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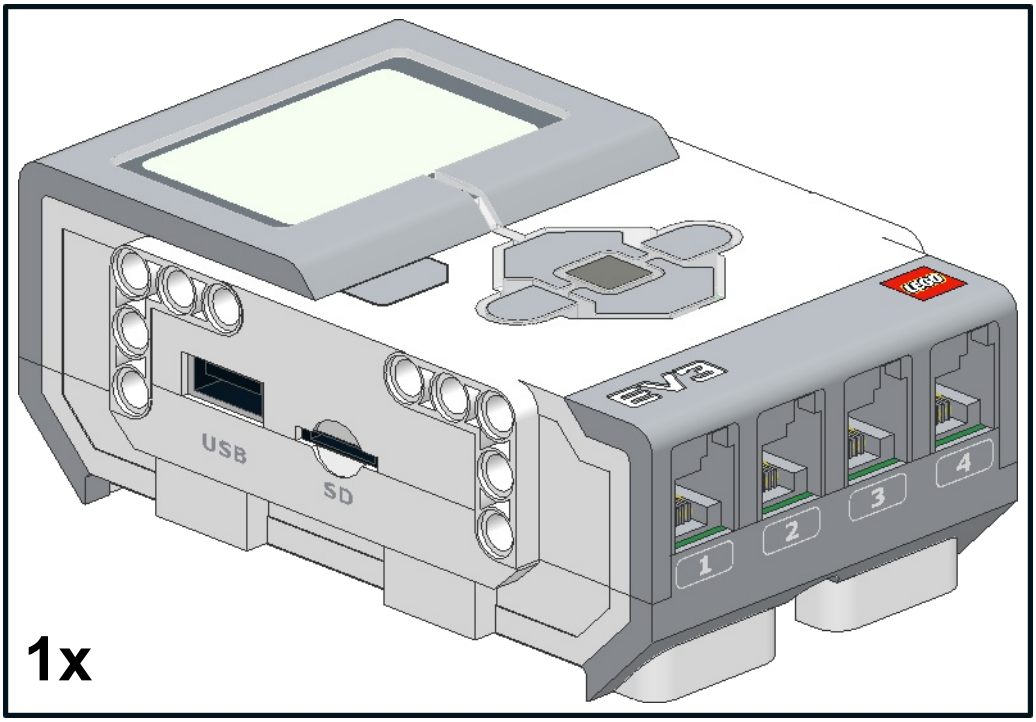

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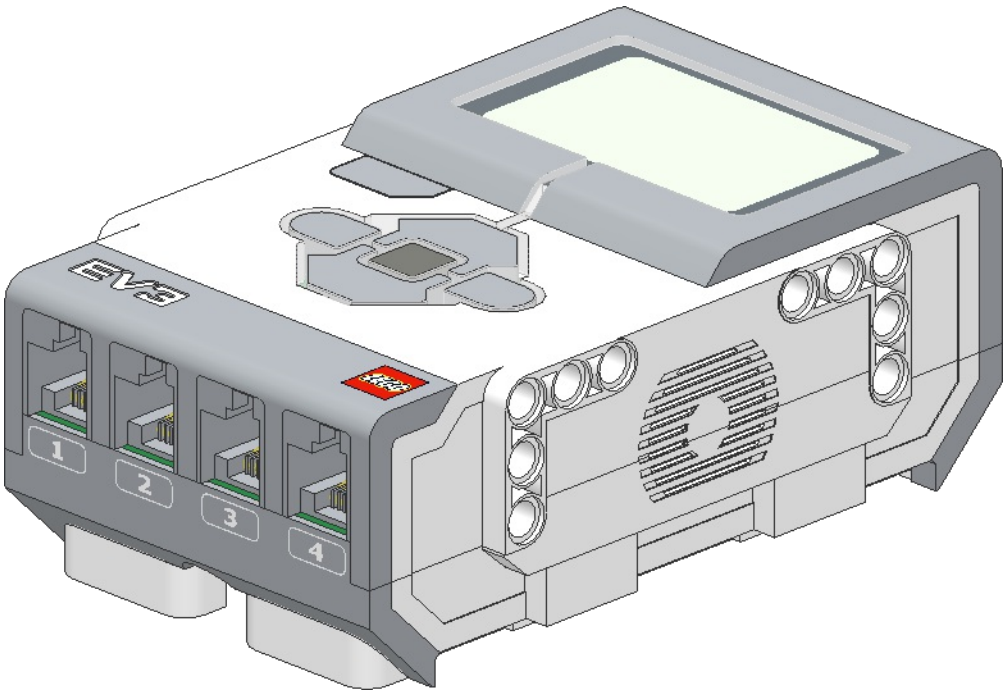

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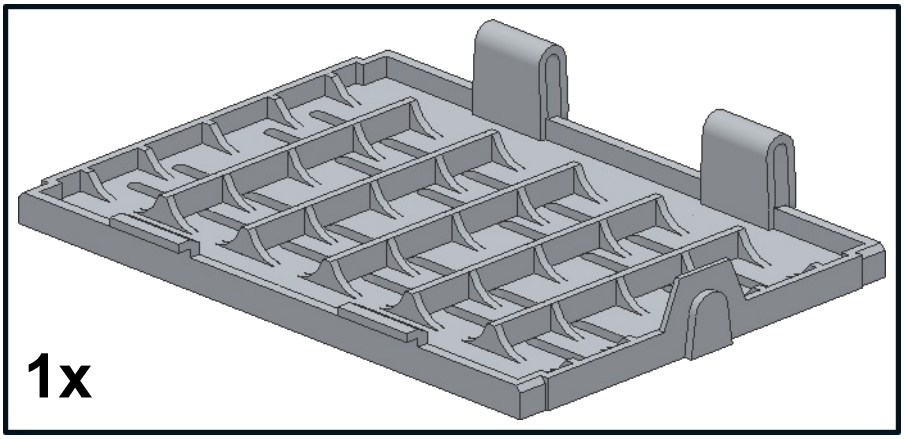

