

4. Markov Chains

- A discrete time process $\{X_n, n = 0, 1, 2, \dots\}$ with discrete **state space** $X_n \in \{0, 1, 2, \dots\}$ is a **Markov chain** if it has the **Markov property**:

$$\begin{aligned}\mathbb{P}[X_{n+1}=j|X_n=i, X_{n-1}=i_{n-1}, \dots, X_0=i_0] \\ = \mathbb{P}[X_{n+1}=j|X_n=i]\end{aligned}$$

- In words, “the past is conditionally independent of the future given the present state of the process” or “given the present state, the past contains no additional information on the future evolution of the system.”
- The Markov property is common in probability models because, by assumption, one supposes that the important variables for the system being modeled are all included in the state space.
- We consider **homogeneous** Markov chains for which $\mathbb{P}[X_{n+1}=j | X_n=i] = \mathbb{P}[X_1=j | X_0=i]$.

Example: **physical systems**. If the state space contains the masses, velocities and accelerations of particles subject to Newton's laws of mechanics, the system is Markovian (but not random!)

Example: **speech recognition**. Context can be important for identifying words. Context can be modeled as a probability distribution for the next word given the most recent k words. This can be written as a Markov chain whose state is a vector of k consecutive words.

Example: **epidemics**. Suppose each infected individual has some chance of contacting each susceptible individual in each time interval, before becoming removed (recovered or hospitalized). Then, the number of infected and susceptible individuals may be modeled as a Markov chain.

- Define $P_{ij} = \mathbb{P}[X_{n+1}=j \mid X_n=i]$.

Let $P = [P_{ij}]$ denote the (possibly infinite) **transition matrix** of the **one-step transition probabilities**.

- Write $P_{ij}^2 = \sum_{k=0}^{\infty} P_{ik} P_{kj}$, corresponding to standard matrix multiplication. Then

$$\begin{aligned}
 P_{ij}^2 &= \sum_k \mathbb{P}[X_{n+1}=k \mid X_n=i] \mathbb{P}[X_{n+2}=j \mid X_{n+1}=k] \\
 &= \sum_k \mathbb{P}[X_{n+2}=j, X_{n+1}=k \mid X_n=i] \\
 &\quad \text{(via the Markov property. Why?)} \\
 &= \mathbb{P}\left[\bigcup_k \{X_{n+2}=j, X_{n+1}=k\} \mid X_n=i\right] \\
 &= \mathbb{P}[X_{n+2}=j \mid X_n=i]
 \end{aligned}$$

- Generalizing this calculation:

The matrix power P_{ij}^n gives the n -step transition probabilities.

- The matrix multiplication identity

$$P^{n+m} = P^n P^m$$

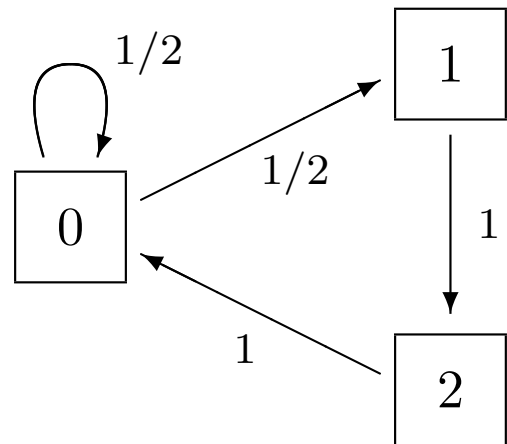
corresponds to the **Chapman-Kolmogorov equation**

$$P_{ij}^{n+m} = \sum_{k=0}^{\infty} P_{ik}^n P_{kj}^m.$$

- Let $\nu^{(n)}$ be the (possibly infinite) row vector of probabilities at time n , so $\nu_i^{(n)} = \mathbb{P}[X_n = i]$. Then $\nu^{(n)} = \nu^{(0)} P^n$, using standard multiplication of a vector and a matrix. Why?

