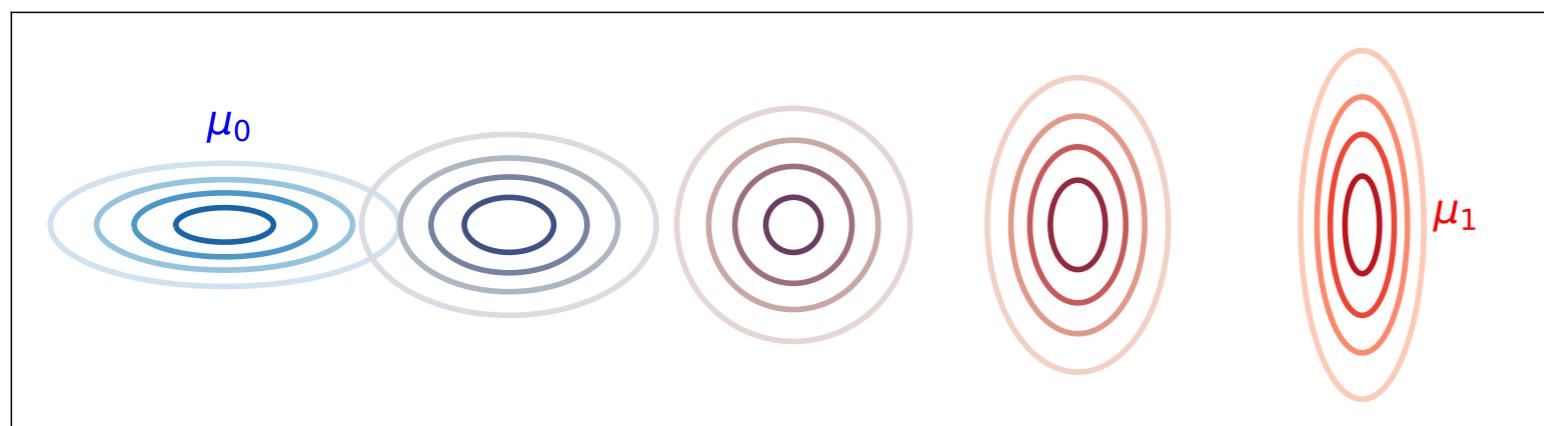
Then $\pi_{MK}(\mu, \nu) = \mathcal{N}(0_{2d}, \Sigma) \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d)$

where $\mathbf{T}^{\mathbf{AB}} \stackrel{\text{def}}{=} \mathbf{A}^{-\frac{1}{2}} (\mathbf{A}^{\frac{1}{2}} \mathbf{B} \mathbf{A}^{\frac{1}{2}})^{\frac{1}{2}} \mathbf{A}^{-\frac{1}{2}}$

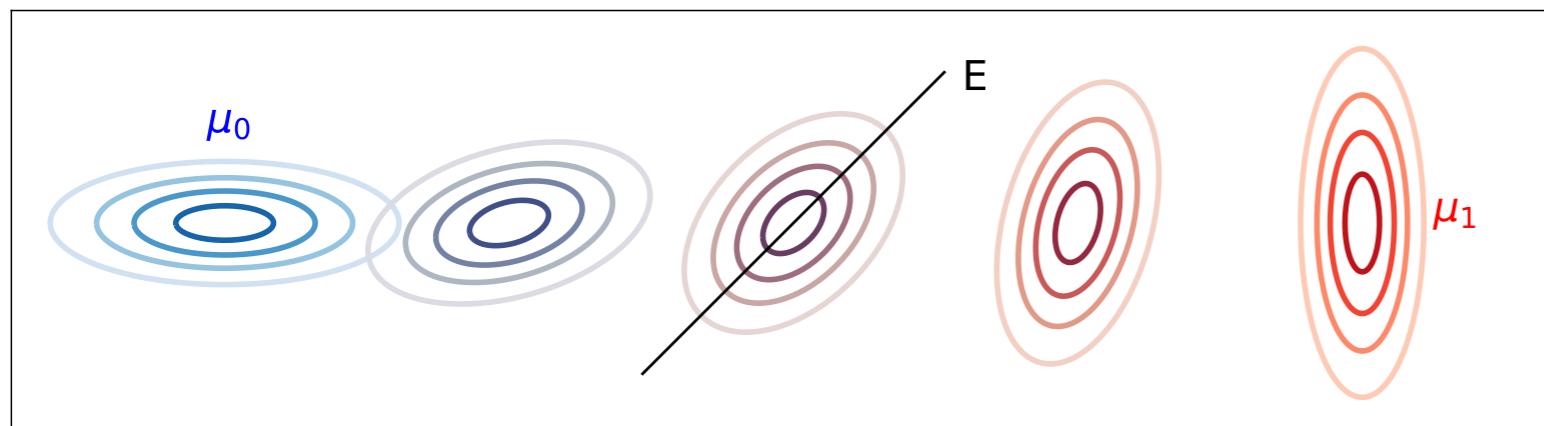
Monge-Knothe: Gaussian Distributions

Prop. $T_{MK} = \begin{pmatrix} T^{A_E B_E} & 0_{k \times (d-k)} \\ [B_{EE^\perp}^\top (T^{A_E B_E})^{-1} - T^{(A/A_E)(B/B_E)} A_{EE^\perp}^\top] (A_E)^{-1} & T^{(A/A_E)(B/B_E)} \end{pmatrix}$

where $A/A_E \stackrel{\text{def}}{=} A_{E^\perp} - A_{EE^\perp}^\top A_E^{-1} A_{EE^\perp}$ is the Schur complement of A w.r.t. A_E and $T^{AB} \stackrel{\text{def}}{=} A^{-\frac{1}{2}} (A^{\frac{1}{2}} B A^{\frac{1}{2}})^{-1} A^{-\frac{1}{2}}$



Monge interpolation



MK interpolation

Application: Semantic Mediation (NLP)

Elliptical word embeddings from [BM&MC'18]:

- each word is represented with a mean vector \mathbf{m} and a PSD matrix Σ

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Influence of context c on the nearest neighbours - Symmetric differences:

Word	Context 1	Context 2	Difference
instrument	monitor	oboe	cathode, monitor, sampler, rca, watts, instrumentation, telescope, synthesizer, ambient
	oboe	monitor	tuned, trombone, guitar, harmonic, octave, baritone, clarinet, saxophone, virtuoso
windows	pc	door	netscape, installer, doubleclick, burner, installs, adapter, router, cpus
	door	pc	screwed, recessed, rails, ceilings, tiling, upvc, profiled, roofs
fox	media	hedgehog	Penny, quiz, Whitman, outraged, Tinker, ads, Keating, Palin, show
	hedgehog	media	panther, reintroduced, kangaroo, Harriet, fair, hedgehog, bush, paw, bunny