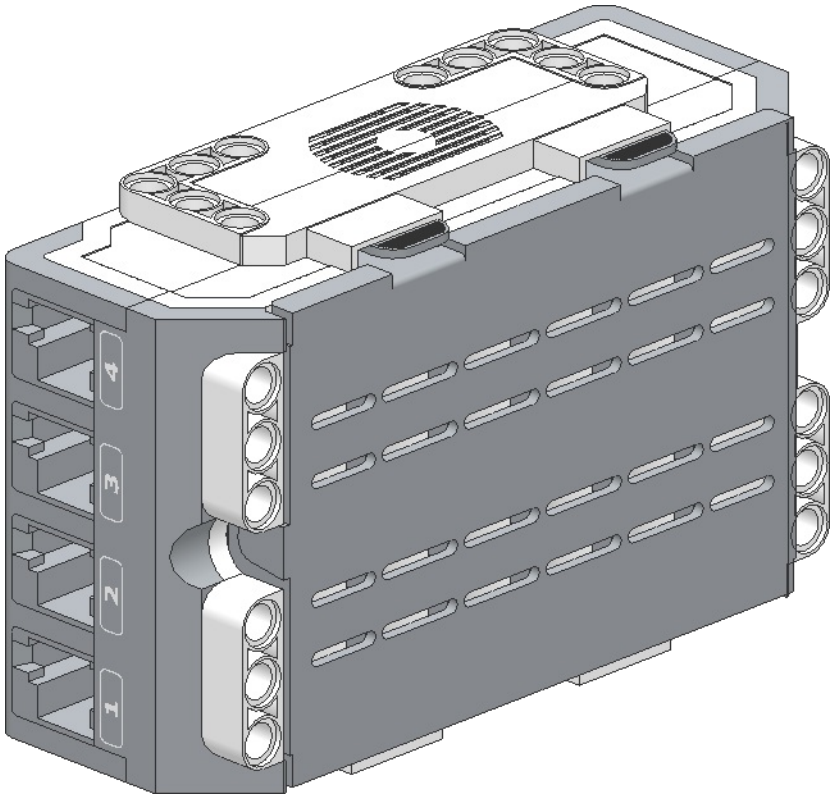

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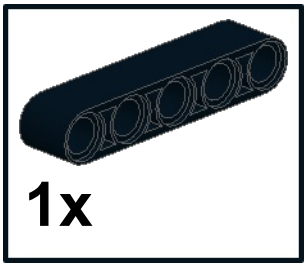

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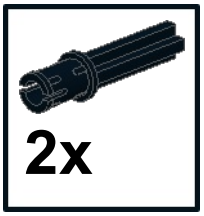

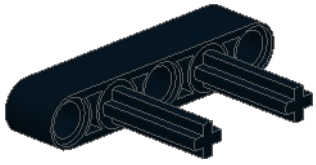

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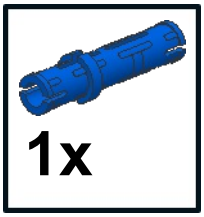

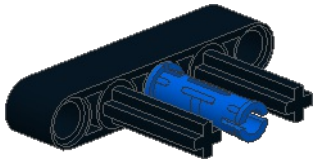

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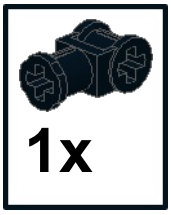

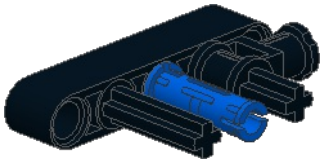

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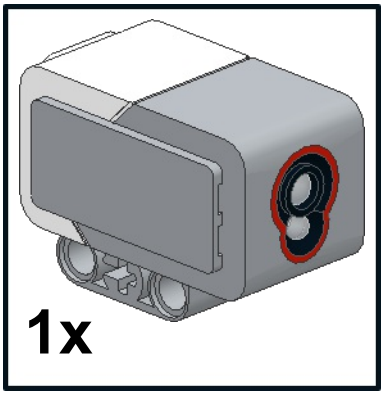

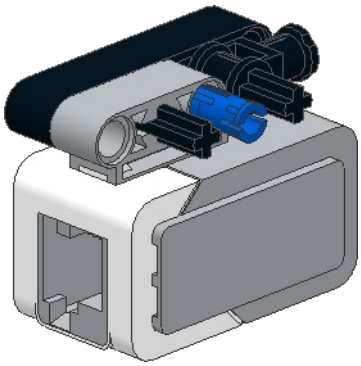

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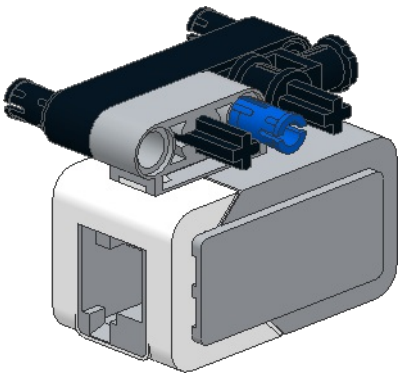

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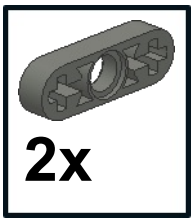

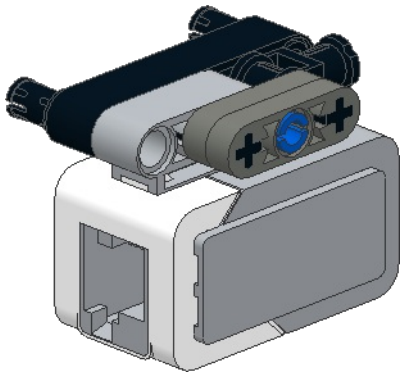

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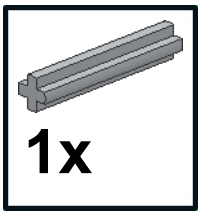

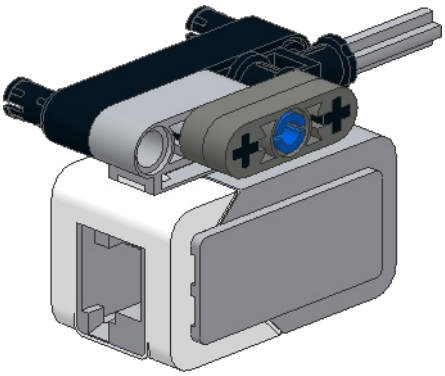

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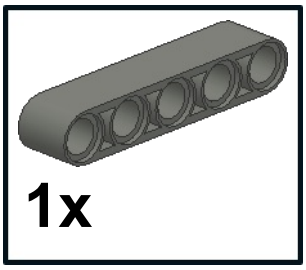

