

## Seminar 11

1. Find the second-order Taylor polynomial for the following functions at the given points:

- (a)  $f(x, y) = \sin(x + 2y)$  at  $(0, 0)$ .      (c)  $f(x, y) = \sin(x) \sin(y)$  at  $(\pi/2, \pi/2)$ .  
(b)  $f(x, y) = e^{x+y}$  at  $(0, 0)$  and  $(1, -1)$ .      (d)  $f(x, y) = e^{-(x^2+y^2)}$  at  $(0, 0)$ .

2. Compute the Hessian matrix and its eigenvalues for the following:

- (a)  $f(x, y) = (y - 1)e^x + (x - 1)e^y$  at  $(0, 0)$ .      (b)  $f(x, y) = \sin(x) \cos(y)$  at  $(\pi/2, 0)$ .

3. Find and classify the critical points for each of the following functions:

- (a)  $f(x, y) = x^3 - 3x + y^2$ .      (c)  $f(x, y) = x^4 + y^4 - 4(x - y)^2$ .  
(b)  $f(x, y) = x^3 + y^3 - 6xy$ .      (d)  $f(x, y, z) = x^2 + y^2 + z^2 - xy + x - 2z$ .

4. Let  $A$  be a symmetric  $n \times n$  matrix and the quadratic function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $f(x) = \frac{1}{2}x^T A x$ . Prove that  $\nabla f(x) = Ax$  and  $H(x) = A$ . *Hint: use the Taylor expansion.*

5. Let  $A$  be an  $m \times n$  matrix,  $b$  a vector in  $\mathbb{R}^m$  and the least squares minimization problem

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|^2.$$

Prove that the solution  $x^*$  of this problem satisfies (the so-called normal equations)

$$A^T A x^* = A^T b.$$

6. ★[Python] Let  $A$  be a  $2 \times 2$  matrix and let the quadratic function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$ ,  $f(x) = \frac{1}{2}x^T A x$ .

- (a) Give a matrix  $A$  such that  $f$  has a unique minimum.  
(b) Give a matrix  $A$  such that  $f$  has a unique maximum.  
(c) Give a matrix  $A$  such that  $f$  has a unique saddle point.

In each case plot the 3d surface, three contour lines and the gradient at three different points.

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Homework questions are marked with ★.

$$1. a) f(x, y) = \sin(x+2y) \quad \text{at } (0,0)$$

$$T_2(x, y) = f(x_0, y_0) + \nabla f(x_0, y_0) \cdot (x - x_0, y - y_0) + \frac{1}{2} (x - x_0, y - y_0) H(x_0, y_0) \begin{pmatrix} x - x_0 \\ y - y_0 \end{pmatrix}$$

$$f(0,0) = 0$$

$$\nabla f(x, y) = (1, 2)$$

$$\frac{\partial f}{\partial x} = \cos(x+2y)$$

$$\frac{\partial f}{\partial y} = 2 \cos(x+2y)$$

$$\frac{\partial^2 f}{\partial x^2} = -\sin(x+2y)$$

$$\frac{\partial^2 f}{\partial y^2} = -4 \sin(x+2y)$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = -2 \sin(x+2y)$$

$$H(0,0) = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$T_2(0,0) = 0 + (1,2)(x,y) = x+2y$$

$$t = x+2y \quad \sin t = t - \frac{t^3}{3!} + \dots, \quad T_2(t) = t$$

$$b) f(x, y) = e^{x+y} \quad \text{at } (0,0), (1,-1)$$

$$t = x+y \quad e^t = \sum_{u=0}^{\infty} \frac{t^u}{u!} = 1 + t + \frac{t^2}{2!} + \frac{t^3}{3!} + \dots$$

$$T_2(t) = 1 + t + \frac{t^2}{2}$$

$$T_2(x, y) = 1 + x + y + \frac{(x+y)^2}{2}$$

$$f(0,0) = e^0 = 1$$

$$f(1,-1) = e^0 = 1$$

$$\nabla f(0,0) = (1,1)$$

$$\nabla f(1,-1) = (1,1)$$

$$\frac{\partial f}{\partial x} = e^{x+y}$$

$$\frac{\partial f}{\partial y} = e^{x+y}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial^2 f}{\partial y^2} = \frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = e^{x+y}$$

