

PyBOP: #1

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**Battery
Intelligence
Lab**

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- ▶ A mixture of the two, (i.e. the ideal situation)

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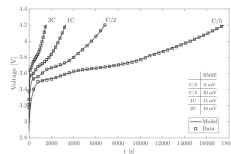
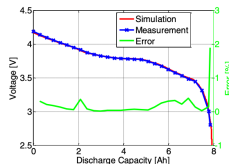
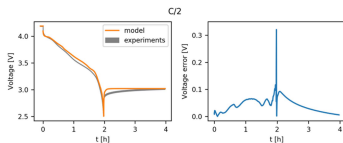
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Uniqueness?

Three different popular parameter sets, each with a different creation method:

- ▶ Chen2020 → DFN w/ trial and error fitting (RMSE), parameter variation between 12% to 1800%
- ▶ Ecker2015 → DFN, variation from 45% to 154%
- ▶ Mohat2020 → MPMe, variation from 0% to ?%



PyBOP: A battery parameterisation and optimisation package

(let's intelligently construct parameter sets and optimise models)

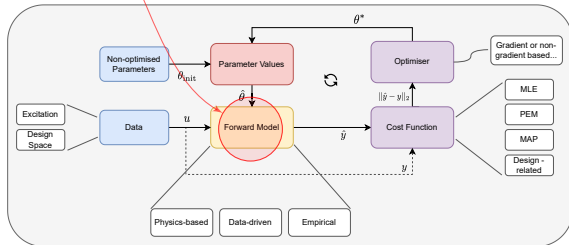


A package to standardised parameter identification and optimisation that provides:

- ▶ An API that offers complexity to advanced users while guiding new users
- ▶ A research platform to improve parameter identification and battery optimisation
- ▶ Performance, both in iter/s and convergence *guarantees*
- ▶ Open-source!

The high-level API is,

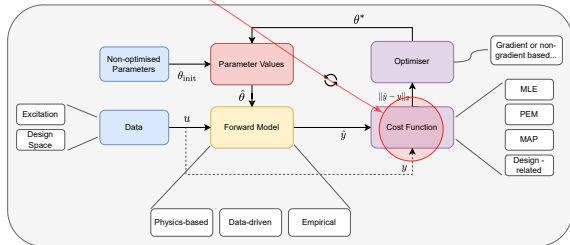
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# Generate problem, cost function, and optimisation class
problem = pybop.Problem(model, parameters, dataset)
cost = pybop.SumSquaredError(problem)
optim = pybop.Optimisation(cost, optimiser=pybop.GradientDescent)
x, final_cost = optim.run()
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Function calls that align with intuition

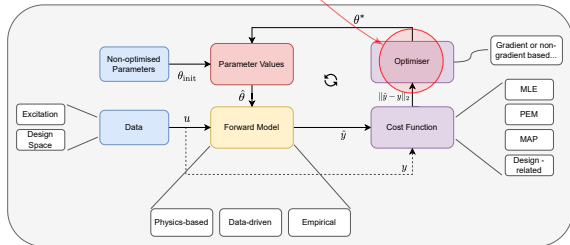
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CMA-ES¹ provides a robust solution to challenging (noisy, multi-modal, etc.) cost landscapes, at the exchange for performance without requiring hyperparameter tuning. The algorithm is defined by the following steps,

1. Sample candidate solutions:

$$\mathbf{x}_k^{(g+1)} \sim \mathbf{m}^{(g)} + \sigma^{(g)} \mathcal{N} (0, \mathbf{C}^{(g)}) , \quad \text{for } g = 1, \dots, \lambda$$

¹I have a blog post that expands on this: bradyplanden.github.io

2. Construct the Evolutionary Paths:

$$\mathbf{p}_c^{(g+1)} = (1 - c_c)\mathbf{p}_c^{(g)} + h_\sigma^{(g+1)} \sqrt{c_c(2 - c_c)\mu_w} dy$$

$$\mathbf{p}_\sigma^{(g+1)} = (1 - c_\sigma)\mathbf{p}_\sigma^{(g)} + \sqrt{c_\sigma(2 - c_\sigma)\mu_w} dz$$

$$h_\sigma^{(g+1)} = \begin{cases} 1, & \text{if } \frac{\|\mathbf{p}_\sigma^{(g+1)}\|^2}{1 - (1 - c_\sigma)^{2 \cdot (g+1)}} < (2 + 4/(d + 1)) d, \\ 0, & \text{otherwise} \end{cases}$$