Example. Set $X_0 = 0$,
and let X_n evolves as a
Markov chain with transi-
tion matrix

$$P = \begin{pmatrix} 1/2 & 1/2 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}.$$



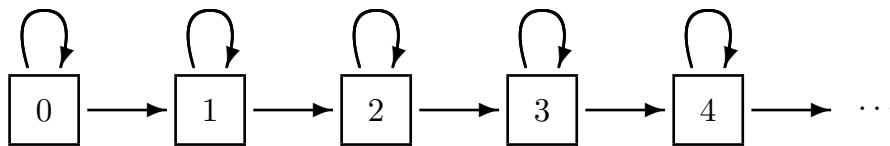
Find $\nu_0^{(n)} = \mathbb{P}[X_n=0]$ by

(i) using a probabilistic argument

(ii) using linear algebra.

Classification of States

- State j is **accessible** from i if $P_{ij}^k > 0$ for some $k \geq 0$.
- The transition matrix can be represented as a **directed graph** with arrows corresponding to positive one-step transition probabilities j is accessible from i if there is a path from i to j .
For example,



Here, 4 is accessible from 0, but not vice versa.

- i and j **communicate** if they are accessible from each other. This is written $i \leftrightarrow j$, and is an **equivalence relation**, meaning that
 - (i) $i \leftrightarrow i$ [reflexivity]
 - (ii) If $i \leftrightarrow j$ then $j \leftrightarrow i$ [symmetry]
 - (iii) If $i \leftrightarrow j$ and $j \leftrightarrow k$ then $i \leftrightarrow k$ [transitivity]

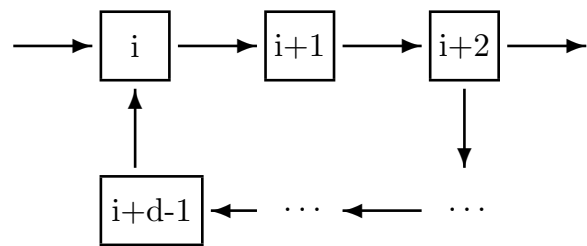
- An equivalence relation divides a set (here, the state space) into disjoint classes of equivalent states (here, called **communication classes**).
- A Markov chain is **irreducible** if all the states communicate with each other, i.e., if there is only one communication class.
- The communication class containing i is **absorbing** if $P_{jk} = 0$ whenever $i \leftrightarrow j$ but $i \nleftrightarrow k$ (i.e., when i communicates with j but not with k). An absorbing class can never be left. A partial converse is ...

Example: Show that a communication class, once left, can never be re-entered.

- State i has **period** d if $P_{ii}^n = 0$ when n is not a multiple of d and if d is the greatest integer with this property. If $d = 1$ then i is **aperiodic**.

Example: Show that all states in the same communication class have the same period.

Note: This is “obvious” by considering a generic directed graph for a periodic state:



- State i is **recurrent** if $\mathbb{P}[\text{re-enter } i \mid X_0=i] = 1$, where $\{\text{re-enter } i\}$ is the event $\bigcup_{n=1}^{\infty} \{X_n = i, X_k \neq i \text{ for } k = 1, \dots, n-1\}$. If i is not recurrent, it is **transient**.
- Let $S_0 = 0$ and S_1, S_2, \dots be times of successive returns to i , with $N_i(t) = \max \{n : S_n \leq t\}$ being the corresponding counting process.
- If i is recurrent, then $N_i(t)$ is a renewal process, since the Markov property gives independence of interarrival times $X_n^A = S_n - S_{n-1}$. Letting $\mu_{ii} = E[X_1^A]$, the **expected return time** for i , we then have the following from renewal theory:
 - ◊ $\mathbb{P}[\lim_{t \rightarrow \infty} N_i(t)/t = 1/\mu_{ii} \mid X_0=i] = 1$
 - ◊ If $i \leftrightarrow j$, $\lim_{n \rightarrow \infty} \sum_{k=1}^n P_{ij}^k/n = 1/\mu_{jj}$
 - ◊ If i is aperiodic, $\lim_{n \rightarrow \infty} P_{ij}^n = 1/\mu_{jj}$ for $j \leftrightarrow i$
 - ◊ If i has period d , $\lim_{n \rightarrow \infty} P_{ii}^{nd} = d/\mu_{ii}$

- If i is transient, then $N_i(t)$ is a **defective renewal process**. This is a generalization of renewal processes where X_1^A, X_2^A, \dots are still iid, but we allow $\mathbb{P}[X_1^A = \infty] > 0$.

