

§ VIII. 1.

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = f(x, t), \quad -\infty < x < \infty$$

$$u(x, 0) = \psi(x), \quad 0 < t < T$$

$$g) \begin{array}{ccccccc} & l-1 & l & l+1 & & n+1 & \\ & \bullet & \bullet & \bullet & & \bullet & \\ & & & & & n & \end{array}$$

Орх-но точки $(l; n+1)$

Разностная схема:

$$\frac{u_{l+1}^{n+1} - u_l^n}{\tau} + \frac{u_{l+1}^{n+1} - u_{l-1}^{n+1}}{2h} = f_l^{n+1}$$

$$u_l^0 = \psi_l$$

1. Априорная оценка

$$\delta f^{(n)} = \ln[u]_n - f^{(n)} = \begin{cases} \frac{[u]_l^{n+1} - [u]_l^n}{\tau} + \frac{[u]_{l+1}^{n+1} - [u]_{l-1}^{n+1}}{2h} - f_l^{n+1} \\ [u]_l^n - \psi_l \end{cases} \quad \text{①}$$

$$[u]_l^n = [u]_l^{n+1} - [\dot{u}_t]_l^{n+1} \tau + [\ddot{u}_{tt}]_l^{n+1} \frac{\tau^2}{2} + O(\tau^3)$$

$$[u]_{l\pm 1}^{n+1} = [u]_l^{n+1} \pm [\dot{u}_x]_l^{n+1} h + [\ddot{u}_{xx}]_l^{n+1} \frac{h^2}{2} \pm \pm [\ddot{u}_{xxx}]_l^{n+1} \frac{h^3}{6} + O(h^4)$$

$$\text{②} \begin{cases} [\dot{u}_t]_l^{n+1} + [\ddot{u}_{tt}]_l^{n+1} \frac{\tau}{2} + [\dot{u}_x]_l^{n+1} + [\ddot{u}_{xx}]_l^{n+1} \frac{h^2}{6} - f_l^{n+1} \\ 0 \end{cases}$$

$$= (C_0) \tau^{1/2} \tau + (C_0) \tau^{1/2} h^2$$

③

$$\|\delta f^{(n)}\| \leq C_0 \tau + C_0 h^2$$

$$\sin\left(1 + \frac{1 - e^{-ix}}{h/r}\right) = 1.$$

$$\sin = \frac{1}{1 + \frac{1 - e^{-ix}}{h/r}} = \frac{1}{1 + \frac{2i \sin \frac{x}{2}}{h/r}}$$

$$|\sin|^2 \leq 1 \Rightarrow 1 \leq 1 + \frac{2^2 \sin^2 \frac{x}{2}}{h^2/r^2}$$

\Rightarrow деэволюция гравитации.
§ VIII.4

$$\frac{\partial^2 u}{\partial t^2} = \frac{\partial^2 u}{\partial x^2}, \quad 0 < x < 1, \quad 0 < t < T$$

$$u(x, 0) = \psi(x); \quad \frac{\partial u}{\partial t}(0, x) = \psi(x); \quad u(0, t) = t,$$

$$u(1, t) = t^2$$

$$2) \quad \begin{matrix} \circ & \circ & \circ & \dots & \circ \\ \vdots & \vdots & \vdots & \dots & \vdots \\ \circ & \circ & \circ & \dots & \circ \end{matrix} \quad (n, l)$$

II Аппроксимация

$$\delta f^{(n)} = \left\{ \begin{aligned} & \frac{[u]_e^{n+1} - 2[u]_e^n + [u]_e^{n-1}}{h^2} - \frac{[u]_{e+1}^n - 2[u]_e^n + [u]_{e-1}^n}{\tau^2} \\ & \frac{[u]_e^n - \psi_e}{\tau} \\ & \frac{[u]_e^n - [u]_{e-1}^n}{\tau} - \psi_e \\ & [u]_0^n - t^n \\ & [u]_1^n - (t^n)^2 \end{aligned} \right.$$

$$[u]_e^{n+1} = [u]_e^n + [u_x]_e^n h + [u_{xx}]_e^n \frac{h^2}{2} + [u_{xxx}]_e^n \frac{h^3}{6} + o(h^4)$$

$$[u]_{e+1}^n = [u]_e^n + [u_x]_e^n h + [u_{xx}]_e^n \frac{h^2}{2} + [u_{xxx}]_e^n \frac{h^3}{6} + o(h^4)$$

$$\Leftrightarrow \begin{cases} [u_{xx}]_e^n \frac{1}{2} \cdot 2 + 2[u_{xx}]_e^n \frac{h^2}{24} - [u_{xx}]_e^n \frac{1}{2} \cdot 2 - 2[u_{xx}]_e^n \frac{h^2}{24} \\ 0 \\ (C_0)_e^n \tau \\ 0 \\ 0 \end{cases}$$

