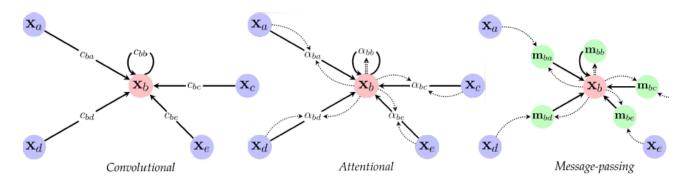
# **GNN** Architectures



$$\mathbf{h}_i = \phi\left(\mathbf{x}_i, igoplus_{j \in \mathcal{N}_i} c_{ij} \psi(\mathbf{x}_j)
ight) \qquad \quad \mathbf{h}_i = \phi\left(\mathbf{x}_i, igoplus_{j \in \mathcal{N}_i} a(\mathbf{x}_i, \mathbf{x}_j) \psi(\mathbf{x}_j)
ight)$$

e.g. GraphSAGE, GCN, SGC

$$\mathbf{h}_i = \phi \left( \mathbf{x}_i, igoplus_{j \in \mathcal{N}_i} a(\mathbf{x}_i, \mathbf{x}_j) \psi(\mathbf{x}_j) 
ight)$$

e.g. MoNet, GAT, GATv2

$$\mathbf{h}_i = \phi \left( \mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} \psi(\mathbf{x}_i, \mathbf{x}_j) \right)$$

e.g. IN, MPNN, GraphNet

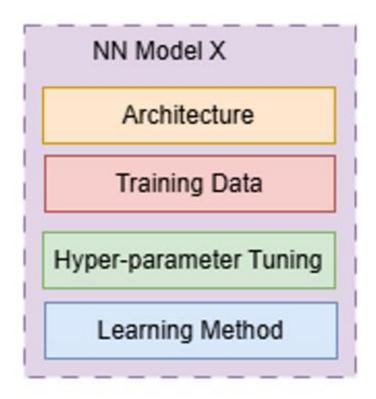






#### A Quick Word....

- Graph Neural Network (GNN) require graph structured data.
- If the data is not graph structured, data need to be converted to a graph structure.
- Always understand the data before implementations.
  - Visualize the graph
  - Summary statistics
- Lots of standard architectures...choose wisely..!
  - Expressivity
  - Spatio-temporal
  - Temporal
- Hyper-parameter tuning is same as in CNN and FFNN models
- Learning methods are same as used in CNN and FFNN models









#### Frameworks and Libraries

- PyTorch Geometric (PyG) and Deep Graph Library (DGL) are the two main GNN libraries used by researchers and industry
- PyG support only PyTorch while DGL support both the PyTorch and TensorFlow frameworks.
- NetworkX is a library used for network analysis, visualization and manipulation.





PyTorch Geometric

NetworkX



DGL



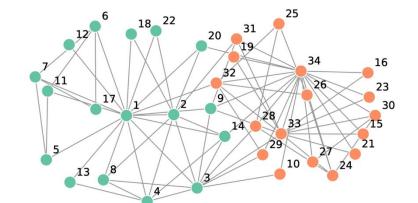


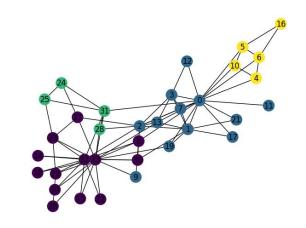




## Iris Dataset of GNN: Zachary Karate Club

- Zachary's Karate Club network is a social network dataset that represents the relationships between members of a karate club at a U.S. university in the 1970s.
- The network is an undirected graph with 34 nodes (each representing a club member).
- The dataset captures the **friendship ties (edges)** between members based on observed interactions resulting in 78 edges.
- Club split into two factions due to a conflict between the club instructor (node 1) and the club administrator (node 34).
- This division is observable through network analysis thus this is ideal dataset for GNNs as well.
- Due to small size and low complexity, this dataset can be considered as the "hello world" dataset of GNN research and can be compared to Iris dataset that play a similar role with classical ML research.
- Feature vector contains 34 values and altogether 4 classes.