Proposition: i is recurrent if and only if

$$\sum_{n=1}^{\infty} P_{ii}^n = \infty.$$

Example: Show that if i is recurrent and $i \leftrightarrow j$ then j is recurrent.

Example: If i is recurrent and $i \leftrightarrow j$, show that $\mathbb{P}[\text{never enter state } j \mid X_0 = i] = 0$.

- If i is transient, then $\mu_{ii} = \infty$. If i is recurrent and $\mu_{ii} < \infty$ then i is said to be **positive recurrent**. Otherwise, if $\mu_{ii} = \infty$, i is **null recurrent**.

Proposition: If $i \leftrightarrow j$ and i is recurrent, then either i and j are both positive recurrent, or both null recurrent (i.e., positive/null recurrence is a property of communication classes).

Random Walks

- The **simple random walk** is a Markov chain on the integers, $\mathbb{Z} = \{\dots, -1, 0, 1, 2, \dots\}$ with $X_0 = 0$ and $\mathbb{P}[X_{n+1} = X_n + 1] = p$, $\mathbb{P}[X_{n+1} = X_n - 1] = 1 - p$.

Example: If X_n counts the number of successes minus the number of failures for a new medical procedure, X_n could be modeled as a random walk, with p the success rate of the procedure. When should the trial be stopped?

- If $p = 1/2$, the random walk is **symmetric**.
- The symmetric random in d dimensions is a vector valued Markov chain, with state space \mathbb{Z}^d , $X_0^{(d)} = (0, \dots, 0)$. Two possible definitions are
 - (i) Let $X_{n+1}^{(d)} - X_n^{(d)}$ take each of the 2^d possibilities $(\pm 1, \pm 1, \dots, \pm 1)$ with equal probability.
 - (ii) Let $X_{n+1}^{(d)} - X_n^{(d)}$ take one of the $2d$ values $(\pm 1, 0, \dots, 0), (0, \pm 1, 0, \dots, 0), \dots$ with equal probability. This is harder to analyze.

Example: A biological signaling molecule becomes separated from its receptor. It starts diffusing, due to thermal noise. Suppose the diffusion is well modeled by a random walk. Will the molecule return to the receptor? If the molecule is constrained to a one-dimensional line? A two-dimensional surface? Three-dimensional space?

Proposition: The symmetric random walk is null recurrent when $d = 1$ and $d = 2$, but transient for $d \geq 3$.

Proof: The method is to employ Stirling's formula, $n! \sim n^{n+1/2} e^{-n} \sqrt{2\pi}$ where $a_n \sim b_n$ means $\lim_{n \rightarrow \infty} (a_n/b_n) = 1$, to approximate $\mathbb{P}[X_n^{(d)} = X_0^{(d)}]$.

Note: This is in HW 5. You are expected to solve the simpler case (i), though you can solve (ii) if you want a bigger challenge.

Stationary Distributions

- $\pi = \{\pi_i, i = 0, 1, \dots\}$ is a **stationary distribution** for $P = [P_{ij}]$ if $\pi_j = \sum_{i=0}^{\infty} \pi_i P_{ij}$ with $\pi_i \geq 0$ and $\sum_{i=0}^{\infty} \pi_i = 1$.
- In matrix notation, $\pi_j = \sum_{i=0}^{\infty} \pi_i P_{ij}$ is $\pi = \pi P$ where π is a row vector.

Theorem: An irreducible, aperiodic, positive recurrent Markov chain has a unique stationary distribution, which is also the **limiting distribution**

$$\pi_j = \lim_{n \rightarrow \infty} P_{ij}^n.$$

- Such Markov chains are called **ergodic**.

