## 1 Morphology chart

Functions	1	2	3	4	5
Navigation	Lines on the floor	GPS location +	Preprogrammed	Sensor fusion	Bluetooth RTLS
$\mathbf{system}$		pallet detection	map	(IMU + GPS)	
Micro	Arduino nano	STM32xx	RaspberryPi	E-ESP32	Option 5
$\operatorname{controller} /$					
processor					
Pallet	LoadCells	Hall Effect	buttons	Ultrasonic	photoelectric
${f recognition}$					
Coding	Option 1	Option 2	Option 3	Option 4	Option 5
$\operatorname{standard}$					
Mast Stage	Simplex	Duplex	Triplex	Quadriplex	-
Lift solution	Linear Actuator	L.A +	Threaded Rod +	String&Bearing	Rack&Pineon
		RollerChain	linear bearings		
Lifting sensing	End stops	Encoder	Stepper Motors	LoadCell	-
	Top&Down				
Motors	Stepper on Mast	DC-Motors	-	-	-
		Movement			
Sensors Fork	LoadCell	-	-	-	-
Sensors Body	Ultrasonic	Infrared Sensors	LiDAR	Optical Sensors	-
	Distance				
	HC-SR04				
Body design	LCD	Tank tracks	Perry the Forklift	Googly Eyes	-
Elements					

<sup>\*</sup> Green cells indicates chosen option.