

Assembler-Processor Simulator

The program simulates the tasks of an assembler and a processor.

The program expects two arguments (in the mentioned order) –

1. An assembly file with ‘.asm’ extension, which contains assembly code following TOYRISC architecture.
2. A file with ‘.out’ extension, which is used by the program to store instructions in their binary codes.

The processor is a pipelined model, which consists of five stages – Instruction Fetch, Operand Fetch, Execute, Memory Access, Register Write, in which stages are stalled in case of a data hazard or a control hazard.

TOYRISC Specification

Memory Model

The memory space is of 256KB. Each word is 4 bytes long, and the memory is word-addressable. That is, a total of 65536 words may be stored. These include the program instructions, the static data, and the stack.

Registers

There are a total of 32 registers: x0 to x31. Each register is 4 bytes wide.

Registers in TOYRISC ISA

Register	Purpose
x0	Zero Register
x1	Stack Pointer
x2	Frame Pointer
x3 – x5	Used by the assembler
x6-x30	General purpose
x31	Special behavior, according to particular instruction
PC	Program Counter

Encoding

32 registers require 5 bits for encoding. x0 is encoded as 00000, x1 as 00001, and so on.

Instruction Formats in the custom ISA

R3-type

opcode	rs1	rs2	rd	unused
5 bits	5 bits	5 bits	5 bits	12 bits

R2I-type

opcode	rs1	rs2	immediate
5 bits	5 bits	5 bits	17 bits

RI-type

opcode	rd	immediate
5 bits	5 bits	22 bits

Arithmetic Instruction in TOYRISC ISA

Operation	Opcode	Format	Description
add	00000	R3-Type	$rd = rs1 + rs2$
addi	00001	R2I-Type	$rd = rs1 + imm$
sub	00010	R3-Type	$rd = rs1 - rs2$
subi	00011	R2I-Type	$rd = rs1 - imm$
mul	00100	R3-Type	$rd = rs1 * rs2$
muli	00101	R2I-Type	$rd = rs1 * imm$
div	00110	R3-Type	$rd = rs1 / rs2$
divi	00111	R2I-Type	$rd = rs1 / imm$
and	01000	R3-Type	$rd = rs1 \& rs2$
andi	01001	R2I-Type	$rd = rs1 \& imm$
or	01010	R3-Type	$rd = rs1 rs2$
ori	01011	R2I-Type	$rd = rs1 imm$
xor	01100	R3-Type	$rd = rs1 (xor) rs2$
xori	01101	R2I-Type	$rd = rs1 (xor) imm$
slt	01110	R3-Type	$rd = 1 \text{ if } rs1 < rs2, 0 \text{ otherwise}$
slti	01111	R2I-Type	$rd = 1 \text{ if } rs1 < imm, 0 \text{ otherwise}$

sll	10000	R3-Type	rd = rs1 logically left shifted by rs2 bits
slli	10001	R2I-Type	rd = rs1 logically left shifted by imm bits
srl	10010	R3-Type	rd = rs1 logically right shifted by rs2 bits
srli	10011	R2I-Type	rd = rs1 logically right shifted by imm bits
sra	10100	R3-Type	rd = rs1 arithmetically right shifted by rs2 bits
srai	10101	R2I-Type	rd = rs1 arithmetically right shifted by imm bits

Note: If the result is greater than 32 bits, the higher bits (63 to 32) are stored in x31. In case of division operation, the remainder is stored in x31. In case of shift operations, the bits shifted out are stored in x31.