Proof

Proof continued

- Irreducible chains which are transient or null recurrent have no stationary distribution. Why?
- Chains which are periodic or which have multiple communicating classes may have $\lim_{n \rightarrow \infty} P_{ij}^n$ not existing, or depending on i .
- A chain started in a stationary distribution will remain in that distribution, i.e., will result in a **stationary** process.
- If we can find any probability distribution solving the stationarity equations $\pi = \pi P$ and we check that the chain is irreducible and aperiodic, then we know that
 - (i) The chain is positive recurrent.
 - (ii) π is the unique stationary distribution.
 - (iii) π is the limiting distribution.

Example: Monte Carlo Markov Chain

- Suppose we wish to evaluate $\mathbb{E}[h(X)]$ where X has distribution π (i.e., $\mathbb{P}[X=i] = \pi_i$). The **Monte Carlo** approach is to generate $X_1, X_2, \dots, X_n \sim \pi$ and estimate
$$\mathbb{E}[h(X)] \approx \frac{1}{n} \sum_{i=1}^n h(X_i)$$
- If it is hard to generate an iid sample from π , we may look to generate a sequence from a Markov chain with limiting distribution π .
- This idea, called **Monte Carlo Markov Chain (MCMC)**, was introduced by Metropolis and Hastings (1953). It has become a fundamental computational method for the physical and biological sciences. It is also commonly used for Bayesian statistical inference.

Metropolis-Hastings Algorithm

- (i) Choose a transition matrix $Q = [q_{ij}]$
- (ii) Set $X_0 = 0$
- (iii) for $n = 1, 2, \dots$
 - ◇ generate Y_n with $\mathbb{P}[Y_n = j \mid X_{n-1} = i] = q_{ij}$.
 - ◇ If $X_{n-1} = i$ and $Y_n = j$, set

$$X_n = \begin{cases} j & \text{with probability } \min(1, \pi_j q_{ji} / \pi_i q_{ij}) \\ i & \text{otherwise} \end{cases}$$

- Here, Y_n is called the **proposal** and we say the proposal is **accepted** with probability $\min(1, \pi_j q_{ji} / \pi_i q_{ij})$. If the proposal is not accepted, the chain stays in its previous state.

Proposition: Set

$$P_{ij} = \begin{cases} q_{ij} \min(1, \pi_j q_{ji} / \pi_i q_{ij}) & j \neq i \\ q_{ii} + \sum_{k \neq i} q_{ik} \{1 - \min(1, \pi_k q_{ki} / \pi_i q_{ik})\} & j = i \end{cases}$$

Then π is a stationary distribution of the Metropolis-Hastings chain $\{X_n\}$. If P_{ij} is irreducible and aperiodic, then π is also the limiting distribution.

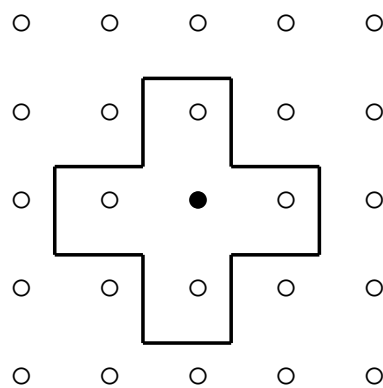
Proof.

Example: (spatial models on a lattice)

Let $\{Y_{ij}, 1 \leq i \leq m, 1 \leq j \leq n\}$ be a spatial stochastic process. Let $\mathcal{N}(i, j)$

define a neighborhood, e.g. $\mathcal{N}(i, j) =$

$\{(p, q) : |p - i| + |q - j| = 1\}$



- We may model the conditional distribution of Y_{ij} given the neighbors. E.g., if your neighbors vote Republican (R), you are more likely to do so. Say,

$$\begin{aligned} \mathbb{P}[Y_{ij} = R \mid \{Y_{pq}, (p, q) \neq (i, j)\}] \\ = \frac{1}{2} + \alpha \left[\left(\sum_{(p, q) \in \mathcal{N}(i, j)} I_{\{Y_{pq} = R\}} \right) - 2 \right]. \end{aligned}$$

- The full distribution π of Y is, in principle, specified by the conditional distributions. In practice, one simulates from π using MCMC, where the proposal distribution is to pick a random (i, j) and swap it from R to D or vice versa.

Example: Sampling conditional distributions.

