

CONTROL ENGINEERING IN JULIA: MODELLING, CONTROL DESIGN AND OPTIMIZATION

2017 AMERICAN CONTROL CONFERENCE

SHERATON SEATTLE HOTEL, SEATTLE, WA, USA

Madeleine Udell, Cornell University, USA

Mikael Johansson, KTH, Sweden

Cristian R. Rojas, KTH, Sweden

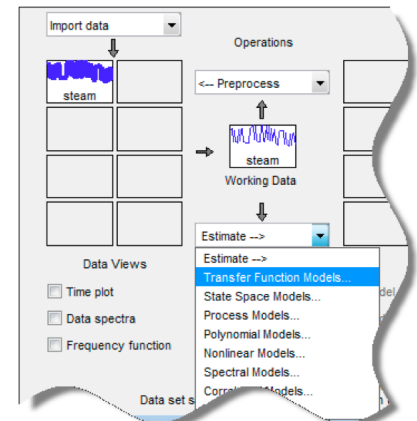
BACKGROUND

- Good software is essential for building engineering applications
- Currently MATLAB/Maple/Mathematica/Octave/Python(SciPy,Numpy)... are our main platforms for education, research and industrial use in automatic control
- Great variety of toolboxes for control, signal processing, identification, statistics, power systems, ...



DRAWBACKS

- Expensive
- Many toolboxes with closed-source code
- Black-box GUIs hiding details
- Limited group of contributors
- Sometimes slow (to run and maintain)...

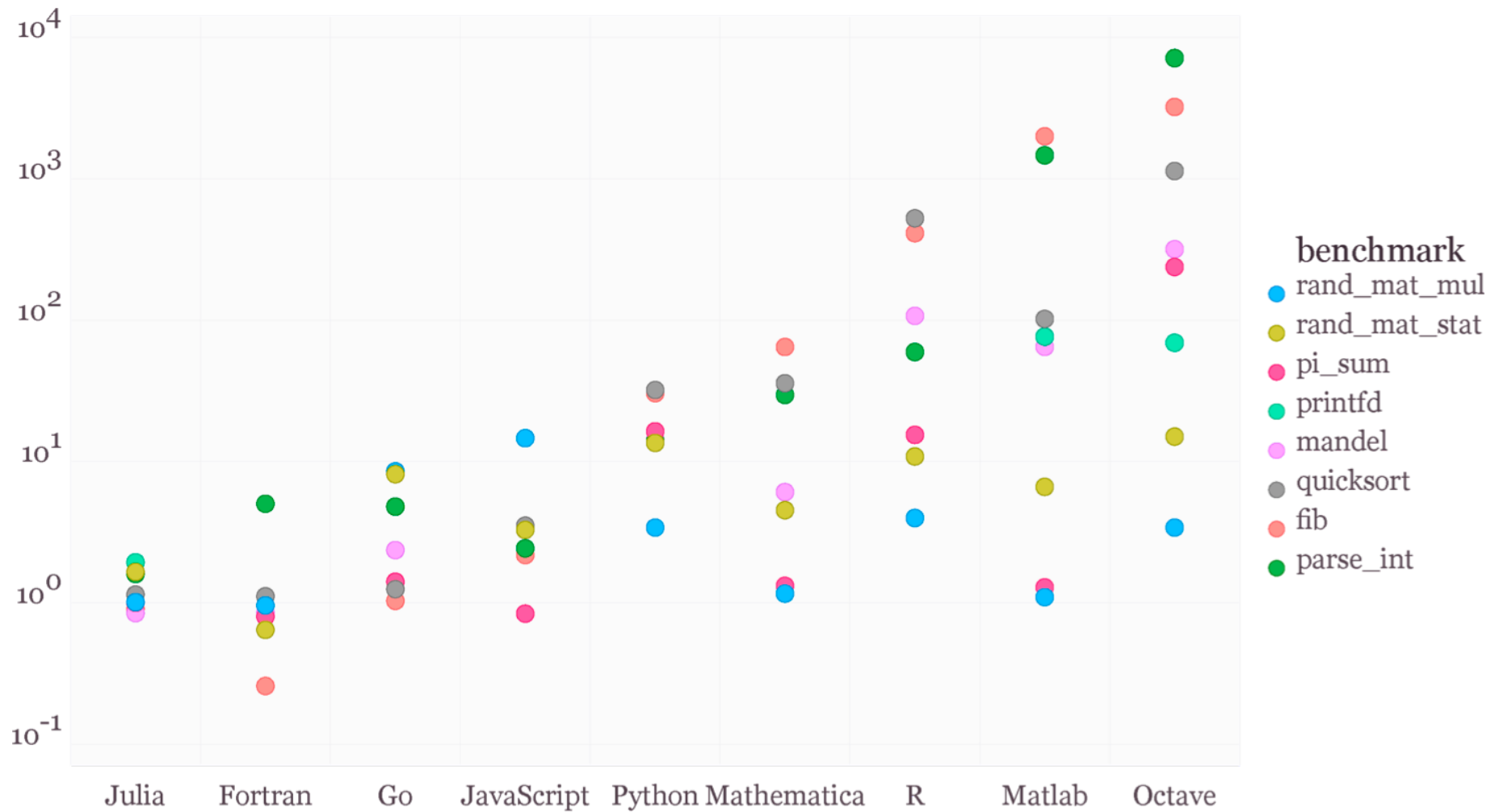


A RECENT ALTERNATIVE: JULIA

- Free and open source
- High-level language (like MATLAB, Python)
- Yet, high performance (like C, FORTRAN)
- Ability to generate low-level code for embedding (via LLVM)
- Fast growing ecosystem of libraries
- Already adopted for classroom teaching at MIT, Stanford, KTH, Cornell, ...



DID WE MENTION FAST?



CURRENT STATUS

A large number of package collections:

- JuliaML: Machine learning
- JuliaStats: Statistics
- JuliaDiffEq: Differential equations
- JuliaPlots: Data visualization
- JuliaOpt: Optimization
- JuliaControl: Control system design
- JuliaSystems: Systems, Identification and Control

... and much, much more!

(check <http://pkg.julialang.org>)

SPEAKERS

- Arda Aytekin (KTH, Sweden)
- Chris Coey (MIT, USA)
- Niklas Everitt (KTH, Sweden)
- Zachary Sunberg (Stanford, USA)
- Madeleine Udell (Cornell, USA)

SCHEDULE

- 8:30-9:30 Tutorial on Julia
- 9:30-10:30 Control and identification toolboxes
- 10:30-11:30 Optimization in Julia
- 11:30-12:30 Research talks:
 - Pajarito Solver for Mixed-Integer Convex Optimization
 - POMDPs.jl: a unified interface for POMDPs

ENJOY!