$$H(0,0) = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$H(1,-1) = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$T_2(0,0) = 1 + (1,1)(x,y) + \frac{1}{2}(x,y) \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$= 1 + x + y + \frac{1}{2}(x,y) \cdot \begin{pmatrix} x+y \\ x+y \end{pmatrix}$$

$$= 1 + x + y + \frac{1}{2}(x,y) \cdot (x+y, x+y)$$

$$= 1 + x + y + \frac{1}{2}(x(x+y) + y(x+y))$$

$$= 1 + x + y + \frac{(x+y)^2}{2}$$

$$T_2(1,-1) = 1 + (1,1)(x-1, y+1) + \frac{1}{2}(x-1, y+1) \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x-1 \\ y+1 \end{pmatrix}$$

$$= 1 + x-1 + y+1 + \frac{1}{2}(x-1, y+1) \begin{pmatrix} x+y \\ x+y \end{pmatrix}$$

$$= 1 + x + y + \frac{(x+y)^2}{2}$$

$$c) \quad f(x, y) = \sin x \sin y \quad \text{at } \left(+\frac{\pi}{2}, \frac{\pi}{2}\right)$$

$$= \frac{1}{2}(\cos(x-y) - \cos(x+y))$$

$$\cos t = \left[1 - \frac{t^2}{2!}\right] + \frac{t^4}{4!} - \dots, \quad \forall t \in \mathbb{R}$$

$$t = x - y \Rightarrow \cos(x-y) = 1 - \frac{(x-y)^2}{2} + \dots$$

$$t = x + y \Rightarrow \cos(x+y) = 1 - \frac{(x+y)^2}{2} + \dots$$

$$\begin{aligned} T_2(x, y) &= \frac{1}{2} \left[ 1 - \frac{(x-y)^2}{2} - 1 + \frac{(x+y)^2}{2} \right] \\ &= \frac{1}{2} \left[ \frac{(x+y - x+y)(x+y + x-y)}{2} \right] \\ &= x \cdot y \end{aligned}$$

$$\begin{aligned} f\left(\frac{\pi}{2}, \frac{\pi}{2}\right) &= \sin\left(+\frac{\pi}{2}\right) \sin \frac{\pi}{2} \\ &= +1 \end{aligned}$$

$$\nabla f\left(\frac{\pi}{2}, \frac{\pi}{2}\right) = (0, 0)$$

$$\frac{\partial f}{\partial x} = \cos x \sin y$$

$$\frac{\partial f}{\partial y} = \sin x \cos y$$

$$d) \quad f(x, y) = e^{-(x^2+y^2)} \quad \text{at } (0, 0)$$

$$f(0, 0) = e^0 = 1$$

$$\nabla f(0, 0) = (0, 0)$$

$$\frac{\partial f}{\partial x} = e^{-(x^2+y^2)} \cdot (-2x)$$

$$\frac{\partial f}{\partial y} = e^{-(x^2+y^2)} \cdot (-2y)$$

$$\begin{aligned} \frac{\partial^2 f}{\partial x^2} &= (-2) \cdot e^{-(x^2+y^2)} + (-2x) \cdot e^{-(x^2+y^2)} \cdot (-2x) \\ &= -2e^{-(x^2+y^2)} + 4x^2 \cdot e^{-(x^2+y^2)} \\ &= e^{-(x^2+y^2)} (4x^2 - 2) \end{aligned}$$

$$\frac{\partial^2 f}{\partial y^2} = e^{-(x^2+y^2)} (4y^2 - 2)$$

$$\begin{aligned} \frac{\partial^2 f}{\partial x \partial y} &= \frac{\partial^2 f}{\partial y \partial x} = e^{-(x^2+y^2)} (-2x)(-2y) \\ &= 4xy \cdot e^{-(x^2+y^2)} \end{aligned}$$

$$H(0,0) = \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix}$$

$$\begin{aligned} T_2(x,y) &= 1 + \frac{1}{2} (x,y) \cdot \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix} \cdot \begin{pmatrix} x \\ y \end{pmatrix} \\ &= 1 + \frac{1}{2} (x,y) \cdot \begin{pmatrix} -2x \\ -2y \end{pmatrix} \\ &= 1 + \frac{1}{2} (-2x^2 - 2y^2) \\ &= 1 - x^2 - y^2 \end{aligned}$$