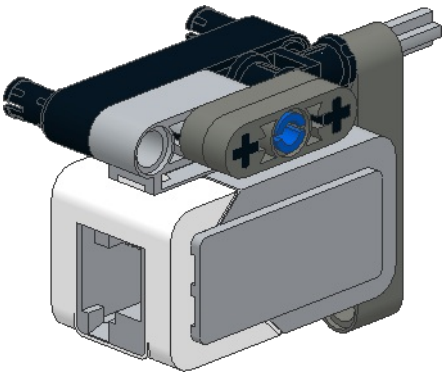

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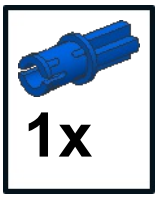

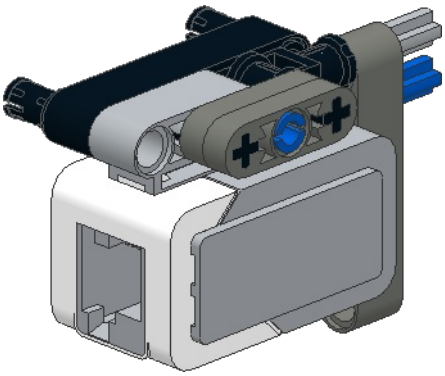

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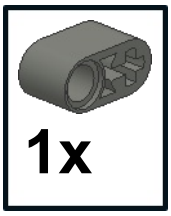

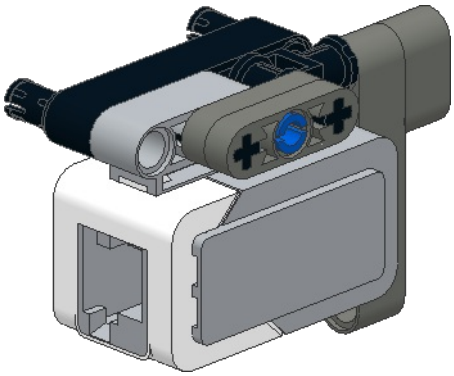

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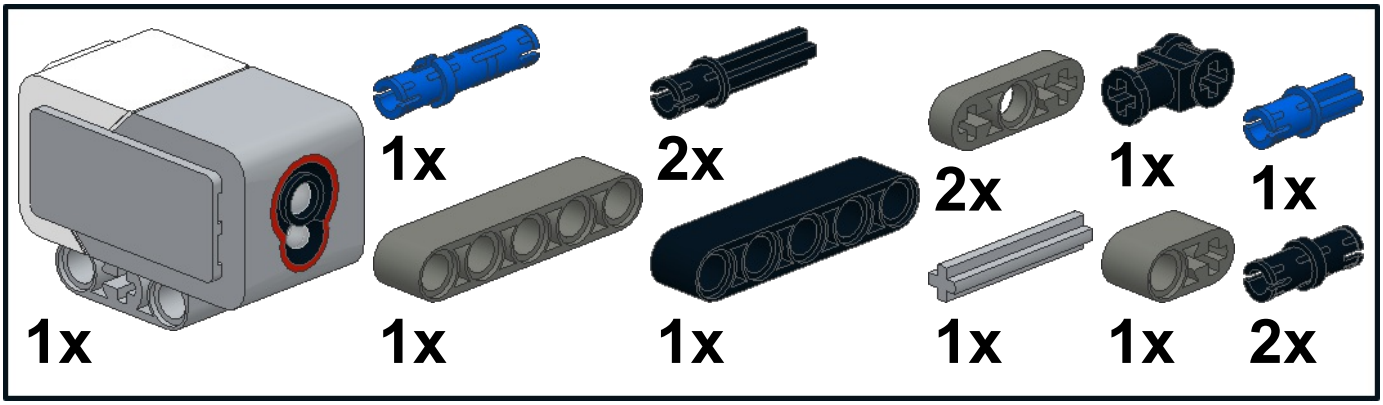