$$\text{III.0. } \|\delta f^{(n)}\| \leq C_0 \tau + C_h h^2$$

§ VIII.5

$$\frac{\partial u}{\partial t} + \frac{\partial v}{\partial x} = f(x, t)$$

$$\frac{\partial v}{\partial t} + \frac{\partial u}{\partial x} = g(x, t)$$

$$u(x, 0) = \psi(x), \quad v(x, 0) = \varphi(x)$$

Запишем систему в характеристическом виде:

$$\frac{\partial \vec{w}}{\partial t} + A \frac{\partial \vec{w}}{\partial x} = \vec{F}, \quad A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\text{c.g. } A = \pm A.$$

Найдем с.б.

$$1) \lambda = 1: \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = 0$$

$$\Rightarrow \vec{w}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$2) \lambda = -1: \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = 0$$

$$\Rightarrow \vec{w}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

Составим $\Omega: \Omega = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}; \Lambda = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

$$\bar{A} = \Omega^{-1} \Lambda \Omega$$

Дополним условие на Ω :

$$\Omega \frac{\partial \bar{w}}{\partial t} + \Omega \Omega^{-1} \Lambda \Omega \frac{\partial \bar{w}}{\partial x} = \Omega \bar{F}$$

$$\Omega \bar{w} = J = \begin{pmatrix} J_1 \\ J_2 \end{pmatrix} = \begin{pmatrix} u+v \\ u-v \end{pmatrix}$$

$$\begin{cases} \frac{\partial J_1}{\partial t} + 1 \frac{\partial J_1}{\partial x} = f + g & \text{с.з. } > 0 \\ \frac{\partial J_2}{\partial t} - 1 \frac{\partial J_2}{\partial x} = f - g & \text{с.з. } < 0 \end{cases}$$

$$\begin{aligned} \frac{(J_1)_{e+h}^{n+1} - (J_1)_e^n}{\tau} + 1 \frac{(J_1)_e^n - (J_1)_{e-h}^n}{h} &= f_e^n + g_e^n \\ \frac{(J_2)_{e+h}^{n+1} - (J_2)_e^n}{\tau} - 1 \frac{(J_2)_e^n - (J_2)_{e-h}^n}{h} &= f_e^n - g_e^n \end{aligned}$$

§ 30.4.4.

$$\frac{\partial^2 u}{\partial t^2} + \alpha \frac{\partial^2 u}{\partial t \partial x} = f(t, x)$$

$$u(0, x) = \psi(x)$$

$$\partial u(0, x) / \partial t = \varphi(x)$$

Запишем схему:

$$(u_e^{n+1} - 2u_e^n + u_e^{n-1}) / \tau^2 + \alpha \frac{u_e^{n+1} - u_{e-1}^{n+1} - u_e^n + u_{e-1}^n}{\tau h} = f_e^n$$

$$u_e^0 = \psi_e; \quad -3u_e^0 + 4u_e^1 - u_e^2 = 2\tau\varphi_e$$

$$\delta f_e^{(1)} = \begin{cases} \frac{[u]_e^{n+1} - 2[u]_e^n + [u]_e^{n-1}}{\tau^2} + \alpha \frac{[u]_e^{n+1} - [u]_{e-1}^{n+1} - [u]_e^n + [u]_{e-1}^n}{\tau h} - f_e^n \\ [u]_e^0 - \psi_e \\ -3[u]_e^0 + 4[u]_e^1 - [u]_e^2 - 2\tau\varphi_e \end{cases} \equiv$$

$$\begin{aligned} [u]_e^{n+1} &= [u]_e^n + [u]_e^n \tau + [u]_{xx}^n \frac{\tau^2}{2} + [u]_{xxx}^n \frac{\tau^3}{6} + O(\tau^4) \\ [u]_{e-1}^{n+1} &= [u]_{e-1}^n + [u]_{e-1}^n \tau + [u]_{xx}^n \tau h - [u]_{xxx}^n \frac{h^2}{2} + O(\tau^4 + h^2) \\ [u]_{e-1}^n &= [u]_e^n - [u]_{xx}^n h + [u]_{xxx}^n \frac{h^2}{2} - [u]_{xxxx}^n \frac{h^3}{6} + O(h^4) \\ [u]_e^1 &= [u]_e^0 + [u]_t^0 \tau + [u]_{xt}^0 \frac{\tau^2}{2} + O(\tau^3) \\ [u]_e^2 &= [u]_e^0 + [u]_{tt}^0 \tau^2 + [u]_{xt}^0 \tau h + [u]_{xxx}^0 \frac{\tau^3}{2} + O(\tau^4) \end{aligned}$$

