



# **Cypress EZ-USB® FX3™ SDK**

## **Trouble Shooting Guide**

**Version 1.3**

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# 1 Introduction



This document provides hints on trouble shooting system errors that are seen when using the EZ-USB FX3 device and the FX3 SDK. It also serves as a FAQ database for the FX3 SDK.

The hints provided here are based on the learning from multiple FX3 based system designs, and will be updated on a periodic basis. This document should be used in conjunction with the FX3 Programmer's Manual and API Guide documents that are part of the SDK package itself.

## 2 USB Trouble Shooting



### 2.1 USB Enumeration Failures

#### I. FX3 does not enumerate as a USB 3.0 device after firmware is downloaded.

In most cases, USB 3.0 enumeration failure is due to poor signal integrity on the USB 3.0 lines of the FX3 device. Please ensure that you are following the FX3 board design guidelines from Cypress. Refer to [AN70707: EZ-USB® FX3™/FX3S™ Hardware Design Guidelines and Schematic Checklist](#) for details.

The USB driver in the SDK is capable of logging USB related events and state changes into a user provided memory buffer. This buffer content can later be read back through USB or UART to identify the event sequence that led to the failed enumeration.

Refer to the CyU3PUsbInitEventLog() API in the FX3 API guide for information on how to initiate these driver logs. The USBBulkSourceSink example in the SDK includes reference code that makes use of this API and provides two ways of reading the event logs out:

- Using a vendor specific USB control request.
- Through UART debug prints

The contents of the event log buffer are single bytes that are to be interpreted using a set of constants defined in the cyu3usb.h header file. Refer to the macro definitions for CYU3P\_USB\_LOG\_VBUS\_OFF onwards.

#### II. FX3 fails to enumerate as a Hi-Speed device when SuperSpeed is enabled

This can happen due to three reasons:

- The 1.2.1 SDK had a known issue with handling the fall back from USB 3.0 to 2.0, when the FX3 device is being clocked using a 26 MHz clock input. This happens because of insufficient delay applied while switching the operating clocks for USB operation.

**This issue has been fixed from the 1.2.2 SDK onwards.**

- If the FX3 device detects SuperSpeed receiver terminations on the host side, and then fails to receive the Polling LFPS signaling from the host; it will enter the USB 3.0 compliance state. The device can only exit from the compliance state if a USB 3.0 Reset is received or if Vbus is turned off. Please verify that the USB host port does not offer receiver terminations without the USB 3.0 host being available.
- The USB driver for FX3 requires that the device be able to detect Vbus voltage changes. If a Vbus change is not detected by the device when it is disconnected from the host; it will only connect as a hi-speed device on a subsequent USB connection.

## 2.2 Unexpected Connection Failures

### I. The SuperSpeed USB connection from FX3 fails abruptly during data transfer, or the device re-enumerates.

- The USB driver in the FX3 SDK monitors the number of USB link errors that are detected by the hardware; and causes a re-enumeration when the number of errors crosses a threshold value (about 64 errors) within a 1 second period. This code is not expected to come into play on a functional link, because there will be not more than one or two errors per second happening. If the device is re-enumerating, it is likely that there is a bad USB link due to bad interconnect cables or traces.
- Another reason for USB 3.0 connection errors is link errors that happen around link power state transitions. The best option to avoid such problems is to prevent USB 3.0 link state transitions, by having the FX3 device systematically reject any low power requests.

The FX3 device can be placed in this mode by making use of the **CyU3PUsbLPMDisable()** API. Please note that using this API can also help improve the USB data transfer performance because of increased link efficiency.

## 2.3 USB Data Transfer Failures

### I. FX3 stops sending data on all USB IN endpoints abruptly.

- It is possible that the endpoint memory block on the FX3 device locks up if the DMA channel for that endpoint is reset or aborted while it is ready from the DMA buffers. The same applies to endpoint reset and flush (**CyU3PUsbResetEp** and **CyU3PUsbFlushEp**) API calls.

The caller should ensure that the endpoint is idle before performing any reset or flush operations on the DMA channel or the endpoint. This can be done by placing the endpoint in NAK/NRDY mode where it does not try to send data to the host. This sequence is shown in the code snippet below.

```
CyU3PUsbSetEpNak (epNum, CyTrue);           // NAK the endpoint.
CyU3PBusyWait (100;                          // Insert a delay
// Do clean-up on the channel and EP now.
CyU3PDmaChannelReset (&epChannel);
CyU3PUsbFlushEp (epNum);
// Finally release the EP from NAK mode.
CyU3PUsbSetEpNak (epNum, CyFalse);
```

- It has also been seen that the use of the **CyU3PUsbEnablePrefetch()** API is causing the endpoints to get stuck, because they try to read very aggressively from the DMA channels. Removing this API call will fix these issues.

It was earlier recommended that this API be used to prevent data corruption errors during high speed data transfers. The device settings that are required to prevent data corruption which were earlier being made as part of this API call; have now been made the default settings for the driver. Therefore, there are no known problems associated with removing this API call.

