

Secure Timeout System NXP S32K3X8EVB

Beamer for the CAOS Project

Andrea Botticella

Fabrizio Emanuel

Elia Innocenti

Renato Mignone

Simone Romano

February 5, 2025





- ► Project Overview
- QEMU Board Emulation
- FreeRTOS Porting
- ▶ Test Application
- Memory Protection Unit (MPU) Implementation
- Conclusion



- The assignment consists of FOUR parts:
 - Part 1: QEMU board emulation
 - o Generating a custom QEMU version to emulate the NXP S32K3X8EVB board.
 - o Ensuring that QEMU emulates the proper CPU, memory map, and the peripherals assigned.
 - Part 2: FreeRTOS porting
 - Ensuring that FreeRTOS runs on the emulated board.
 - Part 3: Writing a simple application
 - Writing a simple application implementing different tasks to test the setup.



- The assignment consists of FOUR parts:
 - Part 4: Documentation and presentation
 - o Creating a tutorial to run and test your code.
 - o Documentation of the code.
- What we've actually done:
 - Secure Timeout System application on the NXP \$32K3X8EVB board using FreeRTOS, emulated with QEMU.
 - Refer to the dedicated markdown files in the repository: README.md and GUIDE.md.
 These files contain all the implementation details and the tutorial to replicate the project.



Table of Contents2 QEMU Board Emulation

- Project Overview
- ► QEMU Board Emulation
- ▶ FreeRTOS Porting
- ▶ Test Application
- Memory Protection Unit (MPU) Implementation
- Conclusion



- Emulate the **NXP S32K3X8EVB** board, which is not natively supported by QEMU.
- Ensure proper emulation of the CPU (ARM Cortex-M7), memory map, and peripherals.





- Added a new machine model to QEMU for the S32K3X8EVB board.
- Used previous QEMU implementations as reference (ARMv7-M architecture).
- Implemented custom initialization routines for memory and peripherals.
- S32K358EVB board has the following specification:
 - ARM Cortex-M7 CPU.
 - \sim 8MB Flash memory, 768KB SRAM, 256KB DTCM, and 128KB ITCM.
 - NVIC with 256 IRQs and 4 priority bits.
 - Multiple peripherals: 16 LPUART, 3 PIT timers, 16 MPU regions.
 - System clock running at 240MHz.



Memory Regions Initialization

2 QEMU Board Emulation

- Flash Memory: Configured multiple blocks:
 - Blocko: Base Address: 0x00400000, Size: 2 MB
 - Block1: Base Address: 0x00600000, Size: 2 MB
 - Block2: Base Address: 0x00800000, Size: 2 MB
 - Block3: Base Address: oxooAooooo, Size: 2 MB
 - Block4: Base Address: 0x10000000, Size: 128 KB
 - Utest: Base Address: 0x18000000, Size: 8 KB
- SRAM Memory:
 - Blocko: Base Address: 0x20400000, Size: 256 KB
 - Block1: Base Address: 0x20440000, Size: 256 KB
 - Block2: Base Address: 0x20480000, Size: 256 KB
- DTCM and ITCM Memory:
 - DTCMo: Base Address: 0x20000000, Size: 128 KB
 - ITCMo: Base Address: oxoooooooo, Size: 64 KB



Peripherals and Interrupts Setup

2 QEMU Board Emulation

- NVIC (Nested Vectored Interrupt Controller):
 - Configured with 256 IRQs and 4 priority bits.
 - Interrupt vectors mapped in system memory.
- LPUART (Low Power UART):
 - Base Address: 0x4006A000
 - The board has 16 LPUART instances.
 - They are mapped starting from the UART base address.
 - Connected to NVIC and clocked by AIPS_PLAT_CLK and AIPS_SLOW_CLK.
- PIT Timers (Periodic Interrupt Timer):
 - Timer1: Base Address: 0x40037000
 - Timer2: Base Address: 0x40038000
 - Timer3: Base Address: 0x40039000
- MPU: 16 regions.



System Clocks and Interrupts

2 OEMU Board Emulation

System Clock:

- Primary System Clock: 240MHz frequency, 4.16ns period.
- AIPS Platform Clock: 80MHz
- AIPS Slow Clock: 40MHz

Interrupt Handling:

- Configured NVIC to handle exceptions and IRQs.
- Supports up to 256 IRQs with 4 priority levels.
- NVIC is connected to system and reference clocks.
- Interrupt sources include timers, UARTs, and peripheral events.