0

20.1.14

$$\begin{aligned} u(0, x, y) &= \varphi(x, y) \\ u(t, 0, y) &= \varphi_0(t, y) \\ u(t, x, 0) &= \varphi_1(t, x) \\ u(t, x, y) &= \chi(t, x) \end{aligned}$$

$$\begin{aligned} [W]_{0,n}^0 &= (v_0)_n^0 \\ [W]_{1,n}^1 &= (v_1)_n^1 \\ [W]_{0,0}^0 &= x_0^0 \\ [W]_{0,n}^1 &= (x_0)_n^1 \end{aligned}$$

$$\textcircled{=}$$

$$[\ddot{u}]_{cm} - [\ddot{u}]_{cm} \frac{\tau}{2} - Q \left([\dot{u}_{xx}]_{cm}^{+1} + [\dot{u}_{xx}]_{cm} \frac{h^2}{12} \right) + 6 \left([\dot{u}_y]_{cm}^{+1} + [\dot{u}_{yy}]_{cm} \frac{h^2}{3} \right) - f_{cm}^{+1}$$

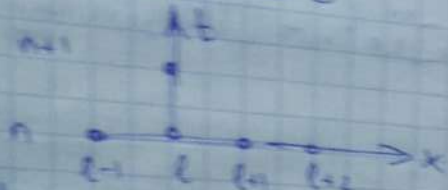


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$$\|f^{(k)}\| \leq C_0 \tau + C_1 h \tau^2 + C_2 h^2$$

$$\frac{\partial u}{\partial t} + 8 \frac{\partial u}{\partial x} = 4\left(\frac{1}{t}, x\right)$$

$$Q = \text{const} > 0$$


$$O(p, k) = ?$$

Метод определения коэффициентов

$$\alpha u_c^{(n)} + \beta u_{c-1}^{(n)} + \gamma u_c^{(n)} + \delta u_{c+1}^{(n)} + \epsilon u_{c+2}^{(n)} = f_c$$

$$\delta t_i^n = \alpha [u]_i^{n+1} + \beta [u]_i^n + \delta [u]_{i-1}^n + \gamma [u]_i^n + \varepsilon [u]_{i+1}^n - t_i^n$$

$$\begin{aligned} \alpha / [U]_e^{n+1} &= [U]_e^n + [U]_e^n \tau + [U]_e^n \tau^2 + O(\tau^3) \\ \delta / [U]_{e+1}^n &= [U]_e^n + [U]_e^n \tau h + [U]_e^n \tau^2 h^2 + [U]_e^n \tau^3 h^3 + O(\tau^4) \\ &+ [U]_e^n \tau^2 h^2 + O(\tau^4) \end{aligned}$$

$$\mathcal{E} \mid [U]_{i+2}^n = [U]_i^n + [U]_i^n \frac{(2h)^2}{2!} + [U]_i^n \frac{(2h)^4}{4!} + [U]_{i+1}^n \frac{(2h)^3}{6} + [U]_{i+1}^n \frac{(2h)^5}{24} + O(h^5)$$

⑦

$$+ \frac{1}{2} \left[\frac{1}{2} \left(\alpha + \beta + \gamma + \delta + \epsilon \right) + \frac{1}{2} \left(\alpha + \beta + \gamma + \delta + \epsilon \right) + \frac{1}{2} \left(\alpha + \beta + \gamma + \delta + \epsilon \right) + \frac{1}{2} \left(\alpha + \beta + \gamma + \delta + \epsilon \right) \right]$$

$$+ [U_{\text{int}}^{\text{int}}]_e^2 \left\{ \frac{h^2}{2} (\delta + \beta + 4\varepsilon) \right\} + [U_{\text{int}}^{\text{int}}]_e^2 \left\{ \frac{h^2}{6} (\delta - \beta + 8\varepsilon) \right\} \\ + [U_{\text{int}}^{\text{int}}]_e^2 \left(\varepsilon^2 \frac{h^4}{3} + \delta h^4 \frac{1}{24} + \beta h^4 \frac{1}{24} \right)$$

$$\alpha + \beta + \gamma + \delta + \varepsilon = 0$$

$\alpha\tau = 1$

$$h(\delta - \beta + 2\epsilon) = a$$

$$\delta + \beta + 4\epsilon = 0$$

$$\delta - \beta + 8\varepsilon = 0$$

$$\begin{aligned} \delta + \beta + 4\varepsilon &= 0 \\ \delta - \beta + 8\varepsilon &= 0 \end{aligned} \quad \Rightarrow \quad \begin{aligned} 1) \delta &= -6\varepsilon \\ 2) \beta &= 2\varepsilon \\ 3) \varepsilon &= -\frac{q}{6h} \\ 4) \delta &= \frac{q}{h}; \beta = -\frac{q}{3h} \\ 5) \alpha &= \frac{1}{h} \\ 6) f &= -\frac{q}{2h} - \frac{1}{h} \end{aligned}$$

$$5) \alpha = \frac{1}{n}$$

$$6) \beta = -\frac{Q}{2h} - \frac{1}{n}$$

ST 0

$$\frac{1}{\tau}(u_c^{n+1} - u_c^n) + \frac{\rho}{6h}(-3u_c^n - u_{c+2}^n + 6u_{c+1}^n - 2u_{c-1}^n) = -f_c^n$$

