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Лабораторная работа №1 по курсу «Численные методы»

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Лабораторная работа №1

Вариант: 4

Задача:

1. Реализовать алгоритм LU - разложения матриц (с выбором главного элемента) в виде программы. Используя разработанное программное обеспечение, решить систему линейных алгебраических уравнений (СЛАУ). Для матрицы СЛАУ вычислить определитель и обратную матрицу.
2. Реализовать метод прогонки в виде программы, задавая в качестве входных данных ненулевые элементы матрицы системы и вектор правых частей. Используя разработанное программное обеспечение, решить СЛАУ с трехдиагональной матрицей.
3. Реализовать метод простых итераций и метод Зейделя в виде программ, задавая в качестве входных данных матрицу системы, вектор правых частей и точность вычислений. Используя разработанное программное обеспечение, решить СЛАУ. Проанализировать количество итераций, необходимое для достижения заданной точности.
4. Реализовать метод вращений в виде программы, задавая в качестве входных данных матрицу и точность вычислений. Используя разработанное программное обеспечение, найти собственные значения и собственные векторы симметрических матриц. Проанализировать зависимость погрешности вычислений от числа итераций.
5. Реализовать алгоритм QR – разложения матриц в виде программы. На его основе разработать программу, реализующую QR – алгоритм решения полной проблемы собственных значений произвольных матриц, задавая в качестве входных данных матрицу и точность вычислений. С использованием разработанного программного обеспечения найти собственные значения матрицы.

1 Исходный код

Исходный код я писал на языке *C++*.

Реализация матрицы:

```
1  #ifndef MATRIX_H
2  #define MATRIX_H
3
4  #include <vector>
5  #include <iostream>
6  #include <cmath>
7
8
9  using namespace std;
10
11 // class with matrix functions:
12 class Matrix{
13 public:
14     Matrix();
15     Matrix(int n, int m);
16
17     void make_ones();
18     void transpose();
19
20     vector<double>& operator[] (const int index);
21     const vector<double>& operator[] (const int index) const;
22
23     friend const Matrix operator+(const Matrix& left, const Matrix& right);
24     friend const Matrix operator-(const Matrix& left, const Matrix& right);
25
26     friend const Matrix operator*(const Matrix& left, const Matrix& right);
27     //friend const Matrix operator*(const vector<double>& left, const vector<double>&
28         right);
29     friend const vector<double> operator*(const Matrix& left, const vector<double>&
30         right);
31     friend const Matrix operator*(const Matrix& left, double right);
32     friend const Matrix operator*(double left, const Matrix& right);
33
34     const Matrix& operator=(const Matrix& right);
35
36     friend std::ostream& operator<<(std::ostream& os, const Matrix& matrix);
37
38     double get_norm() const;
39     double get_upper_norm() const;
40
41     int get_n() const;
42     int get_m() const;
43
44     bool is_three_diagonal() const;
```

```

43     bool is_simmetric() const;
44
45     bool is_quadratic() const;
46
47 private:
48     vector<vector<double>> _matrix;
49     int n_size;
50     int m_size;
51 };

```

Задание №1:

```

1  #include <vector>
2  #include <iostream>
3  #include "Matrix/matrix.h"
4
5  using namespace std;
6
7
8  void compute_solution(const Matrix& U, const Matrix& L, const vector<double>& b,
9      vector<double>& x){
10     x.resize(U.get_m());
11     // Compute solution:
12     // vector z:
13
14     vector<double> z(L.get_m());
15     for(int i = 0; i < L.get_m(); ++i){
16         z[i] = b[i];
17         for(int j = 0; j < i; ++j){
18             z[i] -= (L[i][j] * z[j]);
19         }
20     }
21
22     // vector x:
23     for(int i = U.get_m() - 1; i >= 0; --i){
24         x[i] = z[i];
25         for(int j = i + 1; j < U.get_m(); ++j){
26             x[i] -= (x[j] * U[i][j]);
27         }
28         x[i] /= U[i][i];
29     }
30 }
31
32 // Compute LU matrix, SLAU solution for entered matrix (if LU not exist - exception)
33 // and returns matrix determinant
34 double gauss_completely(const Matrix& matrix, Matrix& L, Matrix& U, Matrix& X, const
35     vector<double>& b, vector<double>& x){
36     if(!matrix.is_quadratic()){
37         throw "LU not exist! Try simple gauss method or enter lines in another order!";
38     }
39 }

```

```

36     }
37     // init:
38     U = matrix;
39     L = Matrix(matrix.get_n(), matrix.get_m());
40     X = Matrix(matrix.get_n(), matrix.get_m());
41     double determinant = 1.0;
42
43     // First Gauss steps (compute L and U):
44     for(int j = 0; j < U.get_m(); ++j){
45         if(U[j][j] == 0.0){
46             throw "LU not exist! Try simple gauss method or enter lines in another
47                 order!";
48         }
49         L[j][j] = 1.0;
50         for(int i = j + 1; i < U.get_n(); ++i){
51             double l_ij = U[i][j] / U[j][j];
52             L[i][j] = l_ij;
53             // line[i] - line[j]
54             for(int k = j; k < U.get_m(); ++k){
55                 U[i][k] -= U[j][k] * l_ij;
56             }
57         }
58     }
59     // Compute solution:
60     compute_solution(U, L, b, x);
61
62     // Compute back matrix like compute sol:
63     vector<double> b_1(b.size());
64     for(int i = 0; i < U.get_n(); ++i){
65         b_1[i] = 1.0;
66         compute_solution(U, L, b_1, X[i]);
67         b_1[i] = 0.0;
68     }
69     X.transpose();
70
71     // Compute determinant:
72     for(int i = 0; i < U.get_m(); ++i){
73         determinant *= U[i][i];
74     }
75
76     return determinant;
77 }
78
79 void ave(){
80     cout << "===== " << endl;
81     cout << "| LABORATORY WORK №1 |" << endl;
82     cout << "| NUMERICAL METHODS |" << endl;
83     cout << "| Task №1 |" << endl;