• Function: s32k3x8_load_firmware

- Parameters:
 - cpu: The ARM CPU instance.
 - ms: The machine state.
 - flash: The memory region representing the flash memory.
 - firmware_filename: The filename of the firmware to be loaded.
- Functionality:
 - Reads the firmware file and loads its contents into the specified flash memory region.



Class initialization

2 QEMU Board Emulation

• s32k3x8_class_init:

```
static void s32k3x8_class_init(ObjectClass *oc, void *data) {
    MachineClass *mc = MACHINE_CLASS(oc):
    mc->name = g_strdup("s32k3x8evb");
    mc->desc = "NXP S32K3X8 EVB (Cortex-M7)";
    mc \rightarrow init = s32k3x8 init:
    mc->default_cpu_tvpe = ARM_CPU_TYPE_NAME("cortex-m7");
    mc->default_cpus = 1;
    mc->min_cpus = mc->default_cpus;
    mc->max_cpus = mc->default_cpus;
    mc \rightarrow no_floppy = 1;
    mc \rightarrow no\_cdrom = 1:
    mc->no_parallel = 1;
```



- Project Overview
- QEMU Board Emulation
- ► FreeRTOS Porting
- ► Test Application
- ▶ Memory Protection Unit (MPU) Implementation
- Conclusion



- To test the FreeRTOS Porting on QEMU, a very simple application was created.
- The application runs a basic task that prints a message every second.
- If everything works correctly, it means that the FreeRTOS Porting has been successfully implemented.



- 1. Cloning the FreeRTOS repository.
- 2. Creating the directory **structure**: App/ and App/Peripherals/.
- 3. Creating and implementing the following files in the App/ directory:
 - s32_startup.c,s32_linker.ld
 - FreeRTOSConfig.h
 - Makefile
 - main.c
 - Peripherals/: uart.c, printf-stdarg.c with their respective header files



Running FreeRTOS on QEMU

3 FreeRTOS Porting

• main.c:

```
xTaskCreate(vTask1, "Task1", configMINIMAL_STACK_SIZE, NULL,
   mainTASK_PRIORITY, NULL);
void vTask1(void *pvParameters)
    (void) pvParameters:
    for (::)
        printf("Task1 is running...\n");
        vTaskDelay(1000);
```



Running FreeRTOS on QEMU

3 FreeRTOS Porting

- Run the Test:
 - cd App && make run

```
Ready to run the scheduler...
Task1 is running...
Task1 is running...
Task1 is running...
Task1 is running...
```

Figure: FreeRTOS Porting Test.



Table of Contents

4 Test Application

- ▶ Project Overview
- QEMU Board Emulation
- FreeRTOS Porting
- ► Test Application
- Memory Protection Unit (MPU) Implementation
- Conclusion



Secure Timeout System Application

4 Test Application

- The application is a simple implementation of a Secure Timeout System.
- It consists of **multiple tasks** that simulate events, monitor activities, and handle alerts.
- Hardware timers are used to generate periodic interrupts for activity detection.





Task Implementation

4 Test Application

Event Task:

- Periodically generates events that can be either user activities or suspicious activities.
- Uses a pseudo-random number generator to decide the type of event.
- Logs the generated event and updates the respective counters.

```
      [EVENT SIMULATOR]
      —— New Cycle Started
      —— Count: 1

      [EVENT SIMULATOR]
      —— New Cycle Started
      —— Count: 1

      [EVENT SIMULATOR]
      Generated: Security Event
      | Count: 1
```

Figure: Generation of a user activity and a suspicious activity.



Hardware Timer Initialization

4 Test Application

• Timer o:

- Configured to generate periodic interrupts.
- Interrupt handler checks for user activities and sets the user activity detection flag.

• Timer 1:

- Configured to generate periodic interrupts.
- Interrupt handler checks for suspicious activities and sets the suspicious activity detection flag.



Task Implementation

4 Test Application

Monitor Task:

- Checks for user activity detection.
- Logs the status of user activity.
- Resets the user activity detection flag after logging.

• Alert Task:

- Checks for suspicious activity detection.
- Logs the status of the system security.
- Initiates security protocols if suspicious activity is detected.
- Resets the suspicious activity detection flag after logging.



Implementation Details

4 Test Application

• Global Variables:

- Four main flags:
 - userActivity, userActivityDetection, suspiciousActivity, suspiciousActivityDetection

• Task Priorities:

- Event Task has the highest priority to ensure timely event generation.
- Monitor Task and Alert Task have lower priorities.

• Timer Frequency:

 Timer 0 and Timer 1 are configured to generate periodic interrupts at a frequency of 2 Hz.



