Probabilistic Machine Learning

EBERHARD KARLS UNIVERSITÄT TÜBINGEN



Exercise 8

Summer Term 2023

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Theory Question

p(
$$f_{x}|g_{x}$$
) = $p(g|f_{x}|x)$ p($f_{x}|x$), using Bayes' Rule

$$p(g|g) = p(g|f_{y}) p(f_{y}) \qquad \text{Without loss of generality for continuous } x$$

$$\log(p(f_{x}|g_{x}x)) = \log p(g|f_{x}) + \log p(f_{x}) + \log p(g)$$

$$= \log \pi \sigma(g_{x}f_{x}) + \log p(f_{x}) + \cos p(g_{x})$$

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 $\log(\rho(\xi x | y_i x)) \cong \left(-\frac{\Sigma}{1} \log(1 + \exp(-y_i f(x_i))\right) - \frac{1}{2} (f_x - m_x) k_{xx} (f_x - m_x)$

b)
$$\nabla \log(p(f_{x}|y_{i}|x)) = \sum_{i=1}^{N} \nabla_{i} \log(\sigma(y_{i}|f(x_{i}))) - K_{xx}(f_{x}-m_{x})$$

$$= \sum_{i=1}^{N} -\nabla f_{x} \log(1+\exp(-y_{i}|f_{x_{i}})) - k_{xx}(f_{x}-m_{x})$$
where $+\frac{\partial(\log(1+\exp(-y_{i}|f_{x_{i}})))}{\partial f_{x_{i}}} = \int_{i}^{i} (\frac{y_{i}+1}{2} - O(f_{x_{i}}))$
where $y_{i} \in \{-1,1\}$

$$\Rightarrow \underbrace{y_{i}+1}_{2} \in \{0,1\}$$

Note that
$$-\frac{2}{24x_i}\log(1+\exp(-y_i fx_i)) = \frac{y_i \exp(-y_i fx_i)}{1+\exp(-y_i fx_i)}$$

①
$$y_i = -1 \Rightarrow -\frac{\exp(\xi_{x_i})}{1 + \exp(\xi_{x_i})} = \frac{-1}{1 + \exp(\xi_{x_i})} = -\sigma(\xi_{x_i})$$

②
$$y_i = 1$$
 =) $\frac{\exp(-fx_i)}{1 + \exp(-fx_i)} = 1 - \frac{1}{1 + \exp(-fx_i)} = 1 - \sigma(fx_i)$

$$\textcircled{3} \Rightarrow \overset{\text{y:+1}}{2} - \sigma(2x_i)$$

$$\frac{\nabla \log \left(\rho(f \times |y|)\right)}{f \times g} = \left[\frac{\frac{(f+1)}{2} - \sigma(f(x_1))}{\frac{(f+1)}{2} - \sigma(f(x_2))}\right] - k_{xx} \left(f_{x-mx}\right)$$

$$\frac{g_{n+1}}{g_{n+1}} - \sigma(f(x_n))$$

c) we know that at the made, fx = fx: Vex log p(fx 1y1x)=0 Using part b -> 7/x log(p(y1fx)) = Kxx (fx-mx) = 0, at the made $\Theta \nabla \log(p(y|\hat{f}x)) = k_{xx}(\hat{f}_{x}-m_{x}), \text{ at the mode}$ $k_{xx}\log(p(y|\hat{f}x)) \quad k_{xx}k_{xx}(\hat{f}_{x}-m_{x}), \text{ at the mode}$ kxxkxx1(fx-mx), at the mode \Rightarrow $m_X + k_{XX} \nabla log(p(y|f_X)) = f_X$, at the mode From the last result, it can be seen that $E[f(0)] = m. + k.x Plog(p(y|f_x))$

More rigorously, as depicted also in Lecture 14, slide 17:

where q(fx) = N(fx; fx, 2)

q(fxly) = Sp(fx) q(fx) dfx

= M(Px; mx + kxx kxx (Pxmx), E posterior)

Thus, Eg[f(.)] = m(.) + k.x kxx (fx-mx) as expected value is precisely the mean of gaussian.

