

Signals and Communication Systems

Laplace Transform

Laplace Transform

(Generalization of Fourier Transform)

Laplace Transform

Laplace Transform is referred to as generalization of FT.

$$X(s) = \int_{-\infty}^{\infty} x(t)e^{-st}dt \quad \text{Analysis equation}$$

$$x(t) = \frac{1}{2\pi j} \int_{\sigma-j\Omega}^{\sigma+j\Omega} X(s) e^{st} d\Omega \quad \text{Synthesis equation}$$

- ❖ For $s = \sigma + j\Omega$, $X(\sigma + j\Omega) = \int_{-\infty}^{\infty} x(t)e^{-(\sigma + j\Omega)t} dt$

$$= \int_{-\infty}^{\infty} \{e^{-\sigma t} x(t)\} e^{-j\Omega t} dt .$$

That is LT can be interpreted as FT of $\{e^{-\sigma t} x(t)\}$.

- ❖ If $s = j\Omega$, then above equations becomes FT.

- ❖ We note, in particular, that just as the Fourier transform does not converge for all signals, the Laplace transform may converge for some values of $\text{Re}\{s\}$ and not for others.
- ❖ ROC: In general, the range of values of ' s ' for which the integral converges is referred to as the *region of convergence* (ROC) of the Laplace transform.
- ❖ The Laplace transform depends on a complex variable $s = \sigma + j\Omega$, composed of damping σ and frequency Ω , while the Fourier transform considers only frequency Ω .

LT of standard signals:

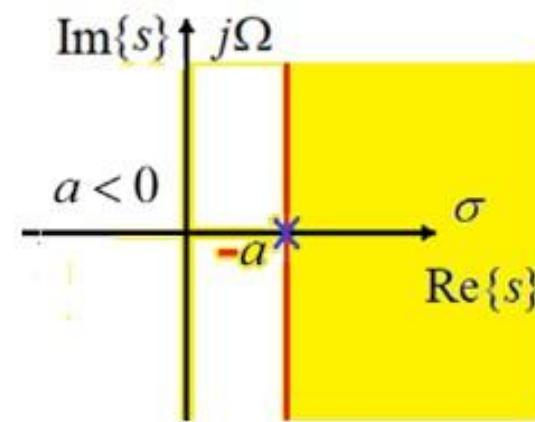
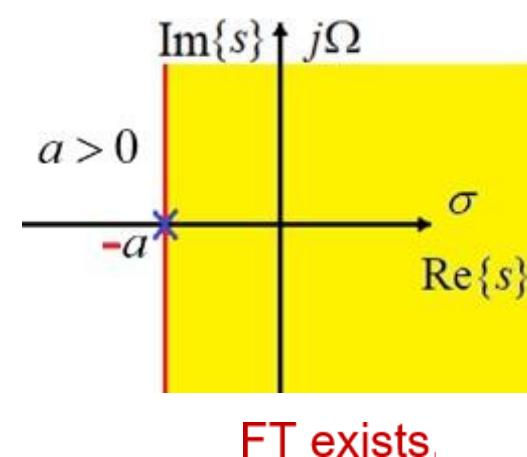
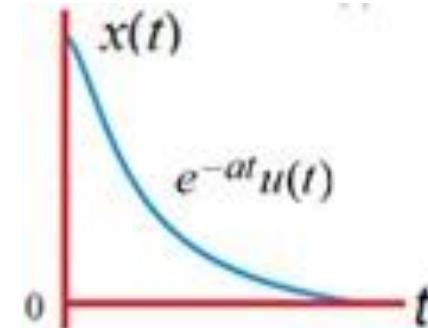
Right sided Signals: $x(t) = e^{-at} u(t)$

$$\begin{aligned}
 X(s) &= \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_{-\infty}^{\infty} e^{-at} u(t) e^{-st} dt \\
 &= \int_0^{\infty} e^{-(s+a)t} dt = -\frac{1}{s+a} \left[e^{-(s+a)t} \right]_0^{\infty} \\
 &= \frac{1}{s+a}, \quad \text{Re}(s+a) > 0 \quad \text{or} \quad \text{Re}(s) > -a
 \end{aligned}$$

$$X(s) = \frac{1}{s+a}, \quad \text{Re}\{s\} > -a$$

$$e^{-at} u(t) \quad \xleftrightarrow{\text{L.T.}} \quad \frac{1}{s+a}, \quad \text{Re}\{s\} > -a$$

