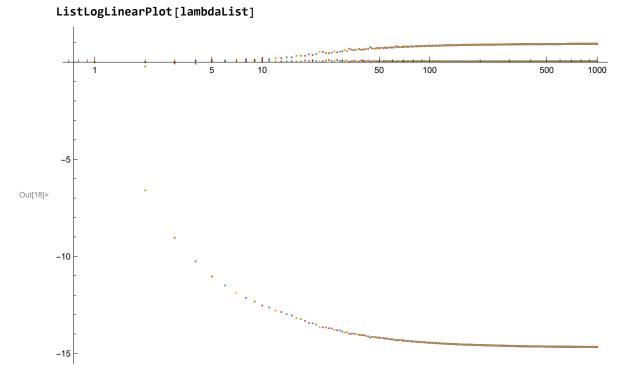
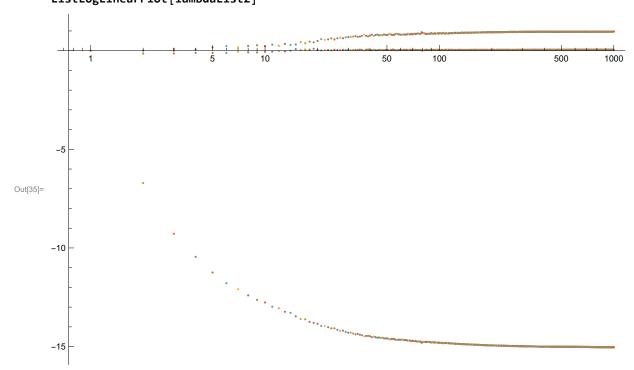
```
In[1]:= Clear["Global`*"]
      (* Initialization *)
      \sigma = 10; b = 8/3; r = 28;
      f[x_{,} y_{,} z_{]} := \sigma * (y - x);
      g[x_{,} y_{,} z_{]} := r * x - y - x * z;
      h[x_{,} y_{,} z_{]} := x * y - b * z;
      J[x_{,}, y_{,}, z_{,}] := \{ \{D[f[x, y, z], x], D[f[x, y, z], y], D[f[x, y, z], z] \}, \}
         \{D[g[x, y, z], x], D[g[x, y, z], y], D[g[x, y, z], z]\},\
         {D[h[x, y, z], x], D[h[x, y, z], y], D[h[x, y, z], z]}
      Tmax = 1000; Tmin = 1;
      s = NDSolve[{x'[t] =  \sigma * (y[t] - x[t]), y'[t] =  r * x[t] - y[t] - x[t] * z[t],}
           z'[t] = x[t] * y[t] - b * z[t], x[0] = y[0] = z[0] = 0.01,
          {x, y, z}, {t, 0, Tmax}, Method → "ExplicitRungeKutta"];
      dt = 0.001;
      Q = IdentityMatrix[3];
      \lambda = ConstantArray[0, 3];
      lambdaList = \{\{0, 0, 0\}\};
      plotIndex = 0;
      (* Main loop *)
      For[i = Tmin, i < Tmax, i = i + dt,</pre>
       trajI = {Evaluate[x[i] /. s], Evaluate[y[i] /. s], Evaluate[z[i] /. s]};
            Jxt = J[x, y, z] /. \{x \to trajI[[1][[1]], y \to trajI[[2][[1]], z \to trajI[[3][[1]]\};
            M = IdentityMatrix[3] + Jxt * dt;
            QR = QRDecomposition[M.Q];
            Qnew = Transpose[QR[[1]]];
            \lambda[[1]] = \lambda[[1]] + 1 / Tmax * Log[Abs[QR[[2]][[1]][1]]];
            \lambda[2] = \lambda[2] + 1 / \text{Tmax} * \text{Log}[Abs[QR[2][2][2]]];
            \lambda[3] = \lambda[3] + 1 / Tmax * Log[Abs[QR[2][3][3]]];
            If[Mod[plotIndex, 1000] == 0, lambdaList = AppendTo[lambdaList,
             \{\{i, Tmax/i * \lambda[1]\}\}, \{i, Tmax/i * \lambda[2]\}\}, \{i, Tmax/i * \lambda[3]\}\}\}\}, \{i\}
            plotIndex = plotIndex + 1;
            Q = Qnew;
      Total[\lambda] (* Total should be -13.67 *)
Out[15]= \{0.940715, 0.0375423, -14.6679\}
Out[16]= -13.6896
```



