# **Brad Whynot**

Electrical Engineer (EIT)

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#### **EDUCATION**

### **Dalhousie University,** Halifax — B.Eng Electrical

September 2019 - May 2024

WORK EXPERIENCE

# Waterlogged Robotics, Dartmouth N.S — Electrical Engineer (Co-op)

March 2025 – Ongoing

- Led the development of an autonomous underwater glider.
- Glider is intended to be more viable for independent researchers with the ease of sensor integration.
- Created Wiring schematics for the glider.
- Utilized Python for real-time data processing and analysis.
- Created reports for operations and project process.
- Managed Build of materials.

# IntegraSEE, Dartmouth N.S — Freelance work

February 2024 – Ongoing

- Led the development of a Raspberry Pi system to gather and analyze data from muscle and clam habitats.
- Integrated sensors for environmental monitoring and Hall Effect signal capture.
- Utilized Python for real-time data processing and analysis.
- Integrated Google Drive API for secure data storage and retrieval.
- Developed visualizations and reports for operations.
- Developed app for pixel measurements with the addition of machine learning later in development.

# **Welaptega Marine Ltd,** Dartmouth N.S — Design Technician (Co-op)

January 2022 - April 2022

- Worked on multiple active R&D projects valued totaled over \$2 million.
- Specialized in R&D for a \$250,000 project that uses electro-optical measurement systems and pressurized electrical systems to measure underwater chains.
- Solely engineered instrument to allow for underwater 3D Scanning with materials already allocated to the project's kit.
- Developed marketing material for the project during down time.
- Completed multiple tests involving Inrush current limiting and In-air/In-water camera accuracy.
- Designed 3D models for prototyping in design review processes.
- Solo team lead for inrush current limiting and 3D printing projects.

#### **SKILLS**

3D modeling/ 3D Printing:
Solidworks, AutoCAD.
Computer Programming: C, C++,
Python, VHDL and Verilog
Circuit Designs and Simulation:
LTSpice
Operation of Electrical Lab
Equipment

### NON-TECHNICAL SKILLS

**Spreadsheet Management** 

**Communication &** 

**Interpersonal:** Organized team meeting and verified project was on schedule, within both academia and workplace.

**Team Lead:** Able to operate as a designated team lead for many projects in both academia and workplace.

#### **PROJECTS**

# **Engineering Capstone Project with NovaResp Technology**

February 2023 – December 2023

- Providing research into appropriate sensors that will aid NovaResp's artificial intelligence for predicting sleep apnea.
- Implementation of designated sensors onto CPAP masks without restricting wearability.

## **Engineering Robotic Design Competition**

May 2022 – September 2022

- Programmed a robot to autonomously move through an obstacle course with the use of lidar.
- 3D modeled a redesigned chassis for the robot to deactivate and collect hidden mines placed throughout the course.
- Implemented internal elevators using servo motors to store up to six mines within the robot.
- Performed under a high stress environment, finishing top 8 out of 25 teams.
- Produced a 38-page technical report outlining our design processes, technical drawings, sample code and competition results.

#### ACADEMIC AWARDS

Hebbville Academy Principal's Award

Johnson Foundation Scholarship

#### **Extra Curriculars**

Active Dalhousie Esports Society Admin

Active within Dalhousie Biking Society