We observe that: Zeros - Nil
Poles at $s = -a$



Ex1: Find the LT of a signal $x(t) = e^{-2t}u(t)$.

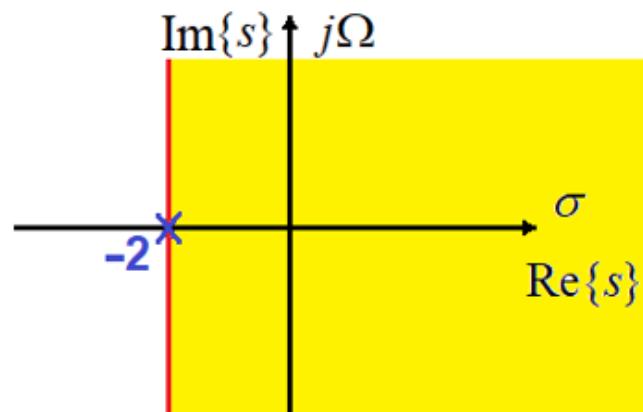
Sketch the pole-zero diagram and indicate the ROC.

Ans:

$$\text{We know that } e^{-at}u(t) \xleftarrow{\text{L.T}} \frac{1}{s+a}, \quad \text{Re}\{s\} > -a$$

$$\text{Then } e^{-2t}u(t) \xleftarrow{\text{L.T}} \frac{1}{s+2}, \quad \text{Re}\{s\} > -2$$

A pole at $s = -2$. The pole zero diagram with ROC is shown in figure.



Ex2: Find the LT of a signal $x(t) = e^{-2t}u(t) + e^{-3t}u(t)$.

Sketch the pole-zero diagram and indicate the ROC.

Ans: We know that $e^{-2t}u(t) \xleftarrow{\text{L.T.}} \frac{1}{s+2}$, $\text{Re}\{s\} > -2$,

and $e^{-3t}u(t) \xleftarrow{\text{L.T.}} \frac{1}{s+3}$, $\text{Re}\{s\} > -3$

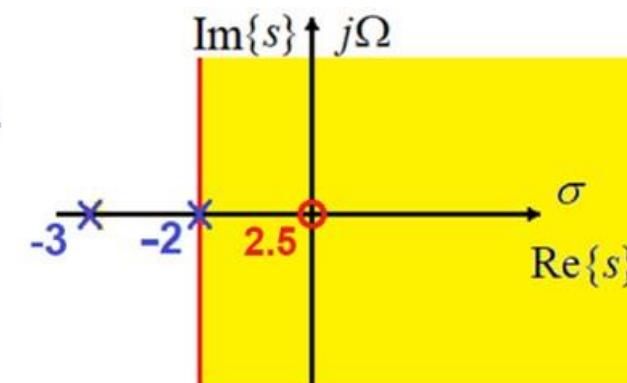
$$\text{Combinedly, } X(s) = \frac{1}{s+2} + \frac{1}{s+3} = \frac{2s+5}{s^2+5s+6}, \text{ Re}\{s\} > -2$$

ROC $\text{Re}\{s\} > -2$ is chosen as the common area of $\text{Re}\{s\} > -2$ and $\text{Re}\{s\} > -3$

We observe that Zeros: A zero at $s = 2.5$, and |

Poles: Two poles: at $s = -2$ and $s = -3$.

The pole zero diagram with ROC is shown in figure.