Using @ to replace $k_{xx}(\hat{f}_x - m_x)$ with $Vlog(p(y|\hat{f}_x))$, the MAP estimate can be written as:

E[f(-)] = m(0) + k, x \(\text{log} \(\rho \) \((g \overline{\phi} \) \(\text{Q.E.D.} \)

d) utilizing the resulte of part b, the explicit form can be written as:

$$\nabla \log (p(y) \hat{f_x}) = \sum_{i=1}^{N} \nabla \hat{f_x} \log (\sigma(y_i \hat{f}(x_i)))$$

$$= \sum_{i=1}^{N} \nabla \hat{f_x} \left[-\log (1 + \exp(-y_i \hat{f}(x_i))) \right]$$

with $\frac{2}{2\hat{f}x_i}(-\log(1+\exp(-y_i\hat{f}(x_i))) = \frac{y_{i+1}}{2} - \sigma(\hat{f}(x_i))$

and
$$\frac{\partial \log \sigma(y; \hat{f}(x_i))}{\partial \hat{f}(x_i)} = \int_{ij} (\frac{y_i+1}{2} - \sigma(\hat{f}(x_i)))$$

observe that when $|\hat{f}(x_i)| \gg 1$, there are two cases: either the $\hat{f}(x_i)$ is too small or too large:

Therefore
$$\hat{f}(x_i) \gg 1$$
, $\sigma(\hat{f}(x_i)) = \frac{1}{1 + \exp(-\hat{f}(x_i))} \approx 1$ as $\lim_{x \to \infty} \exp(-x) = 0$

and the gradient term becomes, $\frac{9i+1}{2} - \sigma(\hat{p}(x_i)) = \frac{1}{2} - 1 = 0$

② when $\hat{f}(x_i) \ll 1$, $\sigma(\hat{f}(x_i)) = \frac{1}{1 + \exp(-\hat{f}(x_i))} \approx 0$ as $\lim_{x \to -\infty} \exp(-x) = \infty$

and the gradient term becomes, $y_{1}+1 - \sigma(f(x_{i})) = \frac{-1+1}{2} - 0 = 0$

therefore, training points far from the decision boundary do almost not contribute to this estimate Eq(f(0)),

We consider the normalization of the suggested likelihood $\sum_{y_i \in \{-1,1\}} C r(y_i; f(x_i))$ with $r(y_i; f(x_i)) = \exp[-\max(0,1-y_if(x_i))]$

Separate negatives and positives

without loss of generality, consider for individual training points in the positive and negative classes. Then for two such points, we have

Without loss of generality, consider the case f(x;)>1, then:

The normalization constant, c should include the term:

Thus $r(y_i, f(x_i))$ is not a family of probability distributions and can't be a likelihood.

Exercise 08

June 26, 2023

1 Probabilistic Machine Learning

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1.1 Exercise Sheet No. 8 — GP Classification on Binary MNIST

Submission by:

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```
[]: # Numpy, JAX
import jax
from jax import jit
import jax.numpy as jnp
import numpy as np
jax.config.update("jax_enable_x64", True) # use double-precision numbers
```

```
[]: # Plotting
from matplotlib import pyplot as plt
from tueplots import bundles

%config InlineBackend.figure_formats = ["svg"]
%matplotlib inline
plt.rcParams.update(bundles.beamer_moml())
plt.rcParams.update({'figure.dpi': 200})
```

```
[]: # Import `gaussians.py` import gaussians
```

1.1.1 0. Overview

In this week's exercise, we will apply Gaussian Process (GP) classification to a subset of the MNIST dataset. Your task is to set up the optimization problem, find the posterior mode, define the GP posterior, and perform some analyses on the results.

1.1.2 1. Training and Test Data

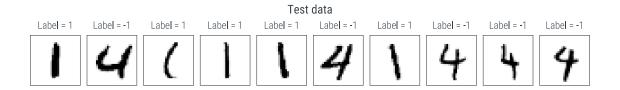
The data has already been prepared for you: X_train and X_test contain 600 training and 600 test images of the digits 1 and 4. The pixel values are normalized to numbers between -1 and 1. The labels (1 for the digit 1 and -1 for the digit 4) for the training and test images are stored in y_train and y_test.

