

Week 3: The Handwritten Hoedown

August 9, 2021



- 1. Neural Networks (continued)
- 2. Classification Loss
- 3. Mini-Batching
- 4. Saving and loading model state

Problem:

BRAINTANK DEEP LEARNING

The University of Guelph runs a yearly square-dancing competition, where contestants send in videos of their choreography, and Agriculture department professors rate their moves on a scale of 0 to 9. Due to poor planning, the university used paper and pen to record their scores, and are having trouble digitizing their results. They have asked BrainTank to take these written scores and label them correctly. We are hoping to be 95% correct in our classification.



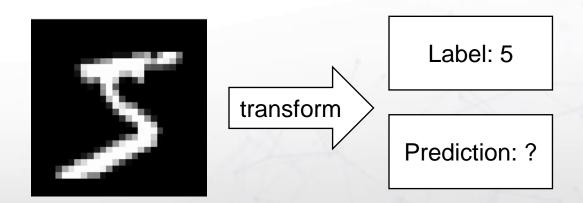


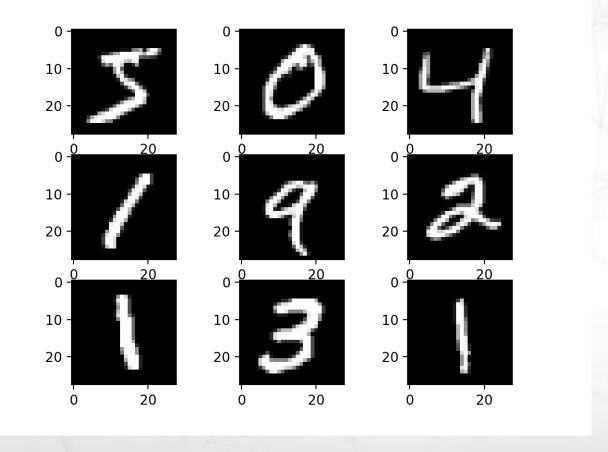
The Dataset

The Dataset

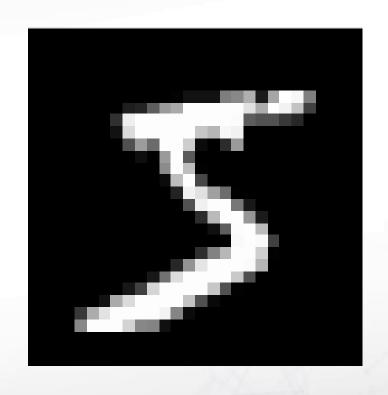
BRAINTANK DEEP LEARNING

- 70,000 images.
- Each image is 28 by 28 pixels
- Each image is in greyscale (black and white)
- We will make a training set of 60,000 images
- We will make a test set of 10,000 images
- All images have a label associated with them.
 Labels are integers of values 0 to 9.



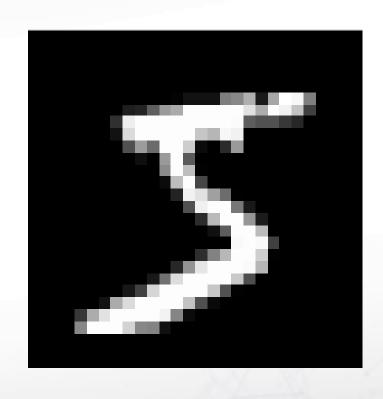








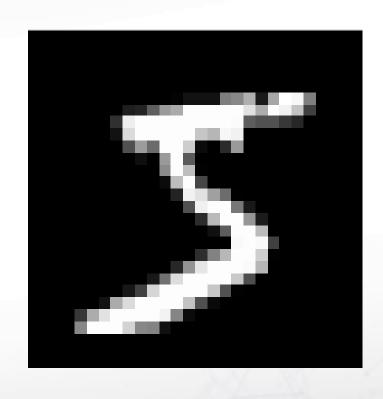




Representation

- 1. 1 colour dimension (black and white)
- 2. 28 pixels high
- 3. 28 pixels wide