- If X and Θ have joint density $f_{X\Theta}(x, \theta)$ and we observe $X = x$, then one wants to sample from $f_{\Theta|X}(\theta | x) = \frac{f_{X\Theta}(x, \theta)}{f_X(x)} \propto f_{\Theta}(\theta) f_{X|\Theta}(x | \theta)$
- For **Bayesian inference**, $f_{\Theta}(\theta)$ is the **prior** distribution, and $f_{\Theta|X}(\theta | x)$ is the **posterior**. The model determines $f_{\Theta}(\theta)$ and $f_{X|\Theta}(x | \theta)$. The normalizing constant,
$$f_X(x) = \int f_{X\Theta}(x, \theta) d\theta,$$
is often unknown.
- Using MCMC to sample from the posterior allows numerical evaluation of the
posterior mean $\mathbb{E}[\Theta | X=x]$,
posterior variance $\text{Var}(\Theta | X=x)$,
or a $1 - \alpha$ **credible region** defined to be a set A such that $\mathbb{P}[\Theta \in A | X=x] = 1 - \alpha$.

Galton-Watson Branching Process

- Let X_n be the size of a population at time n . Suppose each individual has an iid offspring distribution, so $X_{n+1} = \sum_{k=1}^{X_n} Z_{n+1}^{(k)}$ where $Z_{n+1}^{(k)} \sim Z$.
- We can think of $Z_{n+1}^{(k)} = 0$ being the death of the parent, or think of X_n as the size of the n^{th} generation.
- Suppose $X_0 = 1$. Notice that $X_n = 0$ is an absorbing state, termed **extinction**. Supposing $\mathbb{P}[Z = 0] > 0$ and $\mathbb{P}[Z > 1] > 0$, we can show that $1, 2, 3, \dots$ are transient states. Why?
- Thus, the branching process either becomes extinct or tends to infinity.

- Set $\phi(s) = \mathbb{E}[s^Z]$, the **probability generating function** for Z . Set $\phi_n(s) = \mathbb{E}[s^{X_n}]$. Show that $\phi_n(s) = \phi^{(n)}(s) = \phi(\phi(\dots\phi(s)\dots))$, meaning ϕ applied n times.

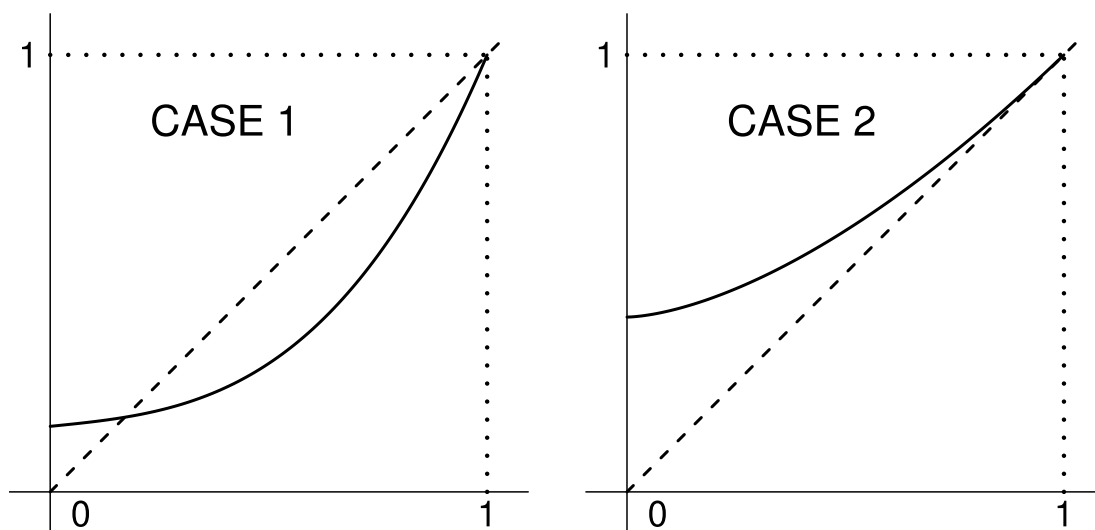
- If we can find a solution to $\phi(s) = s$, we will have $\phi_n(s) = s$ for all n . This suggests plotting $\phi(s)$ vs s , noting that

(i) $\phi(1) = 1$. Why?