## II. Transfer freeze on a burst enabled IN endpoint

- The FX3 device has an errata that causes it to not treat a ZLP (Zero Length Packet) as an end of burst packets in some cases. This error happens intermittently and is caused by a race condition in the device design.

The work-around for this issue is to ensure that DMA channel corresponding to the endpoint is suspended as soon as it has committed any ZLP to the endpoint. This can be achieved by making use of the CY\_U3P\_DMA\_SCK\_SUSP\_EOP option to suspend the consumer socket on the DMA channel. The code snippet for doing this is shown below:

```
/* DMA callback that handles the channel suspension. */
static void
AppDmaCallback (
    CyU3PDmaChannel *chHandle,
    CyU3PDmaCbType_t cbType,
    CyU3PDmaCBInput_t *cbInput)
{
    /* Having the channel suspend is sufficient delay
       to prevent errors. Resume the DMA channel immediately.
    */
    CyU3PDmaChannelResume (chHandle, CyFalse, CyTrue);
}

{
    /* This code is to be inserted after the DMA channel
       is created. */
    CyU3PDmaChannelSetSuspend (chHandle,
        CY_U3P_DMA_SCK_SUSP_NONE, CY_U3P_DMA_SCK_SUSP_EOP);
}
```

## III. Control Request Handling Errors

- The USB driver in the FX3 firmware passes all control requests addressed to an interface (including SET\_INTERFACE/GET\_INTERFACE) to the Setup callback function registered. If the application does not need to track and handle these requests in a customized manner, the setup callback can just return CyFalse to indicate that the request has not been handled. In this case, the USB driver will take the default action (SET\_INTERFACE will be acked, and a value of 0x00 will be returned for GET\_INTERFACE).

If the setup callback returns CyTrue, the driver assumes that the application has handled the request and takes no further action (including trying to stall EP0). Please ensure that the setup callback returns CyTrue if and only if the control request has been handled.

Any control requests that are deferred to a user thread need to be completely handled by the application logic. As the USB driver uses the return value from the callback to identify whether the request has been handled by the application, it is not possible to defer the request handling to a thread; and then hand it back to the driver for handling.

## 2.4 Low USB transfer performance

### I. Poor system performance is seen with specific USB hosts like the Intel USB 3.0 host

- The Intel USB 3.0 host is more aggressive in the usage of USB link power saving as compared to other USB 3.0 hosts like Renesas or ASMedia. This can cause poor data transfer performance because the FX3 device is not capable of automatically exiting a low power state (U1/U2) when it has data to be sent to the host.

The FX3 device requires firmware intervention to initiate a state transition from U1/U2 back to U0. This state change is initiated by making the following API call.

```
CyU3PUsbSetLinkPowerState (CyU3PUsbLPM_U0);
```

The transfer performance can be improved by using the **CyU3PUsbLPMDisable()** API to completely disable low power state transitions; or by periodically calling **CyU3PUsbSetLinkPowerState()** to ensure that the link is reverted to U0.

### II. Poor data transfer on the IN data path with burst enabled endpoints

- In default mode, the FX3 device does not try to combine data from multiple DMA buffers into a single burst transfer on the USB side. This can lead to some performance drop, particularly when using small sized DMA buffers on the data path.

The device can be configured to allow data from multiple buffers to be combined into a single burst, by calling the **CyU3PUsbEPSetBurstMode()** API.

## 2.5 USB Configuration Errors

### I. Device with high bandwidth Isochronous endpoints fails to start up and function properly

- High bandwidth Isochronous endpoints are those that support transfers of more than one packet of data at USB Hi-Speed and one burst of data at USB SuperSpeed, per micro-frame. The FX3 device supports high bandwidth Isochronous transfers only on the Endpoints 3 and 7 (both IN and OUT). Please ensure that these endpoints are selected whenever high bandwidth Isochronous data transfers are used.
- Some USB hosts may have limitations with respect to the amount of bandwidth they can reserve for Isochronous data transfers. If the bandwidth required by the device exceeds these limits, the host will not select the device configuration. It is recommended that the application implement multiple bandwidth settings by varying the burst length and number of bursts per micro-frame. The host can then select the best possible bandwidth setting that it can support.

## 2.6 Isochronous transfer failures at hi-speed

### II. Significant loss of data is seen when using high bandwidth Isochronous endpoints at USB hi-speed

- As per the USB 2.0 specification, a device should use the DATA0 PID when sending a single packet of data during a micro-frame, regardless of the MULT setting for the isochronous endpoint.



The FX3 device has an errata item where the PID on a ISO data packet is always based on the MULT setting alone. i.e., The device uses the DATA2 PID if MULT is set to 2, and the DATA1 PID if MULT is set to 1.

Sending data with the wrong PID causes the USB host to drop the data packet, leading to loss of data at the system level.

The work-around for this issue is to perform the following operations at the beginning of each micro-frame. The beginning of a micro-frame can be identified by registering for a CY\_U3P\_USB\_EVENT\_SOF\_ITP event, or by configuring a GPIO timer to fire every 125 us.