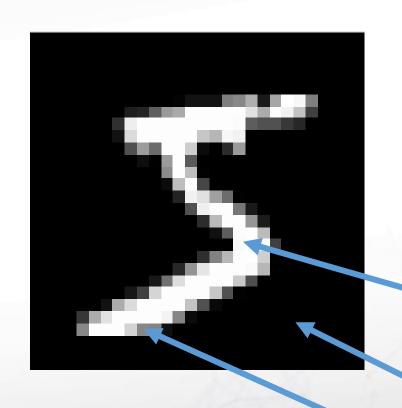


Representation

White pixels have a value of 256
Black pixels have a value of 0
Grey pixels have an intermediate value

- 1. 1 colour dimension (black and white)
- 2. 28 pixels high
- 3. 28 pixels wide



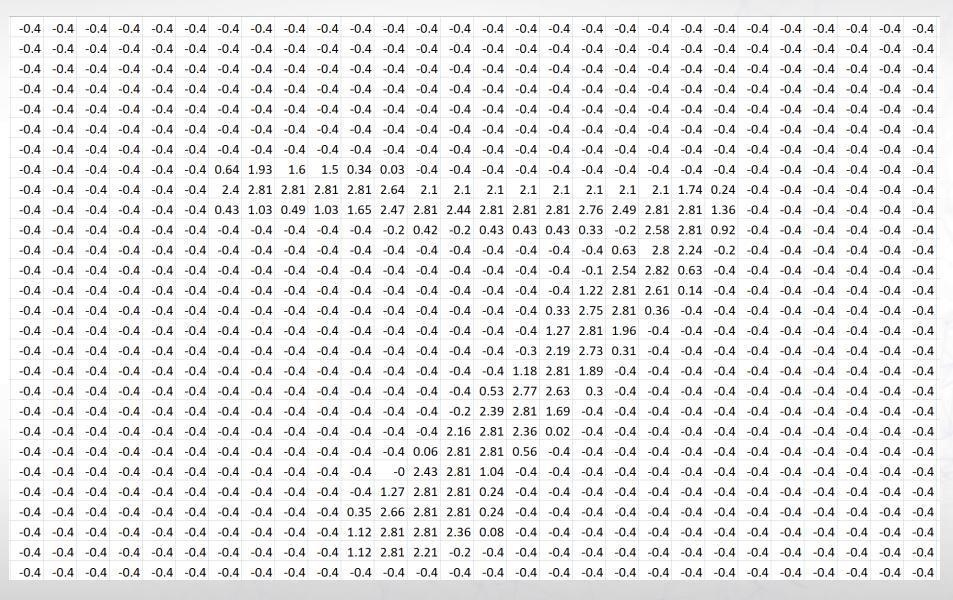


Representation

White pixels have a value of 256
Black pixels have a value of 0
Grey pixels have an intermediate value

- 1. 1 colour dimension (black and white)
- 2. 28 pixels high
- 3. 28 pixels wide

Normalization





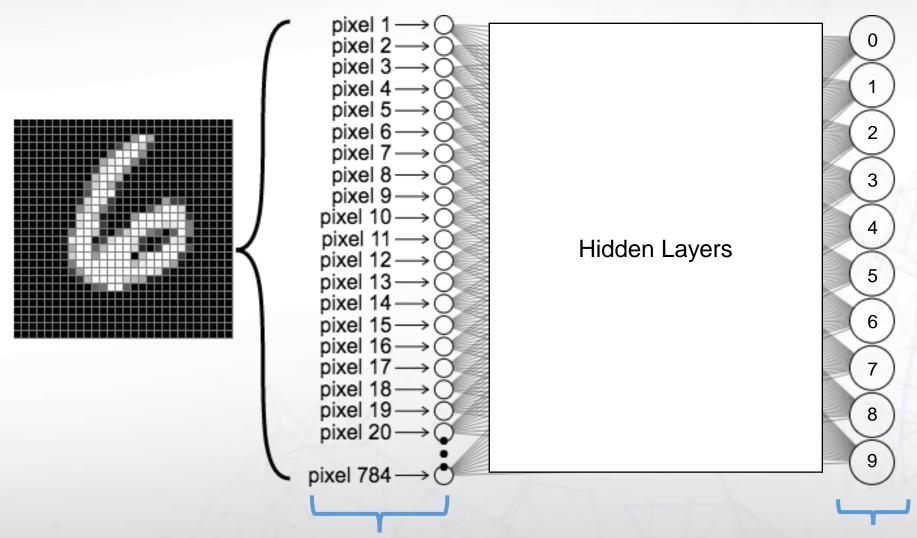
Look closely, you can make out a number 7.