Ex3. Find the signal $x(t)$ if $X(s) = \frac{2s+5}{s^2 + 5s + 6}$, $\text{Re}\{s\} > -2$

Ans: By partial fraction expansion,

$$X(s) = \frac{2s+5}{(s+2)(s+3)} = \frac{A}{(s+2)} + \frac{B}{(s+3)} = \frac{1}{(s+2)} + \frac{1}{(s+3)}$$

Since the ROC $\text{Re}\{s\} > -2$, the signal is right sided signal.

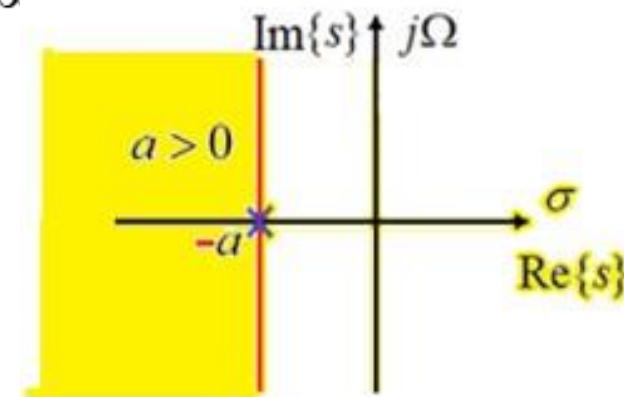
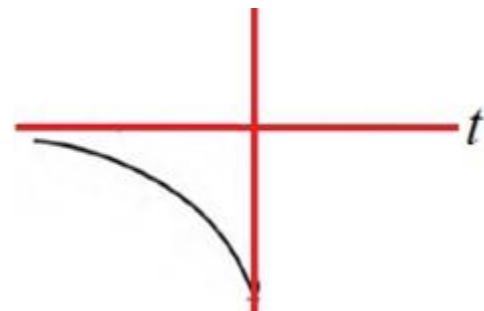
With a standard format $e^{-at}u(t) \xleftarrow{\text{L.T}} \frac{1}{s+a}$, $\text{Re}\{s\} > -a$

We found that $x(t) = e^{-2t}u(t) + e^{-3t}u(t)$

Left sided Signals: $x(t) = -e^{-at}u(-t)$

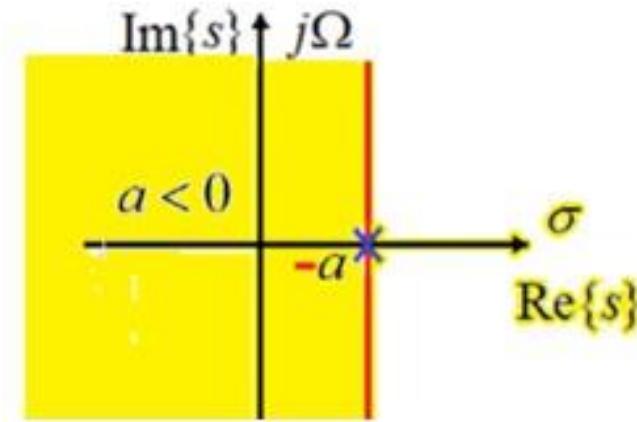
$$\begin{aligned}
 X(s) &= \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_{-\infty}^{\infty} -e^{-at}u(-t) e^{-st} dt \\
 &= \int_{-\infty}^{0} -e^{-(s+a)t} dt = \frac{1}{s+a} \left[e^{-(s+a)t} \right]_{-\infty}^0 \\
 &= \frac{1}{s+a}, \quad \text{Re}(s) < -a
 \end{aligned}$$

$$-e^{-at}u(-t) \quad \xleftarrow{\text{L.T}} \quad \frac{1}{s+a}, \quad \text{Re}\{s\} < -a$$



