

3.26 齐次变换矩阵

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In[1]:= homoT =

$$\begin{pmatrix} \cos[\theta] & -\sin[\theta] & 0 & a \\ \sin[\theta] * \cos[\alpha] & \cos[\theta] * \cos[\alpha] & -\sin[\alpha] & -\sin[\alpha] * d \\ \sin[\theta] * \sin[\alpha] & \cos[\theta] * \sin[\alpha] & \cos[\alpha] & \cos[\alpha] * d \\ 0 & 0 & 0 & 1 \end{pmatrix};$$

T[α_, aa_, dd_, θ_] := homoT /. {theta → θ, alpha → α, a → aa, d → dd};
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每个连杆上的齐次变换矩阵分别为：

```
In[24]:= T0to1 = T[0 Degree, 0, 795.5, theta1]
          |度
T1to2 = T[90 Degree, 250, 0, theta2 + 90 Degree]
          |度          |度
T2to3 = T[0 Degree, 950, 0, theta3]
          |度
T3to4 = T[90 Degree, 300, 1550, 90 Degree + theta4]
          |度          |度
T4to5 = T[-45 Degree, 0, 98.7 * √2, theta5]
          |度
T5to6 = T[45 Degree, 0, 180 - 98.7, theta6]
          |度
```

$$\text{Out[24]} = \begin{pmatrix} \cos(\theta_1) & -\sin(\theta_1) & 0 & 0 \\ \sin(\theta_1) & \cos(\theta_1) & 0 & 0 \\ 0 & 0 & 1 & 795.5 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Out[25]} = \begin{pmatrix} -\sin(\theta_2) & -\cos(\theta_2) & 0 & 250 \\ 0 & 0 & -1 & 0 \\ \cos(\theta_2) & -\sin(\theta_2) & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Out[26]} = \begin{pmatrix} \cos(\theta_3) & -\sin(\theta_3) & 0 & 950 \\ \sin(\theta_3) & \cos(\theta_3) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Out[27]} = \begin{pmatrix} -\sin(\theta_4) & -\cos(\theta_4) & 0 & 300 \\ 0 & 0 & -1 & -1550 \\ \cos(\theta_4) & -\sin(\theta_4) & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Out[28]} = \begin{pmatrix} \cos(\theta_5) & -\sin(\theta_5) & 0 & 0 \\ \frac{\sin(\theta_5)}{\sqrt{2}} & \frac{\cos(\theta_5)}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 98.7 \\ -\frac{\sin(\theta_5)}{\sqrt{2}} & -\frac{\cos(\theta_5)}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 98.7 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$\text{Out[29]} = \begin{pmatrix} \cos(\theta_6) & -\sin(\theta_6) & 0 & 0 \\ \frac{\sin(\theta_6)}{\sqrt{2}} & \frac{\cos(\theta_6)}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & -57.4878 \\ \frac{\sin(\theta_6)}{\sqrt{2}} & \frac{\cos(\theta_6)}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 57.4878 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

于是正运动学解为

In[30]:= **T0to6 = T0to1.T1to2.T2to3.T3to4.T4to5.T5to6 // Simplify**

[化简](#)

$$\text{Out[30]} = \begin{pmatrix} \frac{1}{2} \left(\cos(\theta_4) \left(\cos(\theta_1) \sin(\theta_2 + \theta_3) \left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + \sin(\theta_6) \right) + \cos(\theta_6) \right) \right. \\ \left. \frac{1}{2} \left(\sin(\theta_1) \left(\cos(\theta_3) \left(\cos(\theta_5) (2 \sin(\theta_2) \sin(\theta_4) \cos(\theta_6) + \sin(\theta_6) (\sin(\theta_2) \cos(\theta_4) \right) \right) \right. \right. \right. \\ \left. \left. \left. \frac{1}{2} \left(\sin(\theta_2) \left(\cos(\theta_4) \right) \right) \right) \right) \right) \end{pmatrix}$$