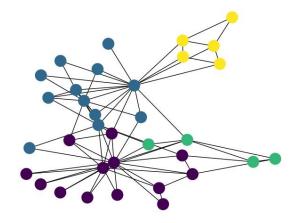


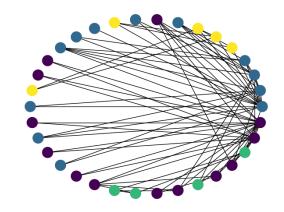


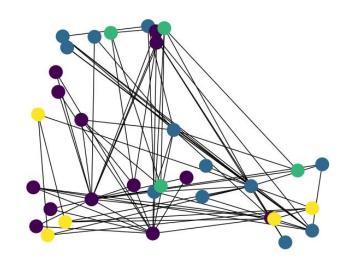


#### Visualization

- NetworkX is used.
- PyG graph should be first converted to a network graph
- Use the draw method!
- Different drawing layouts can be selected
- If none given, spring layout is used
- Different layouts
  - Random
  - Spring
  - Circular
  - Planar only if possible
  - Bipartite only if possible













#### For GNN: PyTorch >>> TensorFlow

- PyG only supports PyTorch
- Two main differences between TensorFlow and PyTorch
  - Model need to be defined as a class (similar to subclassing approach in TF)
  - Training loop need to be explicitly written (no method like model.fit)

```
6 class GCN(torch.nn.Module):
      def init (self):
          super(). init ()
 9
          torch.manual seed(1234)
          self.conv1 = GCNConv(dataset.num features, 4)
10
11
          self.conv2 = GCNConv(4, 4)
12
          self.conv3 = GCNConv(4, 2)
13
          self.classifier = Linear(2, dataset.num classes)
14
      def forward(self, x, edge index):
15
          h = self.conv1(x, edge_index)
16
17
          h = h.tanh()
          h = self.conv2(h, edge index)
18
          h = h.tanh()
19
          h = self.conv3(h, edge index)
20
          h = h.tanh() # Final GNN embedding space.
21
22
23
          # Apply a final (linear) classifier.
          out = self.classifier(h)
24
25
26
          return out, h
27
28 model = GCN()
```

```
1 def train(data):
2    optimizer.zero_grad()
3    out, h = model(data.x, data.edge_index)
4    loss = criterion(out[data.train_mask], data.y[data.train_mask])
5    loss.backward()
6    optimizer.step()
7    return loss, h
```

```
1 for epoch in range(401):
2    loss, h = train(data)
3    losses.append(loss)
4    print(f"Epoch: {epoch}\tLoss: {loss:4f}")
```