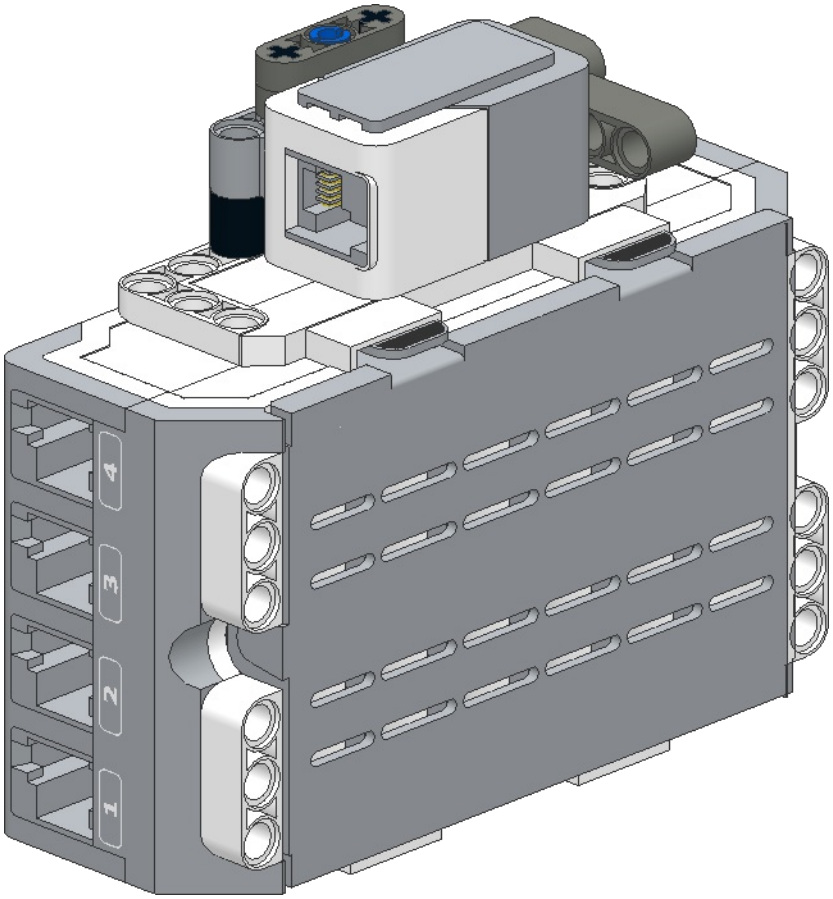

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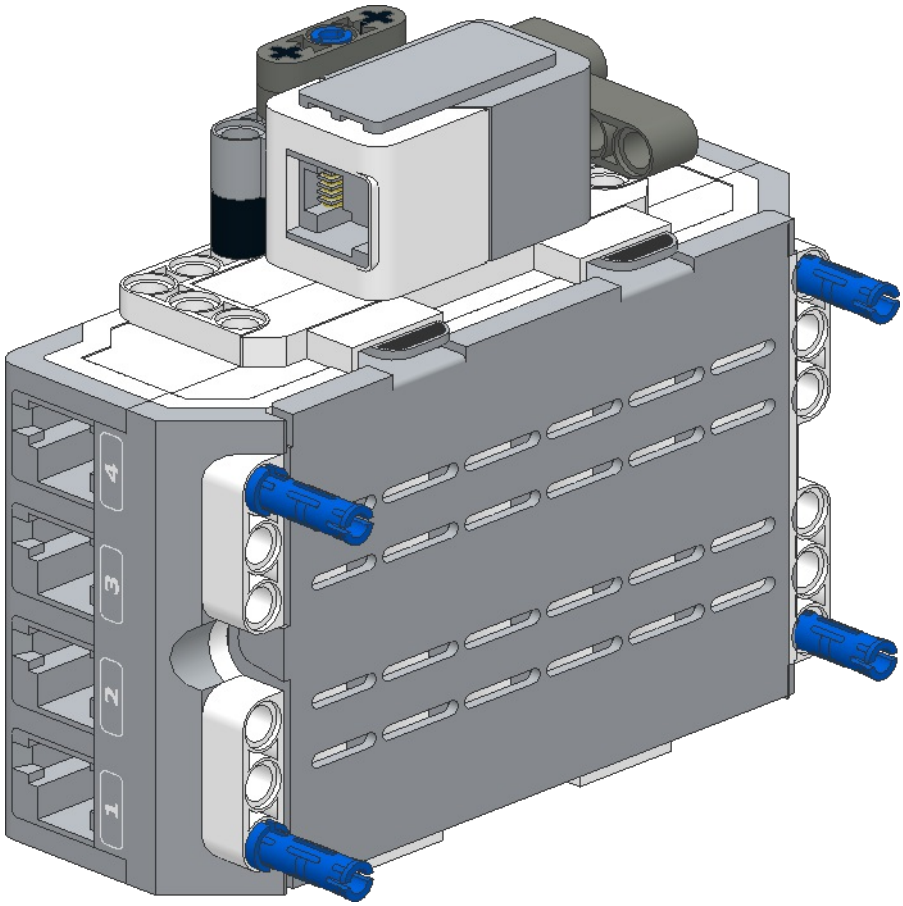

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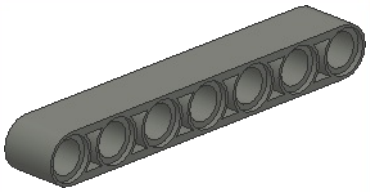

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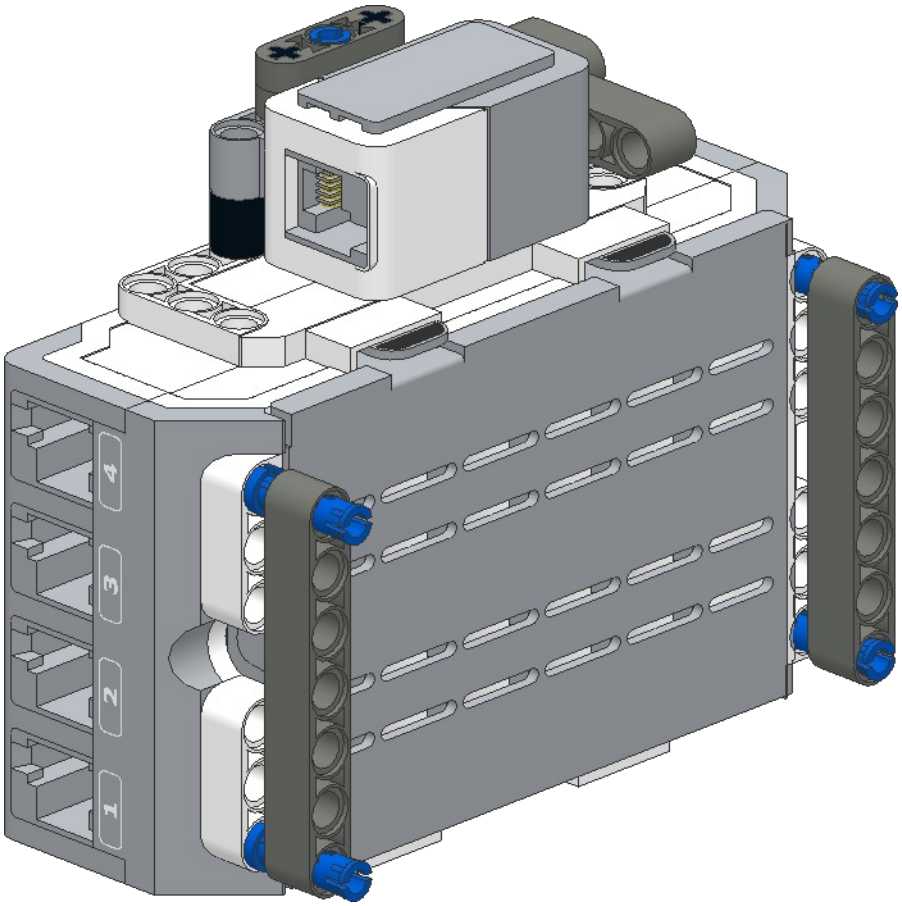

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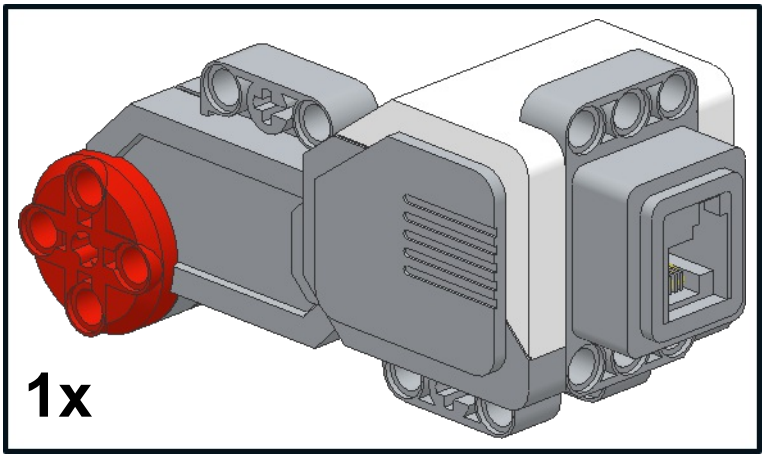