Аппроксимация:

3) NO ↑ - 2^{мил} поперек

$$\pi) -\frac{3}{2} - \frac{4}{2} + \frac{6}{2} - \frac{2}{2} \checkmark$$

$$= \frac{8}{6} + \frac{6}{6} + \frac{2}{6} \checkmark$$

$$\Rightarrow Z^{\text{int}}$$
 порожд. по 1.

VIII.5(2)

$$\frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} = f(x, t), \quad -\infty < x < \infty$$

$$u(x, 0) = \psi(x), \quad 0 \leq t \leq T$$



Force $(l+1/2; l+1/2)$

$$M_{l,n} = \alpha u_{l,n}^{n+1} + \beta u_{l,n}^n + \gamma u_{l,n+1}^n + \delta u_{l,n+1}^{n+1} - f_{l,n+1/2}^{n+1/2} = \delta f^n$$

$$\alpha) [u]_l^{n+1} = [u]_{l+1/2}^{n+1/2} + [\dot{u}_t]_{l+1/2}^{n+1/2} \frac{\tau}{2} - [u_x]_{l+1/2}^{n+1/2} \frac{h}{2} + [\ddot{u}_{tt}]_{l+1/2}^{n+1/2} \frac{\tau^2}{8} + [u_{xx}]_{l+1/2}^{n+1/2} \frac{h^2}{8} - [\dot{u}_{tx}]_{l+1/2}^{n+1/2} \frac{h}{2} \frac{\tau}{2} + O(\tau^3 + h^3 + h^2\tau + \tau^2h)$$

$$\beta) [u]_l^n = [u]_{l+1/2}^{n+1/2} - [\dot{u}_t]_{l+1/2}^{n+1/2} \frac{\tau}{2} - [u_x]_{l+1/2}^{n+1/2} \frac{h}{2} + [\ddot{u}_{tt}]_{l+1/2}^{n+1/2} \frac{\tau^2}{4} + [u_{xx}]_{l+1/2}^{n+1/2} \frac{h^2}{4} + [\dot{u}_{tx}]_{l+1/2}^{n+1/2} \frac{h}{2} \frac{\tau}{2} + O(\dots)$$

$$\gamma) [u]_{l,n+1}^n = [u]_{l+1/2}^{n+1/2} - [\dot{u}_t]_{l+1/2}^{n+1/2} \frac{\tau}{2} + [\ddot{u}_{tt}]_{l+1/2}^{n+1/2} \frac{\tau^2}{8} + [\dot{u}_{tx}]_{l+1/2}^{n+1/2} \frac{h}{2} \frac{\tau}{2} - [u_{xx}]_{l+1/2}^{n+1/2} \frac{h^2}{8} + O(\dots)$$

$$\delta) [u]_{l,n+1}^{n+1} = [u]_{l+1/2}^{n+1/2} + [\dot{u}_t]_{l+1/2}^{n+1/2} \frac{\tau}{2} + [\ddot{u}_{tt}]_{l+1/2}^{n+1/2} \frac{\tau^2}{8} + [u_{xx}]_{l+1/2}^{n+1/2} \frac{h^2}{8} + [\dot{u}_{tx}]_{l+1/2}^{n+1/2} \frac{h}{2} \frac{\tau}{2} + O(\dots)$$

Примечание:

$$(\alpha + \beta + \gamma + \delta) [u]_{l+1/2}^{n+1/2} + (\alpha - \beta - \gamma + \delta) [\dot{u}_t]_{l+1/2}^{n+1/2} \frac{\tau}{2} + (-\alpha - \beta + \gamma + \delta) [u_x]_{l+1/2}^{n+1/2} \frac{h}{2} + (\alpha + \beta + \gamma + \delta) ([\ddot{u}_{tt}]_{l+1/2}^{n+1/2} \frac{\tau^2}{8} + [u_{xx}]_{l+1/2}^{n+1/2} \frac{h^2}{8}) + (-\alpha + \beta - \gamma + \delta) [\dot{u}_{tx}]_{l+1/2}^{n+1/2} \frac{h}{2} \frac{\tau}{2} + O(\dots) - f_{l,n+1/2}^{n+1/2}$$