```

```

84     cout << "| Variant №4 |" << endl;
85     cout << "| |" << endl;
86     cout << "| Student: Bronnikov M.A. |" << endl;
87     cout << "| Date: 23.02.2020 |" << endl;
88     cout << "| |" << endl;
89     cout << "| |" << endl;
90     cout << "| Moscow, 2020 |" << endl;
91     cout << "======" << endl;
92 }
93
94 void bye(){
95     cout << "======" << endl;
96     cout << "| EXIT |" << endl;
97     cout << "======" << endl;
98 }
99
100 int size_init(){
101     int size;
102     cin >> size;
103     return size;
104 }
105
106 void matrix_init(Matrix& A, int size){
107     A = Matrix(size, size);
108     for(int i = 0; i < size; ++i){
109         for(int j = 0; j < size; ++j){
110             cin >> A[i][j];
111         }
112     }
113 }
114
115
116 void vector_init(vector<double>& b, int size){
117     b.resize(size);
118     for(int i = 0; i < size; ++i){
119         cin >> b[i];
120     }
121 }
122
123 void print_vector_x(const vector<double>& x){
124     for(unsigned i = 0; i < x.size(); ++i){
125         cout << 'x' << i + 1 << " = " << x[i] << " ";
126     }
127     cout << endl;
128 }
129
130 void print_solution(const Matrix& U, const Matrix& L, const Matrix& B, const vector<
    double>& x, double determinant){
131     cout << "======" << endl;

```

```

132     cout << "| ANSWER: |" << endl;
133     cout << "===== " << endl;
134     cout << "L matrix:" << endl;
135     cout << L << endl;
136     cout << "===== " << endl;
137     cout << "U matrix:" << endl;
138     cout << U << endl;
139     cout << "===== " << endl;
140     cout << "Back matrix:" << endl;
141     cout << B << endl;
142     cout << "===== " << endl;
143     cout << "x solution:" << endl;
144     print_vector_x(x);
145     cout << "===== " << endl;
146     cout << "Determinant: " << determinant << endl;
147     cout << "===== " << endl;
148     return;
149 }
150
151 void print_statement(const Matrix& A, const vector<double>& b){
152     cout << "===== " << endl;
153     cout << "| EXERCISE: |" << endl;
154     cout << "===== " << endl;
155     cout << "| We need to solve SLAU by LU separating matrix with Gauss |" << endl;
156     cout << "| method. Find determinant, back matrix, L and U matrix. |" << endl;
157     cout << "===== " << endl;
158     cout << "SLAU matrix:" << endl;
159     cout << A << endl;
160     cout << "Free vector:" << endl;
161     for(unsigned i = 0; i < b.size(); ++i){
162         cout.width(8);
163         cout << b[i] << endl;
164     }
165     cout << "===== " << endl;
166 }
167
168 int main(){
169     ave();
170     Matrix L, U, B, A;
171     vector<double> b, x;
172     int size = size_init();
173     matrix_init(A, size);
174     vector_init(b, size);
175     print_statement(A, b);
176
177     // Main function use:
178     double determinant = gauss_completely(A, L, U, B, b, x);
179
180     print_solution(U, L, B, x, determinant);

```

```

181
182     bye();
183     return 0;
184 }

```

Задание №2:

```

1  #include <vector>
2  #include <iostream>
3  #include "Matrix/matrix.h"
4
5  using namespace std;
6
7  void ave(){
8      cout << "===== " << endl;
9      cout << "| LABORATORY WORK №1 |" << endl;
10     cout << "| NUMERICAL METHODS |" << endl;
11     cout << "| Task №2 |" << endl;
12     cout << "| Variant №4 |" << endl;
13     cout << "| |" << endl;
14     cout << "| Student: Bronnikov M.A. |" << endl;
15     cout << "| Date: 23.02.2020 |" << endl;
16     cout << "| |" << endl;
17     cout << "| |" << endl;
18     cout << "| Moscow, 2020 |" << endl;
19     cout << "===== " << endl;
20 }
21
22 void print_statement(const Matrix& A, const vector<double>& b){
23     cout << "===== " << endl;
24     cout << "| EXERCISE: |" << endl;
25     cout << "===== " << endl;
26     cout << "| We need to solve SLAU by race method. |" << endl;
27     cout << "===== " << endl;
28     cout << "SLAU matrix:" << endl;
29     cout << A << endl;
30     cout << "Free vector:" << endl;
31     for(unsigned i = 0; i < b.size(); ++i){
32         cout.width(8);
33         cout << b[i] << endl;
34     }
35     cout << "===== " << endl;
36 }
37
38 void bye(){
39     cout << "===== " << endl;
40     cout << "| EXIT |" << endl;
41     cout << "===== " << endl;
42 }
43