All values are normalized to be between the values of -0.4 and 2.81.

This is an example of normalizing with mean and standard deviation values.

How we going to tackle this problem





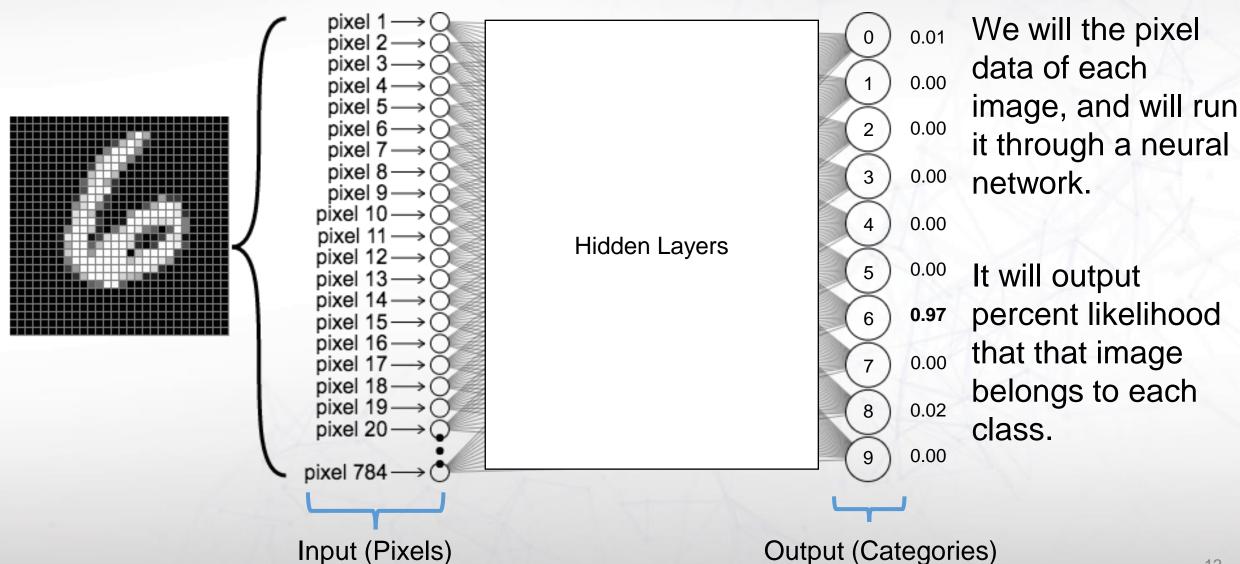
Input (Pixels)

We will the pixel data of each image, and will run it through a neural network.

It will output percent likelihood that that image belongs to each class.

