

Theory Question

a)
$$p(f_x | y, X) = \frac{p(y | f_x, X) p(f_x | X)}{p(y | X)}, \text{ using Bayes' Rule}$$

$$p(f | y) = \frac{p(y | f) p(f)}{p(y)} \quad \rightarrow \text{Without loss of generality for continuous } X$$

$$\begin{aligned} \log(p(f_x | y, X)) &= \log p(y | f_x) + \log p(f_x) + \log p(y) \\ &= \log \prod_{i=1}^N \sigma(y_i f(x_i)) + \log p(f_x) + \text{constant term} \end{aligned}$$

$$p(f_x) = W(f_x; \underbrace{m(X)}_{m_x}, \underbrace{k(X, X)}_{k_{xx}})$$

$$\log(p(f_x | y, X)) \cong \left(-\sum_{i=1}^N \log(1 + \exp(-y_i f(x_i))) \right) - \frac{1}{2} (f_x - m_x)^T k_{xx}^{-1} (f_x - m_x)$$

$$b) \nabla_{f_x} \log(p(f_x | y, X)) = \sum_{i=1}^N \nabla_{f_x} \log(\sigma(y_i, f(x_i))) - K_{xx}^{-1} (f_x - m_x)$$

$$= \sum_{i=1}^N \underbrace{-\nabla_{f_x} \log(1 + \exp(-y_i f_{x_i}))}_{\text{where}} - K_{xx}^{-1} (f_x - m_x)$$

$$\text{where } -\frac{\partial(\log(1 + \exp(-y_i f_{x_i})))}{\partial f_{x_i}} = f_{ij} \left(\frac{y_i + 1}{2} - \sigma(f_{x_i}) \right)$$

$$\text{where } y_i \in \{-1, 1\}$$

$$\Rightarrow \frac{y_i + 1}{2} \in \{0, 1\}$$

$$\text{Note that } -\frac{\partial}{\partial f_{x_i}} \log(1 + \exp(-y_i f_{x_i})) = \frac{y_i \exp(-y_i f_{x_i})}{1 + \exp(-y_i f_{x_i})}$$

$$\textcircled{1} y_i = -1 \Rightarrow -\frac{\exp(f_{x_i})}{1 + \exp(f_{x_i})} = \frac{-1}{1 + \exp(-f_{x_i})} = -\sigma(f_{x_i})$$

$$\textcircled{2} y_i = 1 \Rightarrow \frac{\exp(-f_{x_i})}{1 + \exp(-f_{x_i})} = 1 - \frac{1}{1 + \exp(-f_{x_i})} = 1 - \sigma(f_{x_i})$$

①

$$\textcircled{2} \Rightarrow \frac{y_i + 1}{2} - \sigma(f_{x_i})$$

$$\nabla_{f_x} \log(p(f_x | y)) = \begin{bmatrix} \frac{y_1 + 1}{2} - \sigma(f(x_1)) \\ \frac{y_2 + 1}{2} - \sigma(f(x_2)) \\ \vdots \\ \frac{y_n + 1}{2} - \sigma(f(x_n)) \end{bmatrix} - K_{xx}^{-1} (f_x - m_x)$$

c) We know that at the mode, $f_x = \hat{f}_x$:

$$\nabla_{f_x} \log p(f_x | y, x) \Big|_{f_x = \hat{f}_x} = 0$$

Using part b $\rightarrow \nabla_{f_x} \log(p(y|f_x)) = k_{xx}^{-1} (f_x - m_x) = 0$, at the mode

$$\star \nabla \log(p(y|\hat{f}_x)) = k_{xx}^{-1} (\hat{f}_x - m_x), \text{ at the mode}$$

Way 1

$$k_{xx} \nabla \log(p(y|f_x)) \underset{=1, \text{ spd}}{k_{xx} k_{xx}^{-1}} (f_x - m_x), \text{ at the mode}$$

$$\Rightarrow m_x + k_{xx} \nabla \log(p(y|f_x)) = f_x, \text{ at the mode}$$

From the last result, it can be seen that

$$E_q[f(\cdot)] = m_{\cdot} + k_{\cdot x} \nabla \log(p(y|\hat{f}_x))$$

Way 2 More rigorously, as depicted also in lecture 14, slide 17:

where $q(f_x) = \mathcal{N}(f_x; \hat{f}_x, \Sigma)$

$$\begin{aligned} q(f_x | y) &= \int p(f_x | \tilde{f}_x) q(\tilde{f}_x) d\tilde{f}_x \\ &= \mathcal{N}(f_x; \underbrace{m_x + k_{xx} k_{xx}^{-1} (\hat{f}_x - m_x)}_{\hat{f}_x}, \Sigma_{\text{posterior}}) \end{aligned}$$

