# 

#### 1 Math

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#### 1.1 FindPrime

1 #include <bits/stdc++.h>

```
2 using namespace std;
3
4 //查找 [0,2^15] 中的所有質數 共有3515
6 const int MAXN = 32768; //2^15=32768
7 bool primes[MAXN];
8 vector<int> p; //3515
10 //質數篩法Sieve of Eratosthenes
11 inline void findPrimes() {
      for (int i = 0; i < MAXN; i++) {</pre>
12
          primes[i] = true;
13
14
15
      primes[0] = false;
16
      primes[1] = false;
      for (int i = 4; i < MAXN; i += 2) {</pre>
17
           //將2的倍數全部刪掉(偶數不會是質數)
          primes[i] = false;
18
19
      //開始逐個檢查 ---> 小心 i * i 會有 overflow 問題 ---> 使用 longo
20
           long
21
      for (long long i = 3; i < MAXN; i += 2) {
          if (primes[i]) {
22
               //如果之前還未被刪掉 才做篩法
23
               for (long long j = i * i; j < MAXN; j +=
                   i) {
                   //從 i * i 開始 (因為 i * 2, i * 3... 都被前面處理完 5 7
                  primes[j] = false;
24
              }
25
          }
26
27
      }
      //搜集所有質數
28
      for (int i = 0; i < MAXN; i++) {</pre>
29
30
          if (primes[i]) {
31
              p.emplace_back(i);
32
```

## 2 Graph

}

33

34 }

#### 2.1 Kruskal

```
#include <bits/stdc++.h>
using namespace std;

// Kruskal (MST) 節點從0號開始
struct Edge {
  int v, w, wt;
  Edge(int a, int b, int c) {
    v = a;
    w = b;
    wt = c;
```

```
12
            return wt < e.wt;</pre>
13
14
   };
15
   const int maxN = 100000 + 5; // maxN個節點
16
17
   int parent[maxN];
18
   vector<Edge> edges;
19
   int do_find(int p) {
20
        while (parent[p] >= 0) {
21
22
            p = parent[p];
23
       }
24
        return p;
25
   }
26
27
   void do_union(int p, int q) {
28
        if (parent[p] > parent[q]) {
29
            parent[q] += parent[p];
            parent[p] = q;
30
31
       } else {
            parent[p] += parent[q];
32
33
            parent[q] = p;
34
35 }
36
   int m, n, ta, tb, tc, weight;
38
39
   int main() {
        while (~scanf("%d %d", &m, &n)) {
40
            for (int i = 0; i < n; i++) {</pre>
41
42
                scanf("%d %d %d", &ta, &tb, &tc);
43
                edges.push_back({ta, tb, tc});
44
45
            sort(edges.begin(), edges.end());
            for (int i = 0; i <= m; i++) {</pre>
46
47
                parent[i] = -1;
48
            }
            weight = 0;
49
            for (auto e : edges) {
                ta = do_find(e.v);
51
52
                tb = do_find(e.w);
53
                if (ta != tb) {
54
                     weight += e.wt;
                     do_union(ta, tb);
55
56
57
            }
            printf("%d\n", weight);
59
60
        return 0:
61 }
```

bool operator<(const Edge &e) const {</pre>

## 2.2 Dijkstra

10

11

1

```
1 #include <bits/stdc++.h>
 2
  using namespace std;
 3
 4 //節點從1號開始
  const int maxN = 100000 + 5; // maxN個節點
 5
  struct Edge {
 7
       int v, wt;
       Edge(int a, int c) {
 8
 9
           v = a;
           wt = c:
10
11
       Edge() {}
12
13 };
14
15 vector < Edge > g[maxN];
  vector < bool > visied(maxN);
  vector<int> dis(maxN);
17
18
19
  struct Info {
20
       int v:
```

```
21
       Info(int a, int b) : v(a), wt(b) {}
22
23
       Info() {}
24
25
       bool operator<(const Info &i) const {</pre>
26
           return wt > i.wt;
27
28 }:
29
30 priority_queue < Info > pq;
31
32 void init() {
33
       for (int i = 0; i < maxN; i++) {</pre>
           g[i].clear();
34
35
            visied[i] = false;
           dis[i] = 0x3f3f3f;
36
37
38
       while (!pq.empty()) {
           pq.pop();
39
40
41 }
42
43 void dijkstra(int s) {
       Info info;
44
45
       dis[s] = 0;
46
       visied[s] = true;
47
       pq.push({s, 0});
48
49
       while (!pq.empty()) {
50
           info = pq.top();
           pq.pop();
51
52
            visied[info.v] = true;
           if (dis[info.v] > info.wt) {
53
54
                dis[info.v] = info.wt;
55
           }
           for (auto e : g[info.v]) {
56
57
                if (!visied[e.v]) {
                    pq.push({e.v, dis[info.v] + e.wt});
58
                }
59
60
           }
61
       }
62 }
63
64 int m, n, ta, tb, tc;
65 int main() {
       ios::sync_with_stdio(0);
66
67
       cin.tie(0);
       while (cin >> m >> n) {
68
69
           init();
           while (n--) {
70
71
                cin >> ta >> tb >> tc;
72
                g[ta].push_back({tb, tc});
73
                g[tb].push_back({ta, tc});
74
           }
75
           dijkstra(1); //從1號節點開始
       }
76
77
       return 0;
78 }
```