```



```

44 |
45 | int size_init(){
46 |     int size;
47 |     cin >> size;
48 |     return size;
49 | }
50 |
51 | void matrix_init(Matrix& A, int size){
52 |     A = Matrix(size, size);
53 |     for(int i = 0; i < size; ++i){
54 |         for(int j = 0; j < size; ++j){
55 |             cin >> A[i][j];
56 |         }
57 |     }
58 | }
59 |
60 | /*
61 | void vector_init(vector<double>& b){
62 |     b.resize(5);
63 |     b[0] = -78.0;
64 |     b[1] = -73.0;
65 |     b[2] = -38.0;
66 |     b[3] = 77.0;
67 |     b[4] = 91.0;
68 | }
69 | */
70 |
71 |
72 | void vector_init(vector<double>& b, int size){
73 |     b.resize(size);
74 |     for(int i = 0; i < size; ++i){
75 |         cin >> b[i];
76 |     }
77 | }
78 |
79 |
80 | void print_vector_x(const vector<double>& x){
81 |     for(unsigned i = 0; i < x.size(); ++i){
82 |         cout << 'x' << i + 1 << " = " << x[i] << " ";
83 |     }
84 |     cout << endl;
85 | }
86 |
87 | void matrix_to_vecs(const Matrix& matrix, vector<vector<double>>& vec){
88 |     if(!matrix.is_quadratic()){
89 |         throw "Wrong matrix";
90 |     }
91 |     vec.clear();
92 |     vec.assign(matrix.get_n(), vector<double>(3, 0.0));

```

```

93
94     for(int i = 0; i < matrix.get_n(); ++i){
95         vec[i][0] = i - 1 < 0 ? 0.0 : matrix[i][i - 1];
96         vec[i][1] = matrix[i][i];
97         vec[i][2] = i + 1 < matrix.get_m() ? matrix[i][i + 1] : 0.0;
98     }
99 }
100
101 void race_method(vector<vector<double>>& vec, const vector<double>& b, vector<double>&
    x){
102     x.assign(b.size(), 0.0);
103     vector<double> P(b.size()), Q(b.size());
104     P[0] = -vec[0][2] / vec[0][1];
105     Q[0] = b[0] / vec[0][1];
106     //cout << "P[" << 0 << "]" = " << P[0] << " Q[" << 0 << "]" = " << Q[0] << endl;
107     for(int i = 1; i < (int)x.size(); ++i){
108         double z = (vec[i][1] + vec[i][0] * P[i-1]);
109         P[i] = -vec[i][2];
110         P[i] /= z;
111         Q[i] = (b[i] - vec[i][0] * Q[i - 1]);
112         Q[i] /= z;
113         //cout << "P[" << i << "]" = " << P[i] << " Q[" << i << "]" = " << Q[i] << endl;
114     }
115     x.back() = Q.back();
116     for(int i = x.size() - 2; i >= 0; --i){
117         x[i] = P[i]*x[i+1] + Q[i];
118     }
119 }
120
121 void print_solution(const vector<double>& x){
122     cout << "===== " << endl;
123     cout << "| ANSWER: |" << endl;
124     cout << "===== " << endl;
125     cout << "x solution:" << endl;
126     print_vector_x(x);
127     cout << "===== " << endl;
128 }
129
130
131 int main(){
132     ave();
133
134     Matrix A;
135     vector<double> x, b;
136     vector<vector<double>> vec;
137     int size = size_init();
138     matrix_init(A, size);
139     vector_init(b, size);
140     print_statement(A, b);

```

```

141
142     if(A.is_three_diagonal()){
143         matrix_to_vecs(A, vec);
144     }else{
145         cout << "ERROR! MATRIX IS NOT THREE DIAGONAL! EXIT!" << endl;
146         bye();
147         return 0;
148     }
149
150     race_method(vec, b, x);
151
152     print_solution(x);
153     bye();
154
155     return 0;
156 }

```

Задание №3:

```

1  #include <vector>
2  #include <iostream>
3  #include "Matrix/matrix.h"
4  #include <cmath>
5
6  using namespace std;
7
8  void ave(){
9      cout << "===== " << endl;
10     cout << "| LABORATORY WORK №1 |" << endl;
11     cout << "| NUMERICAL METHODS |" << endl;
12     cout << "| Task №3 |" << endl;
13     cout << "| Variant №4 |" << endl;
14     cout << "| |" << endl;
15     cout << "| Student: Bronnikov M.A. |" << endl;
16     cout << "| Date: 23.02.2020 |" << endl;
17     cout << "| |" << endl;
18     cout << "| |" << endl;
19     cout << "| Moscow, 2020 |" << endl;
20     cout << "===== " << endl;
21 }
22
23 void print_statement(const Matrix& A, const vector<double>& b, double alfa){
24     cout << "===== " << endl;
25     cout << "| EXERCISE: |" << endl;
26     cout << "===== " << endl;
27     cout << "| We need to solve SLAU by simple iteration and Zeidel |" << endl;
28     cout << "| methods. Analyse count of iterations with accuracy. |" << endl;
29     cout << "===== " << endl;
30     cout << "SLAU matrix:" << endl;
31     cout << A << endl;