(* Looks like the Lyapunov exponents have converged. \star)

```
In[19]:= (* Initialization *)
      \sigma = 10; b = 3; r = 28;
     f[x_{y_{y_{z}}} z_{z_{z}}] := \sigma * (y - x);
      g[x_{,} y_{,} z_{]} := r * x - y - x * z;
     h[x_{-}, y_{-}, z_{-}] := x * y - b * z;
      J[x_{,}, y_{,}, z_{,}] := \{ \{D[f[x, y, z], x], D[f[x, y, z], y], D[f[x, y, z], z] \}, \}
          {D[g[x, y, z], x], D[g[x, y, z], y], D[g[x, y, z], z]},
          {D[h[x, y, z], x], D[h[x, y, z], y], D[h[x, y, z], z]}};
      Tmax = 1000; Tmin = 1;
      s = NDSolve[{x'[t] =  \sigma * (y[t] - x[t]), y'[t] =  r * x[t] - y[t] - x[t] * z[t],}
           z'[t] = x[t] * y[t] - b * z[t], x[0] = y[0] = z[0] = 0.01
          \{x, y, z\}, \{t, Tmin, Tmax\}, MaxSteps \rightarrow 1000000];
     dt = 0.001;
      Q = IdentityMatrix[3];
      \lambda = ConstantArray[0, 3];
      lambdaList2 = {{0,0,0}};
      plotIndex = 0;
      (* Main loop *)
      For[i = Tmin, i < Tmax, i = i + dt,</pre>
       trajI = {Evaluate[x[i] /. s], Evaluate[y[i] /. s], Evaluate[z[i] /. s]};
            M = IdentityMatrix[3] + Jxt * dt;
            QR = QRDecomposition[M.Q];
            Qnew = Transpose[QR[[1]]];
            \lambda[[1]] = \lambda[[1]] + 1 / Tmax * Log[Abs[QR[[2]][1]][1]]];
            \lambda[2] = \lambda[2] + 1 / Tmax * Log[Abs[QR[2][2][2]]];
            \lambda[3] = \lambda[3] + 1 / Tmax * Log[Abs[QR[2][3][3]]];
            If[Mod[plotIndex, 1000] == 0, lambdaList2 = AppendTo[lambdaList2,
            \{\{i, Tmax/i*\lambda[1]\}, \{i, Tmax/i*\lambda[2]\}, \{i, Tmax/i*\lambda[3]\}\}\}, \{i, Tmax/i*\lambda[3]\}\}\}
            plotIndex = plotIndex + 1;
           Q = Qnew;
      Total[\lambda] (* Total should be -14 *)
Out[32]= \{0.969316, 0.0394433, -15.0319\}
Out[33]= -14.0231
```

In[34]:= Transpose[lambdaList2]; ListLogLinearPlot[lambdaList2]



(* Looks like the Lyapunov exponents have converged. *)

```
In[36]:= (* Initialization *)
     \sigma = 16; b = 5; r = 350;
     f[x_{y_{y_{z}}} z_{z_{z}}] := \sigma * (y - x);
     g[x_{,} y_{,} z_{]} := r * x - y - x * z;
     h[x_{-}, y_{-}, z_{-}] := x * y - b * z;
     J[x_{,}, y_{,}, z_{]} := \{ \{D[f[x, y, z], x], D[f[x, y, z], y], D[f[x, y, z], z] \}, \}
         {D[g[x, y, z], x], D[g[x, y, z], y], D[g[x, y, z], z]},
         {D[h[x, y, z], x], D[h[x, y, z], y], D[h[x, y, z], z]}};
     Tmax = 2000; Tmin = 1;
     s = NDSolve[{x'[t] =  \sigma * (y[t] - x[t]), y'[t] =  r * x[t] - y[t] - x[t] * z[t],}
          z'[t] = x[t] * y[t] - b * z[t], x[0] = y[0] = z[0] = 0.01
         \{x, y, z\}, \{t, Tmin, Tmax\}, MaxSteps \rightarrow 10000000];
     dt = 0.0001;
     Q = IdentityMatrix[3];
     \lambda = ConstantArray[0, 3];
     lambdaList3 = {{0, 0, 0}};
     plotIndex = 0;
     (* Main loop *)
     For[i = Tmin, i < Tmax, i = i + dt,</pre>
      trajI = {Evaluate[x[i] /. s], Evaluate[y[i] /. s], Evaluate[z[i] /. s]};
           M = IdentityMatrix[3] + Jxt * dt;
           QR = QRDecomposition[M.Q];
           Qnew = Transpose[QR[[1]]];
           \lambda[[1]] = \lambda[[1]] + 1 / Tmax * Log[Abs[QR[[2]][1]][1]]];
           \lambda[2] = \lambda[2] + 1 / Tmax * Log[Abs[QR[2][2][2]]];
           \lambda[3] = \lambda[3] + 1 / Tmax * Log[Abs[QR[2][3][3]]];
           If[Mod[plotIndex, 10000] == 0, lambdaList3 = AppendTo[lambdaList3,
           \{\{i, Tmax/i*\lambda[1]\}, \{i, Tmax/i*\lambda[2]\}, \{i, Tmax/i*\lambda[3]\}\}\}, \{i, Tmax/i*\lambda[3]\}\}\}
           plotIndex = plotIndex + 1;
           If[Mod[plotIndex, 1500000] == 0, Print[i];, f();
           Q = Qnew;
     Total[\lambda] (* Total should be -22 *)
```

151.

301.

451.

601.

751.

901.

1051.

1201.

1351.

1501.

1651.

1801.

1951.

Out[49]= $\{0.11855, -2.99782, -18.9849\}$

Out[50]= -21.8642

In[51]:= Transpose[lambdaList3]; ListLogLinearPlot[lambdaList3]