We observe that: Zeros - Nil

Poles at $s = -a$



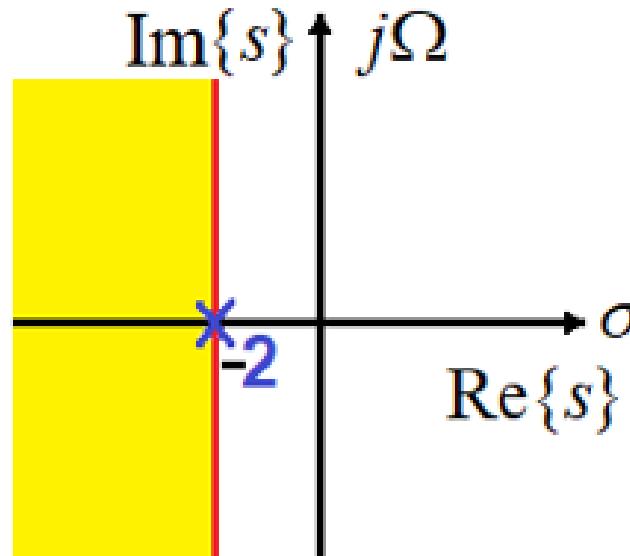
Ex4: Find the LT of a signal $x(t) = -e^{-2t}u(-t)$.

| Sketch the pole-zero diagram and indicate the ROC.

Ans: We know that $-e^{-at}u(-t) \xleftarrow{\text{L.T}} \frac{1}{s+a}$, $\text{Re}\{s\} < -a$

Then $-e^{-2t}u(-t) \xleftarrow{\text{L.T}} \frac{1}{s+2}$, $\text{Re}\{s\} < -2$

A pole at $s = -2$. The pole zero diagram with ROC is shown in figure.



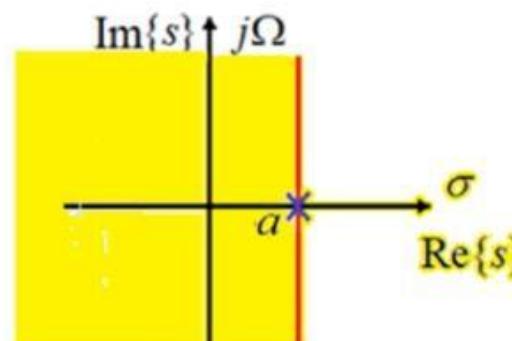
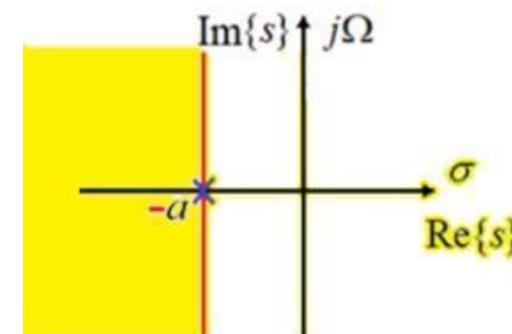
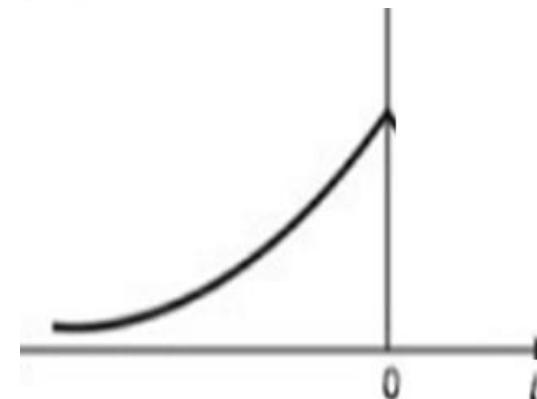
Ex5: Find the LT of a signal $x(t) = e^{at}u(-t)$.

Sketch the pole-zero diagram and indicate the ROC.

