

Department of Computer Science

CSCI 5622: Machine Learning

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Lecture 12: Neural Networks II

Slides adapted from Chris Ketelsen, Jordan Boyd-Graber, and Noah Smith

Administrivia

- •HW2 solution is out
- HW2 feedback
- Google educational credit information in email

Learning Objectives

Understand common components in neural architectures

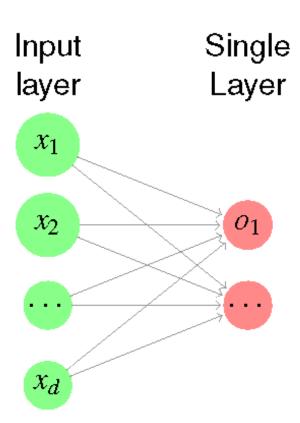
Outline

- Recap
- Layers for structured data

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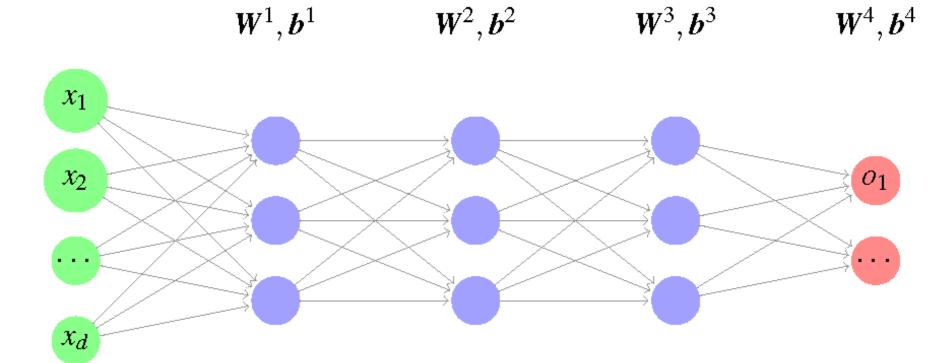
Logistic Regression as a Single-layer Neural Network



- What is the activation used in logistic regression?
- What is the objective function used in logistic regression?

Forward propagation algorithm

How do we make predictions based on a multi-layer neural network? Store the biases for layer l in b^l , weight matrix in W^l



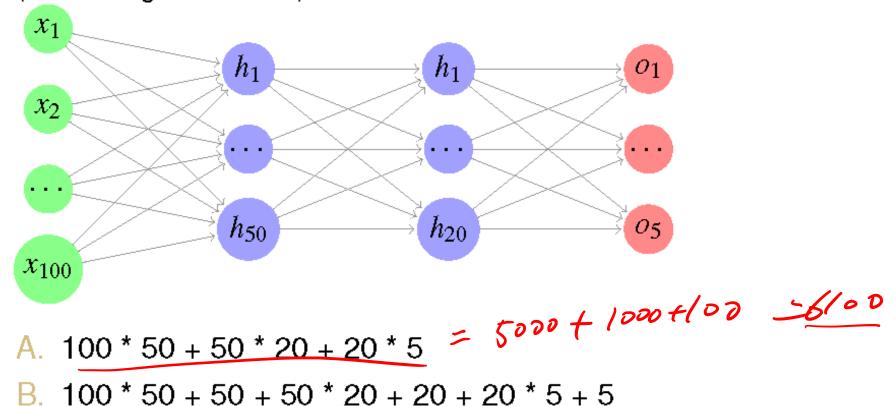
Forward propagation algorithm

Suppose your network has L layers Make prediction for an instance x

- 1: Initialize $a^0 = x$
- 2: **for** l=1 to L **do**
- 3: $\overline{oldsymbol{z}^l = oldsymbol{W}^l oldsymbol{a}^{l-1} + oldsymbol{b}^l}$
- 4: $a^l = g(z^l) // g$ represents the nonlinear activation
- 5: end for
- 6: The prediction \hat{y} is simply a^L

Quiz 1

How many parameters are there in the following feed-forward neural networks (assuming no biases)?



