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## **Project Four – Power in Community:**

### **Solving an Open-Ended Design Problem**

*ENGINEER 1P13 – Integrated Cornerstone Design Projects*

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Tutorial T05

Team Tues-26

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Due: April 15, 2021

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***Academic Integrity Statement***

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## ***Executive Summary***

For this project, we were faced with an open-ended design problem which we had to solve for a client. The client expressed trouble in the form of pain, fatigue, and general discomfort in her arms and leading into her hands while in her place of residence. This affects her on a day-to-day basis in her home, and therefore is the most prominent issue that needs to be solved to improve quality of life for our client. Our group decided that the best course of action was to ease the pain associated with painting, since painting greatly improved her enjoyment of life. Our final prototype as seen in Figure 1 is a sliding rail system which supports her arm as she paints so that she does not spoil her painting. This device reduces pain in her arm and upper body by keeping



*Figure 1: Final Prototype*

her arm elevated, so she does not have to do it herself. This prototype solves the problem by improving quality of life for our client, as was an overarching goal for the motivation behind his project (Figure 2). This prototype benefits the client by conforming to many of the requirements outlined in the client notes, such as the need for comfortability (Figure 3). Currently in the market, there is no device such as this one which does the same thing, making our device unique and innovative. Finally, if we had more time and money to invest in this project, we would have liked to integrate other mechanical advantages into the design, such as hydraulics and robotics which would make our device usable on both horizontal and vertical surfaces (i.e., easel).

## ***Introduction***

Our client is a retired midwife, and the mother of multiple children. In the past few years, she has developed passions in visual arts, as well as gardening, Brazilian Jiu Jitsu, and yoga, but these interests of hers, as well as essential abilities such as preparing meals and cleaning her house, have been hindered as a result of multiple physical disabilities. Previously, she had been a survivor of breast cancer, and it is evident that one of her surgeries had caused damage to her lymphatic system as she has been diagnosed. Lymphedema is a buildup of fluid known as lymph (which normally carries foreign material and bacteria away from bodily tissues), that results in swelling in the soft tissues of a limb [1]. The condition is lifelong, although it can be remedied in the short term with compression therapy, which our client applies frequently (our upcoming design solution takes

advantage of this fact) [2]. This swelling may result in pinched nerves in the axilla, restricting fine movements in the client's limbs [3]. The client's day-to-day life is also affected by both ankylosing spondylitis and fibromyalgia. Her ankylosing spondylitis leads to lower back pain, fatigue and stiffness, especially after periods of inactivity. This makes it difficult for her to perform tasks that involve flexibility, such as gardening. Similarly, fibromyalgia takes its toll on the client through pain and stiffness in soft tissues around the body, especially in the muscles that control the hands [4].

In summary, the client expresses trouble in the form of pain, fatigue, and general discomfort in her limbs, back, and hands while in her home, which affects her on a daily basis and therefore is the most prominent issue that must be solved, constituting our problem statement. She spends a lot of time engaging in her painting hobby, and the goal of this project is to liberate her from the disabilities that prevent her from doing so. The objectives are to ease pain associated with movement, add predictability to her routine, and make her usual tasks easier for her to accomplish. The solution must be reliable, easy for the client to use, and result in a noticeable increase in her quality of life. Additionally, although less important, the design should be simple and thus easy to understand and repair, and also cost effective, to make it more feasible.

Currently, there are no products in the market that perform the same task that this design does in the same manner, however, inspiration was gathered from systems that can easily be moved in a fixed two-dimensional area, such as monitor arms, which also have the ability to bear a lot of weight.

## ***Conceptual Design***

Throughout the project we were required to put ideas into action by creating physical prototypes based on our ideas. To start the ideation process, we took note of the client's main issues and needs (Figure 2) and based our design space on that. We took note of our group's individual skills/abilities (Figure 4), then explored the design space using functional analysis (Figure 5). After we generated many ideas, we decided to break off and focus on coming up with a feasible idea that we may focus on to be a final prototype. We met up with our individual ideas and decided to use a weighted decision matrix to decide which design we were going to focus on (Figures 6,7). We came up with criteria for the decision matrix based on the objectives and constraints of the project, which gave us a good idea of which criteria were the most important for the design. The ideas we came up with (Figures 1,8,9) were compared with each other, and we decided that the sliding rail arm support idea was the best and most feasible. Even though the sliding rail arm support idea did not have the highest rating on our decision matrix, we used the decision matrix to analyze and create talking points about the devices. After refining the prototype and showing it to the TAs, they had little to say, giving feedback only on the aesthetic

aspect of the prototype. We took the feedback and created a more ‘personalized’ version of the prototype, which showcased the engineering fireball and breast cancer ribbons in support of our client (Figure 1).

## ***Final Proposed Design***

### **Design Description**

Our final proposed design is a streamlined version of our final prototype and is modeled and simulated in Autodesk Inventor [20]. The system uses a tracking system similar to that of a railway, as well as a modular component that allows the design to work on almost any horizontal surface of any size. The completed design model (Figures 24.1 – 24.3) uses a spring-loaded arm rest on an aluminum slider (Figure 29) to provide comfort to the client while using the system.

The axis track allows for canvas sizes of up to 89cm in one direction, as it expands from an internal width from 47.5cm to 89cm. The changeable width allows for use in/on multiple surfaces as well as changing canvas sizes.

To allow the armrest to slide, the design uses four rails, 2 on the female slider (Figure 16), and 2 on the male slider (Figure 18) for stability when sliding and also when transferring the sliding arm part (Figure 22) between the female and male sliders. The ends of the slider rails are rounded on the transferring edges of the male and female sliders to avoid jamming when transferring the sliding arm rest.

The ability for the system to be used on most surfaces is very important, and to do this a modular system was designed that provided 3 different types of end support, all with the same floor to rail distance so they can be mixed and interchanged between. All modules use a 2-pin system (Figures 11, 19) to connect to the ends of the female and male sliders, which is then held in place by a long pin (Figure 17) for the female slider, and a short pin (Figure 21) for the male slider. Both pins are made with a large easy grab handle for ease of use.

The first module uses castors (Figure 25) to provide a rolling function, as well as a second axis when used on both sides. This configuration would allow the client to reach and be supported on any part of the canvas. The castors are also free to rotate so that the design can be used with one end fixed, such that the design moves in a rotation motion with one end acting as the centre of rotation. This module is most effective on harder surfaces such as linoleum and hardwood, as well as thin carpet.

The second module (Figure 26) uses a stationary grip pad (Figure 20) to keep at least one end of the system stationary. An added function of the module acts as a holder for tools, paints, brushes, etc. for the client while she uses it. The pad connects to the pad module connector (Figure 19) by a rotational axis that allow the

entire system to rotate. The pad connector then connects to the main sliders using the modular connector and pin. The pad module can either be used on one or both sides of the sliding system (Figure 28) depending on the client's preferences and the surfaces available, although the surfaces must be flat.

The third module (Figure 27) uses a clamping system to hold one end of the rail system (Figure 28) to the end of a surface. It does this by using a threaded screw with a large handle (Figure 15) for easy manipulation, which is connected to a clamping pad (Figure 14) by a spherical lock which not only holds it in place but allows the pad to rotate in all directions to allow it to connect to the most obscure surfaces. The clamp connects to the rail system with the modular connector (Figure 19) with a single pin that also allows for the rotation of the rail system about the clamp when connected.

View [Figure 30](#) for an animation of the system in Autodesk Inventor's [20] dynamic simulation.

## Device Parts

### Armrest (Figure 9):

The armrest is crafted out of aluminum for its strength in the thinner parts where other materials would bend or break. The inside of the armrest contains a soft silk padding to add maximum comfort and cooling for the client's wrist with the hope that it will extend the amount of time being used. The Armrest connects to the sliding part (Figure 22) by a cylinder which is loaded with a spring (Figure 23) to add a bit of vertical adjustability.

### Sliding Part (Figure 22):

The sliding part is built of polished aluminum for its durability, and its ability to slide on the rails of the sliding system (Figure 28). It has 4 holes that lock it onto these sliders. The outside holes are for when the slider is connected to the female slider (Figure 16), and the inside holes are for when the slider is connected to the male slider (Figure 18). The sliding part holds the armrest through a spring-loaded chamber.

### Spring (Figure 23):

The spring is built from a soft steel to avoid breaking and cracking over time of usage. The spring sits between the armrest (Figure 9) and the sliding part (Figure 22) to act as a vertical adjustment for the user as well as added comfort.

### Female Slider (Figure 16):

The female slider is a mostly aluminum construction to stay strong while being lightweight, and to avoid cracking in the thinner spots of the part. The rails on the part connect with the outer holes of the sliding part (Figure 22) and the male slider (Figure 18) fits directly into the female slider. The modular connector on the slider is built out of wood as it is strong when solid and lighter than metal. The ends of the rails are rounded to allow for a smooth transition of the sliding part between the male and female sliders.

### Male Slider (Figure 18)

The male slider is built mostly out of wood and inserts directly into the female slider (Figure 16). Due to its solid construction and large size, the rectangular portion of the part is built out of wood for high strength and low weight. The rails on the part are made of polished aluminum and fit into the inner holes of the sliding part. The ends of the rails are rounded for a smooth transition between the female and male sliders. The part contains the same modular connector as the female slider allowing for interchangeable modules.

### Castor Mount (Figure 11):

The castor mount is what connects the castor arms (Figure 10) to the male and female sliders (Figures 18, 16 respectively) by two aluminum pins that fit into sized holes that is then fixed in place by either the long or short pin which is inserted perpendicularly to the two aluminum pins. The castor arms are connected through two holes in the bottom of the part that allow free rotation. The part is made from wood for its solid construction while being lightweight and strong.

### Castor Arm (Figure 10):

The castor arms are made from a steel construction due to its strength in small sizes. The post of the castor arm fits into the holes in the bottom of the castor mount (Figure 11). The castor wheels (Figure 12) fit on the axle of the castor arm.

### Castor Wheel (Figure 12):

The castor wheel is built from rubber coated plastic to stay lightweight while maintaining a good grip on whatever surface it is on with minimal slippage. The castor wheel connects to the castor arm (Figure 10) through the axle hole on the axle of the arm.



#### Pad Connector (Figure 19):

The pad connector is built from aluminum for its strength while being lightweight. The part has two large pins on the top that allow it to connect to the modular connector on the female and male sliders (Figures 18, 16 respectively). There is a pin connector in the base of the part to connect to the clamp frame (Figure 13) and pad (Figure 20). This pin allows the rotation of the entire system about the part.

#### Clamp Frame (Figure 13):

The clamp frame needs to hold the force of a tightened clamp, and therefore is built from mild steel. Although this is heavier, it is a smaller part and will not make much difference. The top of the clamp frame connects to the pad connector (Figure 19) which allows the clamp frame to rotate. The clamp frame holds a clamp screw (Figure 15) that applies pressure to the top of the clamp that has a rubber pad to prevent slipping and damage to the surface that it is clamped to. It also contains a steel rib to help support the compression force of the clamp.

#### Clamp Screw (Figure 15):

The clamp screw attaches by thread to the clamp frame (Figure 13). The clamp screw is made from nickel coated hardened steel to prevent warping of the threads from the compressive force of the clamp. The clamp screw has a long rubber coated arm which allows for easy turning of the screw and plenty of leverage so not much force is needed to tighten the clamp. The top of the clamp screw is spherical to connect to the clamp pad (Figure 14) while allowing it to freely rotate.

#### Clamp Pad (Figure 14):

The clamp pad is made of mild steel to prevent warping and has a rubber pad on the top to reduce slippage and increase clamping ability. The bottom of the clamp has a spherical slot to connect to the clamp screw (Figure 15) and allow free rotation of the clamp pad.

#### Pad (Figure 20):

The pad is built from an aluminum and wood construction and has the purpose of securing the system to a flat surface. The tray of the pad is built from wood for its light weight and its strength. The underside of the wooden tray is lined with rubber to reduce slipping on flat surfaces. The aluminum shaft of the part connects the wooden tray to the pad connector (Figure 19) that allows free rotation of the system when connected.

Short/Long Pin (Figures 21, 17 respectively):

The short and long pins connect any of the modules (Figures 25, 26, 27) to the male and female sliders (Figures 18, 16 respectively). The pin is made from mild steel for its strength as the part is thin. The handle of the pin is made from rubber coated aluminum for lightweight and its ease to grip the large handle. The short pin is used in the male slider and the long pin is used in the female slider

### **How the Design Meets Objectives**

Objective 1: Ease pain associated with movement of the client. Metric: Pain scale of 1-10

The proposed design in practice will be able to ease the pain caused by the client's challenges by reducing the overall stress on her body while painting. This will allow her to paint for longer periods of time which will not only make it more efficient but will also provide a moral boost. We plan to measure this by reading her pain scale while using the device and not using the device.

Objective 2: Add predictability to day-to-day life of the client. Metric: Consistent ratio of planned to completed tasks

The design can help add predictability to day-to-day life by aiding in the reduction of pain. If the client is painting in a comfortable position, there will be less pain throughout the day that had previously been caused by discomfort from painting. This can be measured by calculating the ratio of planned to completed tasks before and after the device is introduced in to daily life.

Objective 3: Make general problematic tasks easier to accomplish for the client. Metric: Average time to complete tasks

Assuming that the design can reduce overall pain, this will allow the client to complete other tasks in a faster time frame. We can measure this by recording time to complete daily tasks on several occasions before and after the device has begun being used.

## ***Conclusions***

Currently, the team is in the prototype iteration phase. Thus, in order to make further progress, one of the next steps are to test the prototype in a more meaningful way; allowing the client to try the mechanism herself, and gauging her level of satisfaction in our criteria. This will give our team plenty of further insight into the client's desires, and is advantageous since all of our objectives are centered on our client's satisfaction, and because there were few opportunities to communicate with the client to refine our idea with. The testing plans that we have composed will also need to be brought into fruition, such as the "non-slip test", which checks the ability of the wheels and non-slip pad to stay stationary when they are supposed to, and prevent slippage from beneath the user. New tests can be developed if we gather more information regarding what works for our client and what does not.

Over the course of the project, much of the team's work was done individually, with tasks delegated to each team member. This approach is effective in some circumstances, but is missing a significant aspect of communication, that is, peer feedback at every step in the process. This leads to the team meetings being sparse of content, as most of the brainstorming is done as individuals working on a subtask outside of meeting time. Reflecting on this, it appears that despite our work ethic as individuals, the team should strive to enhance precise communication interweaved with our working routine moving forwards. One way to achieve this is to have the project manager assign tasks to multiple group members instead of one, promoting discussion in the sub team, similarly to how the teams were split into graphics and computing sub teams in previous ENGINEER 1P13 design projects. Another way to improve communication in regards to the engineering design process is by creating a standard structure by which the team meetings are to be held. For example, the manager should create a meeting agenda before the meeting is held in order to justify its purpose and keep the meeting on track. In hindsight, having this plan in place will allow for more effective meetings that are concise and allow everyone to understand the status of the project and how it is moving forward.