上面那种形式显示不全，下面是完全的结果：

In[31]:= **Grid[T0to6]**

[格子](#)

$\frac{1}{2} \left(\cos(\theta_4) \right)$	$\frac{1}{2} \left(-\cos(\theta_1) \right)$	$\frac{1}{2\sqrt{2}} \left(\cos(\theta_1) \right)$	$\cos(\theta_1) \left(\sin(\theta_2) \right)$
$\left(\cos(\theta_1) \right)$	$\left(\sin(\theta_2) \right)$	$\left(2 \cos(\theta_2) \right)$	$\left(\cos(\theta_3) \right)$
$\sin(\theta_2 + \theta_3)$	$\left(\cos(\theta_3) \right)$	$\left(\sin(\theta_3) \right)$	$(139.35 -$
$\left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + \sin(\theta_6) \right) +$	$\left(\sin(\theta_4) \right)$	$\left(\sin(\theta_4) \right)$	$40.65 \cos(\theta_5)) +$
$\cos(\theta_5) \left(\cos(\theta_1) \sin(\theta_2 + \theta_3) + 2 \sin(\theta_1) \cos(\theta_6) \right) -$	$\left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + 2 \cos(\theta_5) \sin(\theta_6) \right) +$	$\sin(\theta_5) + \sqrt{2} \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) +$	$57.4878 \sin(\theta_4) \sin(\theta_5) -$
$\sqrt{2} \sin(\theta_1) \sin(\theta_5) \sin(\theta_6) \right) +$	$\sin(\theta_4) \cos(\theta_4) \left(\sqrt{2} \cos(\theta_3) \cos^2\left(\frac{\theta_5}{2}\right) -$	$\sin(\theta_2) \left(\sqrt{2} \sin(\theta_3) \cos(\theta_5) + 1 - 2 \cos(\theta_3) \left(\sin(\theta_4) \sin(\theta_5) + \sqrt{2} \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) \right) \right) +$	$300.) + \sin(\theta_3) (-40.65 \cos(\theta_5) - 1689.35) - 950.) +$
$\cos(\theta_1) \left(\sin(\theta_3) \left(\cos(\theta_2) \sin(\theta_4) \left(2 \cos(\theta_5) \cos(\theta_6) - \sqrt{2} \sin(\theta_5) \sin(\theta_6) \right) + \sin(\theta_2) \cos(\theta_6) \right) + \cos(\theta_1) \left(\sin(\theta_2) \cos(\theta_4) \left(2 \cos(\theta_5) \cos(\theta_6) - \sqrt{2} \sin(\theta_5) \sin(\theta_6) \right) + \sin(\theta_2) \cos(\theta_6) \right) \right) +$	$\left(\sqrt{2} \sin(\theta_5) \sin(\theta_6) - \cos(\theta_5) + 1 \right) \cos(\theta_6) \right) +$	$\sin(\theta_1) \left(2 \cos(\theta_4) \sin(\theta_5) - 2 \sqrt{2} \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) \right) +$	$\cos(\theta_2) \left(\sin(\theta_3) \cos(\theta_4) (139.35 - 40.65 \cos(\theta_5)) + 57.4878 \sin(\theta_4) \sin(\theta_5) - 300.) + \cos(\theta_3) (40.65 \cos(\theta_5) + 1689.35) + 250.) +$
$\sin(\theta_1) \left(\sin(\theta_2) \cos(\theta_4) \left(2 \cos(\theta_5) \cos(\theta_6) - \sqrt{2} \sin(\theta_5) \sin(\theta_6) \right) + \sin(\theta_2) \cos(\theta_6) \right) +$	$\cos(\theta_2) \left(\sin(\theta_3) \left(\sin(\theta_4) \left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + 2 \cos(\theta_5) \sin(\theta_6) \right) + \sin(\theta_4) \cos(\theta_4) \left(\sqrt{2} \cos(\theta_3) \cos^2\left(\frac{\theta_5}{2}\right) - \sin(\theta_2) \left(\sqrt{2} \sin(\theta_3) \cos(\theta_5) + 1 - 2 \cos(\theta_3) \left(\sin(\theta_4) \sin(\theta_5) + \sqrt{2} \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) \right) \right) \right) +$	$\sin(\theta_1) \left(2 \cos(\theta_4) \sin(\theta_5) - 2 \sqrt{2} \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) \right) +$	$\sin(\theta_1) \left(\sin(\theta_2) \cos(\theta_4) (40.65 \cos(\theta_5) - 139.35) +$