Neural networks in a nutshell

- Training data $S_{\text{train}} = \{(x, y)\}$
- Network architecture (model)

$$\hat{y} = \frac{f_w(x)}{7}$$

Loss function (objective function)

$$\mathscr{L}(y,\hat{y})$$

Learning (next week)

Which of the following statements is true? (Suppose that training data is large.)

- A. In training, K-nearest neighbors takes shorter time than neural networks.
- B. In training, K-nearest neighbors takes longer time than neural networks.
- C. In testing, K-nearest neighbors takes shorter time than neural networks.
- D. In testing, K-nearest neighbors takes longer time than neural networks. \checkmark

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Spatial information



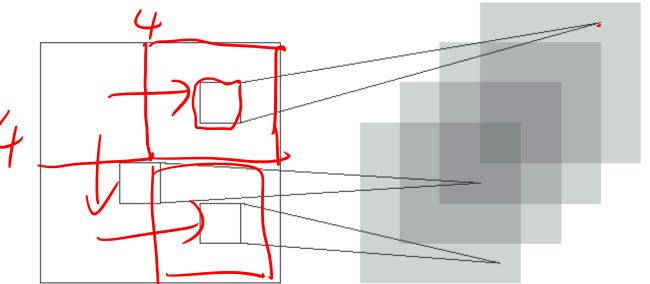
https://www.reddit.com/r/aww/comments/6ip2la/before_and_after_she_was_told_she_was_a_good_girl/

Convolutional Layers

Sharing parameters across patches

input image or input feature map

output feature maps

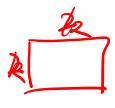




$$a_{i'j'} = \sum_{i=1}^{k} \sum_{j=1}^{k} w_{ij} x_{ij}$$

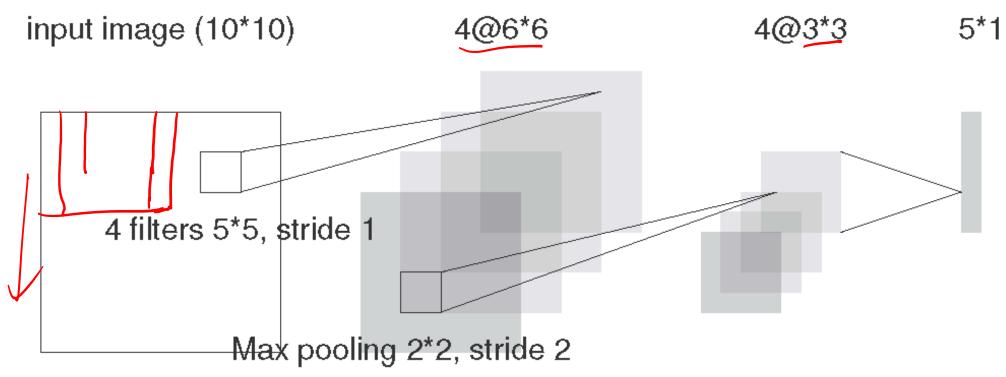
- Number of filters
- Filter shape kxk
- Stride size

https://github.com/davidstutz/latex-resources/blob/master/tikz-convolutional-layer/convolutional-layer.tex



max Xij' 1≤ v≤12 1≤156

A concrete example (assuming no biases, convolution with 4 filters, ReLU, max pooling, and finally a fully-connected softmax layer)



How many parameters are there in the following convolutional neural networks? (assuming no biases, convolution with 4 filters, ReLU, max pooling, and finally a fully-connected softmax layer)

4x5x5

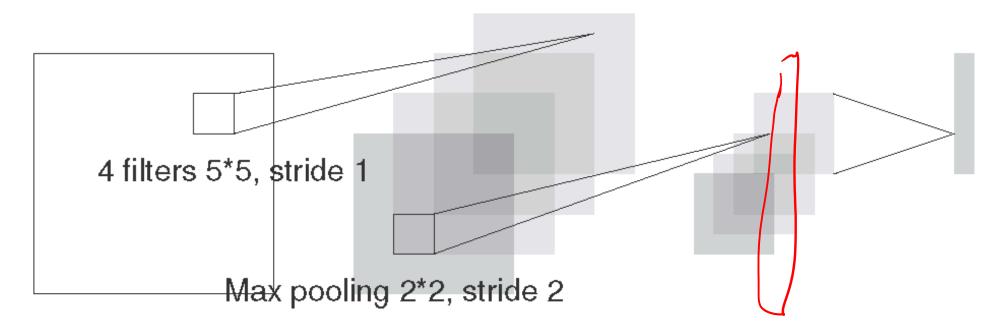
6

(4x5x5)