3. Update the Search Distribution:

$$\mathbf{m}^{(g+1)} = \mathbf{m}^{(g)} + c_m \sum_{i=1}^{\mu} w_i \left(\mathbf{x}_{i:\lambda}^{(g+1)} - \mathbf{m}^{(g)} \right)$$

$$\sigma^{(g+1)} = \sigma^{(g)} \exp \left(\frac{c_\sigma}{d_\sigma} \left(\frac{\|\mathbf{p}_\sigma^{(g+1)}\|}{\mathbb{E}\|\mathcal{N}(0, \mathbf{I})\|} - 1 \right) \right)$$

$$\mathbf{C}^{(g+1)} = (1 - c_1 - c_\mu \sum w_j) \mathbf{C}^{(g)} + \underbrace{c_1 \mathbf{p}_c^{(g+1)} \mathbf{p}_c^{(g+1)T}}_{\text{rank-one update}} + \underbrace{c_\mu \sum_{i=1}^{\lambda} w_i \mathbf{y}_{i:\lambda}^{(g+1)} \left(\mathbf{y}_{i:\lambda}^{(g+1)} \right)^T}_{\text{rank-}\mu \text{ update}}$$

Example: Fitting SPM Parameters from Pulse Data

Active Material Volume Fractions



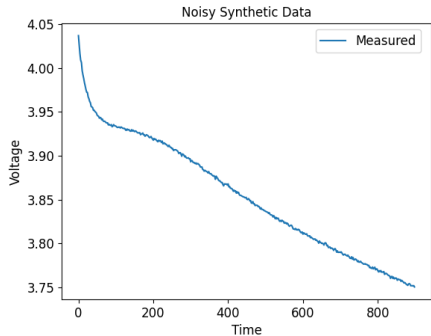
This example fits the active material volume fractions, $\{\epsilon_k\}$ for $k \in \{n, p\}$, using a sum of square errors cost function,

$$\sum_{i=1}^k (Y_i - \hat{Y}_i)^2$$

a Chen2020 parameter set, and a constant applied current of 1C.

The ground truth parameters are:

$$[\epsilon_n = 0.75, \epsilon_p = 0.665]$$



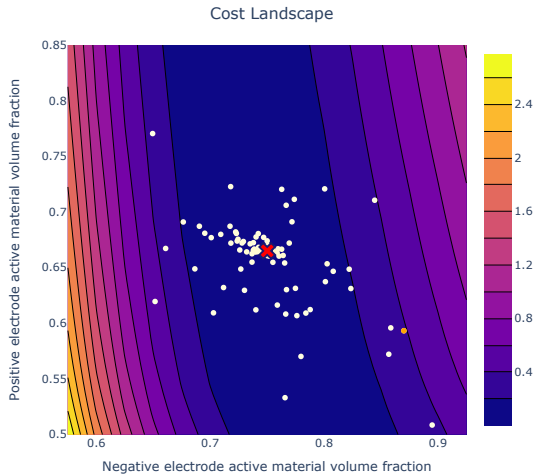
Example: Non-Gradient based MLE

CMA-ES

We define the problem, cost, and corresponding optimisation with CMA-ES

- ▶ $x_{0p} \sim \mathcal{N}(0.53, 0.01)$
- ▶ $x_{0n} \sim \mathcal{N}(0.825, 0.01)$
- ▶ $\text{bounds} = [0.6 - 0.9, 0.5 - 0.8]$
- ▶ Max iters: 500

Traverses the landscape quickly at the beginning.