$$(\alpha + \beta + \gamma + \delta) = 0$$

$$\alpha - \beta - \gamma + \delta = \frac{\tau}{h}$$

$$-\alpha - \beta + \gamma + \delta = \frac{\tau}{h}$$

$$-\alpha + \beta - \gamma + \delta = 0$$

$$\Rightarrow \beta = -\delta; \alpha = -\delta; \gamma = -\frac{\tau}{h} - \delta$$

$$\beta = -\frac{1}{2\tau} - \frac{1}{2h}; \alpha = \frac{1}{2\tau} - \frac{1}{2h}; \gamma = \frac{1}{2h} - \frac{1}{2\tau}; \delta = \frac{1}{2\tau} + \frac{1}{2h}$$

$$\frac{1}{2\tau} \left(\frac{u_{l+1}^{n+1} - u_{l+1}^n}{\tau} + \frac{u_l^{n+1} - u_l^n}{\tau} \right) + \frac{1}{2} \left(\frac{u_{l+1}^{n+1} - u_l^{n+1}}{h} + \frac{u_{l+1}^n - u_l^n}{h} \right) = f_{l+1/2}^{n+1/2}$$

$$u_l^n \rightarrow d_\alpha e^{i\alpha l}$$

$$\frac{d_\alpha^{n+1} e^{i\alpha(l+1)} - d_\alpha^n e^{i\alpha(l+1)}}{\tau} + \frac{d_\alpha^{n+1} - d_\alpha^n e^{i\alpha l}}{h} + \frac{d_\alpha^{n+1} e^{i\alpha(l+1)} - d_\alpha^{n+1} e^{i\alpha l}}{h} - \frac{d_\alpha^n e^{i\alpha l} - d_\alpha^n e^{i\alpha(l+1)}}{h} = 0$$

$$\frac{d_\alpha e^{i\alpha} - e^{i\alpha} + d_\alpha - 1}{\tau} + \frac{d_\alpha e^{i\alpha} - d_\alpha + e^{i\alpha} - 1}{h} = 0$$

$$\Rightarrow d_\alpha = \frac{1 + \tau/h \left(\frac{1 - e^{i\alpha}}{1 + e^{i\alpha}} \right)}{1 - \tau/h \left(\frac{1 - e^{i\alpha}}{1 + e^{i\alpha}} \right)}$$

$$\hookrightarrow \left| \frac{1 + \tau/h + (1 - \tau/h) e^{i\alpha}}{1 - \tau/h + (1 + \tau/h) e^{i\alpha}} \right| \leq 1$$

$$\hookrightarrow |d_\alpha|^2 = 1 \text{ — diskretno yozilma}$$

Thm 1:

$$\frac{\bar{w}_l^{n+1} - \bar{w}_l^n}{\tau} + \left(\frac{4}{-6} \frac{10}{-15} \right) \frac{\bar{w}_{l+1}^{n+1} - \bar{w}_{l-1}^{n+1}}{2h} = f_l^{n+1}$$

Madison + nuqat yozilmasi

$$\bar{w}_l^n \rightarrow d_\alpha^n e^{i\alpha l} \bar{\Delta}_0$$

$$\left(\frac{d_\alpha^{n+1} e^{i\alpha l} - d_\alpha^n e^{i\alpha l}}{\tau} \right) \bar{\Delta}_0 + \left(\frac{4}{-6} \frac{10}{-15} \right) \left(\frac{d_\alpha^{n+1} e^{i\alpha(l+1)} - d_\alpha^{n+1} e^{i\alpha(l-1)}}{2h} \right) \bar{\Delta}_0 = 0$$

$$\bar{\Delta}_0 = 0$$

$$d_\alpha^{n+1}/d_\alpha^n = d_\alpha$$

$$\frac{d_\alpha - 1}{\tau} \bar{\Delta}_0 + A d_\alpha \frac{e^{i\alpha} - e^{-i\alpha}}{2h} \bar{\Delta}_0 = 0$$

$$\left(\frac{d_\alpha - 1}{\tau} E + A d_\alpha \frac{i \sin \alpha}{h} \right) \bar{\Delta}_0 = 0 ; \forall \bar{\Delta}_0 \Rightarrow \det(\cdot) = 0$$

$$\begin{vmatrix} (d_\alpha - 1)/\tau + 4 \frac{d_\alpha \sin \alpha}{h} & 10 d_\alpha \sin \alpha / h \\ -6 \frac{d_\alpha \sin \alpha}{h} & \frac{d_\alpha - 1}{\tau} - 15 \frac{d_\alpha \sin \alpha}{h} \end{vmatrix}$$

$$= \left(\frac{d_\alpha - 1}{\tau} + 4 \frac{d_\alpha \sin \alpha}{h} \right) \left(\frac{d_\alpha - 1}{\tau} - 15 \frac{d_\alpha \sin \alpha}{h} \right) + 60 \frac{d_\alpha^2 \sin^2 \alpha}{h^2}$$