- 1) Use a MANUAL DMA channel instead of an AUTO channel, with each buffer capable of holding the maximum amount of data that can be transferred in a micro-frame (2KB or 3KB based on MULT value).
- 2) Use the CyU3PDmaChannelGetBuffer() API to identify the amount of data that is available to send to the host.
- 3) Set the ISO MULT value for the endpoint based on the actual amount of data to be sent. The CyU3PsetEpConfig API can be called repeatedly for doing this.
- 4) Commit the data to the host by calling CyU3PDmaChannelCommitBuffer.

## 2.7 USB Electrical Compliance Failures

### I. The device fails to send the USB 3.0 compliance test patterns during electrical testing

- The 1.2.3 SDK has a bug which may cause the device to prematurely exit the USB 3.0 compliance state, thereby failing to send the compliance test patterns as required.

This issue has been fixed in the FX3 SDK 1.3 version.

### II. Using the CyU3PUsbDoRemoteWakeup() API causes the FX3 device to drop off the USB bus

- The CyU3PUsbDoRemoteWakeup() API is used to have the FX3 device signal a remote wake condition to notify the host during a USB 2.0 session.

The implementation of this API in the 1.2.3 SDK leaves one of the device registers in an incorrect state leading to the device dropping off the bus.

This issue can be worked-around by writing 0 to the register at the address 0xE0031408, immediately after calling the API. The code for the work-around is shown below.

```

{
    uint32_t tmp = 0;
    stat = CyU3PUsbDoRemoteWakeup ();
    if (stat == CY_U3P_SUCCESS)
    {
        CyU3PWriteDeviceRegisters ((uvint32_t*)0xE0031408, 1,
                                   &tmp);
    }
}

```

This issue has been fixed in the FX3 SDK 1.3 version.

## 3 General Device Trouble Shooting



### 3.1 Device Suspend Mode Handling

#### I. Device wake from Suspend mode based on USB activity does not work

- The drivers in SDK 1.2.3 have a known issue with respect to waking up from suspend mode based on USB bus activity. While this will work most of the time, it is possible that the device fails to wake up intermittently from the low power mode.

This issue has been fixed in the FX3 SDK 1.3 version.

## 4 GPIF II Trouble Shooting



### 4.1 Data Transfer Failures

I. **Data transfers through the GPIF II interface fail when the data bus is 32 bits wide and the interface frequency is 100 MHz (synchronous).**

- If the FX3 device is being clocked using a 19.2 MHz crystal or a 38.4 MHz clock input; the GPIF II hardware will be running at a default frequency of 96 MHz. At this frequency, the block cannot handle data that is incoming at the rate of 32 bits per 10 ns; and will result in a high frequency of overflow errors.

This can be fixed by adjusting the internal clock dividers so that the GPIF II hardware runs at a frequency greater than 100 MHz. This can be done by setting the `setSysClk400` field to `CyTrue` in the `CyU3PSysClockConfig_t` structure passed to the `CyU3PDeviceInit`.

## 5 SDK Tools Trouble Shooting



### 5.1 Elf2img converter issues

#### I. Eclipse post-build step to generate binary image fails

- The Eclipse projects provided as part of the FX3 SDK include a post-built step that uses the elf2img.exe converter utility to generate a loadable firmware binary image. It has been seen that this step fails on some systems and throws error messages such as:

```
/usr/bin/sh: C:\Program Files\Cypress\EZ-USB FX3  
SDK\1.2\util\elf2img\elf2img.exe: command not found
```

This happens due to a Windows path resolution error. This can commonly be fixed by removing the quote (") characters in the post-build command used.

i.e., change the post-build step to:

```
${FX3_INSTALL_PATH}\util\elf2img\elf2img.exe -i  
${ProjName}.elf -o ${ProjName}.img
```

#### II. Programming firmware binary to I2C EEPROM fails

- The FX3 firmware binary (.img) format includes information on how to address the I2C EEPROM device when programming as well as during boot operations. This elf2img.exe converter takes in a command line parameter (-i2cconf) through which the user can specify this information.

The default setting chosen corresponds to Atmel/ST Micro I2C EEPROMs with a capacity of 64 KB or more. This configuration expects that the first 64 KB of EEPROM can be found at I2C device address 'b000, the next 64 KB at device address 'b001 and so on. If the EEPROM device(s) being programmed have a different addressing scheme, the -i2cconf parameter should be used to specify the desired addressing scheme.

Please refer to the \$FX3\_INSTALL\_PATH\util\elf2img\readme.txt document in the SDK installation for information on the format of this parameter.

#### III. Boot from I2C/SPI is slow

- The FX3 firmware binary (.img) format specifies the speed at which the I2C/SPI interface is to be run during the boot operation. This information is also specified through the -i2cconf parameter to the elf2img.exe converter.

The default operating speed for booting will be the lowest supported (100 KHz for I2C and 10 MHz for SPI). Please refer to the \$FX3\_INSTALL\_PATH\util\elf2img\readme.txt document in the SDK installation for information on how the frequency is specified through the i2cconf parameter.