

6-Axis Positioner with Controller

COST-EFFICIENT HEXAPOD



H-820

- Six degrees of freedom, travel ranges to 100 mm / 60°
- Load capacity to 20 kg
- Velocity under full load to 20 mm/s
- Repeatability up to ±1 µm
- MTBF 20,000 h

Standard-class 6-axis positioning system

Parallel-kinematic design for six degrees of freedom making it significantly more compact and stiff than serialkinematic systems, higher dynamic range, no moved cables: Higher reliability, reduced friction

Direct drive with brushless DC motors (BLDC)

Indirect measuring principle

Rotary encoder on motor shaft

Powerful digital controller, open software architecture

User-defined, stable pivot point, software-selectable. Positions commanded in Cartesian coordinates. Macro programming. Open source LabVIEW driver set. Work space simulation software. Optional interface for PLC control

Fields of application

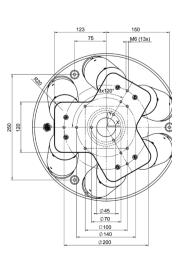
Research and industry. For life science, biotechnology, automation, micromachining

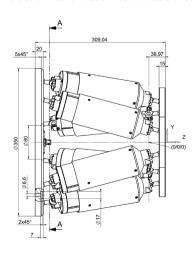


| | H-820.D12 | Unit | Tolerance |
|--|---|--------|-----------|
| Active axes | $X, Y, Z, \theta_{X}, \theta_{Y}, \theta_{Z}$ | | |
| Motion and positioning | | | |
| Travel range* X, Y | ±50 | mm | |
| Travel range* Z | ±25 | mm | |
| Travel range* θ_{x} , θ_{y} | ±15 | 0 | |
| Travel range* θ_z | ±30 | 0 | |
| Actuator drive | Torque motor, brushless (BLDC) | | |
| Single-actuator design resolution | 0.2 | μm | typ. |
| Min. incremental motion X, Y, Z | 10 | μm | typ. |
| Min. incremental motion θ_x , θ_y , θ_z | 25 | μrad | typ. |
| Repeatability X, Y | ±2 | μm | typ. |
| Repeatability Z | ±1 | μm | typ. |
| Repeatability θ_x , θ_y | ±15 | μrad | typ. |
| Repeatability θ_z | ±30 | μrad | typ. |
| Backlash X, Y | 30 | μm | typ. |
| Backlash Z | 10 | μm | typ. |
| Backlash $\theta_{x'}$, θ_{y} | 100 | μrad | typ. |
| Backlash θ_z | 300 | μrad | typ. |
| Max. velocity X, Y, Z | 20 | mm/s | |
| Max. velocity θ_x , θ_y , θ_z | 200 | mrad/s | |
| Mechanical properties | | | |
| Load (baseplate horizontal) | 20 | kg | max. |
| Load (base plate in any orientation) | 10 | kg | max. |
| Holding force (baseplate horizontal) | 200 | N | max. |
| Holding-force (baseplate in any orientation) | 100 | N | max. |
| Miscellaneous | | | |
| Operating temperature range | 0 to +50 | °C | |
| Material | Aluminum | | |
| Mass | 15 | kg | ±5% |
| Cable length | 3 | m | ±10 mm |
| Controller | C-887.21, included in delivery | | |
| Operating voltage | 100-240 VAC, 50/60 Hz | | |

Technical data specified at 20±3°C. Ask about custom designs!

^{*} The travel ranges of the individual coordinates (X, Y, Z, θ_{χ} , θ_{χ} , θ_{χ} , θ_{χ}) are interdependent. The data for each axis in this table shows its maximum travel, where all other axes are at their zero positions. If the other linear or rotational coordinates are not zero, the available travel may be less.





H-820.D12, dimensions in mm