Memory Instructions in TOYRISC ISA

Operation	Opcode	Format	Description
load	10110	R2I-Type	rd = word at [rs1 + imm]
store	10111	R2I-Type	word at [rd + imm] = rs1

Note: imm values can be specified as label or absolute value

Control Flow Instructions in TOYRISC ISA

Operation	Opcode	Format	Description
jmp	11000	RI-Type	PC = PC + rd + imm
beq	11001	R2I-Type	If rs1 = rd, PC = PC + imm
bne	11010	R2I-Type	If rs1,rd, PC = PC + imm
blt	11011	R2I-Type	If rs1<rd, PC = PC + imm
bgt	11100	R2I-Type	If rs1>rd, PC = PC + imm

End Instruction

Assembly Notation			
Operation	Description		
end	terminate execution		
Binary Code			
Operation	Opcode	Format	Description
end	11101	RI-Type	rd and imm are unused

Push Instruction

Assembly Notation			
Operation	Description		
push	push an argument onto the stack		
Binary Code			
Operation	Opcode	Format	Description
push	11110	RI-Type	rs1 and imm are unused

Ret Instruction

Assembly Notation			
Operation	Description		
ret	return the control flow back to the caller		
Binary Code			
Operation	Opcode	Format	Description
ret	11111	RI-Type	rs1, imm and rd are unused

Function Calling

A function is defined by its name, followed by an empty space (' '), with brackets enclosing its arguments. A comma (',') and an empty space (' ') need to be placed in between every two arguments of the function. The body of the function must reside between opening ('{') and closing ('}') braces, with each statement of the body other than a label properly indented with a tab ('\t').

An example is shown below –

Name of the function – 'add'

Arguments of the function – 'number1', 'number2'

Purpose – Adds the two numbers and stores it in x12

add (#number1, #number2){

```
    load %x0, #number1, %x10    // Retrieving the value of the first argument from the RAM and
                                storing it in x10
```

```
    load %x0, #number2, %x11    // Retrieving the value of the second argument from the RAM
                                storing it in x11
```

```

    add %x12, %x10, %x11      // Storing the sum of the two numbers in x12
    ret                       // Returns the control flow back to the caller
}

```

The instruction 'ret' terminates the function and returns the control flow back to the caller. Every function must have at least one 'ret' instruction.

Arguments can be passed using the 'push' instruction, which needs to be done before calling the function. For example, the instruction - 'push %x6' is interpreted as the instruction to push the value stored in 'x6' onto the stack.

A function can be called using the 'jmp' instruction. For example, the instruction - 'jmp add' is interpreted as a call to the function 'add'.

Parameters can be retrieved in the body of a function using the 'load' instruction, as shown in the first two instructions of the above example - To retrieve the value stored in the memory locations [%x2 + imm], where '%x2' is the frame pointer.

Example 1 – A program which adds two numbers

```

.data
a:
    123
    234

.text
main:
    load %x0, $a, %x4
    addi %x0, 1, %x3
    load %x3, $a, %x5
    add %x4, %x5, %x6

end

```

- '.data' is a directive used to signify the beginning of the global data segment.
- 'a' and 'main' are descriptive names for memory addresses. Here 'a' refers to memory address 0, main refers to memory address 2. These are called 'labels', and are not essential – their only purpose is to make writing, understanding and reasoning about assembly programs easier.

- Global data are simply listed one after the other (after the `.data` directive). Value 123 is stored at memory address 0, value 234 at address 1.
- `‘.text’` is a directive used to signify the beginning of the text or the code segment.
- `‘main’` is a special name. It indicates where the execution will commence from (program counter will be set to this value when the program is loaded).
- Destination operands are always written last. `load %x0, $a, %x4` denotes a load operation that writes the read value to register x4.
- In instructions, named addresses are prefixed by a `“$”`. `load $a` denotes a load operation that reads from memory address 0 (recall that `a` refers to address 0).
- Registers are prefixed by a `‘%’`. `load %x0, $a, %x4` denotes a load operation that writes the read value to register x4.
- Immediate values are written simply.
- `‘end’` is a special instruction type used to denote the end of the program.

Example 2 – A program which computes the factorial of a given number

```
.data
a:
    10
.text
main:
    addi %x0, 7, %x5
    addi %x0, 1, %x20
    push %x5
    jmp factorial
    end
factorial (#a){
    load %x2, #a, %x6
    bgt %x6, %x0, continue
```

ret

continue:

mul %x20, %x6, %x20

subi %x6, 1, %x7

push %x7

jmp factorial

ret

}