

4

## 4 Point Operations 85-98

- i. image is described by a histogram
- ii. construct a new image by mapping points in old to points in new

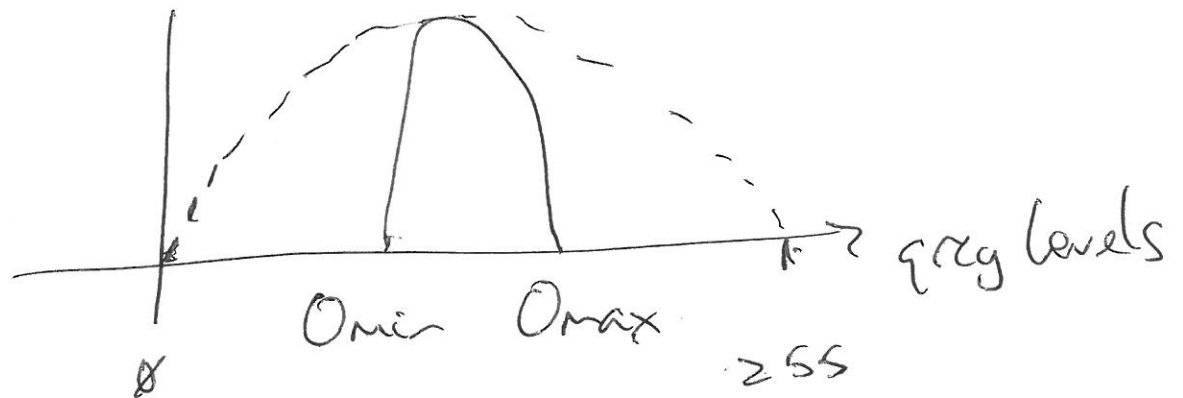
$$N_{x,y} = f(O_{x,y})$$

$$\text{e.g.} \quad = -\log O_{x,y}$$

$$= g \times O_{x,y} \pm \text{offset}$$

$$= \log(O_{x,y}) \text{ (brightness compression)}$$

ii) intensity normalisation  
allows for image comparison



Shift minimum & stretch.

stretch by  $\frac{255}{O_{max} - O_{min}}$

$$N_{x,y} = (O_{x,y} - O_{min}) \times \text{stretch}.$$

iii). histogram equalisation

aim for a 'flat' histogram

good for human vision

good for display only

it's nonlinear

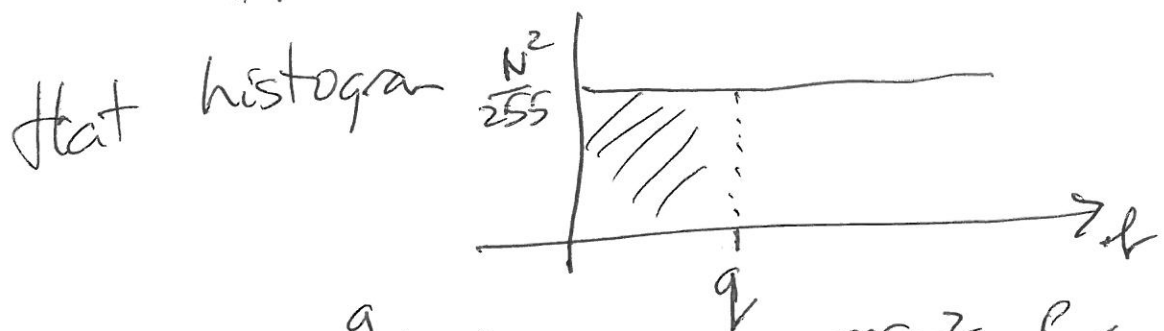
for  $N \times N$  image

# points in new image = # points in old image

... up to level  $q$  = ... up to level  $p$

$$\sum_{l=0}^q N(l) = \sum_{l=0}^p O(l)$$

level  $\rightarrow l=0$   $\uparrow$  gray level  $l$   
# points



$$\sum_{l=0}^q (N(l)) = q \times \frac{N^2}{255} = \sum_{l=0}^p O(l)$$

$$\frac{q}{\sum_{l=0}^P N(l)} = q \times \frac{N^2}{255} = \sum_{l=0}^P O(l)$$

$$q = \frac{255}{N^2} \times \sum_{l=0}^P O(l).$$

gives an equalising function

$$N_{x,y} = F(q, O(x,y))$$

iv/ thresholding.

set points above chosen value to white, everything else to black.  
optimal versions exist.