```
[]: # Load MNIST data
     data = jnp.load("binary_MNIST.npz")
     # Extract data
     X_train, y_train = data["X_train"], data["y_train"]
     X_test, y_test = data["X_test"], data["y_test"]
[]: def print_data_info(X, y, title):
         print(f"\n{title}:")
         print("X.shape = ", X.shape)
         print(f"X in range [{X.min()}, {X.max()}]")
         print("y.shape = ", y.shape)
         for target in jnp.unique(y):
             count = (y == target).sum()
             print(f"Target yi = {target}: Found {count} times")
     print_data_info(X_train, y_train, "Training data")
     print_data_info(X_test, y_test, "Test data")
    No GPU/TPU found, falling back to CPU. (Set TF_CPP_MIN_LOG_LEVEL=0 and rerun for
    more info.)
    Training data:
    X.shape = (600, 784)
    X in range [-1.0, 1.0]
    y.shape = (600,)
    Target yi = -1: Found 300 times
    Target yi = 1: Found 300 times
    Test data:
    X.shape = (600, 784)
    X in range [-1.0, 1.0]
    y.shape = (600,)
    Target yi = -1: Found 300 times
    Target yi = 1: Found 300 times
    Let's visualize some example images from the training and test data.
```

```
[]: def show_mnist_img(ax, img, title=""):
    """Show a single MNIST image in `ax`."""
```

```
ax.imshow(img.reshape(28, 28), cmap="Greys")
    ax.set_title(title)
    # Remove ticks and labels
    ax.get_xaxis().set_visible(False)
    ax.get_yaxis().set_visible(False)
def show_n_mnist_imgs(X_data, y_data, title, n=10):
    """Show the first `n` images from `X_data` with the labels."""
    n = min(n, X_data.shape[0])
    fig, axs = plt.subplots(1, n, figsize=(n * 0.7, 1.2))
    for idx in range(n):
        title_img = f"Label = {y_data[idx]}"
        show_mnist_img(axs[idx], X_data[idx, :], title_img)
    fig.suptitle(title)
    plt.show()
show_n_mnist_imgs(X_train, y_train, "Training data")
print("")
show_n_mnist_imgs(X_test, y_test, "Test data")
```





1.1.3 2. Loss Function

The first step in GP classification is finding the mode \hat{f}_X of the posterior, i.e.

$$\begin{split} \hat{f_X} &= \operatorname{argmax}_{f_X} p(f_X|X,y) \\ &= \operatorname{argmin}_{f_X} \mathcal{L}(f_X), \end{split}$$

where $\mathcal{L}(f_X) := -[\log(p(y|f_X)) + \log(p(f_X|X))]$ denotes the loss-function. We thus need to define the log-prior $\log(p(f_X|X))$ and the log-likelihood $\log(p(y|f_X))$. In order to solve the optimization problem, we will also need access to the gradients of these functions. In the theory exercises (a) and (b), your task is to give a derivation for the quantities given below.

Log-prior: The prior p(f|X) is simply the GP prior (with mean function m and covariance function k) on the latent function evaluated at X. So, it is a Gaussian $p(f_X|X) = \mathcal{N}(f; m(X), k(X, X))$. The log-density is therefore given by the quadratic

$$\log(p(f_X|X)) = -\frac{1}{2}(f_X - m(X))^\top k(X,X)^{-1}(f_X - m(X)) - \frac{1}{2}|k(X,X)| - \frac{N}{2}\log(2\pi).$$

Its gradient with respect to f_X is given by $-k(X,X)^{-1}(f_X-m(X))$.

```
def constant_mean(x, c=0.0):
    return c * jnp.ones_like(x[:, 0])

def RQ_kernel(a, b, theta=1.0, ell=1.0, alpha=1.0):
    return theta**2 * (1 + jnp.sum((a - b) ** 2, axis=-1) / (2 * alpha *_u = ell**2) )**(-alpha)

# Define prior GP for f
mean = functools.partial(constant_mean, c=0.0)
kernel = functools.partial(RQ_kernel, theta=10, ell=17)
prior_GP = gaussians.GaussianProcess(mean, kernel)
```

Task: Complete the val and grad methods below. Sample an example input fX_example and test your grad method against the log-prior's gradient computed via autodiff.