(a)  $f(x, y) = (y-1)e^x + (x-1)e^y$  at  $(0, 0)$ .

$$\frac{\partial f}{\partial x} = (y-1)e^x + e^y$$

$$\frac{\partial^2 f}{\partial x^2} = (y-1)e^x$$

$$\frac{\partial f}{\partial y} = e^x + (x-1)e^y$$

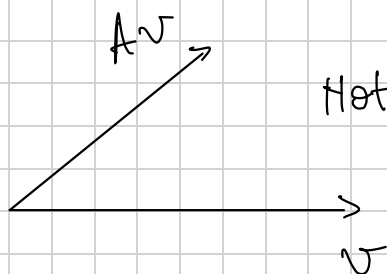
$$\frac{\partial^2 f}{\partial y^2} = (x-1)e^y$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = e^x + e^y$$

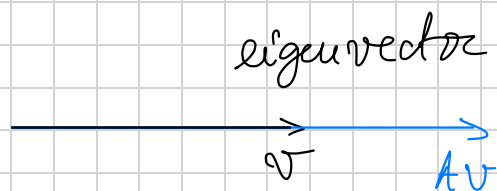
$$H(0, 0) = \begin{bmatrix} -1 & 2 \\ 2 & -1 \end{bmatrix}$$

eigen values

$$A \cdot v = \lambda v$$



Not eigenvector



$$(A - \lambda I) v = 0, v \neq 0$$

$$\det(A - \lambda I) = 0$$

$$H - \lambda I = \begin{pmatrix} -1-\lambda & 2 \\ 2 & -1-\lambda \end{pmatrix}$$

$$\Rightarrow \det = (-1-\lambda)^2 - 4 = \lambda^2 + 2\lambda - 3$$

$$\det(H - \lambda I) = 0$$

$$\lambda^2 + 2\lambda - 3 = 0$$

$$\Delta = 4 + 12 = 16$$

$$\lambda_{1,2} = \frac{-2 \pm 4}{2} \begin{cases} \lambda_1 = -3 \\ \lambda_2 = 1 \end{cases}$$

eigenvalues

$$3. a) f(x, y) = x^3 - 3x + y^2$$

$$\frac{\partial f}{\partial x} = 3x^2 - 3$$

$$\frac{\partial f}{\partial y} = 2y$$

$$\frac{\partial^2 f}{\partial x^2} = 6x$$

$$\frac{\partial^2 f}{\partial y^2} = 2$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = 0$$

$$\nabla f(x, y) = (3x^2 - 3, 2y)$$

$$\nabla f(x, y) = (0, 0) \Leftrightarrow \begin{cases} x = \pm 1 \\ y = 0 \end{cases}$$

$$H(1, 0) = \begin{bmatrix} 6 & 0 \\ 0 & 2 \end{bmatrix}$$

$$H(-1, 0) = \begin{bmatrix} -6 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\lambda_1 = 6 \quad \lambda_2 = 2 > 0$$

$\Rightarrow (1, 0)$  local min.

$$\lambda_1 = -6 \quad \lambda_2 = 2$$

$\Rightarrow (-1, 0)$  saddle point

$$d) f(x, y, z) = x^2 + y^2 + z^2 - xy + x - 2z$$

$$\frac{\partial f}{\partial x} = 2x - y + 1$$

$$\frac{\partial f}{\partial y} = 2y - x$$

$$\frac{\partial f}{\partial z} = 2z - 2$$

$$\nabla f(x, y, z) = (0, 0, 0)$$

$$\Leftrightarrow \begin{cases} 2x - y + 1 = 0 \\ -x + 2y = 0 \\ z = 1 \end{cases}$$



$$\Leftrightarrow \begin{cases} 2x - y = -1 \\ -2x + 4y = 0 \\ z = 1 \end{cases} \Leftrightarrow \begin{cases} 2x - y = -1 \\ 3y = -1 \\ z = 1 \end{cases} \Leftrightarrow \begin{cases} 2x + \frac{1}{3} = -1 \\ y = -\frac{1}{3} \\ z = 1 \end{cases}$$