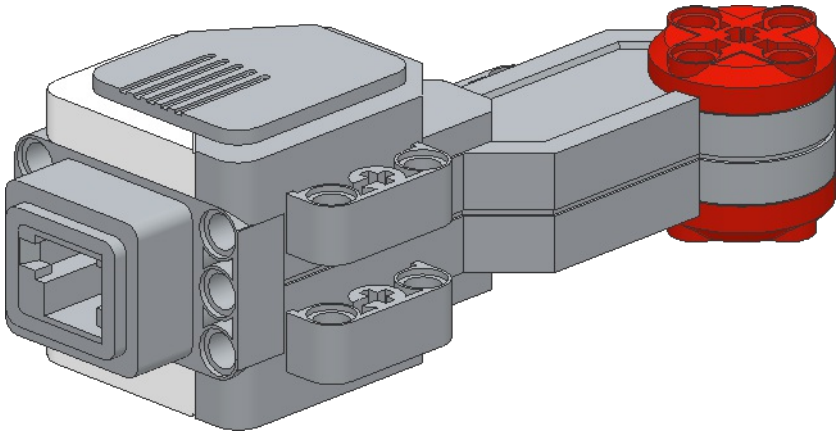

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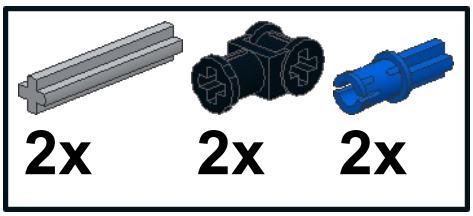

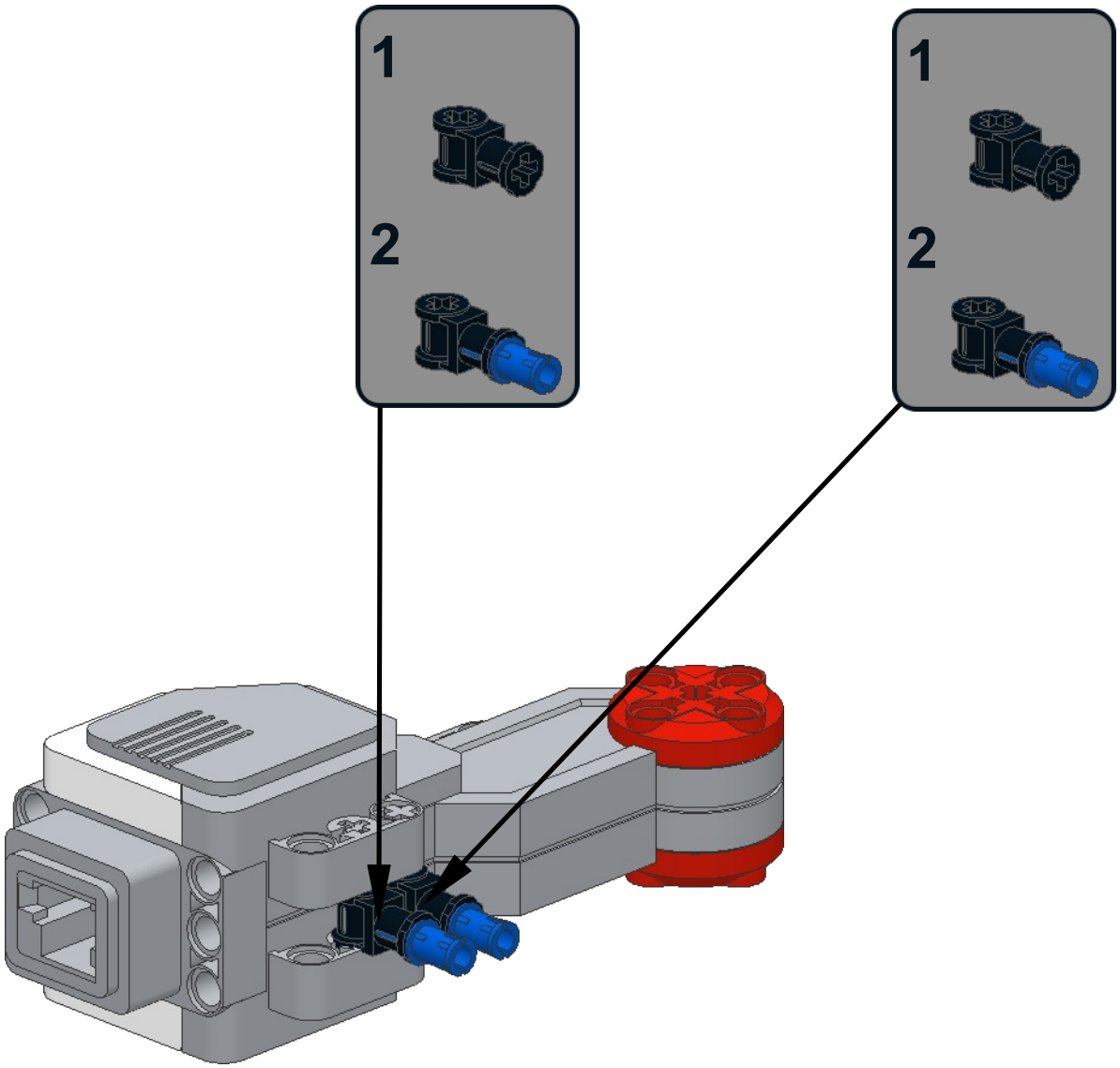

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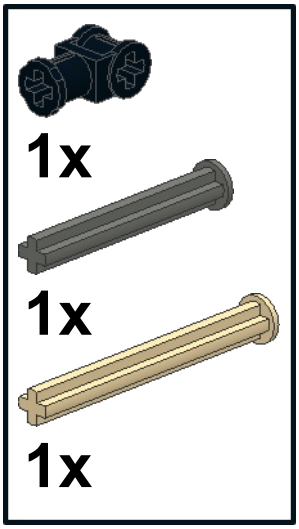