```
value = self.prior_gaussian.log_pdf(fX)
#print('value shape:', value.shape)
return value

def grad(self, fX):
    """Return the gradient of log(p(f_X | X)) evaluated at `fX`."""
    return - self.prior_gaussian.prec_mult(fX - self.prior_gaussian.mu)
```

Custom grad shape: (600,) Autodiff grad shape: (600,) Gradients are close?: True

Log-likelihood: Next, we define the log-likelihood $\log(p(y|f_X))$ and its gradient. Let $\sigma(z) := 1/(1 + \exp(-z))$ denote the logistic function. It holds:

$$\log(p(y|f_X)) = \sum_{i=1}^N -\log(1+\exp(-y_i\cdot f(x_i))).$$

The gradient of $\log(p(y|f_X))$ with respect to f_X is given by $\nabla \log(p(y|f_X)) = t - \pi$, where t = (y+1)/2 and $\pi = \sigma(f_X)$ (applied element-wise).

Task: Complete the val and grad methods below. Again, test the gradient at fX_example against the gradient computed via autodiff.

```
[]: def logistic_func(z):
    return 1.0 / (1.0 + jnp.exp(-z))
```

```
class LogLikelihood:
    """Log-likelihood log(p(y | f_X))."""
    def __init__(self, y_signed):
        self.y_signed = y_signed # fixed

def val(self, fX):
    """Return log(p(y | f_X)) evaluated at `fX`."""
    value = jnp.sum(-jnp.log(jnp.exp(-self.y_signed * fX) + 1))
    #print('value shape:', value.shape)
    return value

def grad(self, fX):
    """Return the gradient of log(p(y | f_X)) evaluated at `fX`."""
    t = (self.y_signed + 1) / 2
    pi = logistic_func(fX)
    return t - pi
```

Gradients are close? : True

Loss function: Now, we can finally define the loss-function $\mathcal{L}(f_X) = -[\log(p(y|f_X)) + \log(p(f_X|X))].$

Task: Complete the function below. Again, test the gradient at fX_example against the gradient computed via autodiff.

```
[]: @jit # We want this to be fast
def loss_val_and_grad(fX):
    """Return the value and gradient of the loss function at `fX`."""
    val = - log_prior.val(fX) - log_likelihood.val(fX)
    grad = - log_prior.grad(fX) - log_likelihood.grad(fX)
    return (val, grad)
```

```
[]: # Test against autodiff
custom_val, custom_grad = loss_val_and_grad(fX_example)
```

Values are close? : True

1.1.4 3. Optimization with Gradient Descent

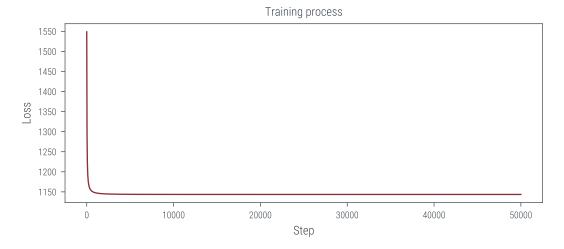
Now, that we can evaluate the loss-function and its gradient, we can implement gradient descent in order to find the minimizer $\hat{f_X}$ of \mathcal{L} (which maximizes the posterior). For this, we initialize fX at zero and iteratively perform updates $f_X \leftarrow f_X - \alpha \nabla \mathcal{L}(f)$ with some learning rate $\alpha > 0$.

Task: Complete the training loop below. For each iteration, store the loss value in losses_list and perform the gradient descent update. Visualize the training process: Plot the loss values (on the y-axis) over the iterations (on the x-axis).