```

```

32     cout << "Free vector:" << endl;
33     for(unsigned i = 0; i < b.size(); ++i){
34         cout.width(8);
35         cout << b[i] << endl;
36     }
37     cout << endl;
38     cout << "Accuracy: " << alfa << endl;
39     cout << "======" << endl;
40 }
41
42 void bye(){
43     cout << "======" << endl;
44     cout << "| EXIT |" << endl;
45     cout << "======" << endl;
46 }
47
48
49 int size_init(){
50     int size;
51     cin >> size;
52     return size;
53 }
54
55 void matrix_init(Matrix& A, int size){
56     A = Matrix(size, size);
57     for(int i = 0; i < size; ++i){
58         for(int j = 0; j < size; ++j){
59             cin >> A[i][j];
60         }
61     }
62 }
63
64 void vector_init(vector<double>& b, int size){
65     b.resize(size);
66     for(int i = 0; i < size; ++i){
67         cin >> b[i];
68     }
69 }
70
71
72
73 void print_vector_x(const vector<double>& x){
74     for(unsigned i = 0; i < x.size(); ++i){
75         cout << 'x' << i + 1 << " = " << x[i] << " ";
76     }
77     cout << endl;
78 }
79
80 void print_solution(const vector<double>& x, int itter){

```

```

81     cout << "===== " << endl;
82     cout << "| ANSWER: |" << endl;
83     cout << "===== " << endl;
84     cout << "x solution:" << endl;
85     print_vector_x(x);
86     cout << "===== " << endl;
87     cout << "Iterations: " << itter << endl;
88     cout << "===== " << endl;
89 }
90
91 vector<double> vector_minus(const vector<double>& a, const vector<double>& b){
92     vector<double> minus = a;
93     for(unsigned i = 0; i < minus.size(); ++i){
94         minus[i] -= b[i];
95     }
96     return minus;
97 }
98
99 vector<double> vector_plus(const vector<double>& a, const vector<double>& b){
100     vector<double> plus = a;
101     for(unsigned i = 0; i < plus.size(); ++i){
102         plus[i] += b[i];
103     }
104     return plus;
105 }
106
107 double norm_of_vector(const vector<double>& vec){
108     double norm = 0.0;
109     for(unsigned i = 0; i < vec.size(); ++i){
110         norm += vec[i] * vec[i];
111     }
112     return sqrt(norm);
113 }
114
115 int simple_iteration(const Matrix& A, const vector<double>& b, vector<double>& x,
116     double alfa){
117     Matrix M = A;
118     x.resize(b.size());
119     vector<double> last(b.size(), 0.0), r = b;
120     double coeff = 0.0;
121
122     // compute new matrix alfa and vector beta
123     if(!M.is_quadratic()){
124         throw "Wrong matrix! Try again!";
125     }
126     for(int i = 0; i < M.get_n(); ++i){
127         if(!A[i][i]){
128             throw "Wrong matrix! Try again!";
129         }
130     }

```

```

129     for(int j = 0; j < M.get_m(); ++j){
130         M[i][j] = i == j ? 0.0 : -A[i][j] / A[i][i];
131     }
132     r[i] /= A[i][i];
133 }
134
135 x = r;
136 coeff = M.get_norm();
137 if(coeff < 1.0){
138     coeff /= 1 - coeff;
139 }else{
140     coeff = 1.0;
141 }
142
143 /* MAKE ITERATIONS HERE: */
144
145 int itter = 0;
146
147 for(itter = 0; coeff * norm_of_vector(vector_minus(x, last)) > alfa; ++itter){
148     x.swap(last);
149     x = vector_plus(r, M * last);
150 }
151
152 return itter;
153 }
154
155 int zeidels_method(const Matrix& A, const vector<double>& b, vector<double>& x, double
    alfa){
156     Matrix M = A;
157     x.resize(b.size());
158     vector<double> last(b.size(), 0.0), r = b;
159     double coeff = 0.0;
160
161     // compute new matrix alfa and vector beta
162     if(!M.is_quadratic()){
163         throw "Wrong matrix! Try again!";
164     }
165     for(int i = 0; i < M.get_n(); ++i){
166         if(!A[i][i]){
167             throw "Wrong matrix! Try again!";
168         }
169         for(int j = 0; j < M.get_m(); ++j){
170             M[i][j] = i == j ? 0.0 : -A[i][j] / A[i][i];
171         }
172         r[i] /= A[i][i];
173     }
174
175     x = r;
176

```

```

177     coeff = M.get_norm();
178     if(coeff < 1){
179         coeff = M.get_upper_norm() / (1 - coeff);
180     }else{
181         coeff = 1.0;
182     }
183
184     // coeff /= 1 - M.get_norm();
185
186     /* MAKE ITERATIONS HERE: */
187
188     int itter = 0;
189
190     for(itter = 0; coeff * norm_of_vector(vector_minus(x, last)) > alfa; ++itter){
191         x.swap(last);
192         x = r;
193         for(int i = 0; i < M.get_n(); ++i){
194             for(int j = 0; j < i; ++j){
195                 x[i] += x[j] * M[i][j];
196             }
197             for(int j = i; j < M.get_m(); ++j){
198                 x[i] += last[j] * M[i][j];
199             }
200         }
201     }
202
203     return itter;
204 }
205
206
207 int main(){
208     ave();
209
210     Matrix A;
211     vector<double> x, b;
212     vector<vector<double>> vec;
213     double accuracy = 0.001;
214     int size = size_init();
215
216     matrix_init(A, size);
217     vector_init(b, size);
218     cin >> accuracy;
219     print_statement(A, b, accuracy);
220
221     //iterations:
222     cout << "Simple Iterations Method:" << endl;
223     int itter = simple_iteration(A, b, x, accuracy);
224     print_solution(x, itter);
225

