## 1 Morphology chart

Functions	1	2	3	4	5
Navigation	green!50Lines	GPS location	green!50Preprog	raned fusion	Bluetooth
system	on the floor	+ pallet	map	(IMU + GPS)	RTLS
		detection			
Micro	Arduino nano	STM32xx	RaspberryPi	green!50E-	Option 5
controller /				ESP32	
processor					
Pallet	green!50LoadCel	lsHall Effect	buttons	Ultrasonic	photoelectric
recognition					
Coding	Option 1	Option 2	Option 3	Option 4	Option 5
$\operatorname{standard}$					
Mast Stage	green!50Simplex	Duplex	Triplex	Quadriplex	-
Lift solution	Linear	L.A +	green!50Threade	edString&Bearing	Rack&Pineon
	Actuator	RollerChain	Rod + linear		
			bearings		
Lifting	green!50End	Encoder	Stepper	green!50LoadCe	1-
sensing	stops		Motors		
	Top&Down				
Motors	green!50Stepper	green!50DC-	-	-	-
	on Mast	Motors			
		Movement			
Sensors Fork	green!50LoadCell-		-	-	-
Sensors	green!50Ultrasor	nigreen!50Infrared	LiDAR	Optical	-
$\mathbf{Body}$	Distance	Sensors		Sensors	
	HC-SR04				
Body design	green!50LCD	Tank tracks	green!50Perry	green!50Googly	-
Elements			the Forklift	Eyes	

 $<sup>\</sup>ensuremath{^*}$  Green cells indicates chosen option.