## References Used in Report

- [1] “Lymphedema”, *Harvard Health Publishing*. Dec. 2018.
- [2] K. Johansson, K. Ochalek, and S. Hayes, “Prevention of arm lymphedema through the use of compression sleeves following breast cancer: results from a targeted literature review,” *Physical Therapy Reviews*, vol. 25, no. 4, pp. 213–218, Jul. 2020.
- [3] S. Klonisch, *Sobotta Clinical Atlas of Human Anatomy*, one volume, English, 2019.
- [4] M. Pérez-de-Heredia-Torres, R. M. Martínez-Piédrola, M. Cigarán-Méndez, R. Ortega-Santiago, C. Fernández-de-las-Peñas. “Bilateral deficits in fine motor control ability and manual dexterity in women with fibromyalgia syndrome”. *Experimental Brain Research*, vol. 226, pp. 137–143. January. 2013. doi: <https://doi.org/10.1007/s00221-013-3417-4>

## Appendices:

### Section 1

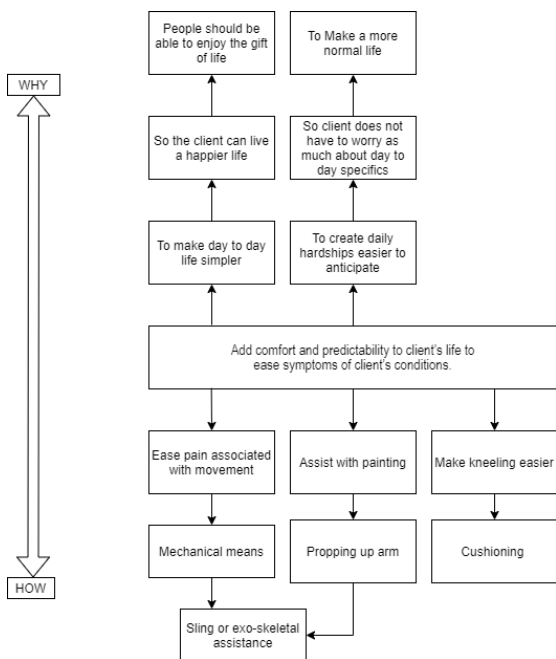


Figure 2 : How/Why Ladder

- She is 5'1.5"
- Her working area is about 4 feet by 7 feet.
- Uses spinal flexibility daily (e.g. to pick things up)
- Affected by extreme temperatures
- Uses angled brushes, enjoys precision brushes
- Uses handle-less brushes to use her whole hand, as it is more gentle on the hands
- Brush size is more of a problem than the brush weight
- Also does gardening
  - Bending over to maintain weeds is the most difficult part
- Doesn't do digital art
- 20-30mm of compression recommended for her
- Has to move constantly, staying still leads to problems and she must listen to her body
- Keeps cane at the top of staircase, step stool in washroom
- Velcro shouldn't be against her skin
- Her big painting is 39.5" by 39.5"
- The colder it is, the worse her pain is
  - Heat better than cold, but no extreme temperatures
- Before pandemic, running errands was difficult
  - Doesn't drive anymore
- Dealt with a lot of ableism, e.g. at grocery store, public transit
- Wants to take control of things that she would usually be responsible for
- No glutenous materials (e.g. paper mache)
- No rough materials
  - Cotton and silk are good for protection
- Wouldn't have painted on the floor if it wasn't for the pain
- Lives with nausea and dizziness, being on the floor stabilizes this and increases focus
- Arm gets tired before body when painting
- Exercises with ankle weights; leg lifts, leg fluttering, core strengthening exercises
- Pushing is easier than pulling because she can put her torso weight on the object
- Shoulder strap will most likely not work due to where lymphedema is
- Compression gear is kind of like very thick tights (nylon, spandex, etc.) like a bra from a 1970s movie?
- The more she can use her palm of her hand, the easier

Figure 3: Some Client Notes

## Section 2

Member	Prior prototyping experience	Relevant skills
Jackson Lippert	1P13: P2 – Modelling sub-team. P3 – Computing sub-team. Box design for business feasibility. Computer science course (Highschool)	Coding in C++ and Python Inventor Hands-on work with carpentry
Andrew Krynski	- P2 Computing Sub team - P3 Modelling Sub team	- Python, C, C++, Java - Solid works, Fusion360, Inventor - Woodworking, machining, welding (MIG, stick) - Kali Linux - Arduino
Ahmed Mohamed	▪ Inventor ▪ Autodesk 3ds Max ▪ Surgical tools box design for a Design Project ▪ Adobe Illustrator	▪ Drawing ▪ Constructing models of large buildings ▪ Car's maintenance
Borna Sadeghi	• See <a href="https://bornasadeghi.github.io">bornasadeghi.github.io</a>	Physical • Arduino • Raspberry Pi GPIO • 3D Printing Software • Server-side development • Game development • Machine Learning

Figure 4: List of relevant skills

Functions	Means 1	Means 2	Means 3	Means 4
Improve muscular endurance (in the arms/hands)	Sling to support weight of arm	Arm rest	Compression gear	Cold/hot compresses
Make painting easier	Remote-controlled painting machine	Pedal-controlled painting mechanism	Rubberized support attaching to the top of the canvas/easel	Easier accessibility to paints (easy to open jars etc.)
Reduce pain associated with gripping	Application of heat/cold	Application of compression/therapeutic massage	Application of remedial creams/fluids	Grip strength exercises by crushing the grip strength tool.
Improve dexterity/accuracy of hand movements	Knuckle stabilizer	Allow hands to rest and preform simple exercises	Easier, wider, and heavier tools to grip	Wrist weights/weighted glove

Figure 5: Functional Analysis

	Ease of use	Quality of life improvement	Cost effective	Reliability	Flexibility (useable for more than one task)	Design and manufacturing simplicity
Ease of use	N/A	0	0	1	0	0
Quality of life improvement	1	N/A	0	1	0	0
Cost Effective	1	1	N/A	1	1	1
Reliability	0	0	0	N/A	0	0
Flexibility (useable for more than one task)	1	1	0	1	N/A	1
Design and manufacturing simplicity	1	1	0	1	0	N/A
Total	4	3	0	5	1	2

Figure 6: Decision Matrix for Criteria

	Weight	Muscle sensor gripper	Arm support with casters	Elastic glove grip
Reliability	5	1	3	2
Ease of use	4	1	2	3
Quality of life improvement	3	3	1	2
Design and manufacturing simplicity	2	1	3	2
Flexibility (useable for more than one task)	1	2	1	3
Total		22	33	35

