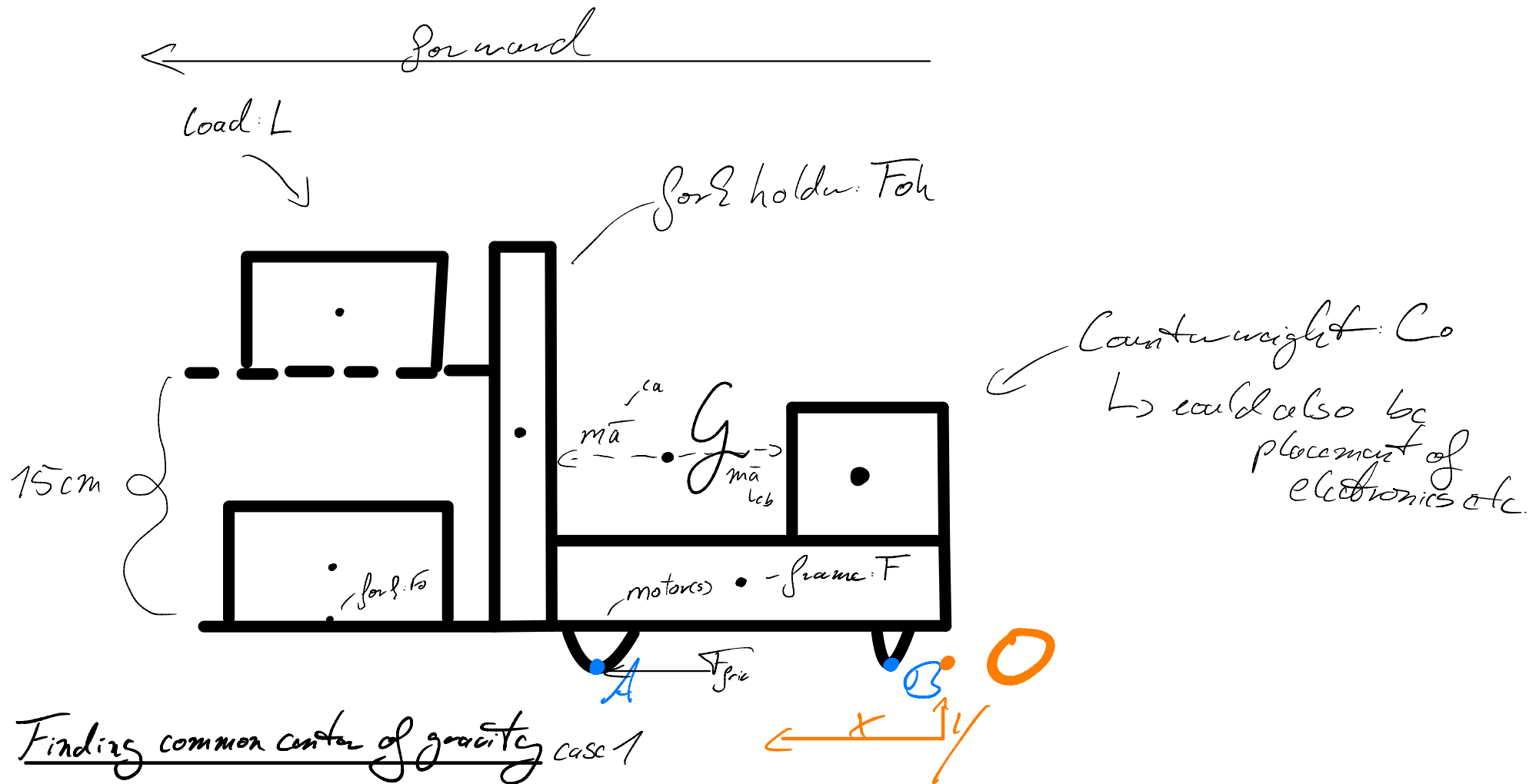


2 cases: for & up & for & down



Finding common center of gravity case 1
- reference Point: O

$$\sum M_{x-axis} (\text{combined body}) = \sum M_{x-axis} (\text{separate bodies})$$

$$(m_L + m_{F_o} + m_F + m_c) \cdot g \cdot \bar{y} = m_L \cdot g \cdot y_L + m_{F_o} \cdot g \cdot y_{F_o} + m_F \cdot g \cdot y_F + m_c \cdot g \cdot y_c + m_{Foh} \cdot g \cdot y_{Foh}$$

$$\Rightarrow \bar{y} = \frac{m_L y_L + m_{F_o} y_{F_o} + m_F y_F + m_c y_c + m_{Foh} y_{Foh}}{m_L + m_{F_o} + m_F + m_c + m_{Foh}}$$

$$\sum M_{y-axis} (\text{combined body}) = \sum M_{y-axis} (\text{separate bodies})$$

$$(m_L + m_{F_o} + m_F + m_c) \cdot g \cdot \bar{x} = m_L \cdot g \cdot x_L + m_{F_o} \cdot g \cdot x_{F_o} + m_F \cdot g \cdot x_F + m_c \cdot g \cdot x_c + m_{Foh} \cdot g \cdot x_{Foh}$$

$$\Rightarrow \bar{x} = \frac{m_L x_L + m_{F_o} x_{F_o} + m_F x_F + m_c x_c + m_{Foh} x_{Foh}}{m_L + m_{F_o} + m_F + m_c + m_{Foh}}$$

Combined x & y g.c.c. center of gravity of Dator with respect to point O