



清华大学

Quantum Computing + X HW4 房天政 2024010794

II 1

$$H = -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + V(x) \quad |\psi\rangle = A e^{-\lambda x^2}$$

$$\langle \psi | H | \psi \rangle = \int_{-\infty}^{+\infty} A^2 e^{-2\lambda x^2} \left(-\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + \alpha x^4 \right) e^{-\lambda x^2} dx$$

$$= \int_{-\infty}^{+\infty} A^2 e^{-2\lambda x^2} \left[\alpha x^4 - \frac{\hbar^2}{2m} (-2\lambda)(x+x) \right] dx$$

$$= \int_{-\infty}^{+\infty} A^2 e^{-2\lambda x^2} \left[\alpha x^4 + \frac{\hbar^2 \lambda}{m} x^2 \right] dx$$

We know that

$$\int_{-\infty}^{+\infty} e^{-x^2} dx = \sqrt{\pi}, \quad \int_{-\infty}^{+\infty} e^{-ax^2} dx = \sqrt{\frac{\pi}{a}}, \quad a > 0$$

$$\int_{-\infty}^{+\infty} e^{-ax^2} x^2 dx = \frac{1}{2a} \int_{-\infty}^{+\infty} e^{-ax^2} x d(ax^2)$$

$$= \frac{1}{2a} (-1) \left[e^{-ax^2} x \right]_{-\infty}^{+\infty} - \int_{-\infty}^{+\infty} e^{-ax^2} dx$$

$$= \frac{1}{2a} \sqrt{\frac{\pi}{a}}$$

$$\int_{-\infty}^{+\infty} e^{-ax^2} x^4 dx = \frac{1}{2a} \int_{-\infty}^{+\infty} e^{-ax^2} x^3 d(ax^2)$$

$$= \frac{1}{2a} (-1) \left[e^{-ax^2} x^3 \right]_{-\infty}^{+\infty} - \int_{-\infty}^{+\infty} e^{-ax^2} d(ax^2)$$

$$= \frac{3}{2a} \int_{-\infty}^{+\infty} e^{-ax^2} x^2 dx$$

$$= \frac{3}{4a^2} \sqrt{\frac{\pi}{a}}$$

$$\langle \psi | H | \psi \rangle = A^2 \left[\alpha \frac{3}{16\lambda^2} \sqrt{\frac{\pi}{2\lambda}} - \frac{2\hbar^2 \lambda^2}{m} \frac{1}{4\lambda} \sqrt{\frac{\pi}{2\lambda}} + \frac{\hbar^2 \lambda}{m} \sqrt{\frac{\pi}{2\lambda}} \right]$$

$$= A^2 \sqrt{\frac{\pi}{2\lambda}} \left[\frac{3}{16} \alpha \frac{1}{\lambda^2} + \frac{\hbar^2}{2m} \lambda \right]$$

$$\langle \psi | \psi \rangle = A^2 \int_{-\infty}^{+\infty} e^{-2\lambda x^2} dx$$

$$= A^2 \sqrt{\frac{\pi}{2\lambda}}$$

$$E(\lambda) = \left[\frac{3}{16} \alpha \frac{1}{\lambda^2} + \frac{\hbar^2}{2m} \lambda \right]$$

$$= \left[\frac{3}{16} \alpha \frac{1}{\lambda^2} + \frac{\hbar^2}{4m} \lambda + \frac{\hbar^2}{4m} \lambda \right]$$

$$\geq 3 \sqrt[3]{\frac{3}{16} \alpha \left(\frac{\hbar^2}{4m} \right)^2}$$

$$= \frac{3}{4} \sqrt[3]{\frac{3 \alpha \hbar^4}{4 m^2}}$$

The equations holds when

$$\frac{3}{16} \alpha \frac{1}{\lambda^2} = \frac{\hbar^2}{4m} \lambda$$

$$\Rightarrow \lambda^3 = \frac{3m\alpha}{4\hbar^2} \quad \lambda = \sqrt[3]{\frac{3m\alpha}{4\hbar^2}}$$

II 2

Please See the code loaded up to the github repo

II 3 $m(x, y) = 8x + 12y + x^2 - 2y^2$

(a) Since the function is analytic

$$\left(\frac{\partial m}{\partial x} = 0 \Rightarrow x = -4 \right)$$

$$\left(\frac{\partial m}{\partial y} = 0 \Rightarrow y = 3 \right)$$

At this point,

$$m(x, y) = (x+4)^2 - 2(y-3)^2 + 2$$

It's obvious that on x direction.

$(-4, 3)$ is a minimum point, while on y direction, $(-4, 3)$ is a maximum point

$\Rightarrow (-4, 3)$ is a saddle point

(b) We have already know
We know that $(-4, 3)$ is not the best point

let

$$g(x, y) = 8x + 12y + x^2 - 2y^2 + \lambda(x^2 + y^2 - 25)$$

$$\frac{\partial g}{\partial x} = 8 + 2x + 2\lambda x = 0$$

$$\frac{\partial g}{\partial y} = 12 - 4y + 2\lambda y = 0$$

$$\frac{\partial g}{\partial \lambda} = x^2 + y^2 - 25 = 0$$

$$\Rightarrow x = -\frac{4}{\lambda+1} \quad y = \frac{-6}{\lambda-2}$$

$$\left(\frac{4}{\lambda+1}\right)^2 + \left(\frac{6}{\lambda-2}\right)^2 = 25$$

$$16(\lambda^2 - 4\lambda + 4) + 36(\lambda^2 + 2\lambda + 1) = 25(\lambda^2 + 2\lambda + 1)$$

$$\Rightarrow 25\lambda^4 - 50\lambda^3 + 27\lambda^2$$

solving the problem using computer

$$\lambda \approx 3.222$$

$$(x, y) \approx (-0.947, -4.909)$$

The direction of gradient descent method is given by

$$\frac{\partial m}{\partial x}(0,0) = 8 \quad \frac{\partial m}{\partial y}(0,0)$$

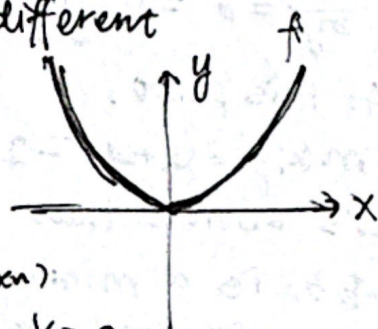
$$\nabla m(0,0) = (8, 12)$$

\therefore the gradient direction is

$$-\nabla m(0,0) = (-8, -12)$$

these two are different

$$\text{[4]} \quad f(x) = |x|^{3/2}$$



$$x_{n+1} = x_n - \alpha f'(x_n)$$

$$f'(x) = \begin{cases} \frac{3}{2}\sqrt{x} & , x > 0 \\ -\frac{3}{2}\sqrt{-x} & , x < 0 \end{cases}$$

$$-\frac{3}{2}\sqrt{-x}$$

If $x_n > 0$

$$x_{n+1} = x_n - \alpha \frac{3}{2}\sqrt{x_n}$$

We just let x_{n+1} & x_n to be symmetric regarding y axis

$$-t = t - \alpha \frac{3}{2}\sqrt{t}$$

$$-x^* = x^* - \alpha \frac{3}{2}\sqrt{x^*}$$

$$\Rightarrow x^* = \left(\frac{2}{3}\alpha\right)^2$$

this is a pair of stationary points that will generate the sequence

$$x^* \rightarrow -x^* \rightarrow x^* \rightarrow -x^* \rightarrow \dots$$

and will not converge

[5] & [6]

Please refer to the code