Figure 7: Weighted Decision Matrix

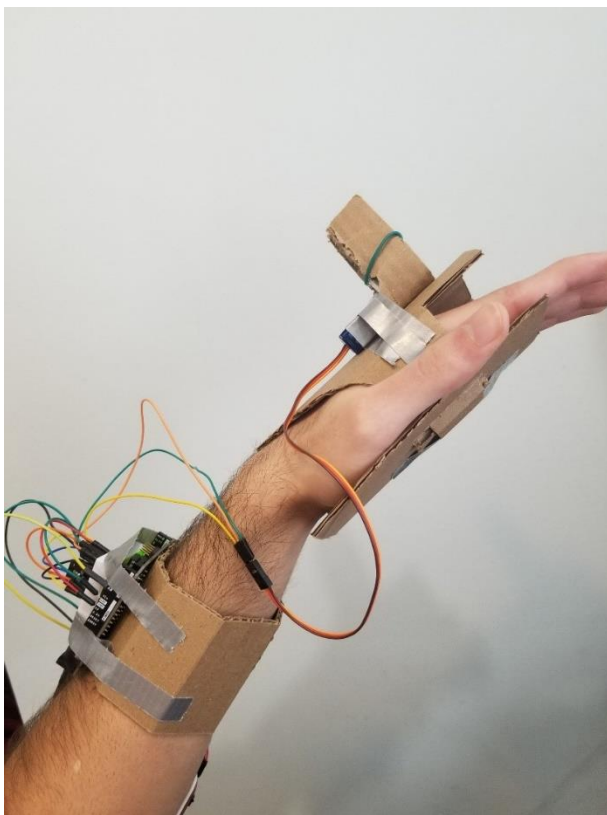


Figure 8: Borna's Prototype



*Figure 9: Andrew's Prototype*



Section 3

Figure 9.1

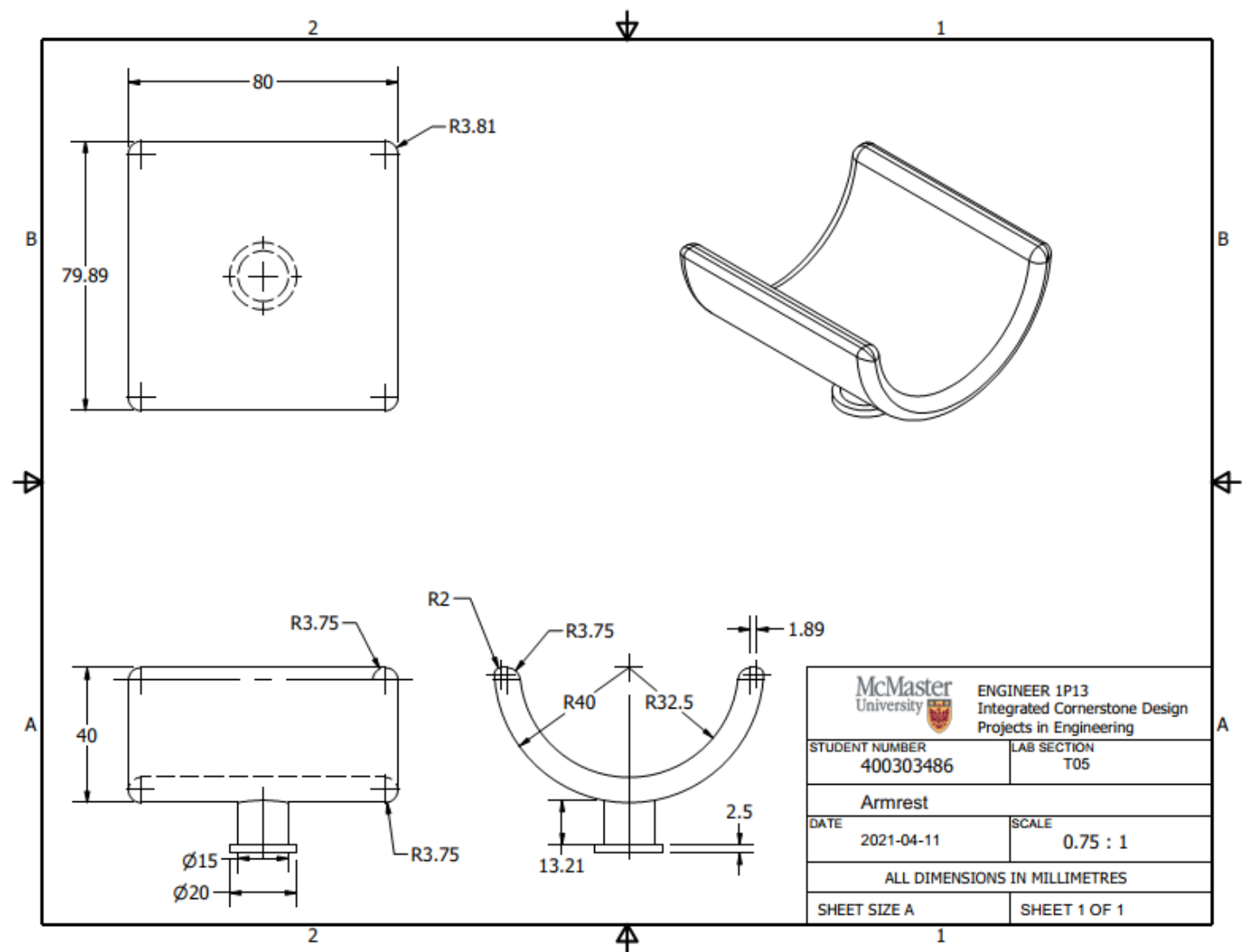


Figure 9.2

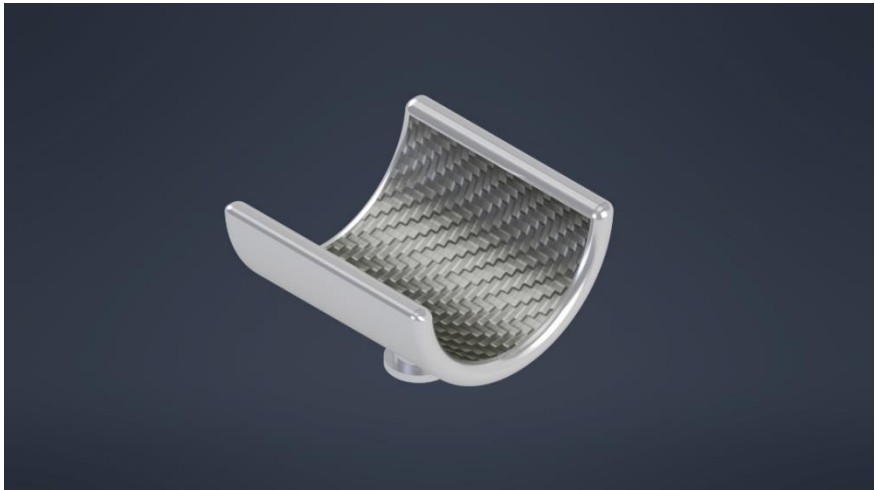


Figure 10.1

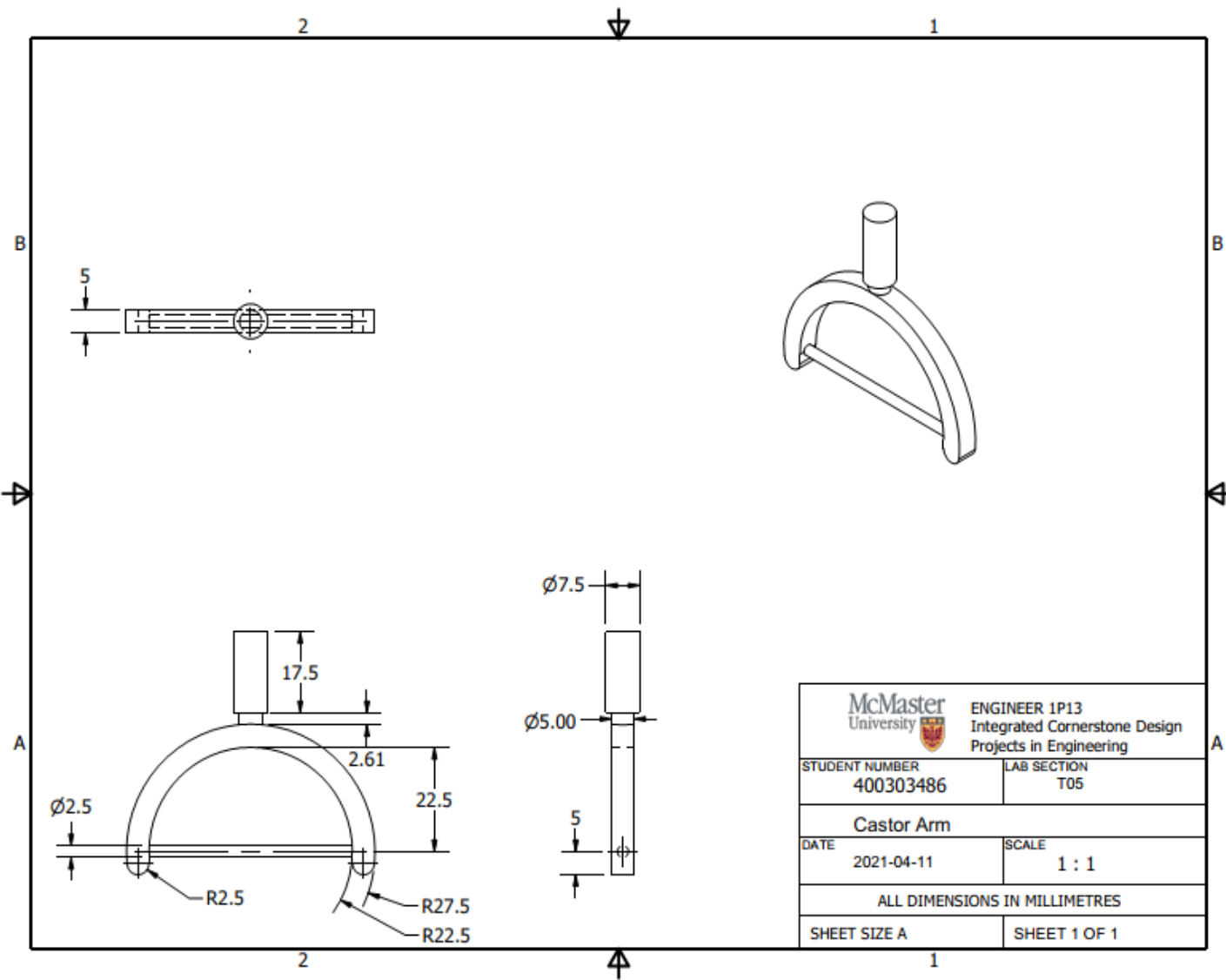


Figure 10.2

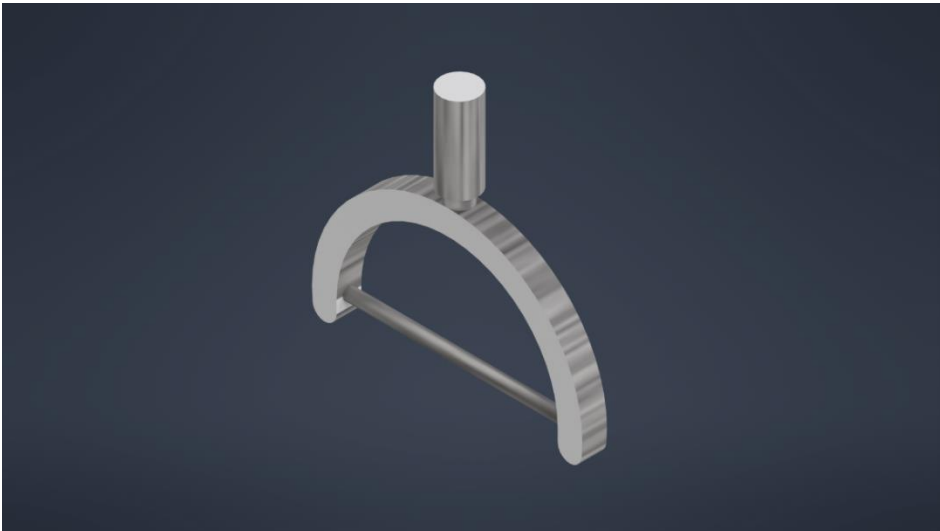


Figure 11.1

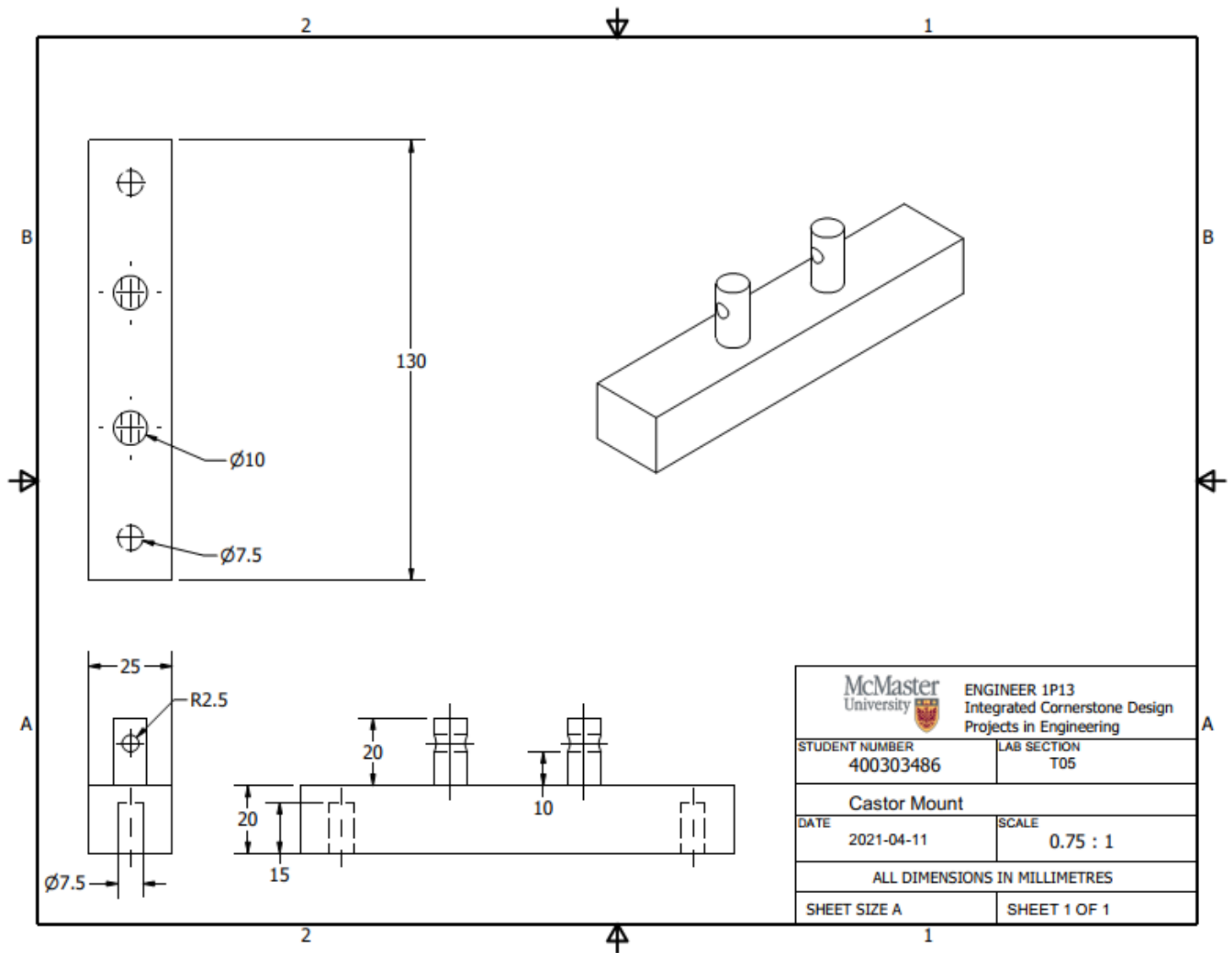


Figure 11.2

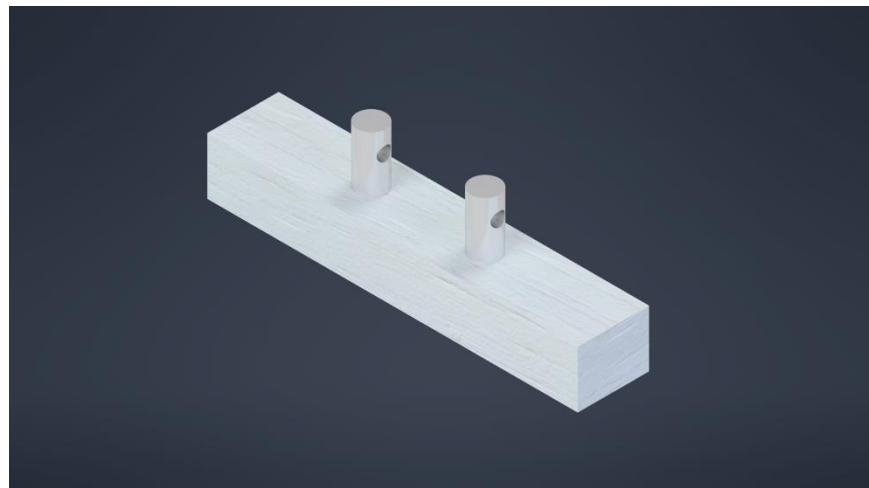


Figure 12.1

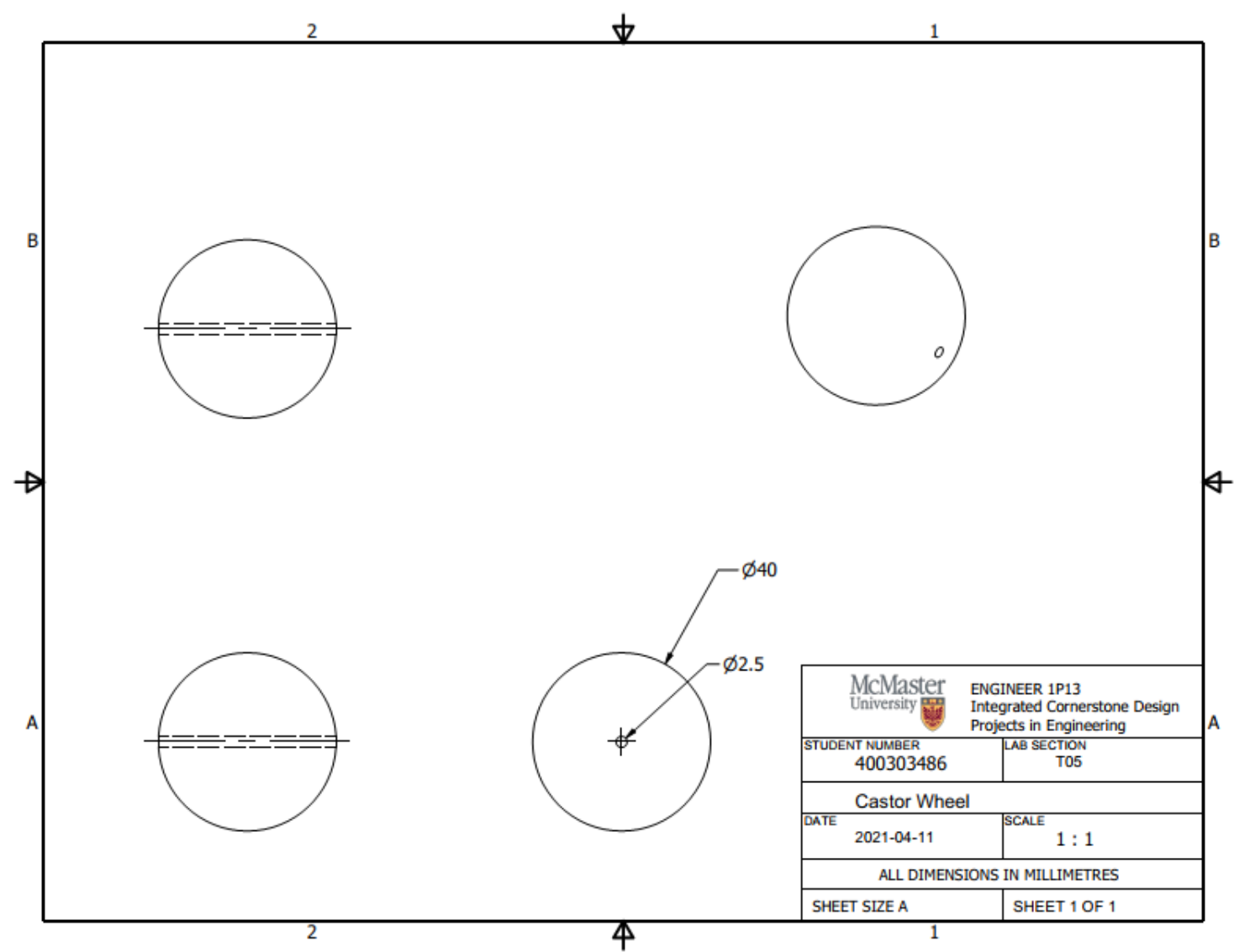


Figure 12.2



The drawing shows a Clamp Frame with the following dimensions and features:

- Top View:** A semi-circular end view with a total width of 45 mm. It features concentric semi-circular profiles with radii R5, R25, R24, and R10. A rectangular section on the left has a width of 20 mm.
- Front View:** A side profile showing a vertical post with a diameter of  $\varnothing 5$  mm. The post has a height of 46 mm from the base of the frame to the top of the post. The frame has a base width of 20 mm and a total height of 146 mm. A horizontal section has a thickness of 5 mm. A semi-circular base has a radius of R10. A vertical section on the left has a height of 15 mm and a width of 10 mm. A horizontal section has a width of 35 mm.
- Side View:** A side profile showing a total height of 146 mm. It features a horizontal section with a thickness of 5 mm and a vertical section with a height of 85 mm. A semi-circular base has a radius of R10.