(ii) $\phi(0) = \mathbb{P}[Z=0]$. Why?

(iii) $\phi(s)$ is **increasing**, i.e., $\frac{d\phi}{ds} > 0$. Why?

(iv) $\phi(s)$ is **convex**, i.e., $\frac{d^2\phi}{ds^2} > 0$. Why?



- Now, notice that, for $0 < s < 1$,

$$\mathbb{P}[\text{extinction}] = \lim_{n \rightarrow \infty} \mathbb{P}[X_n = 0] = \lim_{n \rightarrow \infty} \phi_n(s).$$
- Argue that, in CASE 1, $\lim_{n \rightarrow \infty} \phi_n(s)$ is the unique fixed point $\phi(s) = s$ for $0 < s < 1$. In CASE 2, $\lim_{n \rightarrow \infty} \phi_n(s) = 1$.

- Conclude that in CASE 1 (with $\frac{d\phi}{ds} \big|_{s=1} > 1$, i.e. $\mathbb{E}[Z] > 1$) there is some possibility of infinite growth. In CASE 2 (with $\frac{d\phi}{ds} \big|_{s=1} \leq 1$, i.e. $\mathbb{E}[Z] \leq 1$) extinction is assured.
- Example: take

$$Z = \begin{cases} 0 & w.p. \quad 1/4 \\ 1 & w.p. \quad 1/4 \\ 2 & w.p. \quad 1/2 \end{cases} .$$

Find the chance of extinction.

- Now suppose the founding population has size k (i.e., $X_0 = k$). Find the chance of extinction.

Time Reversal

- Thinking backwards in time can be a powerful strategy. For any Markov chain

$\{X_k, k = 0, 1, \dots, n\}$, we can set $Y_k = X_{n-k}$.

Then Y_k is a Markov chain. Suppose X_k has transition matrix P_{ij} , then Y_k has

inhomogeneous transition matrix $P_{ij}^{*[k]}$, where

$$\begin{aligned} P_{ij}^{*[k]} &= \mathbb{P}[Y_{k+1}=j \mid Y_k=i] \\ &= \mathbb{P}[X_{n-k-1}=j \mid X_{n-k}=i] \\ &= \frac{\mathbb{P}[X_{n-k}=i \mid X_{n-k-1}=j] \mathbb{P}[X_{n-k-1}=j]}{\mathbb{P}[X_{n-k}=i]} \\ &= P_{ji} \mathbb{P}[X_{n-k-1}=j] / \mathbb{P}[X_{n-k}=i]. \end{aligned}$$

- If $\{X_k\}$ is **stationary**, with stationary distribution π , then $\{Y_k\}$ is homogeneous, with

$$\boxed{P_{ij}^* = P_{ji} \pi_j / \pi_i}$$

- Surprisingly many important chains have the **time-reversibility** property $P_{ij}^* = P_{ij}$, for which the chain looks the same forwards as backwards.

Theorem. (detailed balance equations)

If π is a probability distribution with

$\pi_i P_{ij} = \pi_j P_{ji}$, then π is a stationary distribution for P and the chain started at π is time-reversible.

Proof

- The detailed balance equations are simpler than the general equations for finding π . Try to solve them when looking for π , in case you get lucky!
- Intuition: $\pi_i P_{ij}$ is the “rate of going directly from i to j .” A chain is reversible if this equals “rate of going directly from j to i .”
- Periodic chains (π does not give limiting probabilities) and reducible chains (π is not unique) are both OK here.