```

```

226 //zeidel:
227 cout << "Zeidels Method of Iterations:" << endl;
228 itter = zeidels_method(A, b, x, accuracy);
229 print_solution(x, itter);
230 bye();
231
232 return 0;
233 }

```

Задание №4:

```

1  #include <vector>
2  #include <iostream>
3  #include "Matrix/matrix.h"
4  #include <cmath>
5
6  using namespace std;
7
8  void ave(){
9      cout << "===== " << endl;
10     cout << "| LABORATORY WORK №1 |" << endl;
11     cout << "| NUMERICAL METHODS |" << endl;
12     cout << "| Task №4 |" << endl;
13     cout << "| Variant №4 |" << endl;
14     cout << "| |" << endl;
15     cout << "| Student: Bronnikov M.A. |" << endl;
16     cout << "| Date: 24.02.2020 |" << endl;
17     cout << "| |" << endl;
18     cout << "| |" << endl;
19     cout << "| Moscow, 2020 |" << endl;
20     cout << "===== " << endl;
21 }
22
23 void print_statement(const Matrix& A, double alfa){
24     cout << "===== " << endl;
25     cout << "| EXERCISE: |" << endl;
26     cout << "===== " << endl;
27     cout << "| We need to find vectors and values of simmetric matrix |" << endl;
28     cout << "| by rotate method. |" << endl;
29     cout << "===== " << endl;
30     cout << "Simmetric matrix:" << endl;
31     cout << A << endl;
32     cout << "Accuracy: " << alfa << endl;
33     cout << "===== " << endl;
34 }
35
36 void bye(){
37     cout << "===== " << endl;
38     cout << "| EXIT |" << endl;
39     cout << "===== " << endl;

```



```

40 }
41
42
43 int size_init(){
44     int size;
45     cin >> size;
46     return size;
47 }
48
49 void matrix_init(Matrix& A, int size){
50     A = Matrix(size, size);
51     for(int i = 0; i < size; ++i){
52         for(int j = 0; j < size; ++j){
53             cin >> A[i][j];
54         }
55     }
56 }
57
58
59
60 void print_vector_x(const vector<double>& x){
61     for(unsigned i = 0; i < x.size(); ++i){
62         cout << '1' << i + 1 << " = " << x[i] << " ";
63     }
64     cout << endl;
65 }
66
67 void print_solution(const vector<double>& x, const Matrix& U, int itter){
68     cout << "===== " << endl;
69     cout << "| ANSWER: |" << endl;
70     cout << "===== " << endl;
71     cout << "Values:" << endl;
72     print_vector_x(x);
73     cout << "===== " << endl;
74     cout << "Vectors:" << endl;
75     for(int j = 0; j < U.get_m(); ++j){
76         cout << "x" << j + 1 << ": " << endl;
77         for(int i = 0; i < U.get_n(); ++i){
78             cout.width(8);
79             cout << U[i][j] << endl;
80         }
81         cout << endl;
82     }
83     cout << "===== " << endl;
84     cout << "Iterations: " << itter << endl;
85     cout << "===== " << endl;
86 }
87
88 int rotate_method(const Matrix& A, Matrix& U, vector<double>& x, double alfa){

```

```

89     if(!A.is_simmetric()){
90         throw "Matrix not simmteric! Wrong!";
91     }
92
93     Matrix U_k(A.get_n(), A.get_m()), A_k = A;
94     int i_max = 0, j_max = 0, itter = 0;
95     double v_max = 0.0, fitta = 0.0, check = 0.0;
96
97     U = Matrix(A.get_n(), A.get_m());
98     U.make_ones();
99     x.resize(A.get_m());
100
101     do{
102         U_k.make_ones();
103
104         // search max elem in matrix:
105         v_max = 0.0;
106         i_max = j_max = 0;
107         for(int i = 0; i < A_k.get_n(); ++i){
108             for(int j = i + 1; j < A_k.get_m(); ++j){
109                 if(v_max < abs(A_k[i][j])){
110                     v_max = abs(A_k[i][j]);
111                     i_max = i;
112                     j_max = j;
113                 }
114             }
115         }
116
117         // create U:
118         fitta = A_k[i_max][i_max] == A_k[j_max][j_max] ?
119             M_PI_4 :
120             atan(2 * A_k[i_max][j_max] / (A_k[i_max][i_max] - A_k[j_max][j_max])) /
121                 2;
122
123         U_k[i_max][j_max] = -sin(fitta);
124         U_k[i_max][i_max] = cos(fitta);
125         U_k[j_max][j_max] = cos(fitta);
126         U_k[j_max][i_max] = sin(fitta);
127
128         // multiply:
129         // U for vectors
130         U = U * U_k;
131
132         // A_k for values:
133         A_k = A_k * U_k;
134         U_k.transpose();
135         A_k = U_k * A_k;
136