input image (10*10) 4@6*6

4@3*3

5*1 (80





How many ReLU operations are performed on the forward pass? (assuming no biases, convolution with 4 filters, ReLU, max pooling, and finally a fully-connected

softmax layer) input image (10*10) 4@3*3 5*1 4 filters 5*5, stride 1 Max pooling 2*2, stride 2

Sequential information

"My words fly up, my thoughts remain below: Words without thoughts never to heaven go."

-Hamlet

Sequential information

"My words fly up, my thoughts remain below: Words without thoughts never to heaven go."

-Hamlet

- language
- activity history

(V/30000X100

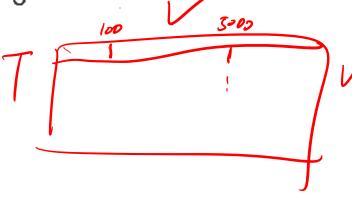
Sequential information

"My words fly up, my thoughts remain below: Words without thoughts never to

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language

activity history



—Hamlet

$$oldsymbol{x} = (x_1, \dots, x_T)$$

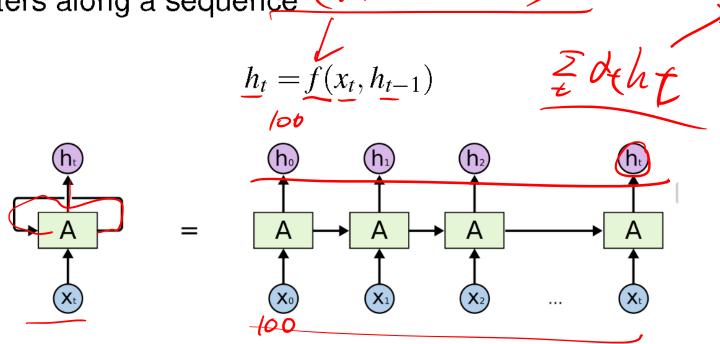
Recurrent Layers

Sharing parameters along a sequence

$$h_t = \underbrace{f(x_t, h_{t-1})}$$

Recurrent Layers

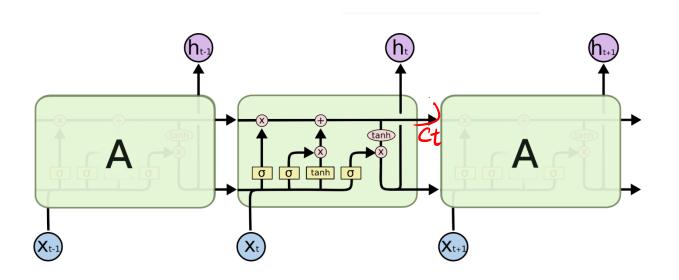
Sharing parameters along a sequence wax t Wh h th



https://colah.github.io/posts/2015-08-Understanding-LSTMs/

Long short-term memory

A commonly used recurrent neural network in natural language processing



$$f_{t} = \sigma(W_{f} \cdot [h_{t-1}, x_{t}] + b_{f})$$

$$i_{t} = \sigma(W_{i} \cdot [h_{t-1}, x_{t}] + b_{i})$$

$$o_{t} = \sigma(W_{o} \cdot [h_{t-1}, x_{t}] + b_{o})$$

$$C_{t} = tanh(W_{C} \cdot [h_{t-1}, x_{t}] + b_{C})$$

$$C_{t} = f_{t} * C_{t-1} + i_{t} * C_{t}$$

$$h_{t} = o_{t} * tanh(C_{t})$$

Wrap up

Neural networks

- Network architecture (a lot more then fully connected layers)
 - Convulutional layer
 - Recurrent layer
- Loss function

What is missing?

- How to find good weights?
- How to make the model work (regularization, even more architecture, etc)?