- An equivalent condition for reversibility of ergodic Markov chains is “every loop of states starting and ending in i has the same probability as the reverse loop,” i.e., for all i_1, \dots, i_k ,

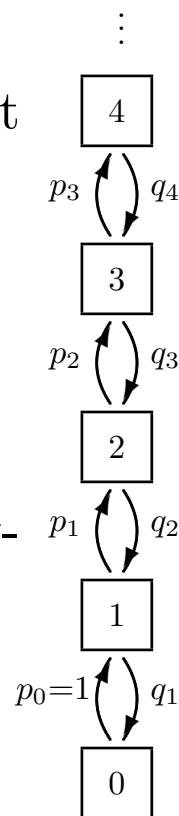
$$P_{ii_1} P_{i_1, i_2} \dots P_{i_{k-1} i_k} P_{i_k i} = P_{ii_k} P_{i_k i_{k-1}} \dots P_{i_2 i_1} P_{i_1 i}$$

Proof

Example: Birth-Death Process.

Let $\mathbb{P}[X_n = X_n + 1 \mid X_n = i] = p_i$ and $\mathbb{P}[X_n = X_n - 1 \mid X_n = i] = q_i = 1 - p_i$.

- If $\{X_n\}$ is positive recurrent, it must be reversible. Heuristic reason:



- Find the stationary distribution giving conditions for its existence.

- Note that this chain is periodic ($d = 2$). There is still a unique stationary distribution which solves the detailed balance equations.

Example: Metropolis Algorithm. The Metropolis-Hastings algorithm with symmetric proposals ($q_{ij} = q_{ji}$) is the **Metropolis algorithm**. Here,

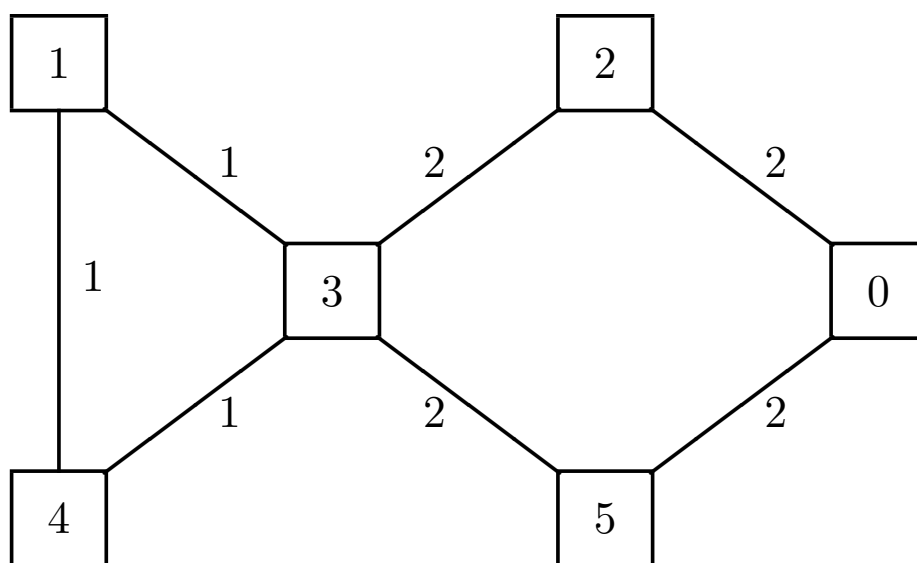
$$P_{ij} = \begin{cases} q_{ij} \min(1, \pi_j/\pi_i) & j \neq i \\ q_{ii} + \sum_{k \neq i} q_{ik} \{1 - \min(1, \pi_k/\pi_i)\} & j = i \end{cases}$$

- Show that P_{ij} is reversible, with stationary distribution π .

Solution

Random Walk on a Graph

- Consider **undirected, connected** graph with a positive **weight** w_{ij} on each **edge** ij . Set $w_{ij} = 0$ if i & j are not connected by an edge.
- Set $P_{ij} = \frac{w_{ij}}{\sum_k w_{ik}}$
- The Markov chain $\{X_n\}$ with transition matrix P is called a random walk on a graph. Think of a driver who is lost: each vertex is an intersection, the weight is the width (in lanes) of a road leaving an intersection, the driver picks a random exit when he/she arrives at an intersection but has a preference for bigger streets.



- Show that the random walk on a graph is reversible, and has stationary distribution

$$\pi_i = \sum_j w_{ij} / \sum_{jk} w_{jk}$$

Note: the double sum counts each weight twice.