How we going to tackle this problem



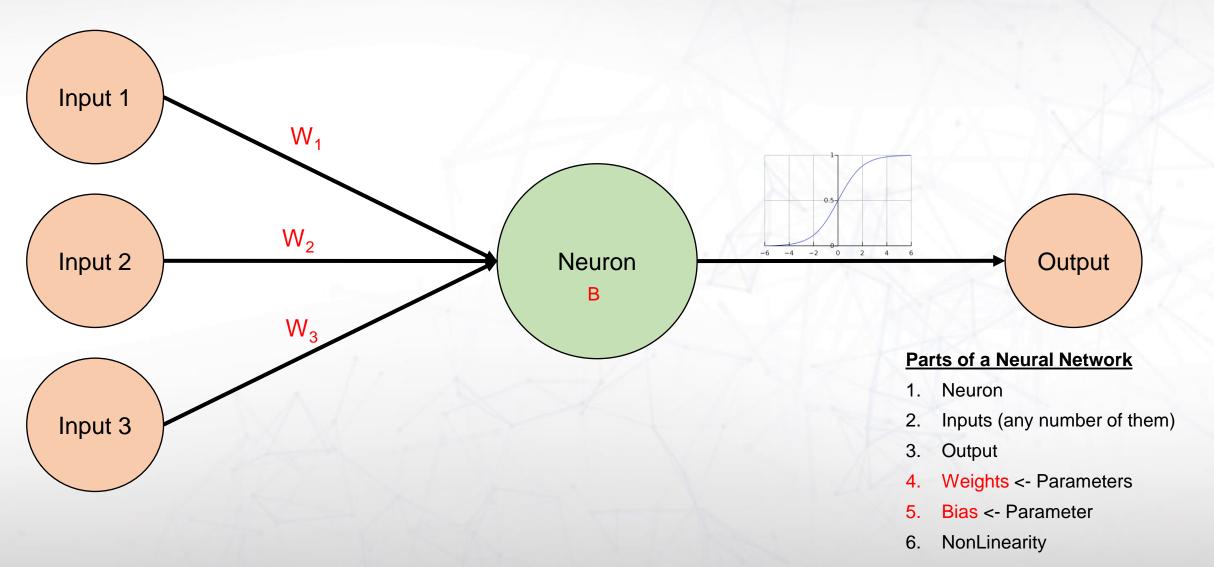




Getting Deeper with Neural Networks

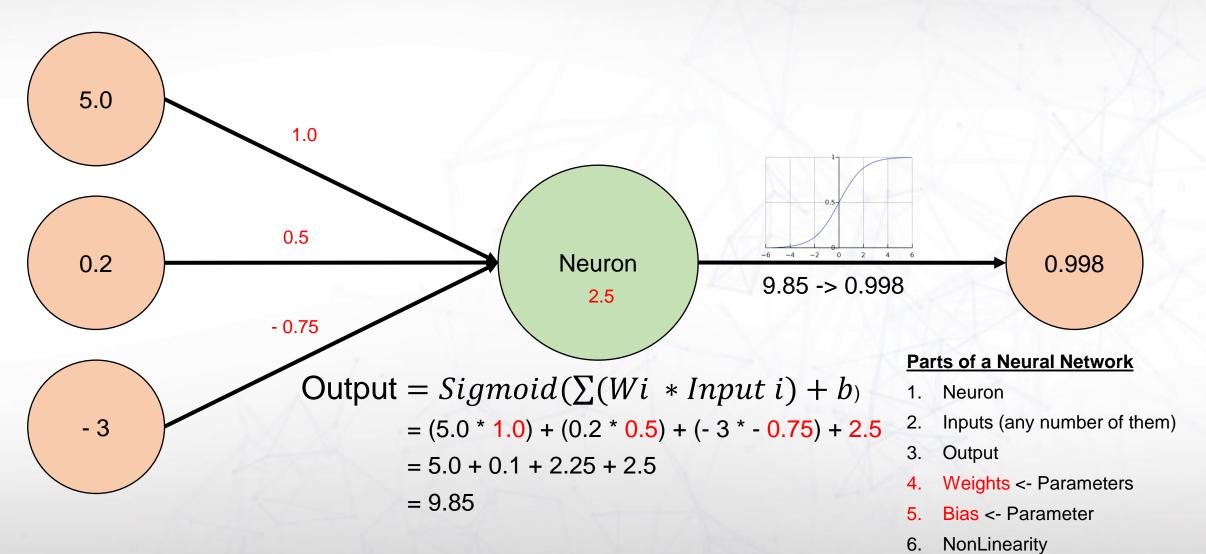
The Neuron





The Neuron





Remember: Parameters are just numbers

If one neuron is strong, thousands are stronger



How sunny is it today?