$$= \left(\frac{d_\alpha - 1}{\tau} \right)^2 - \frac{11 d_\alpha \sin \alpha}{h} \frac{d_\alpha - 1}{\tau} = 0$$

$$= \left(\frac{d_\alpha - 1}{\tau} \right) \left(\frac{d_\alpha - 1}{\tau} - \frac{11 d_\alpha \sin \alpha}{h} \right) = 0$$

$$J_x = 1$$

$$J_x - 1 - \frac{c^2}{h^2} \sin^2 \alpha \cdot J_x = 0$$

$$\Rightarrow \frac{1}{1 + \frac{c^2}{h^2} \sin^2 \alpha} \leq 1$$

$$\Rightarrow \frac{c^2}{h^2} \geq 0 \Rightarrow \text{схема деградации устойчива}$$

$$\frac{\partial u}{\partial t} - 6 \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} = f(t, x)$$

$$\frac{\partial v}{\partial t} - 12 \frac{\partial v}{\partial x} - \frac{\partial u}{\partial x} = g(t, x)$$

$$\bar{w} = \begin{pmatrix} u \\ v \end{pmatrix}; A = \begin{pmatrix} -6 & 1 \\ -12 & -12 \end{pmatrix}; F = \begin{pmatrix} f \\ g \end{pmatrix}$$

$$\bar{w}_t + A \bar{w}_x = F; A^T = \begin{pmatrix} -6 & -12 \\ 1 & -12 \end{pmatrix}$$

$$\text{ч.з. матрица } A: (-6-1)(-1-1) + 12 =$$

$$= (6+1)(1+1) + 12 = 1^2 + 18 \cdot 1 + 12 = 0$$

$$\Rightarrow \lambda = -7; \lambda = -15$$

$$\lambda = -7:$$

$$\begin{pmatrix} 1 & -5 \\ 1 & -5 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = 0$$

$$\begin{pmatrix} 5 \\ 1 \end{pmatrix} = \bar{w}_1$$

$$\bar{w}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Omega = \begin{pmatrix} 5 & 1 \\ 1 & 1 \end{pmatrix}; \Omega^T = \Omega; \Lambda = \begin{pmatrix} -7 & 0 \\ 0 & -15 \end{pmatrix}$$

$$\times \Omega^T$$

$$\frac{\partial}{\partial t} \Omega^T \bar{w} + \frac{\Lambda \Omega^T}{\Omega^T A} \frac{\partial}{\partial x} \bar{w} = \Omega^T F$$

$$\frac{\partial}{\partial t} (u+v) - 7 \frac{\partial}{\partial x} (u+v) = f+g$$

$$\frac{\partial}{\partial t} (u+v) - 15 \frac{\partial}{\partial x} (u+v) = f+g$$

$$\frac{\partial \bar{J}}{\partial t} + \Lambda \frac{\partial \bar{J}}{\partial x} = \Omega^T F$$

$$\frac{\bar{J}_i^{n+1} - \bar{J}_i^n}{\tau} + \Lambda \frac{\bar{J}_{i+1}^n - \bar{J}_i^n}{h} = (\Omega^T F)_i^n$$

Рассуждая от-но точки $(1, l)$ получаем, что

$$\| \delta f^{(n)} \| = \left\| \frac{\bar{J}_i^{n+1} - \bar{J}_i^n}{\tau} + \Lambda \frac{\bar{J}_{i+1}^n - \bar{J}_i^n}{h} - (\Omega^T F)_i^n \right\|$$

$$< C_1 \tau + C_2 h$$

II. Устойчивость.

$$\sigma = c/h$$

$$\bar{J}_i^n \rightarrow \lambda_i^n e^{i x l} \bar{\Delta}_0$$

$$\left(\frac{\lambda_i^{n+1} - \lambda_i^n}{\tau} \right) e^{i x l} \bar{\Delta}_0 + \Lambda \lambda_i^n e^{i x l} \frac{e^{i x} - 1}{h} \bar{\Delta}_0 = 0$$

$$\left(\frac{\lambda_i - 1}{\tau} E + \Lambda \frac{e^{i x} - 1}{h} \right) \bar{\Delta}_0 = 0$$

$$[(1\alpha-1)E + \Lambda(e^{i\alpha}-1)\sigma]Z_0 = 0$$

$$\det[...] = 0$$

$$\begin{vmatrix} (1\alpha-1) - 7\sigma(e^{i\alpha}-1) & 0 \\ 0 & (1\alpha-1) - 11\sigma(e^{i\alpha}-1) \end{vmatrix}$$