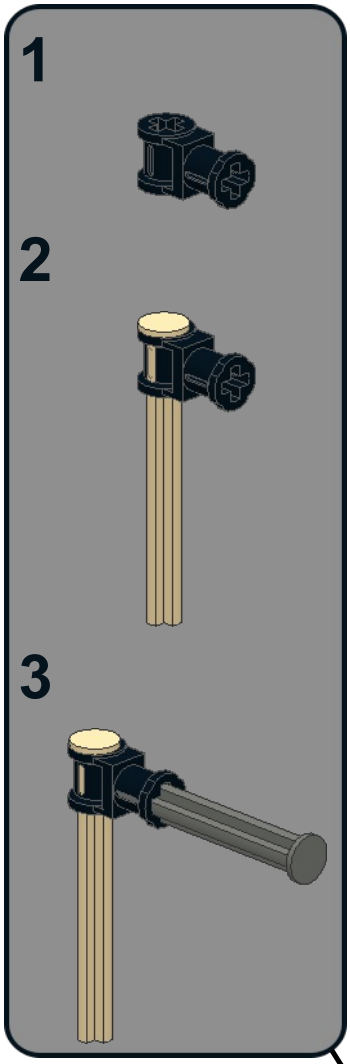

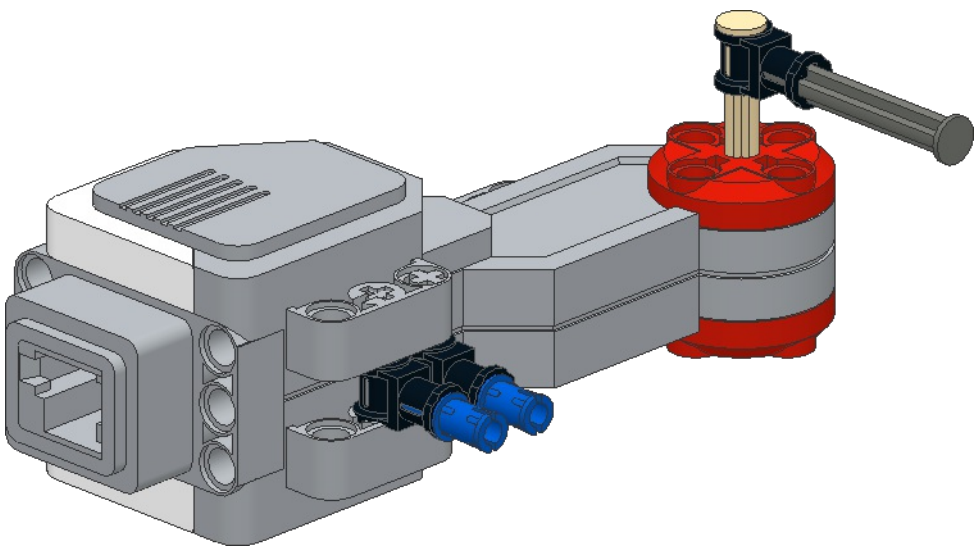

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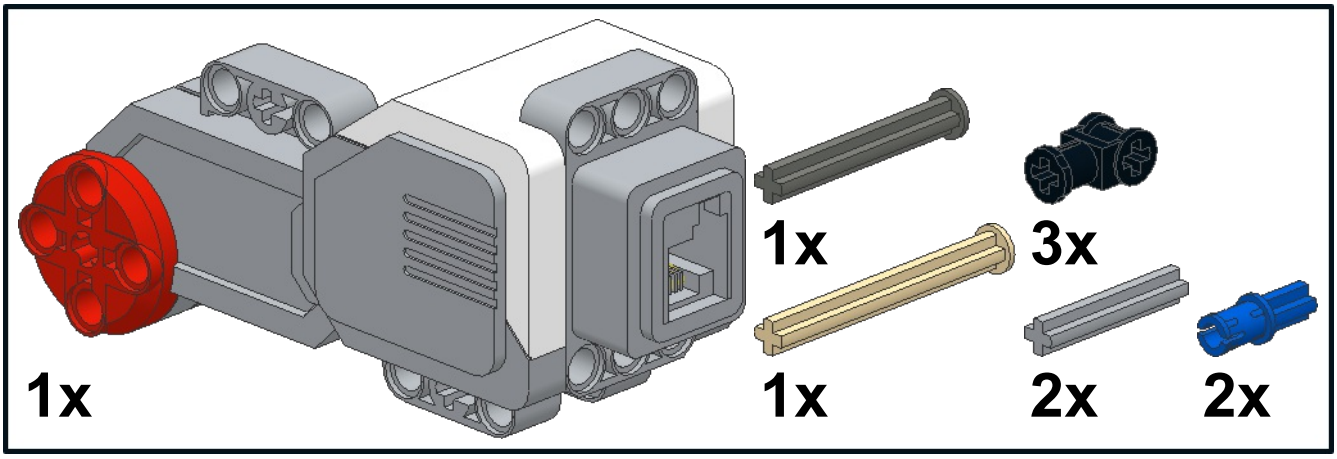