```
[]: import tqdm
     # Optimization parameters
     num_steps = 50000
     alpha = 0.1
     # Initializations
     fX = jnp.zeros_like(y_train)
     losses_list = []
     for step_idx in tqdm.trange(num_steps):
         # Compute loss and gradient
         loss_val, loss_grad = loss_val_and_grad(fX)
         # Update `fX`
         fX = fX - alpha * loss_grad
         # Store loss
         losses_list.append(loss_val)
     # Store final `f` in `fX_hat`
     fX_hat = fX
     # Visualization of training process
```

```
fig, ax = plt.subplots()
ax.plot(losses_list)
ax.set_xlabel("Step")
ax.set_ylabel("Loss")
ax.set_title("Training process")
plt.show()
```

100%| | 50000/50000 [00:05<00:00, 8922.71it/s]



1.1.5 4. Posterior GP

The posterior mean and covariance function are given by

$$\hat{m}(x_*) = m(x_*) + k(x_*, X) \cdot \nabla \log(p(y|\hat{f_X})) \tag{1}$$

$$\hat{k}(a,b) = k(a,b) - k(a,X)^{T} (k(X,X) + W^{-1})^{-1} k(X,b), \tag{2}$$

where W is a diagonal matrix with $\operatorname{diag}(W) = \pi \odot (1 - \pi)$ (\odot denotes the element-wise product of two vectors) and $\pi = \sigma(\hat{f}_X)$.

Task: Implement the posterior mean and covariance functions. For evaluating the posterior covariance, compute the Cholesky factorization of $k(X, X) + W^{-1}$ only once.

```
[]: m = prior_GP.m
ker = prior_GP.k
def posterior_mean(x):
    """Posterior mean function as defined above"""
    m_x = m(x)
    k_xX = ker(x[..., None, :], X_train[None, :, :])
    update = k_xX @ log_likelihood.grad(fX_hat)
    return m_x + update
```

```
W = logistic_func(fX_hat) * (1 - logistic_func(fX_hat))
W_inv = jnp.diag(1 / W)
k_XX = ker(X_train[:, None, :], X_train[None, :, :])
kW_1_2, lower_kW = jax.scipy.linalg.cho_factor(k_XX + W_inv)

def posterior_covar(a, b):
    """Posterior covariance function as defined above"""
    k_aX = ker(a, X_train[None, :, :])
    k_Xb = ker(X_train[:, None, :], b)
    k_ab = ker(a, b)
    # Implement the posterior mean and covariance functions. For evaluating the_u_posterior covariance, compute the Cholesky factorization of $k(X, X) +_u_y^{-1}$ only once.
    kW_inv_kXb = jax.scipy.linalg.cho_solve((kW_1_2, lower_kW), k_Xb)
    return k_ab - k_aX @ kW_inv_kXb
```

Posterior GP: Now, we can construct the posterior GP.

```
[ ]: post_GP = gaussians.GaussianProcess(posterior_mean, posterior_covar)
```

1.1.6 5. Further analyses

In the following, we will use the posterior GP for further analyses.

By evaluating the posterior GP on some data x_* , we obtain a Gaussian $p(f_*) = \mathcal{N}(f_*; \hat{m}(x_*), \hat{k}(x_*, x_*))$. The predictive probability for the positive class (the digit 1) is given by

$$\mathbb{E}_{p(f_*)}[\sigma(f_*)] = \int_{f_*} \sigma(f_*) \cdot p(f_*) df_*$$

We consider two approaches: 1. We can approximate the predictive probability by $\mathbb{E}_{p(f_*)}[\sigma(f_*)] \approx \sigma(\hat{m}(x_*))$, i.e. by mapping the mean of the Gaussian through the logistic function. 2. Another approximation (developed by David JC MacKay, 1992) is given by

$$\mathbb{E}_{p(f_*)}[\sigma(f_*)] \approx \sigma\big(\frac{\hat{m}(x_*)}{\sqrt{1+\frac{\pi}{8}\hat{k}(x_*,x_*)}}\big).$$

Task: Complete predictive_probs_2 below. Use approach 2 to compute the predictive probabilities for the training and test data.