$$= (1\alpha-1-7\sigma(e^{i\alpha}-1))(1\alpha-1-11\sigma(e^{i\alpha}-1))$$

$$= 0$$

$$\lambda_{\alpha 1} = 1 + 7\sigma(e^{i\alpha}-1) \quad |\lambda_{\alpha 1}| \leq 1$$

$$\lambda_{\alpha 2} = 1 + 11\sigma(e^{i\alpha}-1)$$

$$\begin{cases} 7\sigma \cos \alpha + 7\sigma i \sin \alpha - 7\sigma + 1 \\ 11\sigma \cos \alpha + 11\sigma i \sin \alpha - 11\sigma + 1 \end{cases}$$

$$a) 1 - 14\sigma \sin^2 \frac{\alpha}{2} + 7\sigma i \sin \alpha \leq 4$$

$$1 - 28\sigma \sin^2 \frac{\alpha}{2} + 196\sigma^2 \sin^4 \frac{\alpha}{2} + 49\sigma^2 \sin^2 \alpha \leq 4$$

$$-1 + 7\sigma \sin^2 \frac{\alpha}{2} + 7\sigma \cos^2 \frac{\alpha}{2} \leq 0$$

$$7\sigma - 1 \leq 0$$

$$\tau \leq \frac{1}{7}h$$

$$\tau \leq \frac{1}{11}h$$

Р.3.3.

$$\begin{cases} \frac{\partial u}{\partial t} - 5 \frac{\partial u}{\partial x} + 7 \frac{\partial v}{\partial x} = f(t, x) \\ \frac{\partial v}{\partial t} + 0 \frac{\partial u}{\partial x} + 3 \frac{\partial v}{\partial x} = g(t, x) \end{cases} \quad 0 \leq t \leq 1, 0 \leq x \leq 1$$

Структура и характер. буря.

$$\frac{\partial \bar{w}}{\partial t} + A \frac{\partial \bar{w}}{\partial x} = \bar{F} \quad ; \quad A = \begin{pmatrix} -5 & 7 \\ 0 & 3 \end{pmatrix} \rightarrow A^T = \begin{pmatrix} -5 & 0 \\ 7 & 3 \end{pmatrix}$$

$$\text{С.г. } A^T: (-5-1)(3-1) = 0$$

$$\lambda_1 = -5; \quad \lambda_2 = 3$$

$$\lambda_1 = -5: \begin{pmatrix} 0 & 0 \\ 7 & -2 \end{pmatrix} \rightarrow 7w_1 = 2w_2 \rightarrow \begin{pmatrix} 2 \\ 7 \end{pmatrix} = \bar{w}_1$$

$$\lambda_2 = 3: \begin{pmatrix} -8 & 0 \\ 7 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \bar{w}_2$$

$$Q = \begin{pmatrix} 2 & 0 \\ 7 & 1 \end{pmatrix}; \quad \Lambda = \begin{pmatrix} -5 & 0 \\ 0 & 3 \end{pmatrix}$$

$$Q^T = \begin{pmatrix} 2 & 7 \\ 0 & 1 \end{pmatrix}$$

* Q^T

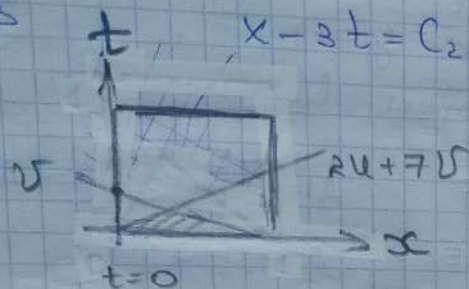
$$\frac{\partial (2u+7v)}{\partial t} - 5 \frac{\partial (2u+7v)}{\partial x} = 2f+7g$$

$$\frac{\partial (0u+v)}{\partial t} + 3 \frac{\partial (0u+v)}{\partial x} = 0f+1g$$

Характеристики:

$$\frac{dx}{dt} = -5 \Rightarrow x + 5t = C_1$$

$$\frac{dx}{dt} = 3 \Rightarrow x - 3t = C_2$$



а) нет

б) нет

в) нет

г) да

$$\Delta u = f(x, y)$$

$$u|_r = \varphi(s)$$

$$0 \leq x, y \leq 1$$

З.П.3.10.