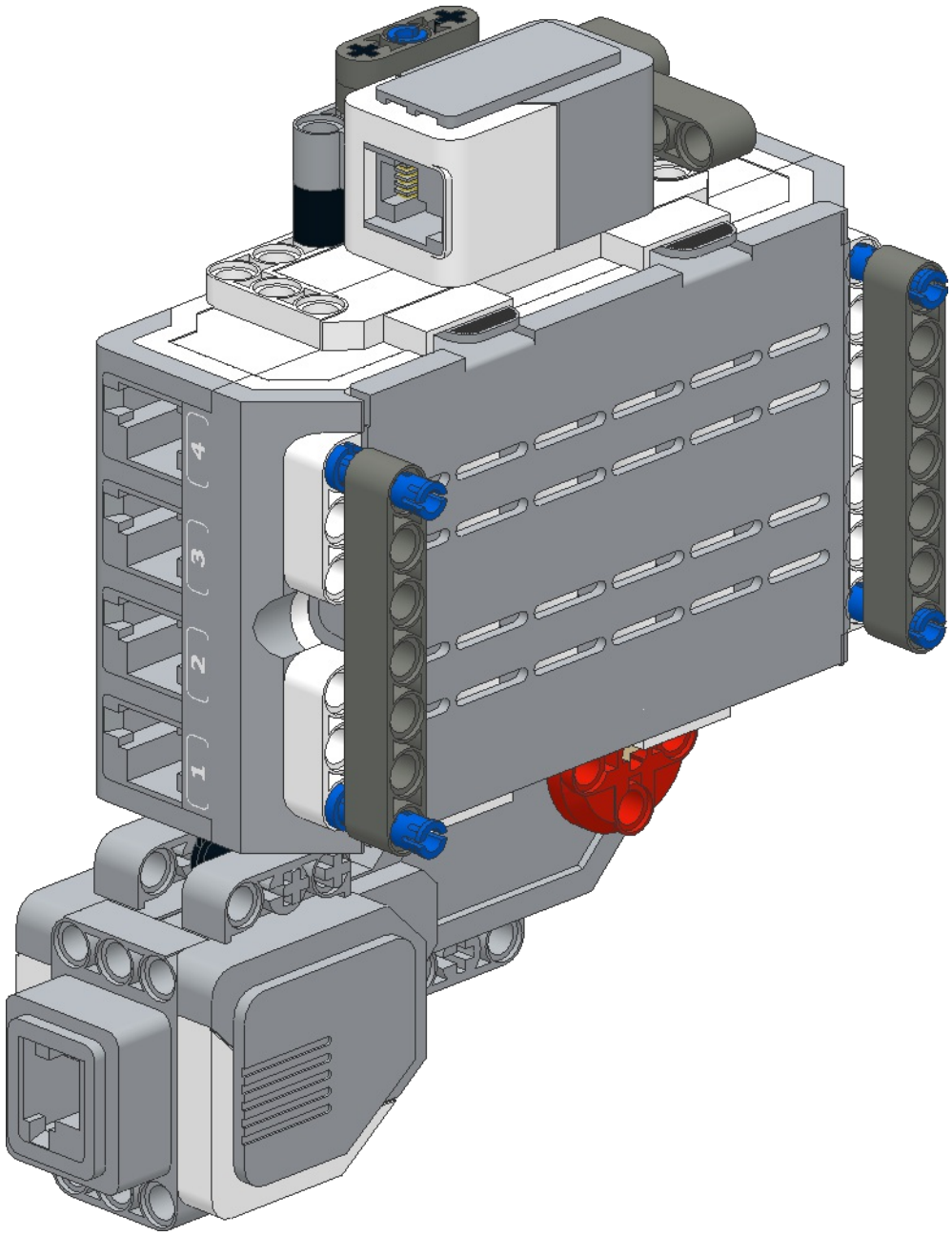

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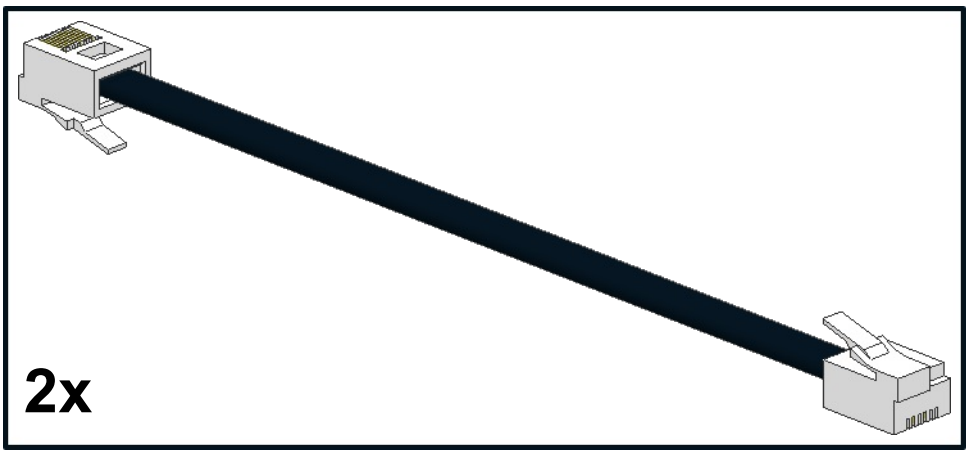
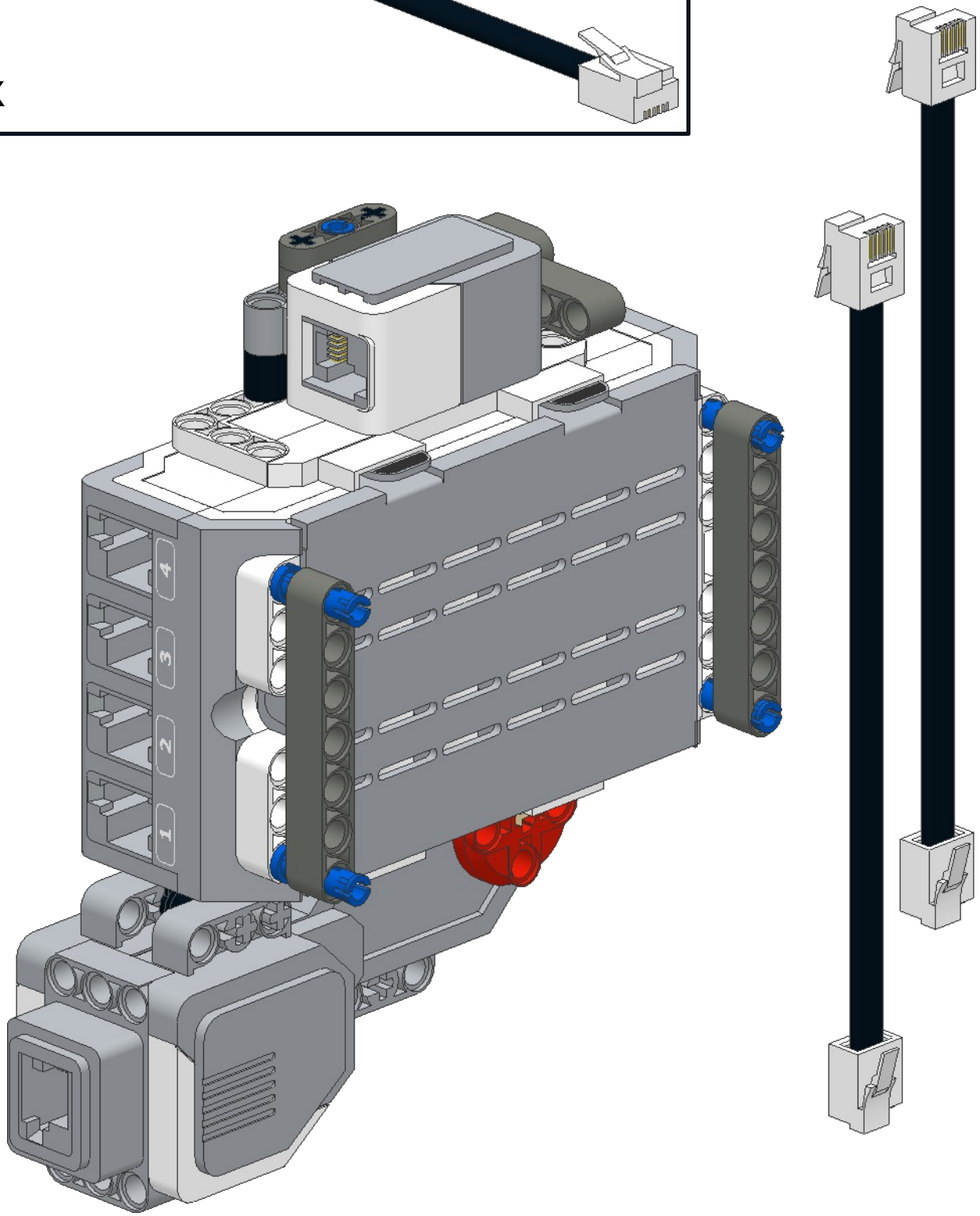
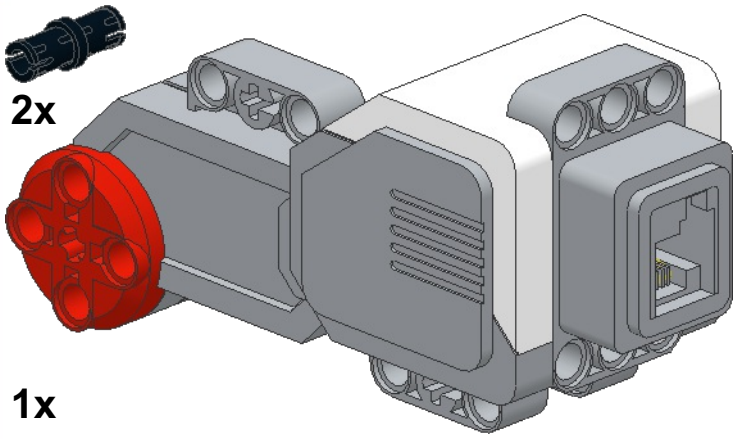