Ans: Using direct LT integral formula

$$\begin{aligned} X(s) &= \int_{-\infty}^{\infty} x(t) e^{-st} dt = \int_{-\infty}^{\infty} e^{at} u(-t) e^{-st} dt \\ &= \int_{-\infty}^0 e^{-(s-a)t} dt = -\frac{1}{s-a} \left[e^{-(s-a)t} \right]_{-\infty}^0 \\ &= -\frac{1}{s-a}, \quad \text{Re}(s) < a \end{aligned}$$

$$e^{at}u(-t) \xleftarrow{\text{L.T}} -\frac{1}{s-a}, \quad \text{Re}\{s\} < a$$



Two sided Signals: $x(t) = e^{-a|t|}$

The time domain representation of signal is shown below:

The given signal can be represented as

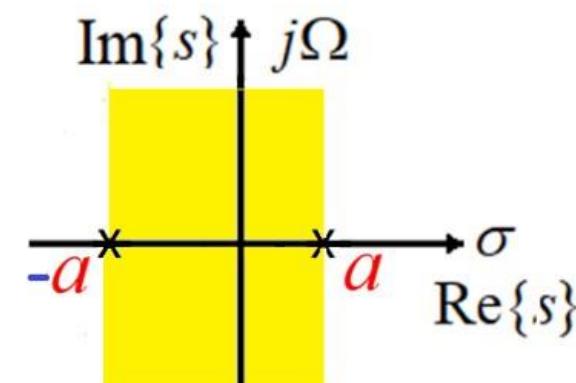
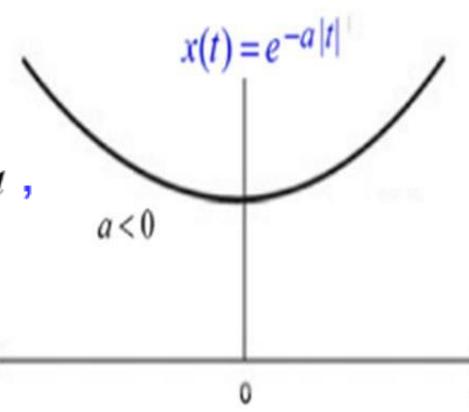
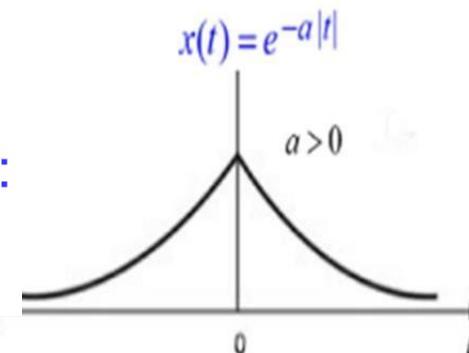
$$x(t) = e^{-a|t|} = e^{-at}u(t) + e^{at}u(-t)$$

We know that $e^{-at}u(t) \xrightarrow{\text{L.T.}} \frac{1}{s+a}$, $\text{Re}\{s\} > -a$,

and $e^{at}u(-t) \xrightarrow{\text{L.T.}} -\frac{1}{s-a}$, $\text{Re}\{s\} < a$

Then $e^{-a|t|} \xrightarrow{\text{L.T.}}$

$$\frac{1}{s+a} - \frac{1}{s-a} = \frac{-2a}{s^2 - a^2}$$
, $-a < \text{Re}\{s\} < a$



Ex6: Sketch the pole-zero diagram and find the signal $x(t)$,

$$\text{if } X(s) = \frac{2}{s^2 - 9}, \quad -3 < \text{Re}\{s\} < 3.$$

Ans: The pole-zero diagram with ROC is shown in figure:

Given that $X(s) = \frac{2}{s^2 - 9}$, $-3 < \text{Re}\{s\} < 3$ which is a LT of two-sided signal.