```

```

137     // compute check:
138     check = 0.0;
139     for(int i = 0; i < A_k.get_n(); ++i){
140         for(int j = i + 1; j < A_k.get_m(); ++j){
141             check += A_k[i][j] * A_k[i][j];
142         }
143     }
144     check = sqrt(check);
145     ++itter;
146 }while(check > alfa);
147
148 for(int i = 0; i < A_k.get_n(); ++i){
149     x[i] = A_k[i][i];
150 }
151
152 return itter;
153 }
154
155
156 int main(){
157     ave();
158
159     Matrix A, U;
160     vector<double> x;
161     double accuracy = 0.01;
162     int size = size_init();
163     matrix_init(A, size);
164     cin >> accuracy;
165     print_statement(A, accuracy);
166
167     //rotate:
168     cout << "Rotate Method:" << endl;
169     int itter = rotate_method(A, U, x, accuracy);
170     print_solution(x, U, itter);
171     bye();
172
173     return 0;
174 }

```

Задание №5:

```

1  #include <vector>
2  #include <iostream>
3  #include "Matrix/matrix.h"
4  #include <cmath>
5  #include <algorithm>
6
7  using namespace std;
8
9  #define value_pair pair<pair<double, double>, pair<double, double>>

```

```

10
11 void ave(){
12     cout << "===== " << endl;
13     cout << "| LABORATORY WORK №1 |" << endl;
14     cout << "| NUMERICAL METHODS |" << endl;
15     cout << "| Task №5 |" << endl;
16     cout << "| Variant №4 |" << endl;
17     cout << "| |" << endl;
18     cout << "| Student: Bronnikov M.A. |" << endl;
19     cout << "| Date: 25.02.2020 |" << endl;
20     cout << "| |" << endl;
21     cout << "| |" << endl;
22     cout << "| Moscow, 2020 |" << endl;
23     cout << "===== " << endl;
24 }
25
26 void print_statement(const Matrix& A, double alfa){
27     cout << "===== " << endl;
28     cout << "| EXERCISE: |" << endl;
29     cout << "===== " << endl;
30     cout << "| We need to find values of matrix using QR separation. |" << endl;
31     cout << "===== " << endl;
32     cout << "Matrix:" << endl;
33     cout << A << endl;
34     cout << "Accuracy: " << alfa << endl;
35     cout << "===== " << endl;
36 }
37
38 void bye(){
39     cout << "===== " << endl;
40     cout << "| EXIT |" << endl;
41     cout << "===== " << endl;
42 }
43
44 int size_init(){
45     int size;
46     cin >> size;
47     return size;
48 }
49
50 void matrix_init(Matrix& A, int size){
51     A = Matrix(size, size);
52     for(int i = 0; i < size; ++i){
53         for(int j = 0; j < size; ++j){
54             cin >> A[i][j];
55         }
56     }
57 }
58

```

```

59
60
61 void print_vector_x(const vector<pair<double, double>>& x){
62     for(unsigned i = 0; i < x.size(); ++i){
63         cout << '1' << i + 1 << " = " << x[i].first;
64         if(x[i].second){
65             if(x[i].second > 0){
66                 cout << " + ";
67             }else{
68                 cout << " - ";
69             }
70             cout << abs(x[i].second) << "i";
71         }
72         cout << endl;
73     }
74     cout << endl;
75 }
76
77 void print_solution(const vector<pair<double, double>>& x, int itter){
78     cout << "===== " << endl;
79     cout << "| ANSWER: |" << endl;
80     cout << "===== " << endl;
81     cout << "Values:" << endl;
82     print_vector_x(x);
83     cout << "===== " << endl;
84     cout << "Iterations: " << itter << endl;
85     cout << "===== " << endl;
86 }
87
88 double mult_1xn_nx1_vecs(const vector<double>& left, const vector<double>& right){
89     double ans = 0.0;
90     if(left.size() != right.size()){
91         throw "Wrong sizes of vectors!";
92     }
93     for(unsigned i = 0; i < left.size(); ++i){
94         ans += right[i] * left[i];
95     }
96     return ans;
97 }
98
99 Matrix mult_nx1_1xn_vecs(const vector<double>& left, const vector<double>& right){
100     Matrix ans(left.size(), right.size());
101     for(int i = 0; i < ans.get_n(); ++i){
102         for(int j = 0; j < ans.get_m(); ++j){
103             ans[i][j] = left[i] * right[j];
104         }
105     }
106     return ans;
107 }

```

```

108
109 double sign(double num){
110     if(!num){
111         return 0.0;
112     }
113     return num > 0 ? 1.0 : -1.0;
114 }
115
116 void solve_eq(double a, double b, double c, pair<pair<double, double>, pair<double,
117     double>>& ans){
118     double D = b * b - 4.0 * a * c;
119     if(D >= 0.0){
120         ans.first.first = (-b + sqrt(D)) / (2 * a);
121         ans.first.second = 0.0;
122         ans.second.first = (-b - sqrt(D)) / (2 * a);
123         ans.second.second = 0.0;
124     }else{
125         ans.first.first = -b / (2 * a);
126         ans.first.second = sqrt(-D) / (2 * a);
127         ans.second.first = -b / (2 * a);
128         ans.second.second = -sqrt(-D) / (2 * a);
129     }
130 }
131
132 double complex_check(const value_pair& last, const value_pair& cur){
133     pair<double, double> r1, r2;
134     // x[j]
135     r1.first = cur.first.first - last.first.first; // x
136     r1.second = cur.first.second - last.first.second; // y
137     // x[j+1]
138     r2.first = cur.second.first - last.second.first; // x
139     r2.second = cur.second.second - last.second.second; // y
140     return max(sqrt(r1.first*r1.first + r1.second*r1.second), sqrt(r2.first*r2.first +
141         r2.second*r2.second));
142 }
143
144 // QR separate by Hausholder matrix:
145 void QRseparate_method(const Matrix& A, Matrix& Q, Matrix& R){
146     Matrix E(A.get_n(), A.get_m());
147     E.make_ones();
148     Q = E;
149     R = A;
150
151     for(int j = 0; j < R.get_m() - 1; ++j){
152         vector<double> v(R.get_n(), 0.0);
153         double norm = 0.0;
154
155         // compute vector v:
156         // first non zero elem:

```

```

155     v[j] = R[j][j];
156     for(int i = j; i < R.get_n(); ++i){
157         norm += R[i][j] * R[i][j];
158     }
159     norm = sqrt(norm);
160     v[j] += sign(R[j][j]) * norm;
161
162     // another elements:
163     for(int i = j + 1; i < R.get_n(); ++i){
164         v[i] = R[i][j];
165     }
166
167     // compute Hausdorf matrix:
168     Matrix H = E - (2.0 / mult_1xn_nx1_vecs(v, v)) * mult_nx1_1xn_vecs(v, v);
169
170     // update matrix:
171     Q = Q * H;
172     R = H * R;
173 }
174 }
175
176 int QRmethod_values(const Matrix& A, vector<pair<double, double>>& x, double alfa){
177     Matrix Q, R, A_k = A;
178     x.resize(A_k.get_m());
179     int itter = 0;
180     double check;
181     value_pair curr;
182     bool flag = true;
183
184     for(itter = 0; flag; ++itter){
185         QRseparate_method(A_k, Q, R); // separate
186         A_k = R * Q; // update A_k
187
188         //check:
189         flag = false;
190         for(int j = 0; j < A_k.get_m(); ++j){
191             check = 0.0;
192             for(int i = j + 1; i < A_k.get_n(); ++i){
193                 check += A_k[i][j] * A_k[i][j];
194             }
195             check = sqrt(check);
196
197             if(check > alfa){
198                 solve_eq(1.0, -A_k[j][j]-A_k[j+1][j+1], A_k[j][j]*A_k[j+1][j+1]-A_k[j
199                     +1][j]*A_k[j][j+1], curr);
200                 if(complex_check(curr, value_pair(x[j], x[j+1]))) > alfa){
201                     flag = true;
202                 }
203                 x[j] = curr.first;

```

```

203         x[j + 1] = curr.second;
204         ++j;
205     }else{
206         x[j].first = A_k[j][j];
207         x[j].second = 0.0;
208     }
209 }
210 // end of check
211 }
212 // if flag == false => check is true and stop iteration
213 return itter;
214 }
215
216 int main(){
217     ave();
218
219     Matrix A;
220     vector<pair<double, double>> x;
221     double accuracy = 0.01;
222     int size = size_init();
223     matrix_init(A, size);
224     cin >> accuracy;
225     print_statement(A, accuracy);
226
227     //QR:
228     cout << "QR Method:" << endl;
229     int itter = QRmethod_values(A, x, accuracy);
230     print_solution(x, itter);
231     bye();
232
233     return 0;
234 }

```


2 Демонстрация работы

```
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ make all
g++ -std=c++17 -Wall -pedantic -c task1.cpp
g++ -std=c++17 -Wall -pedantic -c Matrix/matrix.cpp -o Matrix/matrix.o
g++ task1.o Matrix/matrix.o -o task1
rm -rf task1.o
g++ -std=c++17 -Wall -pedantic -c task2.cpp
g++ task2.o Matrix/matrix.o -o task2
rm -rf task2.o
g++ -std=c++17 -Wall -pedantic -c task3.cpp
g++ task3.o Matrix/matrix.o -o task3
rm -rf task3.o
g++ -std=c++17 -Wall -pedantic -c task4.cpp
g++ task4.o Matrix/matrix.o -o task4
rm -rf task4.o
g++ -std=c++17 -Wall -pedantic -c task5.cpp
g++ task5.o Matrix/matrix.o -o task5
rm -rf task5.o
rm -rf Matrix/matrix.o
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ ./task1 <data/m
m1.txt m2.txt m3.txt m4.txt m5.txt
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ ./task1 <data/m1.txt
=====
|                                LABORATORY WORK №1                                |
|                                NUMERICAL METHODS                                |
|                                Task №1                                           |
|                                Variant №4                                        |
|                                                                              |
|                                Student: Bronnikov M.A.                         |
|                                Date: 23.02.2020                               |
|                                                                              |
|                                                                              |
|                                Moscow, 2020                                    |
|                                                                              |
=====
|                                EXERCISE:                                       |
|                                                                              |
=====
| We need to solve SLAU by LU separating matrix with Gauss |
| method. Find determinant, back matrix, L and U matrix.   |
```

```

=====
SLAU matrix:
Matrix 4x4:
2      7      -8      6
4      4      0      -7
-1     -3      6      3
9      -7     -2     -8

Free vector:
-39
41
4
113
=====

=====
|                                ANSWER:                                |
=====

L matrix:
Matrix 4x4:
1      0      0      0
2      1      0      0
-0.5   -0.05   1      0
4.5     3.85 -9.85714  1

=====

U matrix:
Matrix 4x4:
2      7      -8      6
0     -10     16     -19
0      0     2.8     5.05
0      0      0  87.9286

=====

Back matrix:
Matrix 4x4:
0.102356 0.0718928 0.161251 0.0743298
0.039805 0.111292 0.034931 -0.0544273
-0.00365556 0.0867181 0.154955 -0.0205118
0.0812348 -0.0381803 0.112104 0.0113729
=====