$$\frac{\partial u}{\partial t} = \Delta u - f(x, y)$$

$$u(0, x, y) = \varphi(x, y)$$

$$u|_r = \varphi(s)$$

Сделаю:

$$\frac{u_{m,j}^{n+1} - u_{m,j}^n}{\tau} = \frac{u_{m+1,j}^n - 2u_{m,j}^n + u_{m-1,j}^n}{h_x^2} + \frac{u_{m,j+1}^n - 2u_{m,j}^n + u_{m,j-1}^n}{h_y^2}$$

$$+ \frac{u_{m,j}^{n+1} - 2u_{m,j}^n + u_{m,j-1}^n}{h_y^2}; \quad u_{0,m}^n = \varphi_{0,m}$$

$$e_{l,m}^n = u_{l,m}^n - u_{l,m}^{*n}$$

Сделаю следующие допущения:

$$\psi_{l,m}^{(k,j)} = R \sin \frac{k\pi x}{L} \sin \frac{j\pi y}{M}$$

$$e_{l,m}^n = \sum_{k=1}^{L-1} \sum_{j=1}^{M-1} C_{k,j}^n \psi_{l,m}^{(k,j)}$$

$$\sum_{k=1}^{L-1} \sum_{j=1}^{M-1} \frac{C_{k,j}^{n+1} - C_{k,j}^n}{\tau} \psi_{l,m}^{(k,j)} = \sum_{k=1}^{L-1} \sum_{j=1}^{M-1} 2C_{k,j}^n \left[\sin^2 \frac{j\pi y}{M} \cdot \frac{\sin \frac{k\pi(L+1)}{L} - R \sin \frac{k\pi L}{L} + \sin \frac{k\pi(L-1)}{L}}{h_x^2} + \sin \frac{k\pi L}{L} \frac{\sin \frac{j\pi(M+1)}{M} - R \sin \frac{j\pi M}{M} + \sin \frac{j\pi(M-1)}{M}}{h_y^2} \right]$$

$$= \sum_{k=1}^{L-1} \sum_{j=1}^{M-1} C_{k,j}^n \psi_{l,m}^{(k,j)} \left[-\frac{4}{h_x^2} \sin^2 \frac{k\pi}{2L} - \frac{4}{h_y^2} \sin^2 \frac{j\pi}{2M} \right]$$

$$\Rightarrow C_{k,j}^{n+1} = C_{k,j}^n [1 - \tau \lambda_{k,j}]$$

$$C_{k,j}^N = C_{k,j}^0 \prod_{n=0}^{N-1} (1 - \tau \lambda_{k,j})$$

$$\mu_M \approx 2\pi^2; \quad \mu_M \approx 4(L^2 + M^2)$$

$$\mu = \frac{\mu_M + \mu_N}{2} + \frac{\mu_M - \mu_N}{2} D, \quad D \in [-1, 1]$$

$$\overline{T_N} = \frac{1}{2^{N-1}} \cos(N \arccos p_N)$$

$$p_N = \cos \frac{\pi(2N-1)}{2N}$$

$$C_n = \frac{2}{(\mu_M + \mu_N) + (\mu_M - \mu_N) \cos \frac{\pi(2N-1)}{2N}}$$

§ 2.3.9

$$\frac{U_{l,m}^{n+1} - U_{l,m}^n}{\tau_n} = \frac{U_{l+1,n}^n - 2U_{l,m}^n + U_{l-1,n}^n}{h_x^2} + \frac{U_{l,m+1/2}^n - 2U_{l,m}^n + U_{l,m-1/2}^n}{h_y^2/4} - f_{l,m}$$

Самое: $\mathcal{E}_{l,m}^n = U_{l,m}^{*n} - U_{l,m}^n = \sum_{k=1}^{L-1} \sum_{j=1}^{M-1} C_{k,j}^n \sin \frac{k\pi l}{L} \sin \frac{j\pi m}{M}$

III.9:

$$\frac{C_{k,j}^{n+1} - C_{k,j}^n}{\tau_n} \psi_{l,m}^{(k,j)} = C_{k,j}^n \psi_{l,m}^{(k,j)} \left[-\frac{4}{h_x^2} \sin^2 \frac{k\pi}{2L} - \frac{4}{h_y^2} \sin^2 \frac{j\pi}{2M} \right], \quad l=0, L-1$$

$$C_{k,j}^{n+1} = C_{k,j}^n (1 - \tau_n \mu_{k,j})$$

$$(\mu_{k,j})_{\min} = \pi^2 + 4\pi^2 = 5\pi^2$$

$$(\mu_{k,j})_{\max} = 4L^2 + 4M^2 = 4(L^2 + 4M^2)$$

$$\mu = \frac{\mu_{\max} + \mu_{\min}}{2} + \frac{\mu_{\max} - \mu_{\min}}{2} \varphi, \quad \varphi \in [-1, 1]$$

$$\overline{T_N} = \frac{1}{N^{N-1}} \cos(N \arccos \varphi_N)$$

$$\varphi_N = \frac{\pi(2N-1)}{2N}$$

$$\tau_n = \frac{\tau^2}{(\mu_{\max} + \mu_{\min}) + (\mu_{\max} - \mu_{\min}) \cos \frac{\pi(2N-1)}{2N}}$$