```
[]: def predictive_probs_1(gaussian):
    """Predictive probabilities from a given Gaussian `gaussian` based
    on approach 1 above"""
    return logistic_func(gaussian.mu)

def predictive_probs_2(gaussian):
```

```
"""Predictive probabilities from a given Gaussian `gaussian` based
on approach 2 above"""

m_hat = gaussian.mu
k_hat = jnp.diag(gaussian.Sigma)
return logistic_func(m_hat / jnp.sqrt(1 + jnp.pi * k_hat / 8))

# Evaluate the posterior GP on the training and test data
post_gaussian_train = post_GP(X_train)
post_gaussian_test = post_GP(X_test)

# Compute the predictive probabilities using approach 2
probs_train = predictive_probs_2(post_gaussian_train)
probs_test = predictive_probs_2(post_gaussian_test)
```

Next, we can use the predictive probabilities to compute confidences for the training and test data points. The confidence is given by the maximum of the probabilities over all classes.

```
[]: # Confidence
confs_train = np.maximum(probs_train, 1 - probs_train)
confs_test = np.maximum(probs_test, 1 - probs_test)
```

With those confidence vectors, we can determine the k most/least certain digits.

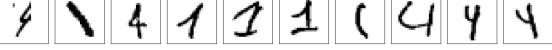
```
[]: def show k most least confident(X data, y data, title, confs, k=5):
         """Plot the `k` most/least certain data points."""
         sorted_indides = np.argsort(confs)
         indices_most = sorted_indides[-k:] # last k indices
         indices_least = sorted_indides[:k] # first k indices
         # Set upo figures for most and least confident data points
         fig_most, axs_most = plt.subplots(1, k, figsize=(k * 0.7, 1.5))
         fig_least, axs_least = plt.subplots(1, k, figsize=(k * 0.7, 1.5))
         for axs, indices in zip([axs_most, axs_least], [indices_most,__
      →indices_least]):
             for ax_idx, idx in enumerate(indices):
                 title_img = f"Label = {y_data[idx]}\n conf = {100 * confs[idx]:.1f}_\_
      ب%<sup>۱۱</sup>
                 show_mnist_img(axs[ax_idx], X_data[idx, :], title_img)
         fig_most.suptitle(title + " (most confident)")
         fig_least.suptitle(title + " (least confident)")
         plt.show()
```

Training data (most confident)

Label = 1 Label

Training data (least confident)

Label = -1 Label = -1



Test data (most confident)

Test data (least confident)

Label = 1 Label = 1 Label = -1 La





















We can also use the confidence vectors to make predictions.

```
[]: def predict_y(probs):
    """Compute the predicted class based on the probabilities for the
    positive class."""
    y_pred = np.zeros_like(probs).astype(int)
    y_pred[probs >= 0.5] = 1
    y_pred[probs < 0.5] = -1
    return y_pred</pre>
```

```
y_pred_train = predict_y(probs_train)
y_pred_test = predict_y(probs_test)
```

By comparing the predicted classes to the ground truth (y_train and y_test), we can compute accuracies on both data sets.

Task: Compute and print the training and test accuracy. *Hint*: If everything works correctly you should achieve a training accuracy of 100% and a test accuracy of 99.67%.

```
[]: def compute_accuracy(y_pred, y_true):
    """Compute the accuracy of the predictions `y_pred` compared to the
    true labels `y_true`."""
    return np.mean(y_pred == y_true)

acc_train = compute_accuracy(y_pred_train, y_train)
acc_test = compute_accuracy(y_pred_test, y_test)

print(f"Accuracy on training data: {100 * acc_train:.2f} %")
print(f"Accuracy on test data: {100 * acc_test:.2f} %")
```

Accuracy on training data: 100.00 % Accuracy on test data: 99.67 %

We can use the function below to show the misclassified data points.