**McMaster University**  
**ENGINEER 1P13**  
**Integrated Cornerstone Design**  
**Projects in Engineering**

STUDENT NUMBER <b>400303486</b>	LAB SECTION <b>T05</b>
<b>Clamp Frame</b>	
DATE <b>2021-04-11</b>	SCALE <b>1 / 2</b>
ALL DIMENSIONS IN MILLIMETRES	
SHEET SIZE A	SHEET 1 OF 1




Figure 14.1

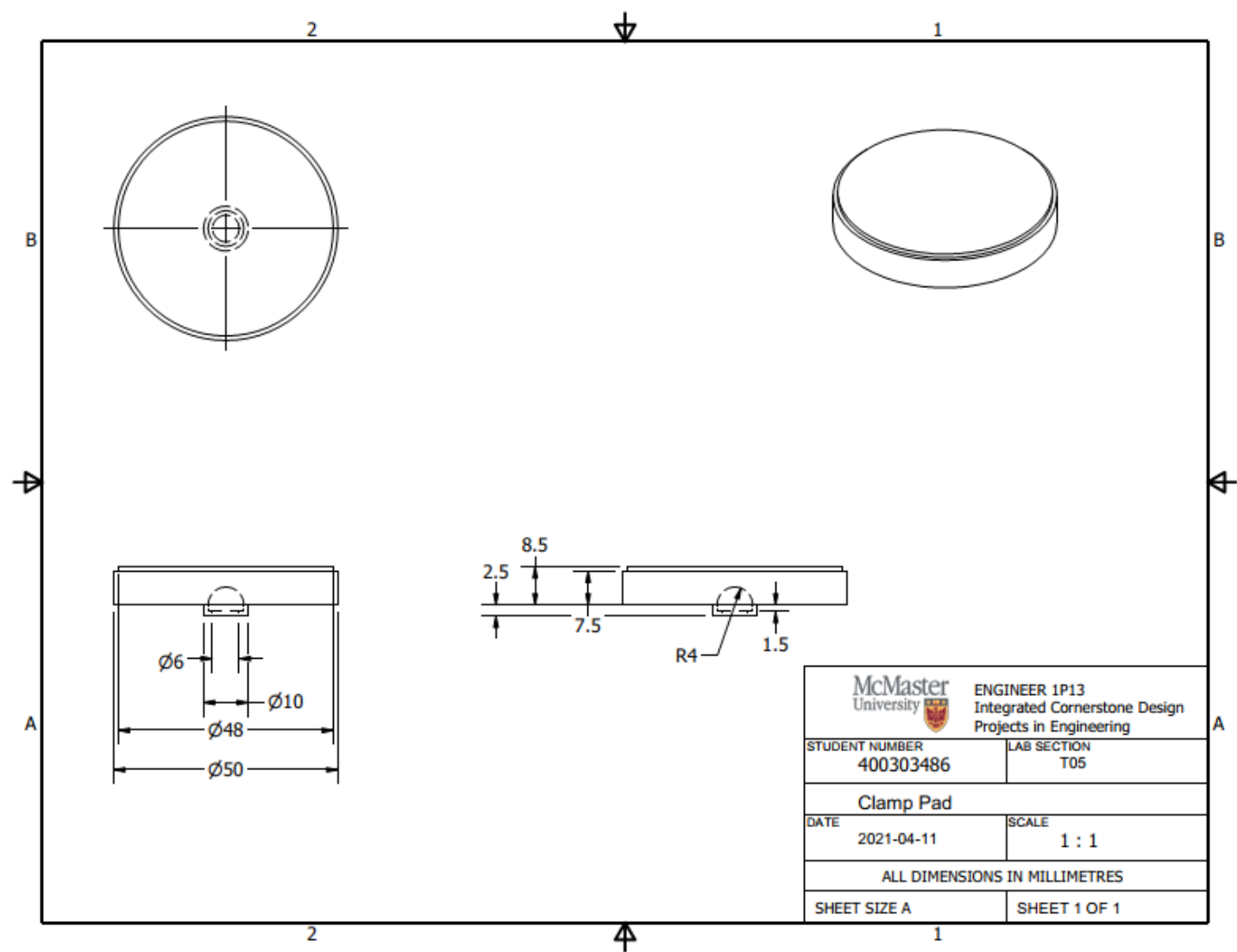
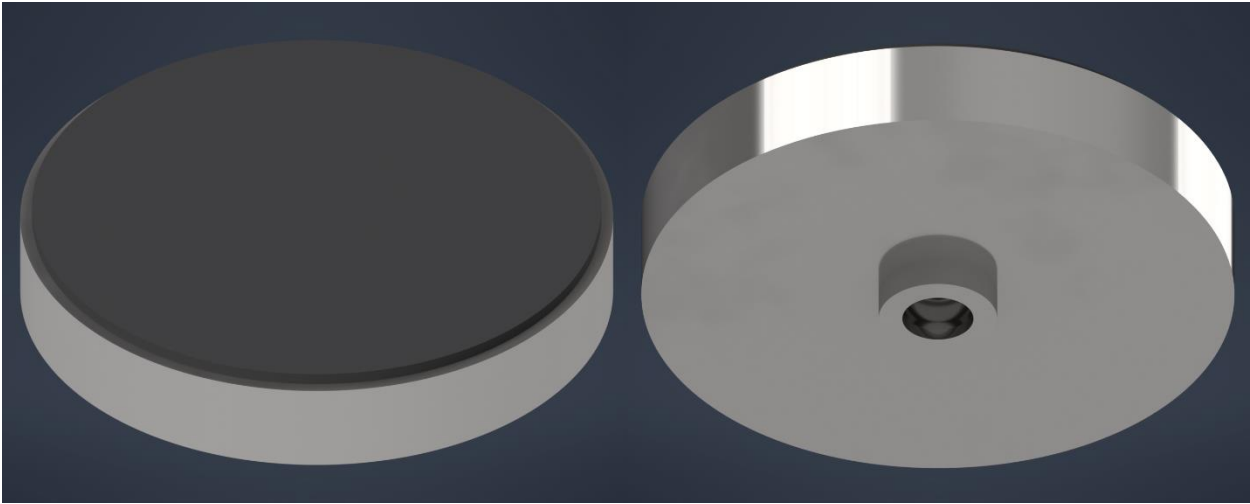


Figure 14.2



Technical drawing of a Clamp Screw, showing three views: Front View, Top View, and Side View. The drawing includes dimensions in millimeters.

**Front View Dimensions:**

- Vertical section height: 86.46
- Top flange thickness: 0.6
- Top flange radius: R12
- Horizontal section total length: 69.17
- Horizontal section central slot width: 5
- Horizontal section central slot radius: R5
- Horizontal section end radius: R5
- Horizontal section end thickness: 10
- Horizontal section central hole diameter: 10

**Top View Dimensions:**

- Horizontal section total length: 35.4
- Horizontal section central slot width: 15.43
- Horizontal section central slot radius: R5
- Horizontal section end radius: R5

**Side View Dimensions:**

- Horizontal section total length: 35.4
- Horizontal section central slot width: 15.43
- Horizontal section central slot radius: R5
- Horizontal section end radius: R5

**Title Block Information:**

McMaster University		ENGINEER 1P13 Integrated Cornerstone Design Projects in Engineering	
STUDENT NUMBER 400303486		LAB SECTION T05	
Clamp Screw			
DATE 2021-04-11		SCALE 2/3	
ALL DIMENSIONS IN MILLIMETRES			
SHEET SIZE A		SHEET 1 OF 1	