Thus, $E_q[f(\cdot)] = m(\cdot) + k_{\cdot x} k_{xx}^{-1} (\hat{f}_x - m_x)$ as expected value is precisely the mean of gaussian.

Using \star to replace $k_{xx}^{-1} (\hat{f}_x - m_x)$ with $\nabla \log(p(y|\hat{f}_x))$, the MAP estimate can be written as:

$$E_q[f(\cdot)] = m(\cdot) + k_{\cdot x} \nabla \log(p(y|\hat{f}_x)) \quad \text{Q.E.D.}$$

d) Utilizing the results of part b, the explicit form can be written as:

$$\begin{aligned}\nabla \log(p(y) \hat{f}_x) &= \sum_{i=1}^N \nabla_{\hat{f}_x} \log(\sigma(y_i \hat{f}(x_i))) \\ &= \sum_{i=1}^N \nabla_{\hat{f}_x} [-\log(1 + \exp(-y_i \hat{f}(x_i)))]\end{aligned}$$

with $\frac{\partial}{\partial \hat{f}_{x_i}} (-\log(1 + \exp(-y_i \hat{f}(x_i)))) = \frac{y_i + 1}{2} - \sigma(\hat{f}(x_i))$

and $\frac{\partial \log \sigma(y_i \hat{f}(x_i))}{\partial \hat{f}_{x_j}} = \delta_{ij} \left(\frac{y_i + 1}{2} - \sigma(\hat{f}(x_i)) \right)$

Observe that when $|\hat{f}(x_i)| \gg 1$, there are two cases: either the $\hat{f}(x_i)$ is too small or too large:

① when $\hat{f}(x_i) \gg 1$, $\sigma(\hat{f}(x_i)) = \frac{1}{1 + \exp(-\hat{f}(x_i))} \approx 1$ as $\lim_{x \rightarrow \infty} \exp(-x) = 0$

and the gradient term becomes, $\frac{y_i + 1}{2} - \sigma(\hat{f}(x_i)) = \frac{1 + 1}{2} - 1 = 0$

② when $\hat{f}(x_i) \ll 1$, $\sigma(\hat{f}(x_i)) = \frac{1}{1 + \exp(-\hat{f}(x_i))} \approx 0$ as $\lim_{x \rightarrow -\infty} \exp(-x) = \infty$

and the gradient term becomes, $\frac{y_i + 1}{2} - \sigma(\hat{f}(x_i)) = \frac{-1 + 1}{2} - 0 = 0$

therefore, training points far from the decision boundary do almost not contribute to this estimate $E_g(f(\cdot))$.

e) We consider the normalization of the suggested likelihood
 $\sum_{y_i \in \{-1, 1\}} c r(y_i; f(x_i))$ with $r(y_i; f(x_i)) = \exp[-\max(0, 1 - y_i f(x_i))]$

Separate negatives and positives

$$\sum_{y_i = -1} c \exp[-\max(0, 1 + f(x_i))] + \sum_{y_i = 1} c \exp[-\max(0, 1 - f(x_i))]$$

without loss of generality, consider for individual training points in the positive and negative classes. Then for two such points, we have

$$\underbrace{c \exp[-\max(0, 1 + f(x_i))]}_{y_i = -1 \text{ case}} + \underbrace{c \exp[-\max(0, 1 - f(x_i))]}_{y_i = 1 \text{ case}}$$

Without loss of generality, consider the case $f(x_i) > 1$, then:

$$c \exp[-(1 + f(x_i))] + c \exp[0] = c [1 + e^{-(1 + f(x_i))}]$$

The normalization constant, c should include the term:

$$c = c_1 \frac{1}{1 + e^{-(1 + f(x_i))}} \quad \text{yet this is not independent of } f(x_i)$$

Thus $r(y_i, f(x_i))$ is not a family of probability distributions and can't be a likelihood.