Implementation Details

4 Test Application

• Task Priorities:

```
// filepath: /App/SecureTimeoutSystem/secure_timeout_system.c
#define MONITOR_TASK_PRIORITY (tskIDLE_PRIORITY + 2)
#define ALERT_TASK_PRIORITY (tskIDLE_PRIORITY + 3)
#define EVENT_TASK_PRIORITY (tskIDLE_PRIORITY + 4)
```

• Timer Frequency:

```
// filepath: /App/Peripherals/IntTimer.c
#define tmrTIMER_O_FREQUENCY (2UL)
#define tmrTIMER_1_FREQUENCY (2UL)
```



Run Example

4 Test Application

```
[EVENT SIMULATOR] ---- New Cycle Started -
[EVENT SIMULATOR] Generated: Security Event | Count: 1
Timer 0 Interrupt: looking for user activities...
Timer 1 Interrupt: looking for suspicious activities...
SECURITY ALERT] Suspicious activity detected | Status: ALARM
[SECURITY ALERT] Initiating security protocols ...
[USER MONITOR] No activity
                                              | Status: IDLE
Timer 0 Interrupt: looking for user activities ...
Timer 1 Interrupt: looking for suspicious activities...
Timer 0 Interrupt: looking for user activities ...
Timer 1 Interrupt: looking for suspicious activities...
[SECURITY ALERT] Suspicious activity detected | Status: ALARM
[SECURITY ALERT] Initiating security protocols ...
[USER MONITOR] No activity
                                              | Status: TDLE
Timer 0 Interrupt: looking for user activities...
Timer 1 Interrupt: looking for suspicious activities...
Timer 0 Interrupt: looking for user activities ...
Timer 1 Interrupt: looking for suspicious activities...
[SECURITY ALERT] Suspicious activity detected | Status: ALARM
SECURITY ALERT1 Initiating security protocols ...
[USER MONITOR] No activity
                                              | Status: IDLE
Timer 0 Interrupt: looking for user activities...
Timer 1 Interrupt: looking for suspicious activities...
Timer @ Interrupt: looking for user activities ...
Timer 1 Interrupt: looking for suspicious activities...
[SECURITY ALERT] Suspicious activity detected | Status: ALARM
[SECURITY ALERT] Initiating security protocols...
FUSER MONITOR1 No activity
                                              | Status: TDLF
Timer Ø Interrupt: looking for user activities ...
Timer 1 Interrupt: looking for suspicious activities...
Timer 0 Interrupt: looking for user activities...
Timer 1 Interrupt: looking for suspicious activities...
[SECURITY ALERT] Suspicious activity detected | Status: ALARM
SECURITY ALERT Initiating security protocols...
[USER MONITOR] No activity
                                              | Status: IDLE
Timer 0 Interrupt: looking for user activities...
Timer 1 Interrupt: looking for suspicious activities...
```



Table of Contents

- Project Overview
- QEMU Board Emulation
- FreeRTOS Porting
- ► Test Application
- ► Memory Protection Unit (MPU) Implementation
- Conclusion



Overview

- The MPU enhances security by restricting memory access based on region configurations.
- The ARM Cortex-M7 processor supports up to 16 MPU regions.
- FreeRTOS provides built-in MPU support for ARM Cortex-M4, which can be theoretically adapted for Cortex-M7.
 - Errata 837070: Requires workarounds for Cortex-M7 ropo and rop1 revisions.



Theoretical Steps for Implementation

- **Define MPU Region Count in FreeRTOSConfig.h**:
 - Set configENABLE_MPU to 1.
 - Set configTOTAL_MPU_REGIONS to 16.
 - Set configENABLE_ERRATA_837070_WORKAROUD to 1.
- Enable Errata Workaround: Apply fix for Cortex-M7 ropo and rop1 by modifying port.c.
- Integrate FreeRTOS Changes: Adapt ARM_CM4_MPU/port.c to support Cortex-M7.



MPU Configuration

- Each MPU region is configured with:
 - Base address
 - Region size
 - Access permissions (privileged/unprivileged, read/write/execute)
- Enables separation of kernel and user-mode tasks.





Table of Contents

6 Conclusion

- ▶ Project Overview
- QEMU Board Emulation
- ▶ FreeRTOS Porting
- Test Application
- Memory Protection Unit (MPU) Implementation
- **▶** Conclusion



- The s32k3x8evb_board.c file plays a crucial role in the emulation of the NXP S32K3X8EVB board within QEMU.
- It provides the necessary functions to load firmware, initialize memory regions, set up hardware components, and manage system clocks and interrupts.
- All the implementations and detailed information about the project are contained in the repository.
- Repository link: https://baltig.polito.it/caos2024/group2.git



Thank you for listening!
Any questions?