Figure 16.1

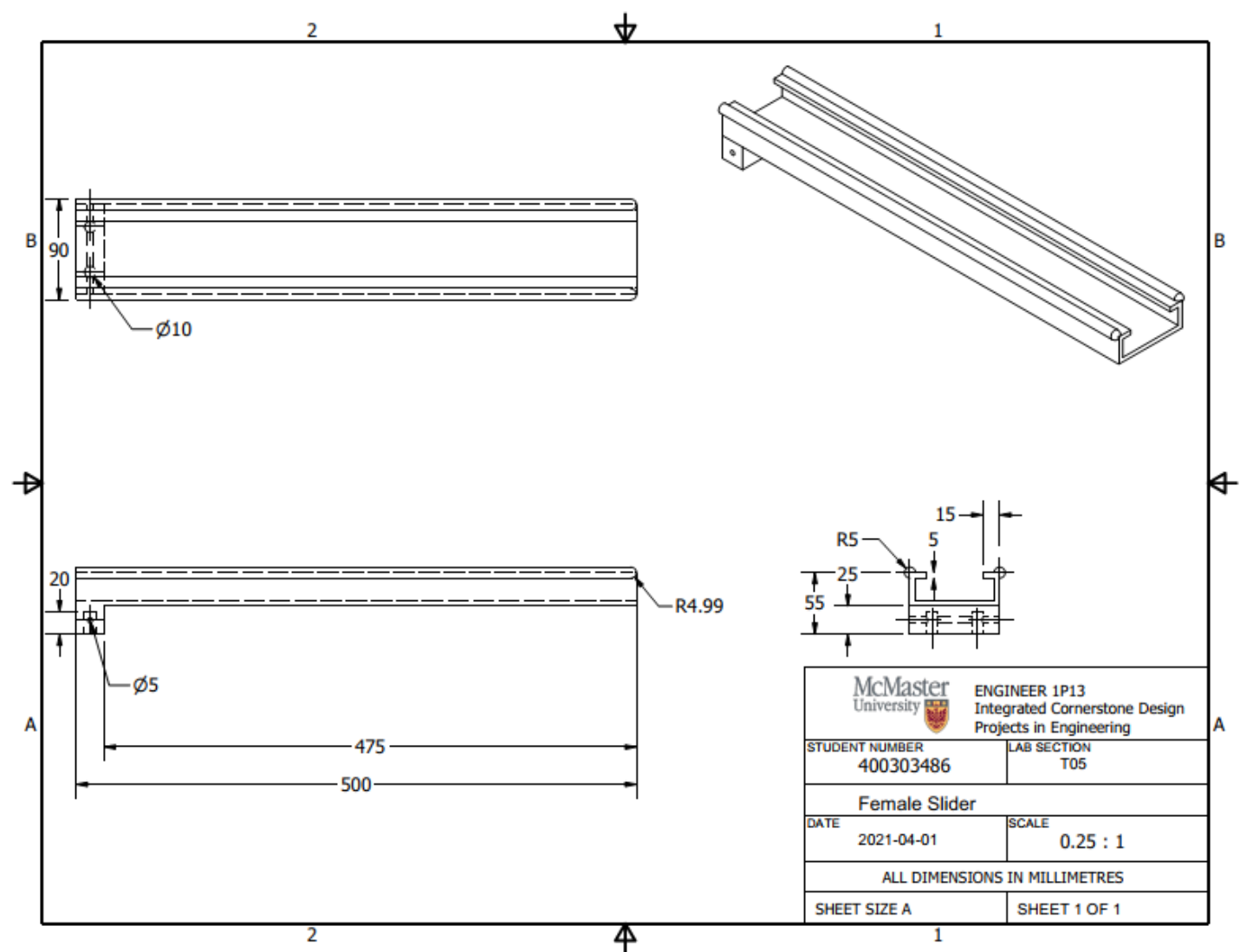


Figure 16.2

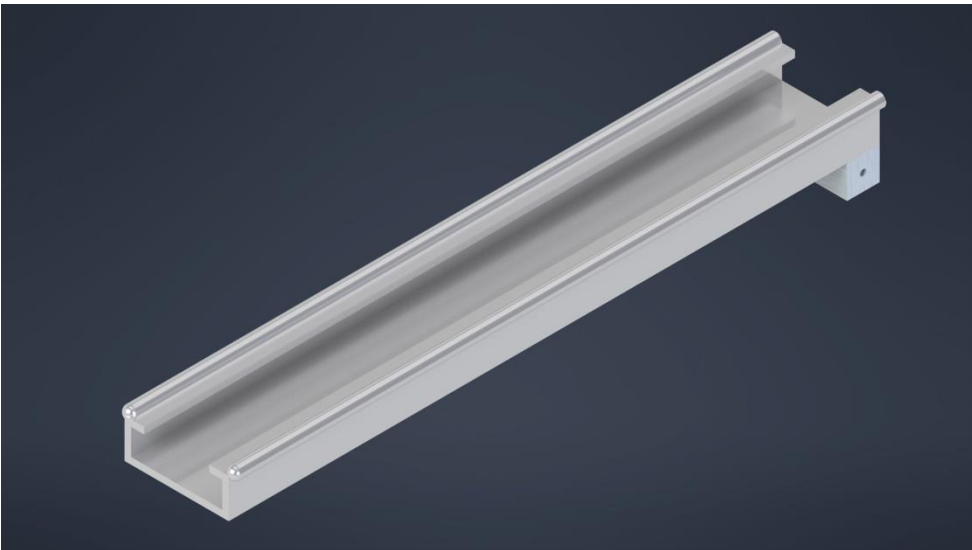




Figure 17.1

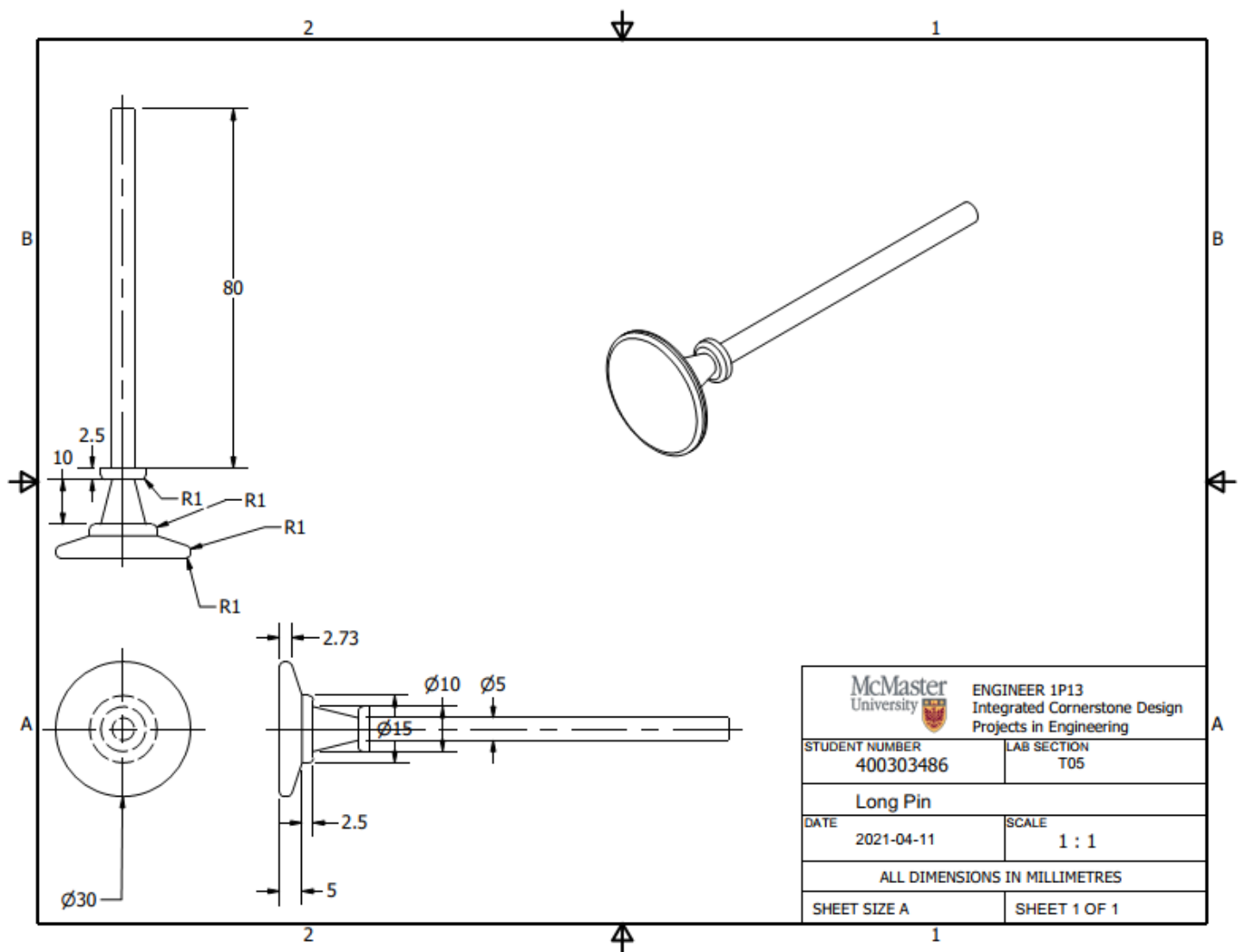


Figure 17.2



Figure 18.1

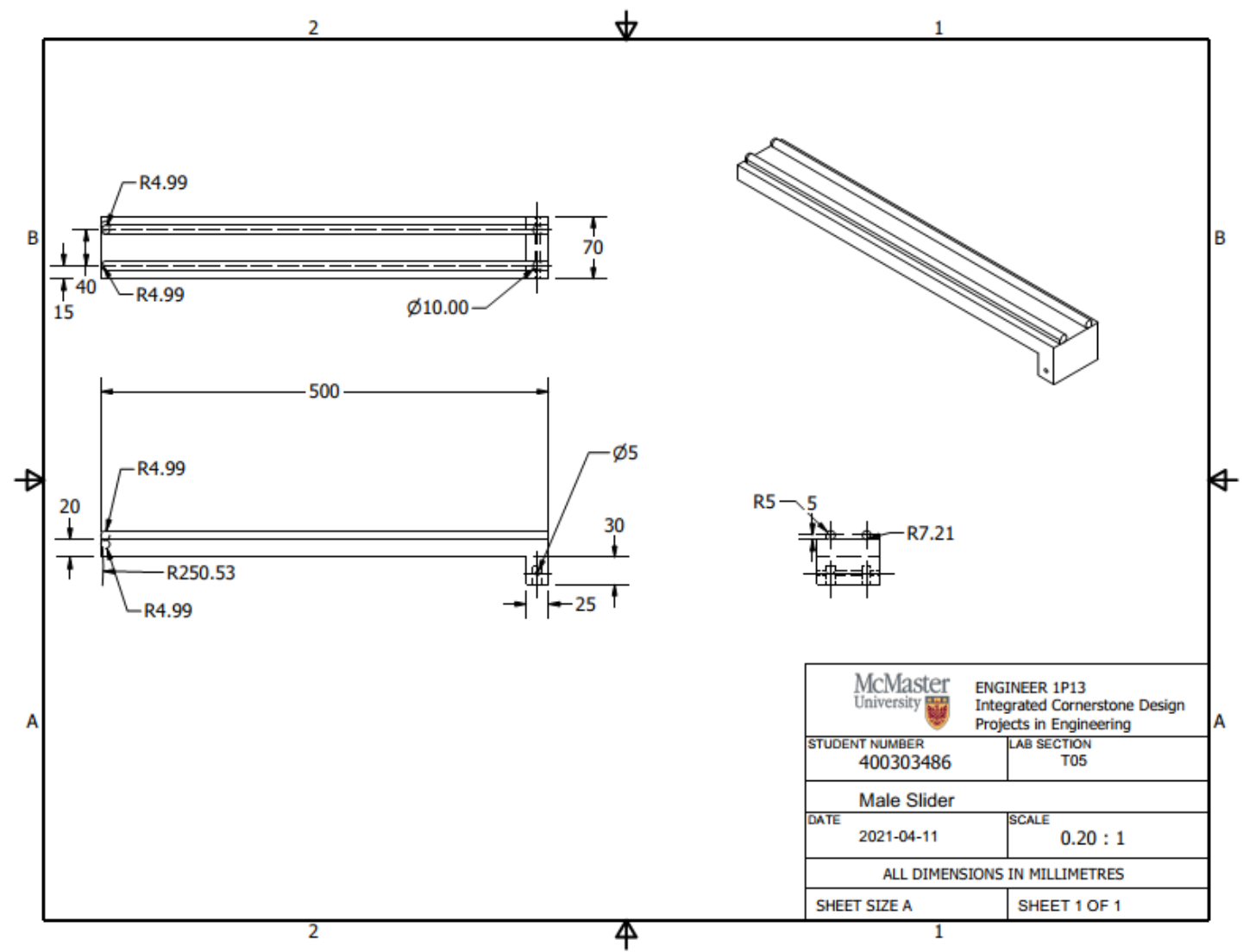


Figure 18.2

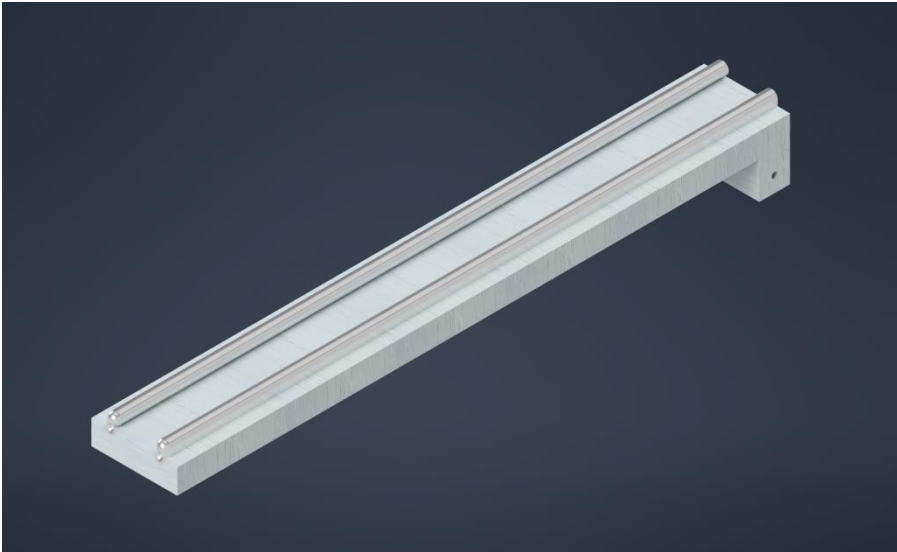


Figure 19.1

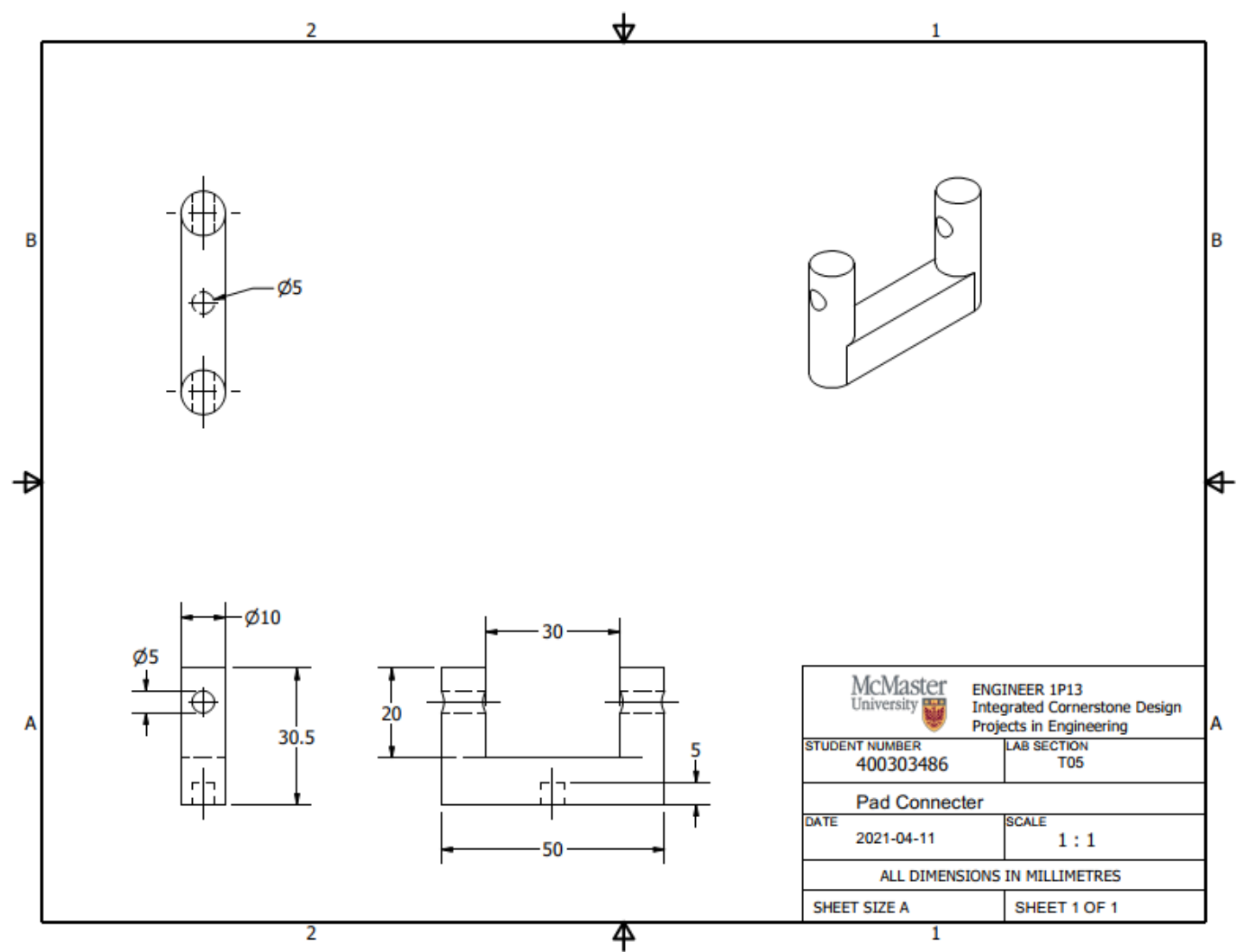


Figure 19.2

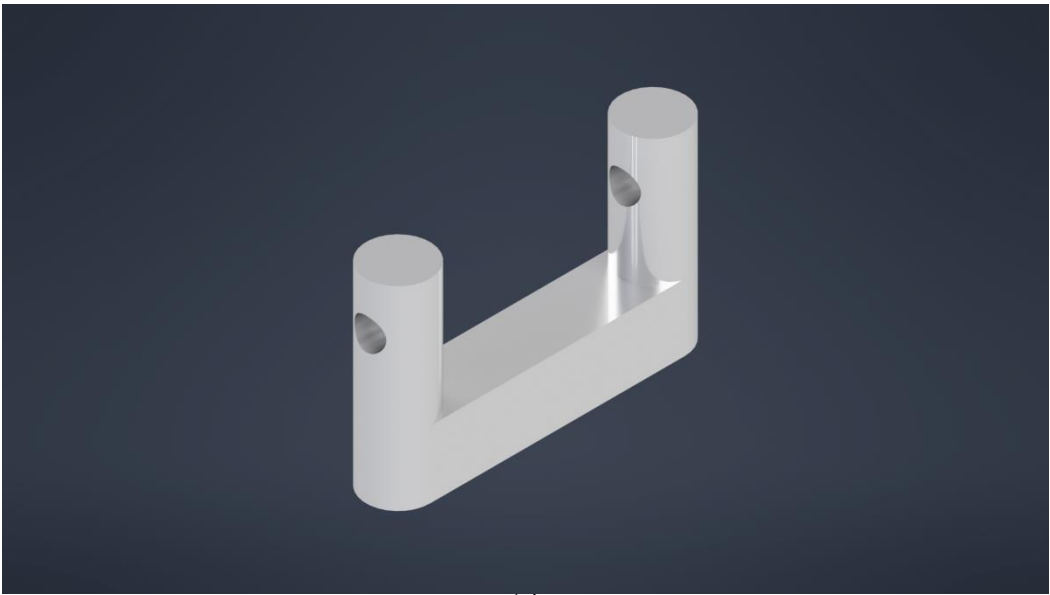


Figure 20.1

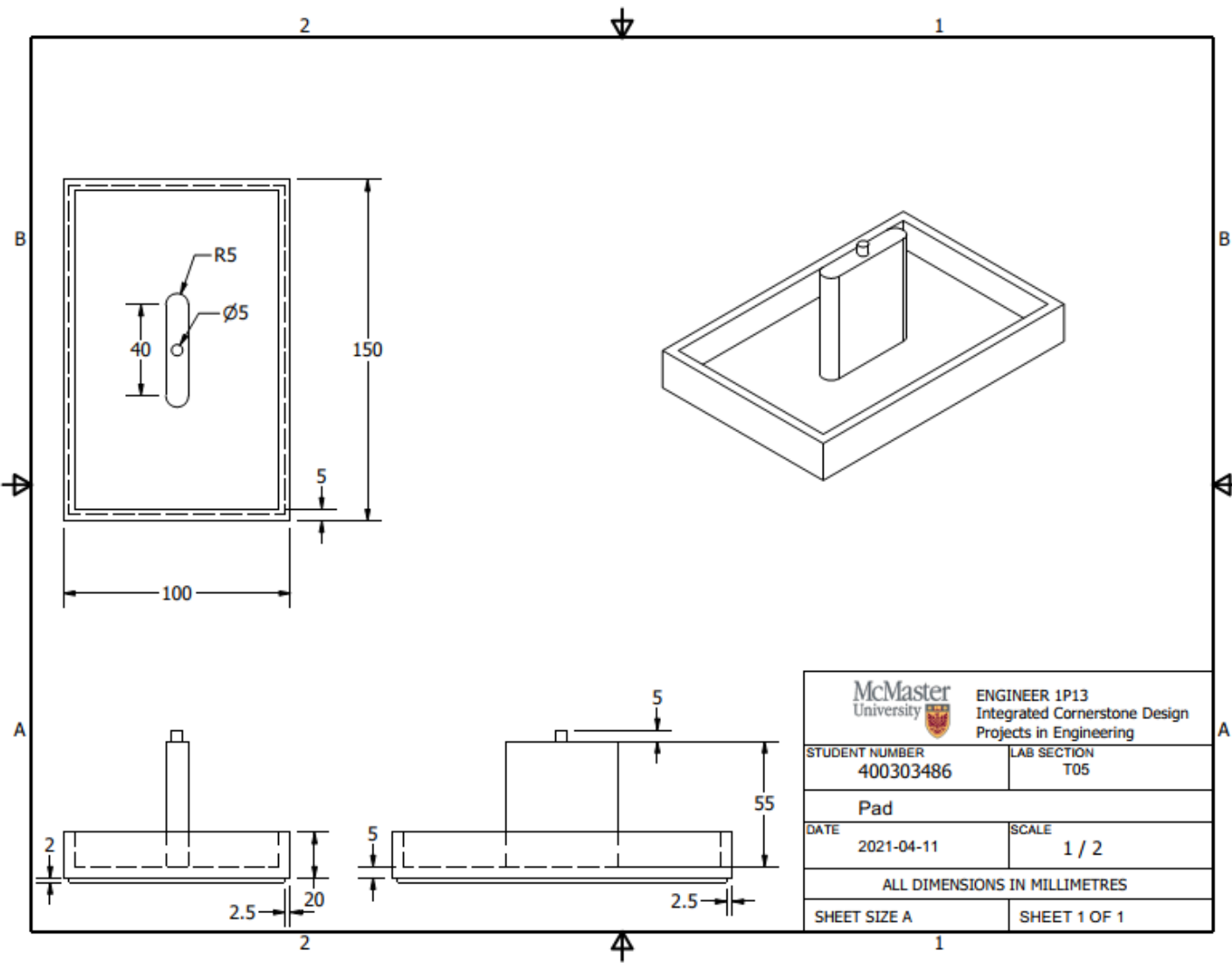


Figure 20.2

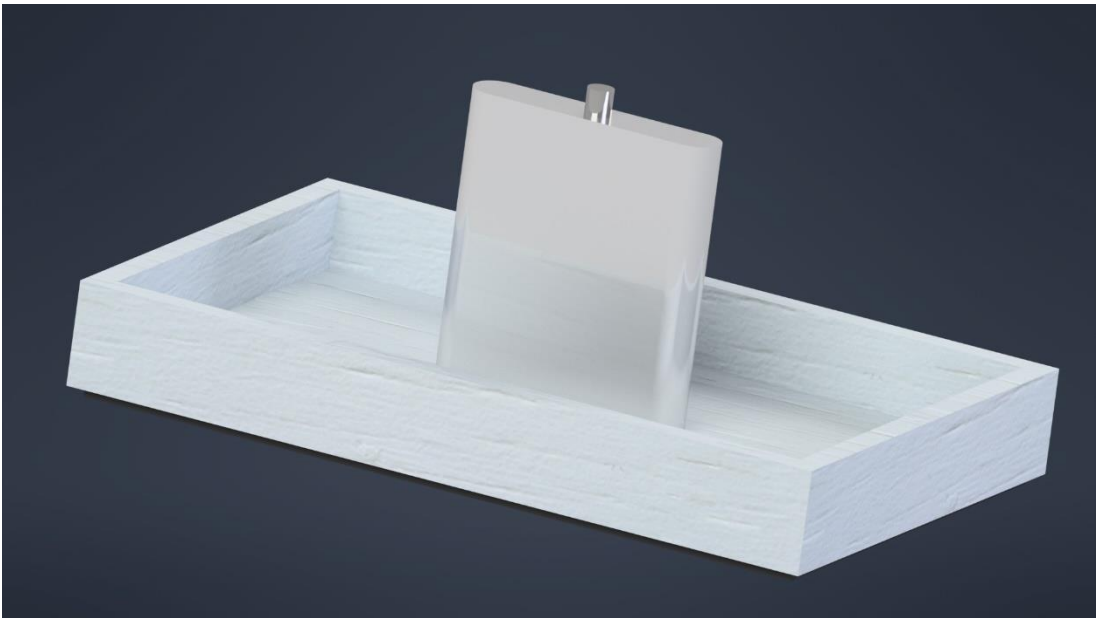


Figure 21.1

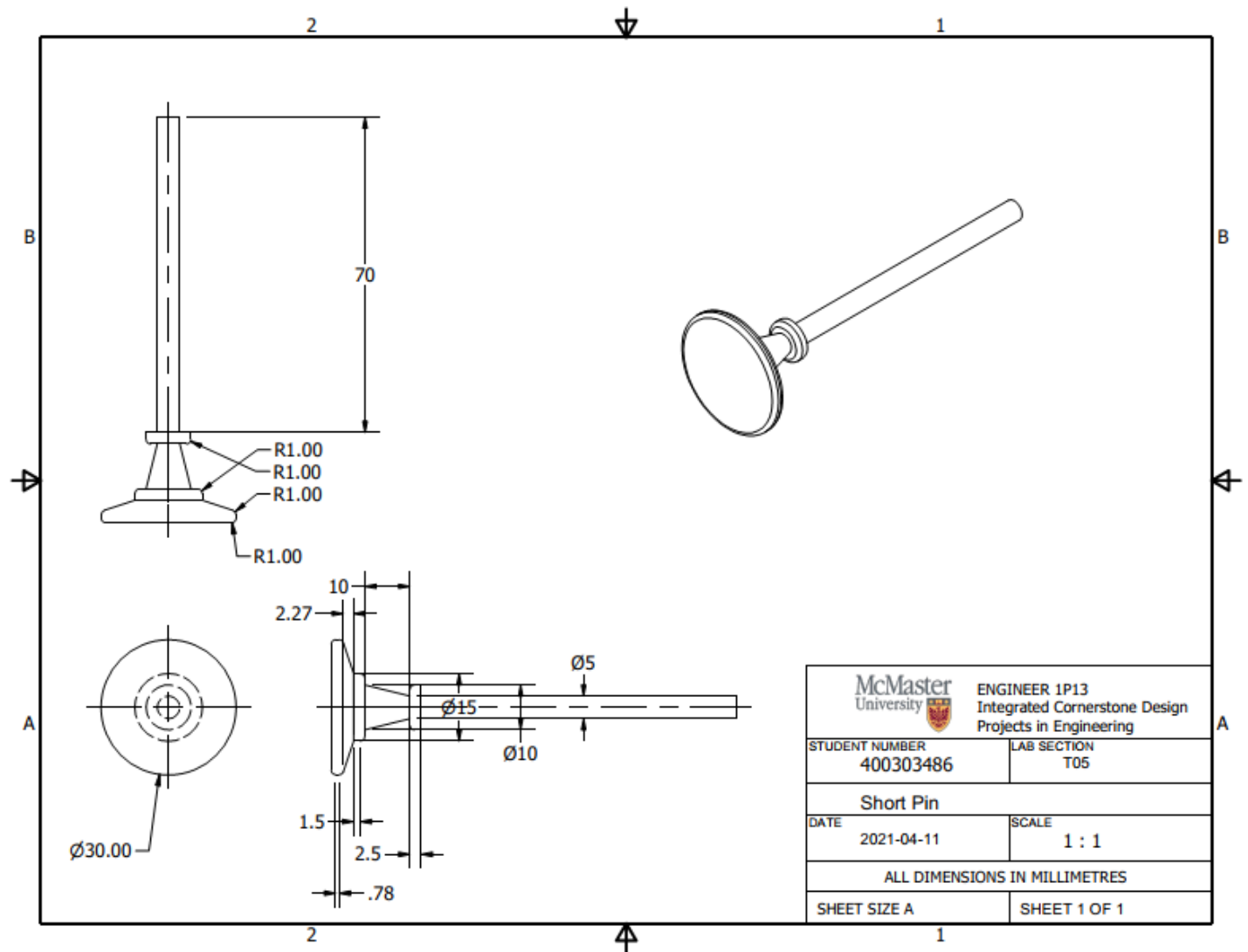


Figure 21.2



The drawing shows a mechanical part with the following dimensions and features:

- Top View:** A rectangular plate with a width of 60 mm and a length of 80 mm. It features a central circular hole with an outer diameter of  $\varnothing 20$  mm and an inner diameter of  $\varnothing 15$  mm. The hole is centered 20 mm from the top edge and 10 mm from the bottom edge.
- Side View:** Shows the profile of the part with a total height of 17.5 mm. The top surface is flat, and the bottom edge has a rounded corner with a radius of R10. The central hole is 10 mm deep.
- Isometric View:** A 3D representation of the part, showing its rectangular shape, central hole, and rounded bottom edge.

<b>McMaster University</b>		<b>ENGINEER 1P13</b> Integrated Cornerstone Design Projects in Engineering	
STUDENT NUMBER <b>400303486</b>		LAB SECTION <b>T05</b>	
<b>Sliding Part</b>			
DATE 2021-04-11		SCALE 3/4	
ALL DIMENSIONS IN MILLIMETRES			
SHEET SIZE A		SHEET 1 OF 1	