- Hence, find the limiting probability of being at vertex 3 on the graph shown above.

Ergodicity

- A stochastic process $\{X_n\}$ is **ergodic** if limiting time averages equal limiting probabilities, i.e.,

$$\lim_{n \rightarrow \infty} \frac{\text{time in state } i \text{ up to time } n}{n} = \lim_{n \rightarrow \infty} \mathbb{P}[X_n = i].$$

- Show that an irreducible, aperiodic, positive recurrent Markov chain is ergodic (i.e., this general idea of ergodicity matches our definition for Markov chains).

Semi-Markov Processes

- A **Semi-Markov process** is a discrete state, continuous time process $\{Z(t), t \geq 0\}$ for which the sequence of states visited is a Markov chain $\{X_n, n = 0, 1, \dots\}$ and, conditional on $\{X_n\}$, the times between transitions are independent.

Specifically, define transition times S_0, S_1, \dots by $S_0 = 0$ and $S_n - S_{n-1} \sim F_{ij}$ conditional on $X_{n-1} = i$ and $X_n = j$. Then, $Z(t) = X_{N(t)}$ where $N(t) = \sup \{n : S_n \leq t\}$.

- $\{X_n\}$ is the **embedded Markov chain**.
- The special case where $F_{ij} \sim \text{Exponential}(\nu_i)$ is called a **continuous time Markov chain**
- The special case when

$$F_{ij}(t) = \begin{cases} 0, & t < 1 \\ 1, & t \geq 1 \end{cases}$$

results in $Z(n) = X_n$, so we retrieve the discrete time Markov chain.

Example: A taxi serves the airport, the hotel district and the theater district. Let $Z(t) = 0, 1, 2$ if the taxi's current destination is each of these locations respectively. The time to travel from i to j has distribution F_{ij} . Upon arrival at i , the taxi immediately picks up a new customer whose destination has distribution given by P_{ij} . Then, $Z(t)$ is a semi-Markov process.

- To study the limiting behavior of $Z(t)$ we make some definitions...
- Say $\{Z(t)\}$ is **irreducible** if $\{X_n\}$ is irreducible
- Say $\{Z(t)\}$ is **non-lattice** if $\{N(t)\}$ is non-lattice
- Set H_i to be the c.d.f. of the time in state i before a transition, so $H_i(t) = \sum_j P_{ij} F_{ij}(t)$ and the expected time of a visit to i is
$$\mu_i = \int_0^\infty x dH_i(x) = \sum_j P_{ij} \int_0^\infty x dF_{ij}(x).$$
- Let T_{ii} be the time between successive visits to i and define $\mu_{ii} = \mathbb{E}[T_{ii}]$.

Proposition: If $\{Z(t)\}$ is an irreducible, non-lattice semi-Markov process with $\mu_{ii} < \infty$, then

$$\begin{aligned} \lim_{t \rightarrow \infty} \mathbb{P}[Z(t)=i \mid Z(0)=j] &= \frac{\mu_i}{\mu_{ii}} \\ &= \lim_{t \rightarrow \infty} \frac{\text{time in } i \text{ before } t}{t} \quad \text{w.p. 1} \end{aligned}$$

Proof: identify a relevant alternating renewal process.

- By counting up time spent in i differently, we get another identity

$$\lim_{t \rightarrow \infty} \frac{\text{time in } i \text{ during } [0, t]}{t} = \frac{\pi_i \mu_i}{\sum_j \pi_j \mu_j}$$

supposing that $\{X_n\}$ is ergodic (irreducible, aperiodic, positive recurrent) with stationary distribution π .

Proof

- Calculations with semi-Markov models typically involve identifying a suitable renewal, alternating renewal, regenerative or reward process.

Example Let $Y(t) = S_{N(t)+1} - t$ be the residual life process for an ergodic, non-lattice semi-Markov model. Find an expression for $\lim_{t \rightarrow \infty} \mathbb{P}[Y(t) > x]$.

Hint: Consider an alternating renewal process which switches “on” when $Z(t)$ enters i , and switches “off” immediately if the next transition is not j or switches “off” once the time until the transition to j is less than x .

Proof (continued)