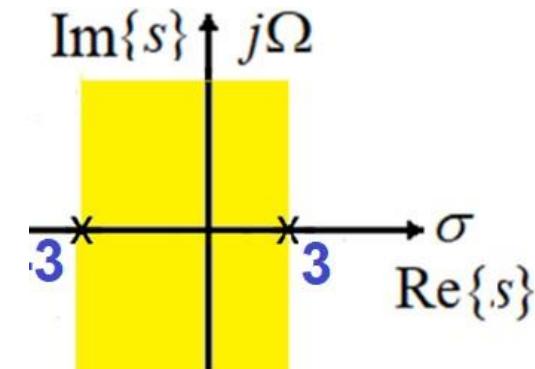
We know that $e^{-a|t|} \xleftarrow{\text{L.T.}} \frac{2a}{s^2 - a^2}, \quad -a < \text{Re}\{s\} < a$

From the given equation, we observe that $a = 3$,
and the given equation can be represented as

$$X(s) = \frac{2a}{s^2 - a^2} = \frac{2}{s^2 - 9} = 2 \cdot \frac{1}{6} \left(\frac{6}{s^2 - 3^2} \right) = \frac{1}{3} \left(\frac{6}{s^2 - 3^2} \right)$$

Therefore $X(s) = \frac{1}{3} \left(\frac{6}{s^2 - 3^2} \right), \quad -3 < \text{Re}\{s\} < 3 \xleftarrow{\text{L.T.}} x(t) = \frac{1}{3} e^{-3|t|}$

The required signal is $x(t) = \frac{1}{3} e^{-3|t|}$



Ex7: Find the LT and sketch the pole zero diagrams with ROC for the following signals.

- (a) $x(t) = e^{-2t}u(t) + e^{-3t}u(t)$ (b) $x(t) = e^{2t}u(-t) + e^{-3t}u(t)$ (c) $x(t) = e^{2t}u(t) + e^{-3t}u(-t)$

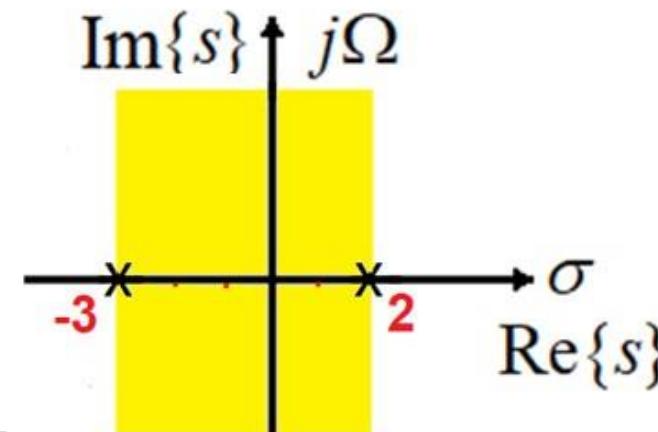
Ans: (a) Refer Ex2.

(b) Given that $x(t) = e^{2t}u(-t) + e^{-3t}u(t)$

We know that $e^{2t}u(-t) \xleftarrow{\text{L.T}} -\frac{1}{s-2}$, $\text{Re}\{s\} < 2$, and

$$e^{-3t}u(t) \xleftarrow{\text{L.T}} \frac{1}{s+3}, \quad \text{Re}\{s\} > -3$$

Combinedly, $X(s) = -\frac{1}{s-2} + \frac{1}{s+3} = \frac{-5}{s^2+s-6}$, $-3 < \text{Re}\{s\} < 2$



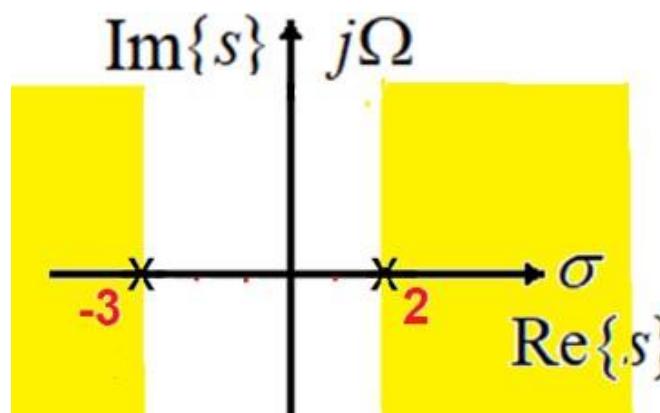
(c) Given that $x(t) = e^{2t}u(t) + e^{-3t}u(-t)$