$$\Leftrightarrow \begin{cases} x = -\frac{2}{3} \\ y = -\frac{1}{3} \\ z = 1 \end{cases}$$

$$\frac{\partial^2 f}{\partial x^2} = 2$$

$$\frac{\partial^2 f}{\partial y^2} = 2$$

$$\frac{\partial^2 f}{\partial z^2} = 2$$

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x} = -1$$

$$\frac{\partial^2 f}{\partial x \partial z} = \frac{\partial^2 f}{\partial z \partial x} = 0$$

$$\frac{\partial^2 f}{\partial y \partial z} = \frac{\partial^2 f}{\partial z \partial y} = 0$$

$$H\left(-\frac{2}{3}, -\frac{1}{3}, 1\right) = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$\det(H - \lambda I) = \begin{vmatrix} 2-\lambda & -1 & 0 \\ -1 & 2-\lambda & 0 \\ 0 & 0 & 2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (2-\lambda)^3 - (2-\lambda) = 0$$

$$(2-\lambda) \left[ (2-\lambda)^2 - 1 \right] = 0$$

$$\lambda_1 = 2 > 0 \quad \lambda^2 - 4\lambda + 3 = 0$$

$$\Delta = 16 - 12 = 4$$

$$\lambda_{2,3} = \frac{4 \pm 2}{2} \begin{cases} \lambda_2 = 3 > 0 \\ \lambda_3 = 1 > 0 \end{cases}$$

$\Rightarrow H(x, y, z)$  is positive def.  $\Rightarrow (-\frac{2}{3}, -\frac{1}{3}, 1)$  local minimum

4.  $f(x+h) = f(x) + \nabla f(x) \cdot h + \frac{1}{2} h^T H(x) \cdot h + \dots$

Taylor expansion

$$f(x) = \frac{1}{2} x^T \cdot A x$$

Method 1:  $\frac{\delta f}{\delta x_i} = ?$

Method 2:  $f(x+h) = \frac{1}{2} (x+h)^T \cdot A (x+h)$

$$= \frac{1}{2} x^T \cdot A(x) + \frac{1}{2} x^T \cdot A(h) + \frac{1}{2} h^T A(x) + \frac{1}{2} h^T A(h)$$

$$x^T \cdot A h = \langle x, A h \rangle = x \cdot (A h)$$

$$= \langle A h, x \rangle \quad \langle a, b \rangle = a^T b$$

$$= A h^T \cdot x$$

$$(A \cdot B)^T = A^T \cdot B^T$$

$$= h^T \cdot A^T x$$

$$= h^T \cdot A x$$

$$= \langle h, A x \rangle$$

$$f(x+h) = f(x) + \underbrace{A x \cdot h}_{\nabla f(x)} + \frac{1}{2} h^T \underbrace{A h}_{H(x)}$$

5. Let  $A$  be an  $m \times n$  matrix,  $b$  a vector in  $\mathbb{R}^m$  and the least squares minimization problem

$$\min_{x \in \mathbb{R}^n} \|Ax - b\|^2.$$

Prove that the solution  $x^*$  of this problem satisfies (the so-called normal equations)

$$A^T A x^* = A^T b.$$

$$f(x) = \|Ax - b\|^2 = \langle Ax - b, Ax - b \rangle$$

$$f(x) \rightarrow \min, \quad \nabla f(x) = 0$$

$$f(x) = \langle Ax, Ax \rangle - 2\langle Ax, b \rangle + \langle b, b \rangle$$

$$\begin{aligned} \langle Ax, Ax \rangle &= (Ax)^T \cdot Ax = A^T \cdot x^T \cdot A \cdot x \\ &= x^T (A^T \cdot A) \cdot x \end{aligned}$$

$$f(x) = x^T (A^T \cdot A) x - 2 \underbrace{b^T Ax}_{\langle x, A^T b \rangle = x \cdot (A^T b)} + \|b\|^2$$

$$\nabla f(x) = 2 A^T A x - 2 A^T b = 0$$

$$\Rightarrow A^T A x - A^T b = 0$$

$$A^T A x = A^T b$$