### 2.3 BellmanFord

```
1 #include <bits/stdc++.h>
2 using namespace std;
3 //節點從0開始(適用於無向圖)
4 // 備註: 如果圖為無向圖且包含負權邊 則必定有負權環
5 struct Edge {
     int f, t, wt;
6
7
      Edge() {}
8
      Edge(int a, int b, int c) {
         f = a;
9
10
         t = b;
         wt = c;
11
12
      }
13 };
14
```

```
//節點與邊數
15 int V, E;
16 const int maxN = 100000; //最多 maxN 個 節 點
17 vector<vector<Edge>> G(maxN);
18 vector < int > distTo(maxN); //到節點i的權重
19 bool hasNegtiveCycle;
20 Edge e;
22
   void init() {
       for (int i = 0; i < V; i++) {</pre>
23
24
            G[i].clear();
25
            distTo[i] = 0x3f3f3f;
26
27 }
28
29 bool detectHasCycle() {
       for (int i = 0; i < V; i++) {
30
31
            for (int j = 0; j < G[i].size(); j++) {</pre>
                e = G[i][j];
32
                if (distTo[e.f] + e.wt < distTo[e.t]) {</pre>
33
34
                     return true;
35
                }
            }
36
37
       return false;
38
39 }
40
41
  void bellmanFord(int s) { //從s點開始
42
       distTo[s] = 0;
43
       //執行節點 - 1 次鬆弛
       for (int pass = 1; pass < V; pass++) {</pre>
44
45
            for (int i = 0; i < V; i++) {</pre>
                for (int j = 0; j < G[i].size(); j++) {</pre>
46
47
                     e = G[i][j];
                     if (distTo[e.f] + e.wt < distTo[e.t])</pre>
48
                         distTo[e.t] = distTo[e.f] + e.wt;
49
                     }
50
                }
51
           }
52
53
       //檢測負權環
54
55
       hasNegtiveCycle = detectHasCycle();
56 }
57
58
   int main() {
59
       scanf("%d %d", &V, &E);
60
       init();
       for (int i = 0; i < E; i++) {</pre>
61
            scanf("%d %d %d", &e.f, &e.t, &e.wt);
62
63
            G[e.f].push_back(e);
64
       bellmanFord(0); //從節點 0開始
65
66
       if (!hasNegtiveCycle) {
            for (int i = 0; i < V; i++) {
    printf("%d ", distTo[i]);</pre>
67
68
            }
69
            printf("\n");
70
71
       } else {
72
            printf("Has Negtive Cycle.");
       }
73
74
       return 0;
75 }
```

### 3 DataStructure

#### 3.1 BitIndexTree

```
1  #include <bits/stdc++.h>
2  using namespace std;
3  4  // bit 陣列索引從1開始
5  const int maxN = 100000 + 5; // bit容量
```

```
//資料大小
6 const int dataSize = 5;
      arr[0,5)--->bit[1,5]
7 int bit[maxN];
8
9 int query(int x) {
      // query prefix sum in BIT
10
11
      int ret = 0;
      while (x) {
12
          ret += bit[x];
13
14
          x -= x & (-x);
      }
15
      return ret;
16
17 }
18
19 //更新 bit [x]的值
20 void update(int x, int d) {
      while (x <= dataSize) {</pre>
21
          bit[x] += d;
22
          x += x & (-x);
23
      }
24
25 }
26
27 // 區間和 [1,r]
28 int rSum(int 1, int r) {
      return query(r) - query(1 - 1);
29
30 }
31
32 int main() {
      memset(bit, 0, sizeof(bit));
33
34
      int arr[dataSize] = {1, 2, 3, 4, 5};
      for (int i = 0; i < dataSize; i++) {</pre>
35
          update(i + 1, arr[i]); //
36
               arr[i]放bit[i+1]的位置
37
      printf("%d \ n", rSum(2, 4)); // arr[2,4]=2+3+4
38
39
      return 0;
40 }
```