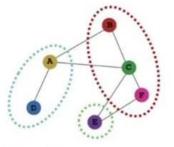






## Another important point...

Transductive node classification



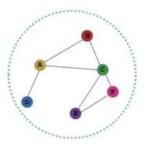
**Training** 

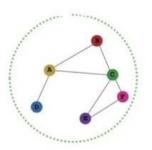
Validation

Test

Inductive node classification







**Training** 

Validation

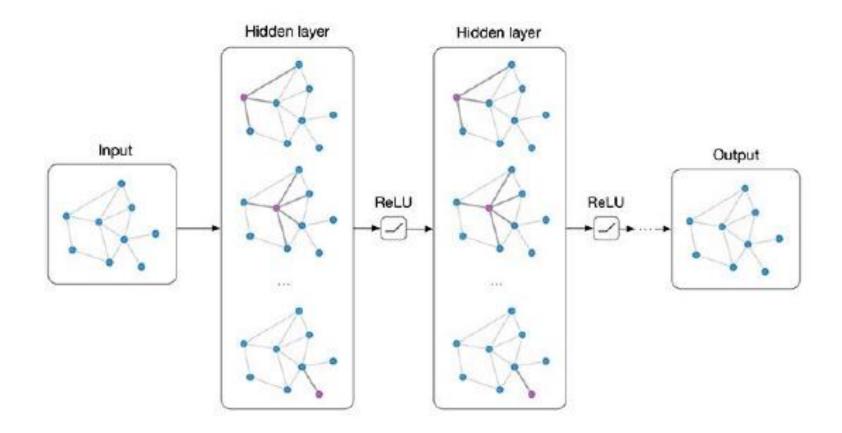
Test







#### **GNN** Architectures









# Graph Convolutional Network (GCN)

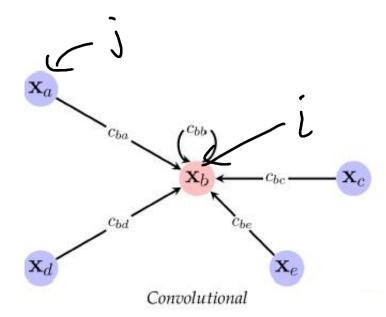
MPGNN equation

$$\mathbf{h}_{u}^{(k)} = \sigma \left( \mathbf{W}_{self}^{(k)} \mathbf{h}_{u}^{(k-1)} + \mathbf{W}_{neigh}^{(k)} \sum_{v \in \mathcal{N}(u)} \mathbf{h}_{v}^{(k-1)} + \mathbf{b}^{(k)} \right)$$

- GCN use weight sharing thus there is only one weight matrix
- Some GCN normalizes the aggregated messages by degree.
- Other GCNs use re-normalization method.

$$h_{i}^{(l+1)} = \sigma \left( \sum_{j \in \mathcal{N}_{i}} \frac{1}{c_{ij}} h_{j}^{(l)} W^{(l)} \right), \quad \forall j \in \mathcal{N}_{i} = \mathcal{J}_{i}$$

[1] Kipf, T.N. and Welling, M., 2016. Semi-supervised classification with graph convolutional networks. *arXiv preprint arXiv:1609.02907*.



$$\mathbf{h}_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \in \mathcal{N}_i} c_{ij} \psi(\mathbf{x}_j)\right)$$



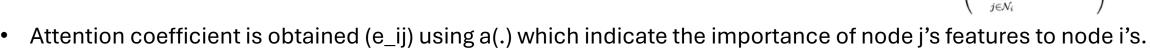




## Graph Attention Network (GAT)

 Attention mechanism has shown promising results with Transformer architectures in many areas.

$$e_{ij} = a(\mathbf{W}\vec{h}_i, \mathbf{W}\vec{h}_j)$$



Global attention looses structural information so neighborhood structure is used with attention (i.e., local attention).

$$\alpha_{ij} = \operatorname{softmax}_{j}(e_{ij}) = \frac{\exp(e_{ij})}{\sum_{k \in \mathcal{N}_{i}} \exp(e_{ik})}.$$

$$\alpha_{ij} = \frac{\exp\left(\operatorname{LeakyReLU}\left(\vec{\mathbf{a}}^{T}[\mathbf{W}\vec{h}_{i}\|\mathbf{W}\vec{h}_{j}]\right)\right)}{\sum_{k \in \mathcal{N}_{i}} \exp\left(\operatorname{LeakyReLU}\left(\vec{\mathbf{a}}^{T}[\mathbf{W}\vec{h}_{i}\|\mathbf{W}\vec{h}_{k}]\right)\right)}$$

$$\vec{h}'_{i} = \sigma\left(\sum_{i \in \mathcal{N}_{i}} \alpha_{ij} \mathbf{W}\vec{h}_{j}\right).$$

$$\vec{h}'_{i} = \prod_{k=1}^{K} \sigma\left(\sum_{i \in \mathcal{N}_{i}} \alpha_{ij}^{k} \mathbf{W}^{k} \vec{h}_{j}\right)$$

[2] Veličković, P., Cucurull, G., Casanova, A., Romero, A., Lio, P. and Bengio, Y., 2017. Graph attention networks. *arXiv preprint arXiv:1710.10903*.