Example: Non-Gradient based MLE

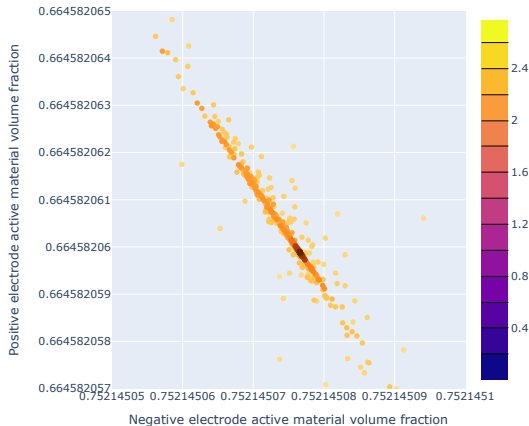
CMA-ES

Quickly finds an optimal & spends a large amount of time around this point.

Optimal at:

$$[\epsilon_n = 0.7508, \epsilon_p = 0.6650]$$

Cost Landscape



Example: with Gradient based MLE

Gradient Descent ($\eta = 0.01$)

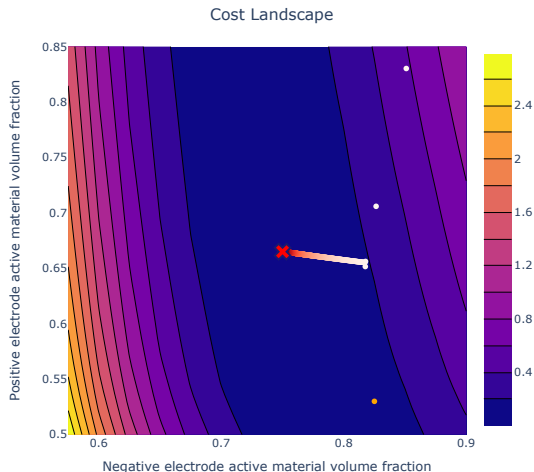
Gradient descent² to minimise the cost function, passing $\frac{\partial f}{\partial \theta}$ from the forward model to Pints'.

- ▶ $x_0 \sim \mathcal{N}(\mu, \sigma^2)$
- ▶ Max iters: 500
- ▶ η : 0.01

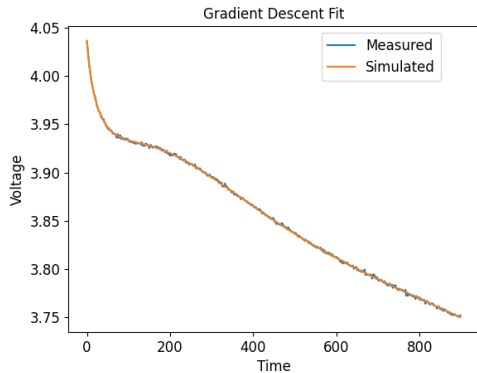
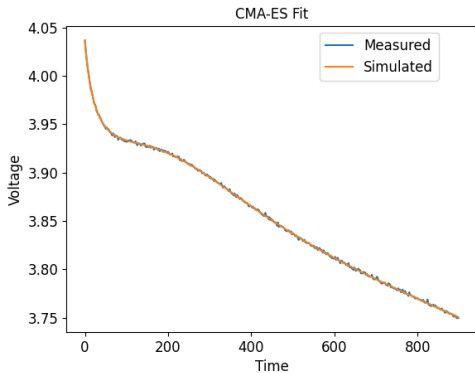
Calculating $\frac{\partial f}{\partial \theta}$ is expensive, and results in slower fitting.

$$[\epsilon_n = 0.7504, \epsilon_p = 0.6651]$$

^aWe run this daily on the cloud!



Example: Time-Series Comparison



We are currently working on the following:

- ▶ Adding bayesian methods: HMC, ABC, etc.
- ▶ Implement a version of PEM (Injecting terms into the model structure before discretising)
- ▶ Methods to acquire Hessian information
- ▶ More workflows & benchmarks for users

Automated testing is a step change in performance



Consider adding a testing suite to your individual research repositories. It solves a considerable amount of problems:

- ▶ Catches bugs / mistypes in your code before publishing results
- ▶ Tells you right away when you broke something
- ▶ Can be used for benchmarking
- ▶ Can format your code for consistency
- ▶ It's parametric, and free!