$\begin{aligned} & \sin(\theta_5) \\ & \cos(\theta_6) + \\ & (\cos(\theta_5) - 1) \\ & \sin(\theta_6)) - \\ & \cos(\theta_3) \\ & (\sqrt{2} \\ & \sin(\theta_2) \\ & \sin(\theta_4) \\ & \sin(\theta_5) \\ & \sin(\theta_6) + \\ & \cos(\theta_5) \\ & (\cos(\theta_2) \\ & \sin(\theta_6) - \\ & 2 \sin(\theta_2) \\ & \sin(\theta_4) \\ & \cos(\theta_6)) + \\ & \sqrt{2} \cos(\theta_2) \\ & \sin(\theta_5) \\ & \cos(\theta_6) - \\ & \cos(\theta_2) \\ & \sin(\theta_6)) - \\ & \sin(\theta_1) \\ & \sin(\theta_4) \\ & (\sqrt{2} \\ & \sin(\theta_5) \\ & \cos(\theta_6) + \\ & (\cos(\theta_5) + 1) \\ & \sin(\theta_6)) \end{aligned}$	$\begin{aligned} & \sin(\theta_5) \\ & \cos(\theta_6) + \\ & 2 \cos(\theta_5) \\ & \sin(\theta_6)) + \\ & \cos(\theta_4) \\ & (\sqrt{2} \\ & \sin(\theta_5) \\ & \sin(\theta_6) - \\ & (\cos(\theta_5) + \\ & 1) \cos(\theta_6)) + \\ & \cos(\theta_3) \\ & ((\cos(\theta_5) - 1) \\ & \cos(\theta_6) - \\ & \sqrt{2} \sin(\theta_5) \sin(\theta_6))) - \\ & \sin(\theta_1) \\ & (\cos(\theta_6) \\ & \sin(\theta_4) \\ & \cos(\theta_5) + \\ & \sqrt{2} \\ & \cos(\theta_4) \\ & \sin(\theta_5) + \\ & \sin(\theta_4)) + \\ & \sin(\theta_6) \\ & (2 \\ & \cos(\theta_4) \\ & \cos(\theta_5) - \\ & \sqrt{2} \\ & \sin(\theta_4) \\ & \sin(\theta_5))) \end{aligned}$	$\sin^2\left(\frac{\theta_5}{2}\right)$	<p>57.4878</p> $\cos(\theta_4) \sin(\theta_5)$
$\frac{1}{2} (\sin(\theta_1)$	$\frac{1}{2} (\sin(\theta_1) \sin(\theta_2) \cos(\theta_2)$		$\sin(\theta_1) (\sin(\theta_2)$