Connect Port B to the motor

Connect Port #3 to the sensor



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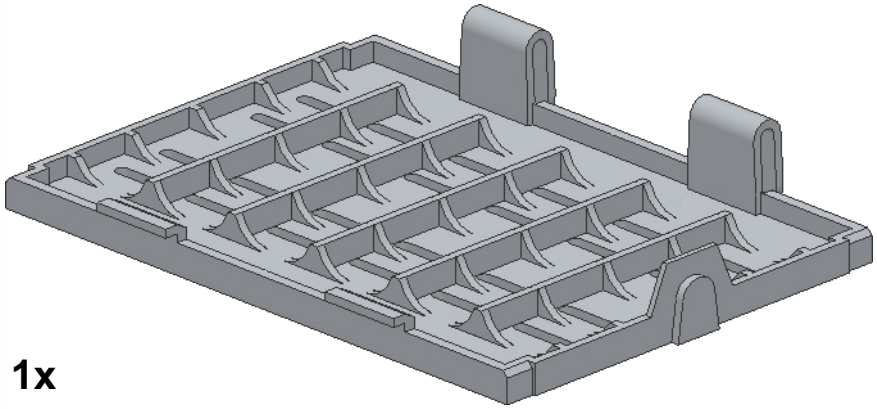

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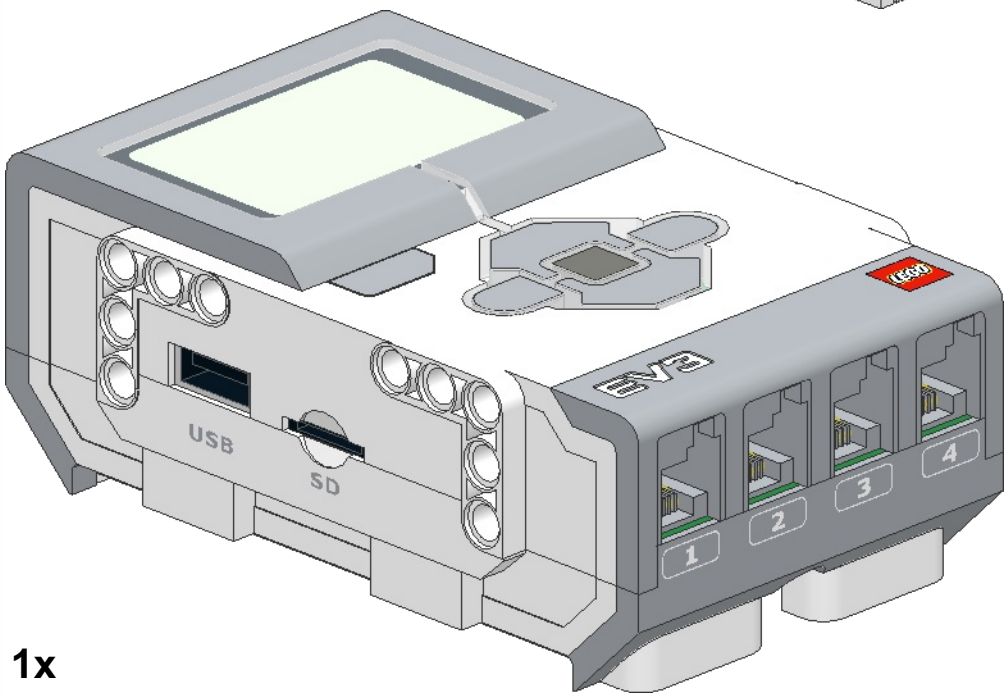

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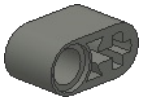

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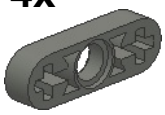

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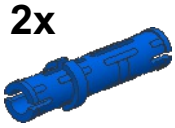

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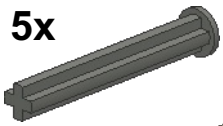

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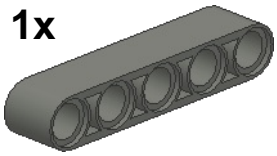

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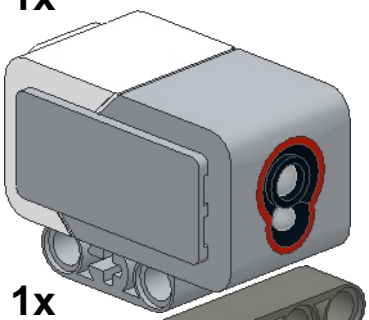

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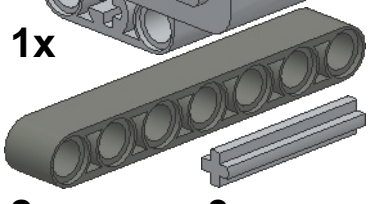

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