We know that $e^{2t}u(t) \xleftarrow{\text{L.T}} \frac{1}{s-2}$, $\text{Re}\{s\} > 2$,

and $e^{-3t}u(-t) \xleftarrow{\text{L.T}} -\frac{1}{s+3}$, $\text{Re}\{s\} < -3$

Combinedly,

$$X(s) = -\frac{1}{s-2} - \frac{1}{s+3} = \frac{1}{s^2 + s - 6}, \quad -3 > \text{Re}\{s\} > 2$$



Ex8: Consider a LT of signal is given by $X(s) = \frac{2s+5}{s^2 + 5s + 6}$.

Find the corresponding right sided, left sided and two-sided signals.

Ans: By partial fraction expansion,

$$X(s) = \frac{2s+5}{(s+2)(s+3)} = \frac{A}{(s+2)} + \frac{B}{(s+3)} = \frac{1}{(s+2)} + \frac{1}{(s+3)}$$

From the given equation, we observe that there two poles at $s = -2$ and $s = -3$.

Case(i): Right sided signal: For right-sided signal, the ROC must be $\text{Re}\{s\} > -2$

Therefore, the required signal is $x(t) = e^{-2t}u(t) + e^{-3t}u(t)$

Case(ii): Left sided signal: For left-sided signal, the ROC must be $\text{Re}\{s\} < -3$.

Therefore, the required signal is $x(t) = -e^{-2t}u(-t) - e^{-3t}u(-t)$

Case(iii): Two sided signal: For two-sided signal, the ROC must be $-3 < \text{Re}\{s\} < -2$.

Therefore, the required signal is $x(t) = -e^{-2t}u(-t) + e^{-3t}u(t)$

Exercise1: Sketch the pole zero diagrams and indicate the ROC and find the inverse LT of the following signals.

(a) $X(s) = \frac{1}{s^2 + 5s + 6}$, $\text{Re}\{s\} > -2$ **(b)** $X(s) = \frac{2s+4}{s^2 + 4s + 3}$, $\text{Re}\{s\} > -1$

(c) $X(s) = \frac{-5}{s^2 + s - 6}$, $-3 < \text{Re}\{s\} < 2$

Comparison between FT and LT

Signal	FT	LT
$\delta(t)$	1, for all Ω	1, ROC is the entire 's-plane'
$u(t)$	$\pi \delta(\Omega) + \frac{1}{j\Omega}$	$\frac{1}{s}$, $\text{Re}\{s\} > 0$
$e^{-at}u(t)$	$\frac{1}{a + j\Omega}$	$\frac{1}{s + a}$, $\text{Re}\{s\} > -a$
$-e^{-at}u(-t)$	$-\frac{1}{a + j\Omega}$	$\frac{1}{s + a}$, $\text{Re}\{s\} < -a$
$e^{at}u(-t)$	$\frac{1}{a - j\Omega}$	$-\frac{1}{s - a}$, $\text{Re}\{s\} < a$
$e^{-a t }$	$\frac{2a}{a^2 + \Omega^2}$	$\frac{2a}{s^2 - a^2}$, $-a < \text{Re}\{s\} < a$

Comparison between FT and LT

Signal	FT	LT
Time shifting Property. $x(t - t_0)$	$e^{-j \Omega t_0} X(j\Omega)$	$e^{-s t_0} X(s)$
Frequency shifting property	$e^{j \Omega_0 t} x(t) \xleftrightarrow{\text{F.T.}} X(j(\Omega - \Omega_0))$	$e^{s_0 t} x(t) \xleftrightarrow{\text{L.T.}} X(s - s_0)$
Time differentiation property $\frac{d}{dt} x(t)$	$j\Omega X(j\Omega)$	$s X(s)$
Time Convolution property $x(t) * h(t)$	$X(j\Omega) H(j\Omega)$	$X(s)H(s)$

End