$\frac{1}{2} \left(\sin(\theta_2) \left(\cos(\theta_5) (2 \sin(\theta_3) \sin(\theta_4) \cos(\theta_6) + \sin(\theta_6) (\sin(\theta_3) \cos(\theta_4) - \cos(\theta_3))) + \sin(\theta_3) (\cos(\theta_4) (\sqrt{2} \sin(\theta_5) \cos(\theta_6) + \sin(\theta_6)) - \sqrt{2} \sin(\theta_4) \sin(\theta_5) \sin(\theta_6)) + \cos(\theta_3) (\sin(\theta_6) - \sqrt{2} \sin(\theta_5) \cos(\theta_6)) \right) \right) -$	$\frac{1}{2} \left(\sin(\theta_2) \left(\sin(\theta_3) \left(\cos(\theta_4) (-\sqrt{2} \sin(\theta_5) \sin(\theta_6) + \cos(\theta_5) \cos(\theta_6) + \cos(\theta_6)) - \sin(\theta_4) (\sqrt{2} \sin(\theta_5) \cos(\theta_6) + 2 \cos(\theta_5) \sin(\theta_6)) \right) + \cos(\theta_3) \left(\sqrt{2} \sin(\theta_5) \sin(\theta_6) - \cos(\theta_5) \cos(\theta_6) + \cos(\theta_6) \right) \right) \right) +$	$\frac{1}{2} \left(\cos(\theta_3) \left(2 \sin(\theta_2) \cos^2\left(\frac{\theta_5}{2}\right) - \cos(\theta_2) \left(\sqrt{2} \sin(\theta_4) \sin(\theta_5) + 2 \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right) \right) + \sin(\theta_3) \left(\sin(\theta_2) (\sqrt{2} \sin(\theta_4) \sin(\theta_5) + 2 \cos(\theta_4) \sin^2\left(\frac{\theta_5}{2}\right)) + \cos(\theta_2) (\cos(\theta_5) + 1) \right) \right) \right)$	$57.4878 \sin(\theta_2) \sin(\theta_3) \sin(\theta_4) \sin(\theta_5) - 40.65 \sin(\theta_2) \sin(\theta_3) \cos(\theta_4) \cos(\theta_5) + \cos(\theta_2) (\cos(\theta_3) (-57.4878 \sin(\theta_4) \sin(\theta_5) + \cos(\theta_4) (40.65 \cos(\theta_5) - 139.35) + 300.) + \sin(\theta_3) (40.65 \cos(\theta_5) + 1689.35) + 950.) + 139.35 \sin(\theta_2) \sin(\theta_3) \cos(\theta_4) + \sin(\theta_2) \cos(\theta_3) (40.65 \cos(\theta_5) +$
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$\begin{aligned} & \cos(\theta_2) \\ & \left(\cos(\theta_3) \right. \\ & \quad \left(-\sqrt{2} \right. \\ & \quad \sin(\theta_4) \\ & \quad \sin(\theta_5) \\ & \quad \sin(\theta_6) + \\ & \quad \cos(\theta_4) \\ & \quad \left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + \sin(\theta_6) \right) + \\ & \quad \cos(\theta_5) \\ & \quad (2 \sin(\theta_4) \cos(\theta_6) + \cos(\theta_4) \sin(\theta_6)) + \\ & \quad \sin(\theta_3) \\ & \quad \left(\sqrt{2} \sin(\theta_5) \cos(\theta_6) + (\cos(\theta_5) - 1) \sin(\theta_6) \right) \Big) \Big) \Big) \Big) \\ & 0. \end{aligned}$	$\begin{aligned} & \left(\cos(\theta_3) \right. \\ & \quad \left(\sin(\theta_4) \right. \\ & \quad \left(\sqrt{2} \right. \\ & \quad \sin(\theta_5) \\ & \quad \cos(\theta_6) + \\ & \quad 2 \cos(\theta_5) \sin(\theta_6) \Big) + \\ & \quad \cos(\theta_4) \\ & \quad \left(\sqrt{2} \right. \\ & \quad \sin(\theta_5) \\ & \quad \sin(\theta_6) - \\ & \quad (\cos(\theta_5) + 1) \cos(\theta_6) \Big) \Big) + \\ & \quad \sin(\theta_3) \\ & \quad \left(\sqrt{2} \right. \\ & \quad \sin(\theta_5) \\ & \quad \sin(\theta_6) - \\ & \quad \cos(\theta_5) \cos(\theta_6) + \\ & \quad \cos(\theta_6) \Big) \Big) \Big) \Big) \\ & 0. \end{aligned}$	$\begin{aligned} & \sqrt{1689.35} - \\ & 300. \sin(\theta_2) \\ & \sin(\theta_3) + 795.5 \\ & 0. \end{aligned}$
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