```
[]: def show misclassified imgs(X data, y_data, y_pred, confs, title):
         mis_indices = list((y_pred != y_data).nonzero()[0])
         num_mis = len(mis_indices)
         if num mis == 0:
             return # Return if no misclassifications
         fig, axs = plt.subplots(1, num_mis, figsize=(num_mis * 0.7, 1.5))
         for idx, mis_idx in enumerate(mis_indices):
             title img = f"Label = {y data[mis idx]}\n conf = {100 * confs[mis idx]:.
      →1f} %"
             show_mnist_img(axs[idx], X_data[mis_idx, :], title_img)
         fig.suptitle(title)
         plt.show()
     # Plot misclassified test data points
     show_misclassified_imgs(X_train, y_train, y_pred_train, confs_train, __
      ⇔"Misclassified training data")
     print("")
     show_misclassified_imgs(X_test, y_test, y_pred_test, confs_test, "Misclassified_
      →test data")
```

Misclassified test data

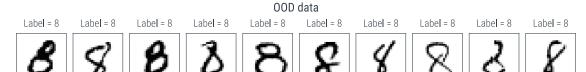
Label = -1 Label = -1 conf = 64.6 % conf = 64.8 %





Finally, let's compare the two approaches for the predictive probabilities on out-of-distribution data.

```
[]: # Load/show the data
X_ood, y_ood = data["X_ood"], data["y_ood"]
show_n_mnist_imgs(X_ood, y_ood, "OOD data", n=10)
print_data_info(X_ood, y_ood, "OOD data")
```



```
OOD data:
X.shape = (100, 784)
X in range [-1.0, 1.0]
y.shape = (100,)
Target yi = 8: Found 100 times
```

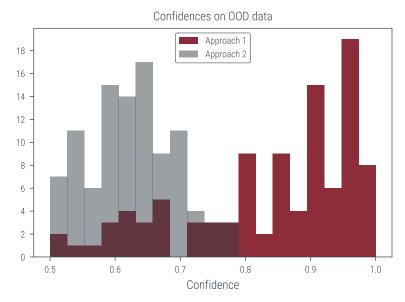
```
[]: # Evaluate the posterior GP on `X_ood`, compute predicted probabilities
post_gaussian_ood = post_GP(X_ood)
probs_ood_1 = predictive_probs_1(post_gaussian_ood)
probs_ood_2 = predictive_probs_2(post_gaussian_ood)

# Compute confidences
confs_ood_1 = np.maximum(probs_ood_1, 1 - probs_ood_1)
confs_ood_2 = np.maximum(probs_ood_2, 1 - probs_ood_2)
```

```
[]: fig, ax = plt.subplots(1, 1, figsize=(4, 3))
bins = np.linspace(0.5, 1, 20)

ax.hist(confs_ood_1, bins=bins, alpha=1.0, label="Approach 1")
ax.hist(confs_ood_2, bins=bins, alpha=0.5, label="Approach 2")
# Set y axis integer ticks
ax.yaxis.set_major_locator(plt.MaxNLocator(integer=True))
```

```
# General settings
ax.set_title("Confidences on OOD data")
ax.set_xlabel("Confidence")
ax.legend(loc="upper center")
plt.show()
```



Task: How can the difference between the two histograms be explained? Which of the two approaches would you prefer? Explain your decision briefly.

Your answer: In the second approach (and thus, histogram), the covariances $(\hat{k}(x_*, x_*))$ are also taken into consideration:

$$\mathbb{E}_{p(f_*)}[\sigma(f_*)] \approx \sigma\big(\frac{\hat{m}(x_*)}{\sqrt{1+\frac{\pi}{8}\hat{k}(x_*,x_*)}}\big).$$

This allows better approximation of the confidence values using predictive probabilities since intuitively, as the (co)variance of the prediction increases, confidence on the predicted value should decrease. This is achieved in the second approach by scaling the mean's effect by variance. Therefore, second approach would be preferable.

Note also that, assuming $\frac{\pi}{8}\hat{k}(x_*, x_*) << 1$:

$$\begin{split} \sqrt{1+\frac{\pi}{8}\hat{k}(x_*,x_*)} &\approx 1+\frac{\pi}{16}\hat{k}(x_*,x_*) \\ \mathbb{E}_{p(f_*)}[\sigma(f_*)] &\approx \sigma\big(\frac{\hat{m}(x_*)}{1+\frac{\pi}{16}\hat{k}(x_*,x_*)}\big). \end{split}$$

The result above further displays how the scaling effect of covariance works.