Figure 23.1

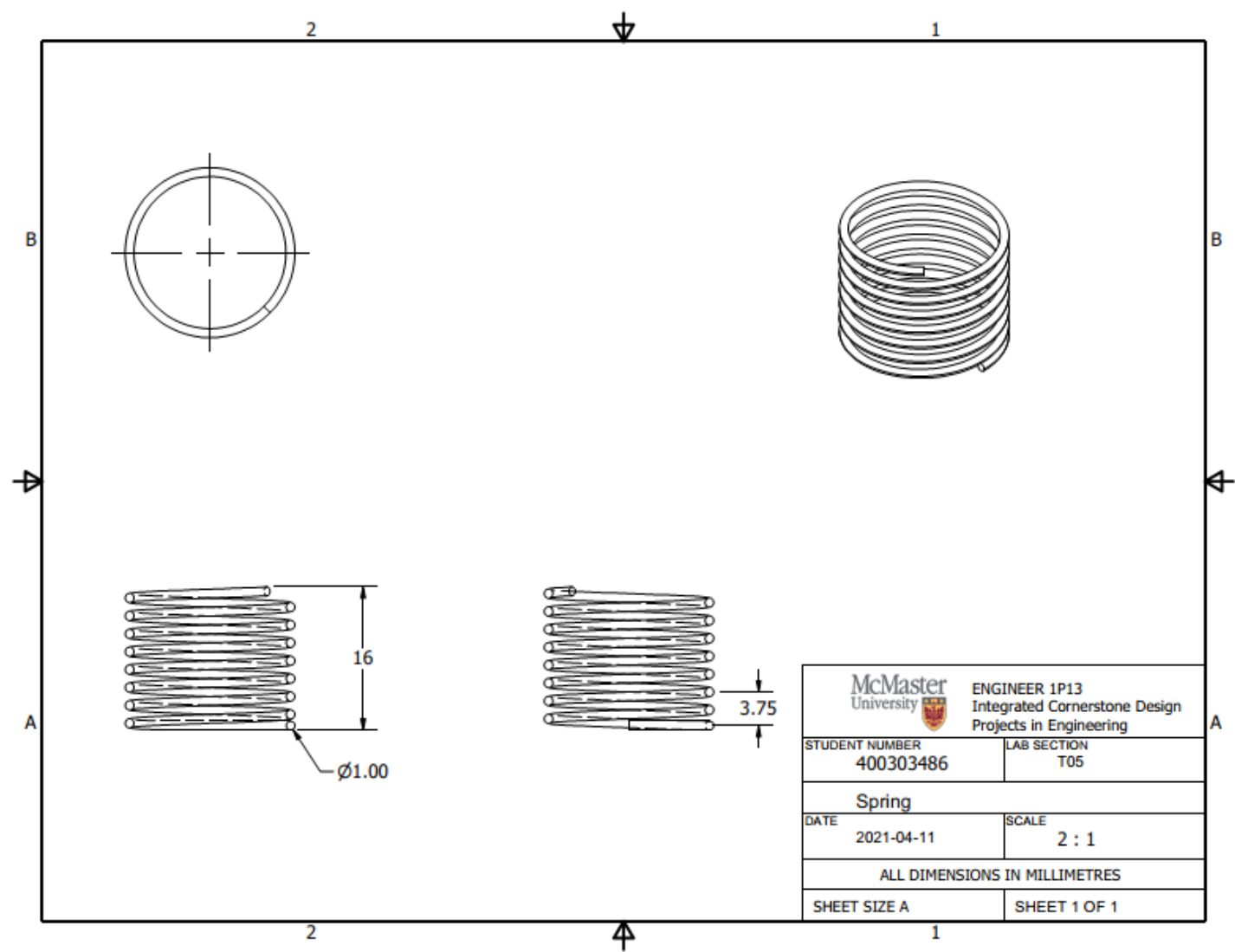


Figure 23.2



Figure 24.1



Figure 24.2





Figure 24.3



Figure 25

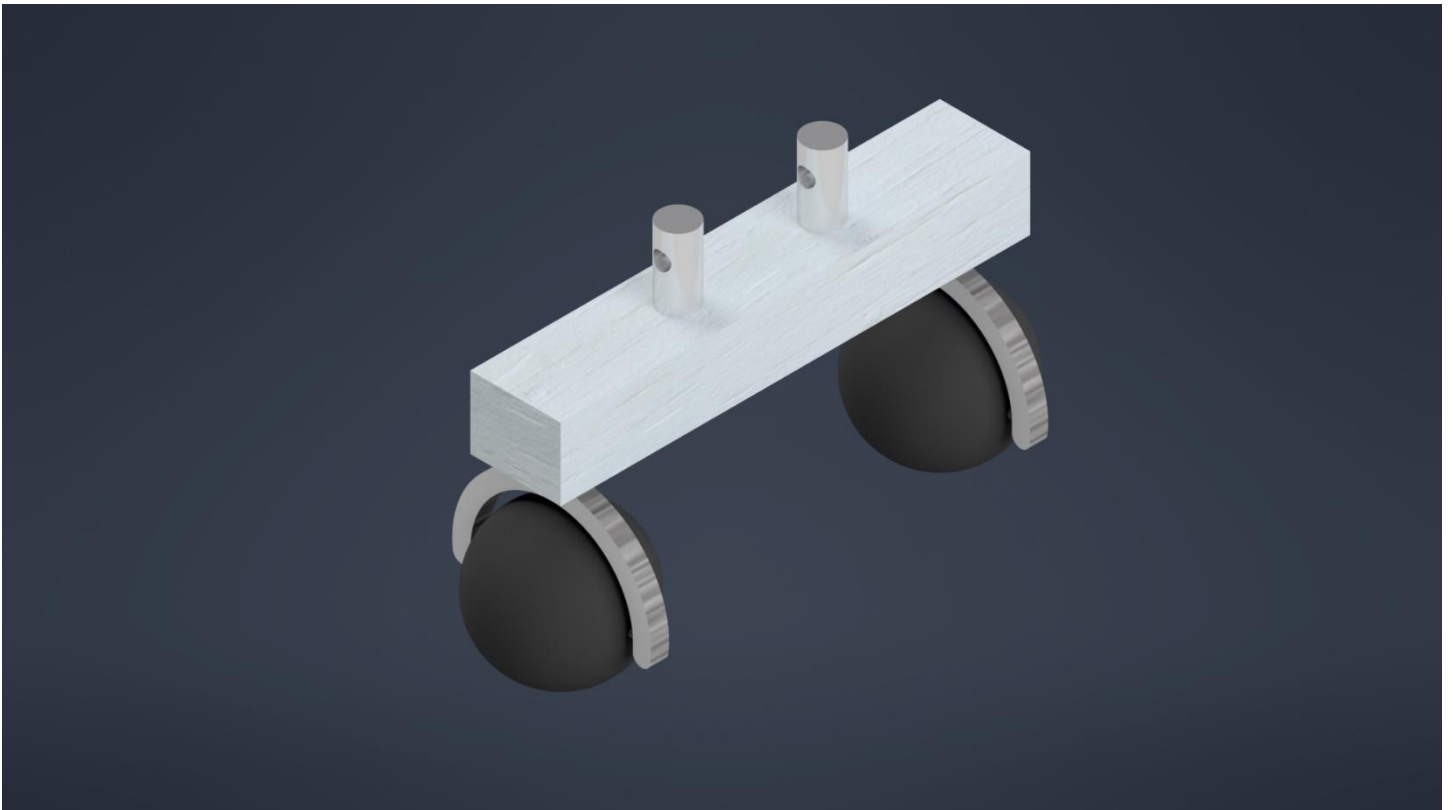


Figure 26

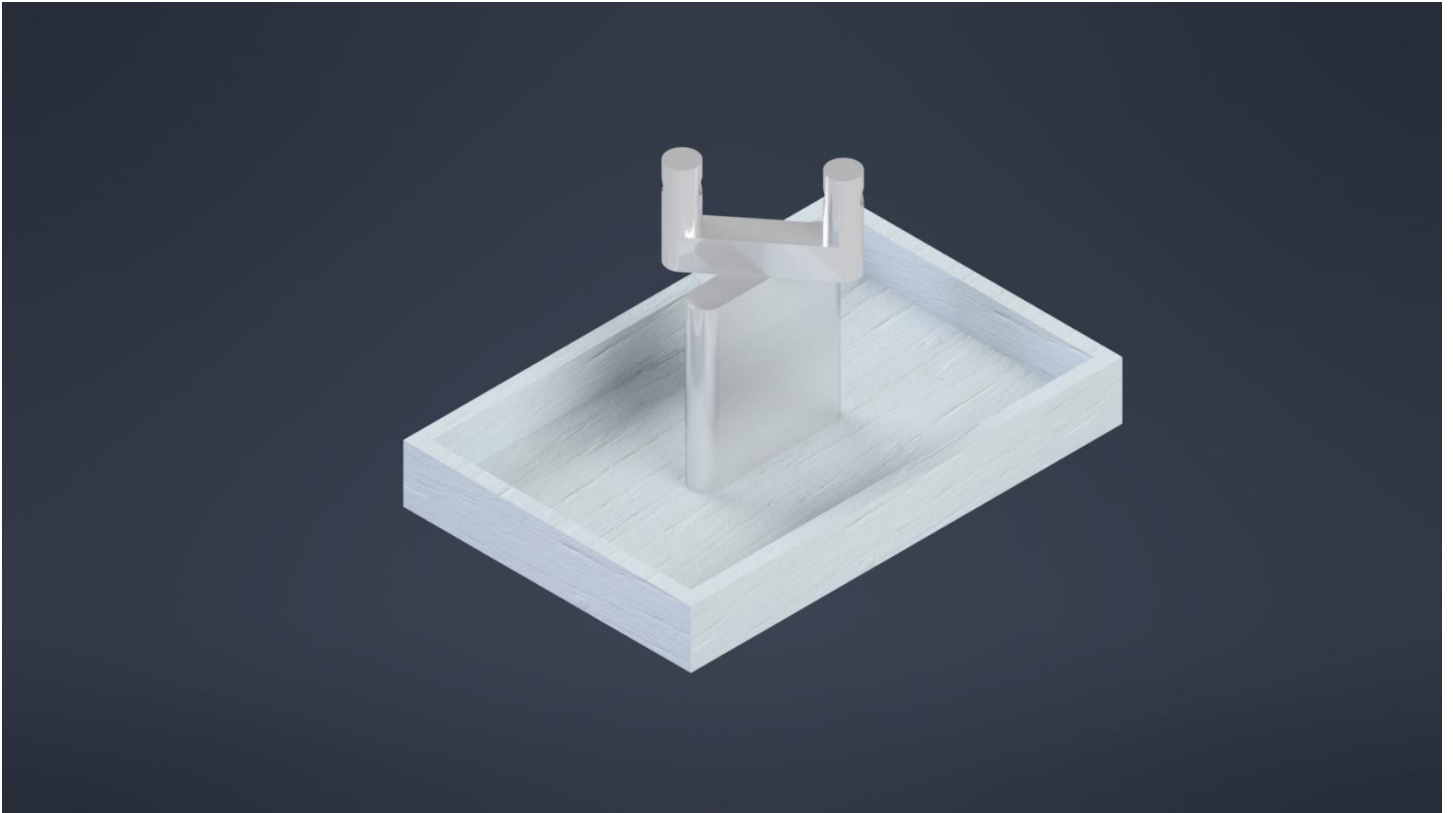


Figure 27

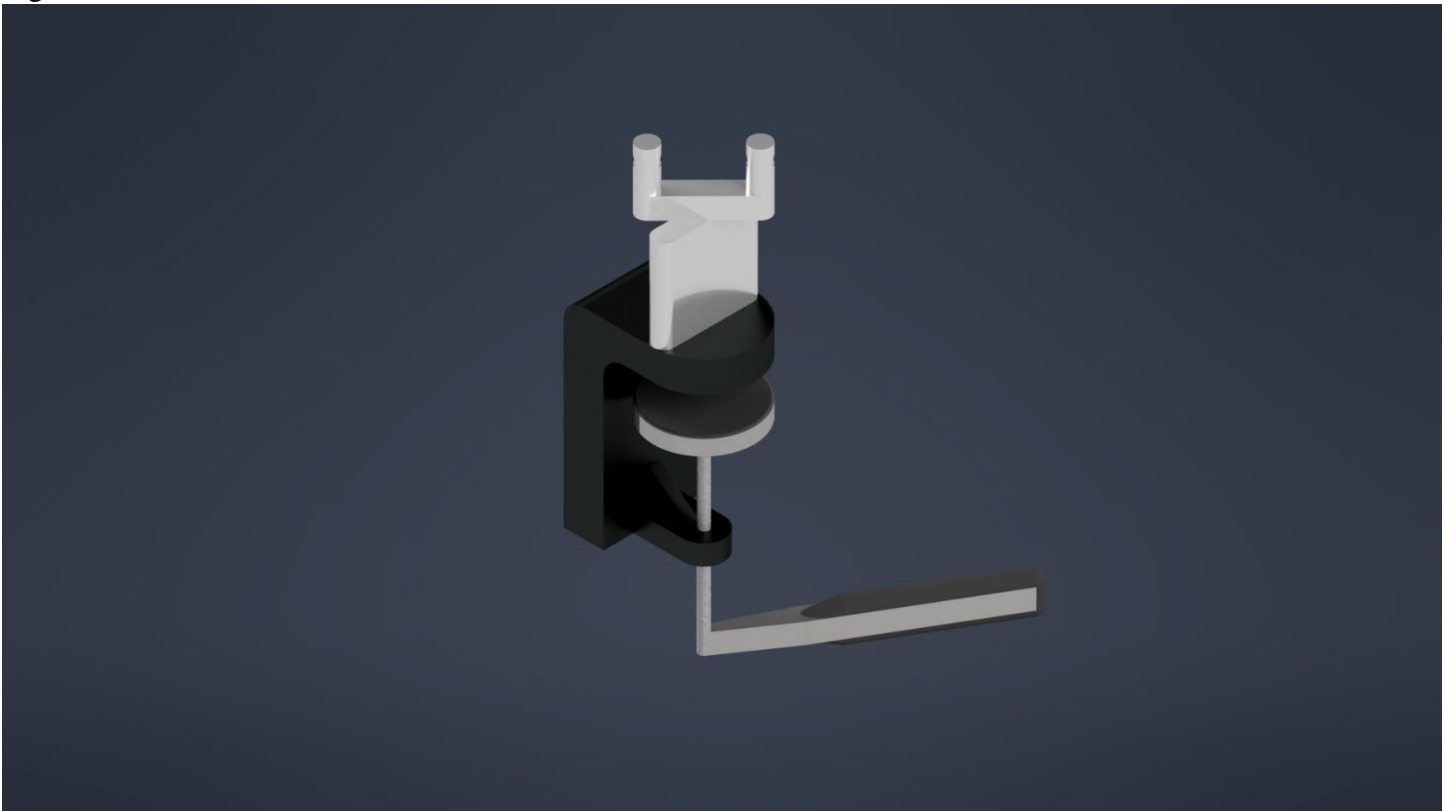


Figure 28

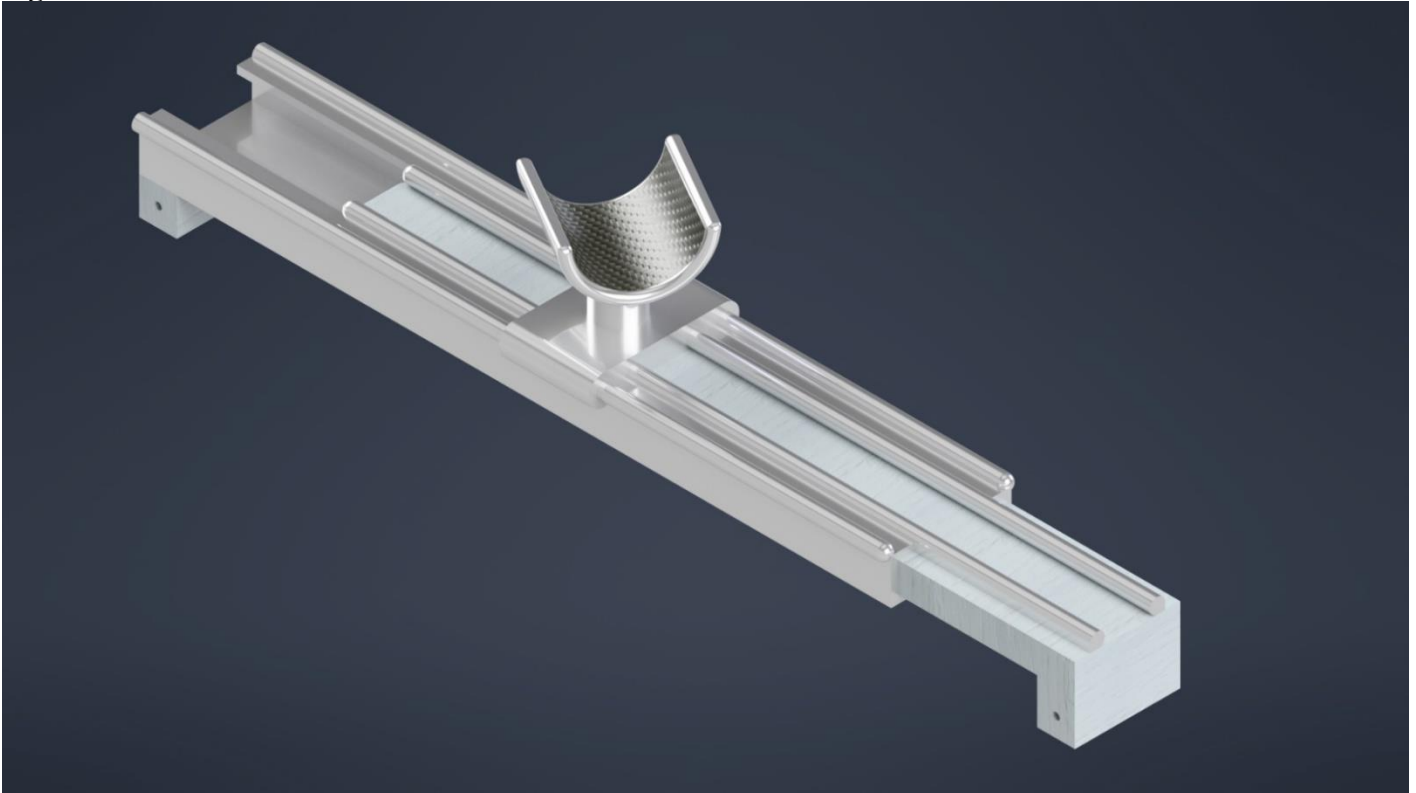
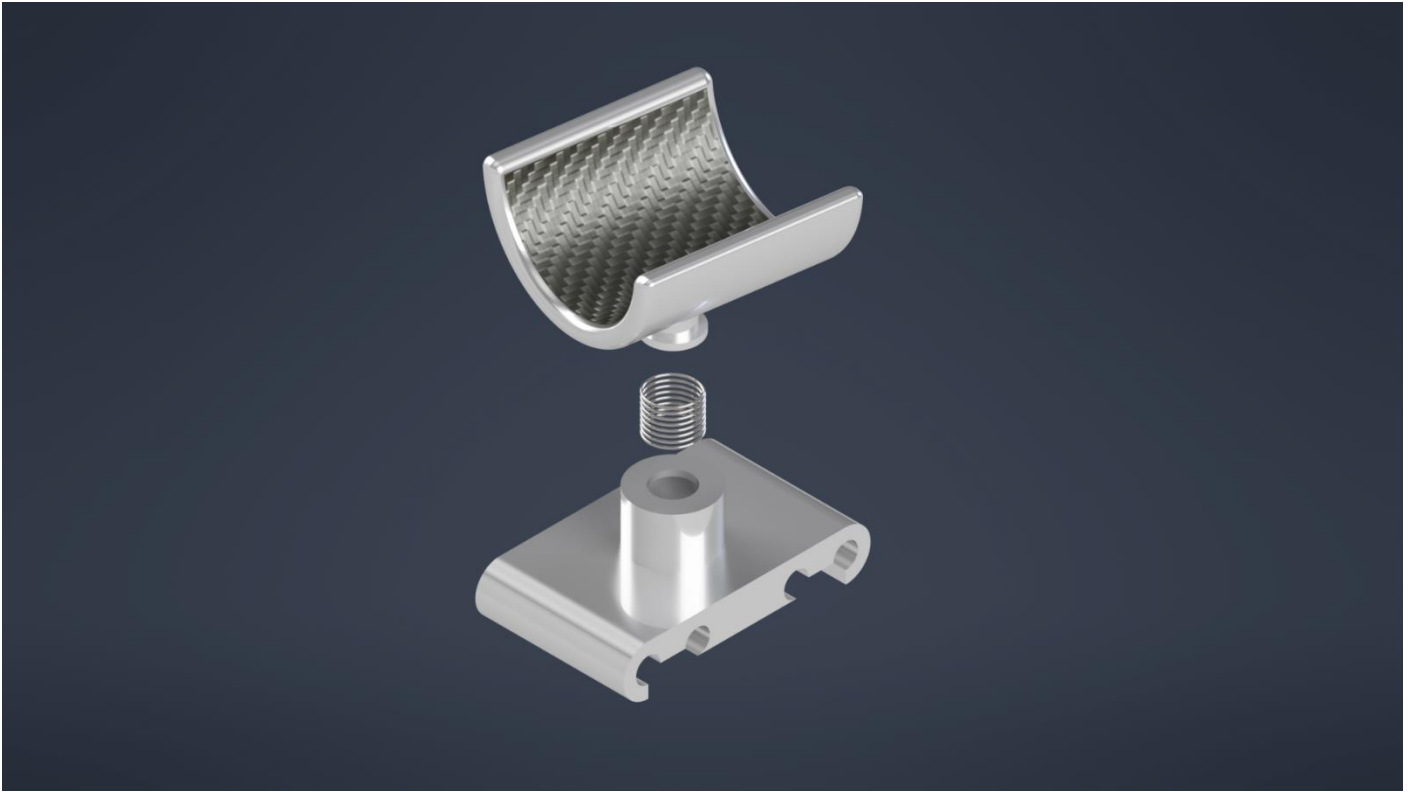