```

```

x solution:
x1 = 8 x2 = -3 x3 = 2 x4 = -3
=====
Determinant: -4924
=====
|                                     |
|                               EXIT |
|                                     |
=====
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ ./task2 <data/m2.txt
=====
|                                     |
|          LABORATORY WORK №1      |
|          NUMERICAL METHODS        |
|          Task №2                  |
|          Variant №4               |
|                                     |
|                                     |
|          Student: Bronnikov M.A.  |
|          Date: 23.02.2020         |
|                                     |
|                                     |
|          Moscow,2020              |
|                                     |
=====
|                                     |
|          EXERCISE:                |
|                                     |
=====
| We need to solve SLAU by race method. |
=====
SLAU matrix:
Matrix 5x5:
-14    -6     0     0     0
-9     15    -1     0     0
0       1   -11     1     0
0       0    -7    12     3
0       0     0     6    -7

Free vector:
-78
-73
-38
77
91
=====

```

```

=====
|                                ANSWER:                                |
=====

x solution:
x1 = 5.99374 x2 = -0.985396 x3 = 4.27539 x4 = 10.0146 x5 = -4.41602
=====

|                                EXIT                                |
=====

(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ ./task3 <data/m3.txt
=====

|                                LABORATORY WORK №1                                |
|                                NUMERICAL METHODS                                |
|                                Task №3                                |
|                                Variant №4                                |
|                                                                |
|                                Student: Bronnikov M.A.                |
|                                Date: 23.02.2020                        |
|                                                                |
|                                                                |
|                                Moscow, 2020                            |
=====

|                                EXERCISE:                                |
=====

| We need to solve SLAU by simple iteration and Zeidel |
| methods. Analyse count of iterations with accuracy.  |
=====

SLAU matrix:
Matrix 4x4:
26      -9      -8      8
9       -21     -2      8
-3       2     -18      8
1       -6     -1     11

Free vector:
20
-164
140
-81

```

Accuracy: 0.001

Simple Iterations Method:

| ANSWER: |

x solution:

x1 = 1.99999 x2 = 8.00001 x3 = -9 x4 = -4.00001

Iterations: 40

Zeidels Method of Iterations:

| ANSWER: |

x solution:

x1 = 1.99999 x2 = 7.99999 x3 = -9 x4 = -4

Iterations: 11

| EXIT |

(base) max@max-Lenovo-B50-30:~/NumMethods/lab1\$./task4 <data/m4.txt

| LABORATORY WORK №1 |

| NUMERICAL METHODS |

| Task №4 |

| Variant №4 |

| |

| Student: Bronnikov M.A. |

| Date: 24.02.2020 |

| |

| |

| Moscow, 2020 |

| EXERCISE: |

| We need to find vectors and values of symmetric matrix |

| by rotate method. |

```

=====
Simmetric matrix:
Matrix 3x3:
8      2      -1
2      -5     -8
-1     -8     -5

Accuracy: 0.01
=====
Rotate Method:
=====
|                                ANSWER:                                |
=====
Values:
l1 = 8.79893 l2 = -13.0241 l3 = 2.22517
=====
Vectors:
x1:
0.938312
0.265083
-0.222039

x2:
-0.0340734
0.709877
0.703501

x3:
0.344106
-0.652538
0.675118

=====
Itterations: 4
=====
|                                EXIT                                |
=====
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$ ./task5 <data/m5.txt
=====
|                                LABORATORY WORK №1                                |
=====

```

```

|               NUMERICAL METHODS               |
|               Task №5                          |
|               Variant №4                      |
|                                               |
|               Student: Bronnikov M.A.        |
|               Date: 25.02.2020               |
|                                               |
|               Moscow, 2020                   |
|=====|
|=====|
|               EXERCISE:                      |
|=====|
| We need to find values of matrix using QR separation. |
|=====|
Matrix:
Matrix 3x3:
-4      -6      -3
-1       5      -5
 6       2       5

Accuracy: 0.05
|=====|
QR Method:
|=====|
|               ANSWER:                      |
|=====|
Values:
l1 = 7.10756
l2 = -0.553782 + 3.8273i
l3 = -0.553782 -3.8273i

|=====|
Iterations: 11
|=====|
|=====|
|               EXIT                        |
|=====|
(base) max@max-Lenovo-B50-30:~/NumMethods/lab1$

```

3 Выводы

Выполнив первую лабораторную работу по курсу «Численные методы», я получил новые знания о методах решения систем линейных алгебраических уравнений.

Кроме этого я самостоятельно реализовал самые основные из них, а также узнал об основных проблемах этих методов, таких как наличие нулей на главной диагонали.

Я рад, что я познакомился с этой темой и уверен что полученные знания и опыт я еще не раз применю на практике в будущем.