Figure 29

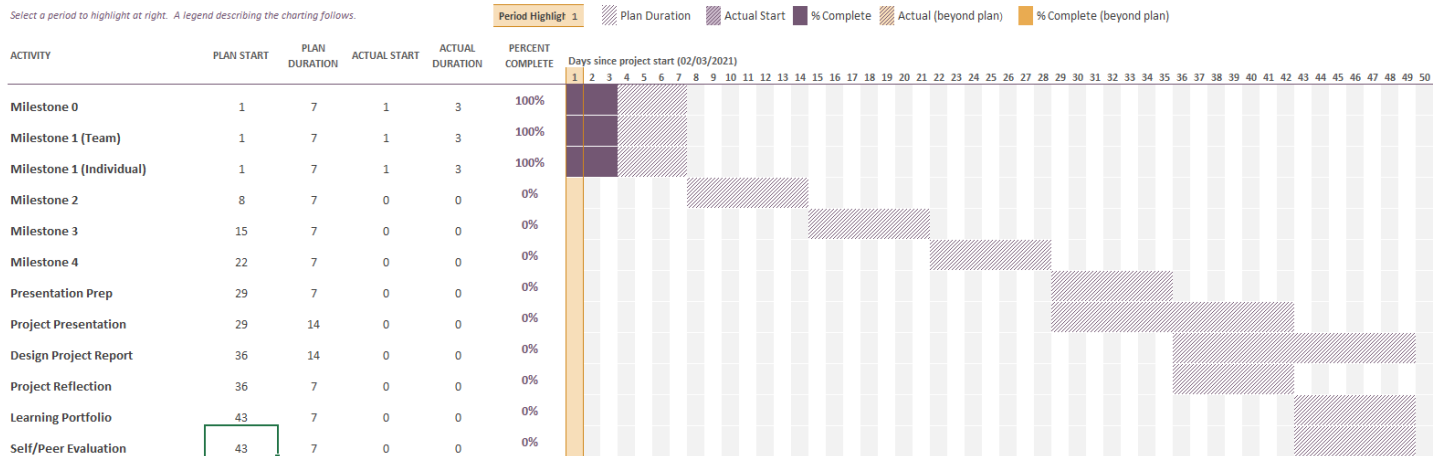
**Figure 30:** <https://drive.google.com/file/d/1iYrfG0rWP9wvIDGAkfaaEysD6CJ14NVC/view?usp=sharing>

## Section 4

## Preliminary Gantt Chart

## Project-4 Planner

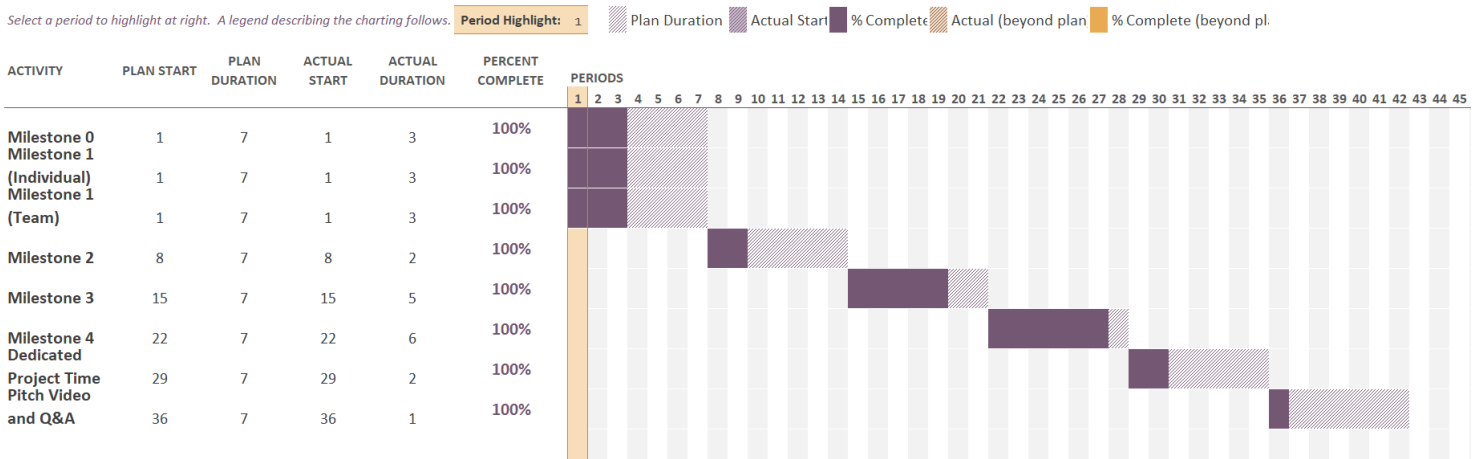
Select a period to highlight at right. A legend describing the charting follows.



## Final Gantt Chart

## Final Gantt Chart

Select a period to highlight at right. A legend describing the charting follows.



**Logbook of Additional Meetings and Discussions**

Meeting Date	Meeting Topic	Meeting Length	Meeting Attendees
<b>March 29/2021</b>	<b>General Meeting</b>	<b>30m</b>	<b>Jackson Lippert, Ahmed Mohammed</b>
<b>April 6/2021</b>	<b>Final Deliverables</b>	<b>30m</b>	<b>Andrew Krynski, Jackson Lippert, Borna Sadeghi, Ahmed Mohammed</b>
<b>April 13/2021</b>	<b>Design report</b>	<b>1h 15m</b>	<b>Andrew Krynski, Jackson Lippert, Borna Sadeghi</b>
<b>April 15/2021</b>	<b>Finalizing design report</b>	<b>1h 45m</b>	<b>Andrew Krynski, Jackson Lippert, Borna Sadeghi, Ahmed Mohammed</b>

**ENGINEER 1P13****MEETING WITH TEAM 26 - TUESDAY, MARCH 16, 2021****ATTENDANCE**

Role	Name	Mac ID	Attendance (Yes/No)
Manager	<u>Andrew Krynski</u>	<u>krynskia</u>	Yes
Administrator	<u>Ahmed Mohamed</u>	<u>mohaa97</u>	Yes
Coordinator	<u>Borna Sadeghi</u>	<u>sadegb1</u>	Yes
Subject Matter Expert	<u>Jackson Lippert</u>	<u>lippertj</u>	Yes
Guest			

**AGENDA ITEMS**

1. Initial prototypes of our previous ideas are to be brought to the meeting and presented to each other
2. Obtain feedback from course administrators regarding the feasibility of each prototype
3. Use a decision matrix to pick the most feasible prototype

**MEETING MINUTES**

1. We introduced our prototypes to each other, explaining how they work, and bounced ideas around about how they could be improved or combined in following iterations
2. Discussion about the most important features that our refined prototype should have
  - a. We settle on reliability, ease of use, quality of life improvement, design and manufacturing simplicity, and flexibility
3. We discuss the results of our decision matrix and justify our choice of prototype to continue with

**POST-MEETING ACTION ITEMS**

1. Jackson must create the refined prototype as he has the available materials

## ENGINEER 1P13

MEETING WITH TEAM 26 - TUESDAY, MARCH 23, 2021

## ATTENDANCE

Role	Name	Mac ID	Attendance (Yes/No)
Manager	Andrew Krynski	krynskia	Yes
Administrator	Ahmed Mohamed	mohaa97	Yes
Coordinator	Borna Sadeghi	sadegb1	Yes
Subject Matter Expert	Jackson Lippert	lippertj	Yes
Guest			

## AGENDA ITEMS

1. Jackson will demonstrate the refined [prototype](#)
2. Create a testing plan for our prototype (how will we test and make future iterations of it?)
3. Present our most recent prototype along with our ideas to the science students for [feedback](#)

## MEETING MINUTES

1. We discussed the role of the second caster wheel, and the different configurations that the mechanism can be put into so that it can work on the floor and other flat [surfaces](#)
2. We brainstormed a variety of different ways in which we could test our prototype for further [refinement](#)
3. Feedback
  - a. Personalize the aesthetics of the design to the [client](#)

## POST-MEETING ACTION ITEMS

1. Implement the feedback received from the science [students](#)

## ENGINEER 1P13

MEETING WITH TEAM 26 - THURSDAY, APRIL 1, 2021

## ATTENDANCE

Role	Name	Mac ID	Attendance (Yes/No)
Manager	Andrew Krynski	krynskia	Yes
Administrator	Ahmed Mohamed	mohaa97	Yes
Coordinator	Borna Sadeghi	sadegb1	Yes
Subject Matter Expert	Jackson Lippert	lippertj	Yes
Guest	Arina Deboer	deboea2	Yes

## AGENDA ITEMS

1. Finalize our prototype presentation and script, and record our demonstration [video](#)

## MEETING MINUTES

1. Based off of our script which was already written, we created a visual [presentation](#)
2. Did some research on existing products that we could compare our arm support [to](#)
3. We got feedback on our presentation from [Arina](#)

## POST-MEETING ACTION ITEMS

1. Append Jackson's demo of the prototype to the [video](#)
  - a. Will be done by [Borna](#)
2. Make any necessary edits to the [video](#)

## ENGINEER 1P13

MEETING WITH TEAM 26 - TUESDAY, APRIL. 6, 2021

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### ATTENDANCE

Role	Name	Mac ID	Attendance (Yes/No)
Manager	Andrew Krynski	krynskia	Yes
Administrator	Ahmed Mohamed	mohaa97	Yes
Coordinator	Borna Sadeghi	sadegb1	Yes
Subject Matter Expert	Jackson Lippert	lippertj	Yes
Guest			

### AGENDA ITEMS

1. Prepare for our team's design presentation to the [TAs](#)

### MEETING MINUTES

1. We review our slide show, and prepare a link that we can submit to the assignment [dropbox](#)
2. We are moved into a separate voice channel to present our recorded video to the TAs and answer their [questions](#)

### POST-MEETING ACTION ITEMS

1. Begin work on final [deliverables](#)

## ENGINEER 1P13

MEETING WITH TEAM 26 - TUESDAY, APRIL. 13, 2021

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### ATTENDANCE

Role	Name	Mac ID	Attendance (Yes/No)
Manager	Andrew Krynski	krynskia	Yes
Administrator	Ahmed Mohamed	mohaa97	Yes
Coordinator	Borna Sadeghi	sadegb1	Yes
Subject Matter Expert	Jackson Lippert	lippertj	Yes
Guest			

### AGENDA ITEMS

1. Start a work period for our final design [report](#)

### MEETING MINUTES

1. Updates
  - a.
2. Work period
  - a. Jackson finished the executive [summary](#)
  - b. Borna has written most of the introduction [section](#)

### POST-MEETING ACTION ITEMS

1. Get in contact with Ahmed to see when he can meet to finish off his assigned [sections](#)

**ENGINEER 1P13**

MEETING WITH TEAM 26 - THURSDAY, APRIL 15, 2021

**ATTENDANCE**

Role	Name	Mac ID	Attendance (Yes/No)
Manager	Andrew Krynski	krynskia	Yes
Administrator	Ahmed Mohamed	mohaa97	Yes
Coordinator	Borna Sadeghi	sadegb1	Yes
Subject Matter Expert	Jackson Lippert	lippertj	No
Guest			

**AGENDA ITEMS**

1. Finalize conclusions, appendices and sources in the final design [report](#)

**MEETING MINUTES**

1. Updates
  - a. Introduction section and sources are [completed](#)
  - b. Andrew's CAD models have been rendered and added to the final [report](#)
  - c. We still need to complete our individual [reflections](#)
2. Work period
  - a. The report is [finalized](#)

**POST-MEETING ACTION ITEMS**

1. *Complete learning portfolio website addition [Everyone]*
2. *Complete individual reflections by April 16 [Everyone]*

**Meeting Agendas**

Date/Time	Agenda
<b>March 18/2021 at 12:05</b>	<b>Andrew: Introduce group Ahmed and Andrew: present prototype 1 Jackson and Borna: present prototype 2 Accept feedback from reviewers</b>
<b>March 25/2021 at 12:05</b>	<b>Andrew: Introduce group Jackson: present refined prototype Borna and Ahmed: Describe inspiration Andrew: Discuss future plans Accept feedback from reviewers</b>
<b>April 6/2021 at 2:00</b>	<b>Video Presentation Accept questions from evaluators Give all members the opportunity to speak</b>



## Section 5

### Source Materials Database

(Including those referenced and not referenced in this project report)

- [1] Leonard Kim, “5 Hand Exercises to Help You Maintain Your Dexterity & Flexibility,” University of Southern California, (online). Available: <https://uscvhh.org/news-and-stories/5-hand-exercises-to-help-you-maintain-your-dexterity-flexibility.html>. [Accessed: March 8, 2021].
- [2] Kristeen Cherney, “Everything You Need to Know About Fibromyalgia,” Healthline, 2020, (online). Available: <https://www.healthline.com/health/fibromyalgia>. [Accessed: March 8, 2021].
- [3] “Hand and Wrist Pain,” Versus Arthritis, (online). Available: <https://www.versusarthritis.org/about-arthritis/conditions/hand-and-wrist-pain/>. [Accessed: March 8, 2021].
- [4] “Top 5 Ways to Reduce Crippling Hand Pain,” Harvard Health Publishing, 2020, (online). Available: <https://www.health.harvard.edu/pain/top-5-ways-to-reduce-crippling-hand-pain>. [Accessed: March 8, 2021].
- [5] “Body Anatomy: Upper Extremity Muscles: The Hand Society,” *Body Anatomy: Upper Extremity Muscles / The Hand Society*. [Online]. Available: [https://www.assh.org/handcare/safety/muscles#:~:text=In%20the%20forearm%2C%20the%20FDS,finger%20\(except%20the%20thumb\)](https://www.assh.org/handcare/safety/muscles#:~:text=In%20the%20forearm%2C%20the%20FDS,finger%20(except%20the%20thumb)). [Accessed: 15-Mar-2021].
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- [11] J. Raymond, K. Morrow, Krause and Mahan's Food and the Nutrition Care Process E-Book (15th ed.), 2020. [E-book] Available: [https://www.ebooks.com/en-sa/book/210014656/krause-and-mahan-s-food-and-the-nutrition-care-process-e-book/raymond-janice-l-morrow-kelly/?src=feed&gclid=Cj0KCQjwi7yCBhDJARIsAMWFScNY9RCWZOI\\_Izi7JI3pUJXUnFrsQf\\_2MracSQ9vS-5XiRu8OGBQZNlaAhkqEALw\\_wcB](https://www.ebooks.com/en-sa/book/210014656/krause-and-mahan-s-food-and-the-nutrition-care-process-e-book/raymond-janice-l-morrow-kelly/?src=feed&gclid=Cj0KCQjwi7yCBhDJARIsAMWFScNY9RCWZOI_Izi7JI3pUJXUnFrsQf_2MracSQ9vS-5XiRu8OGBQZNlaAhkqEALw_wcB).
- [12] S. Rea, "Neurobiological Changes Explain How Mindfulness Meditation Improves Health," 04, Feb, 2016. Available: <https://www.cmu.edu/news/stories/archives/2016/february/meditation-changes-brain.html>. [Accessed Mar. 15, 2021].
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