Value -1 -> raining

Value 1 -> sunny

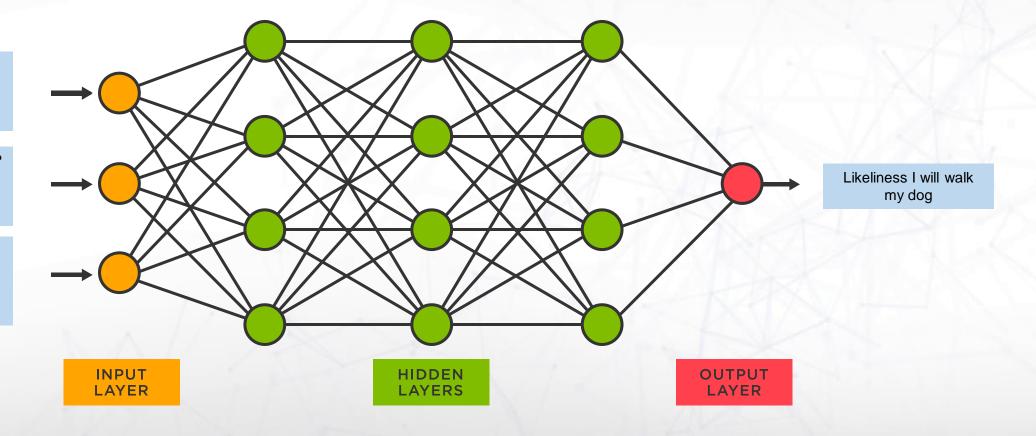
Do I feel Like Walking?

Value -1 -> no

Value 1 -> yes

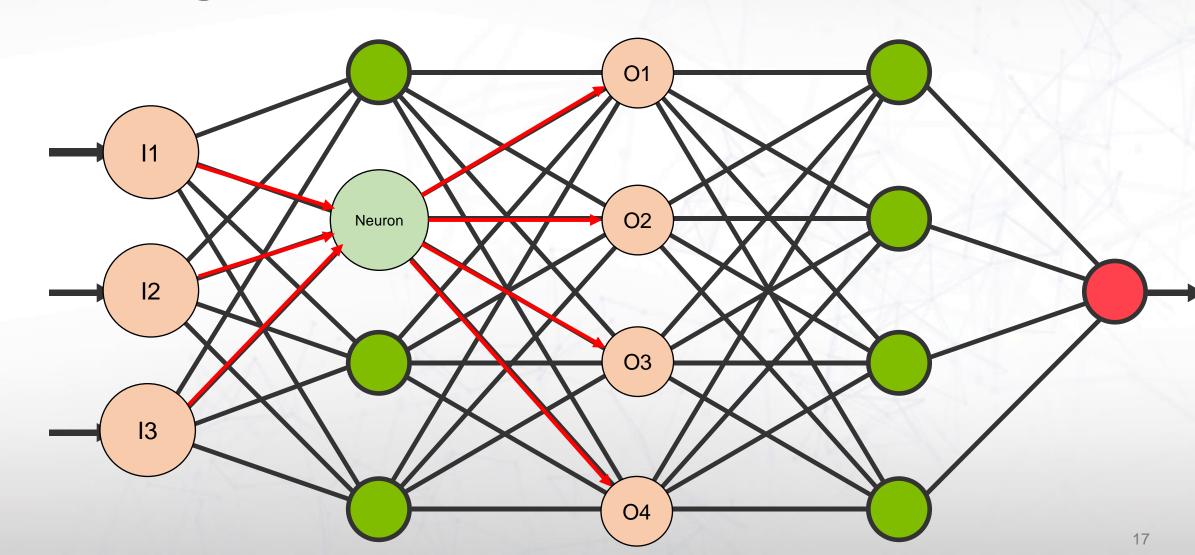
Is the dog at
Grandma's right now?
Value 0 -> no

Value 1 -> yes



If one neuron is strong, thousands are stronger





Using PyTorch to define models



```
self.layer1 = torch.nn.Linear(24, 1000)
self.layer2 = torch.nn.Linear(1000, 500)
self.layer3 = torch.nn.Linear(500, 200)
self.layer4 = torch.nn.Linear(500, 200)
self.layer5 = torch.nn.Linear(200, 1)
```

This neural net has 5 layers.

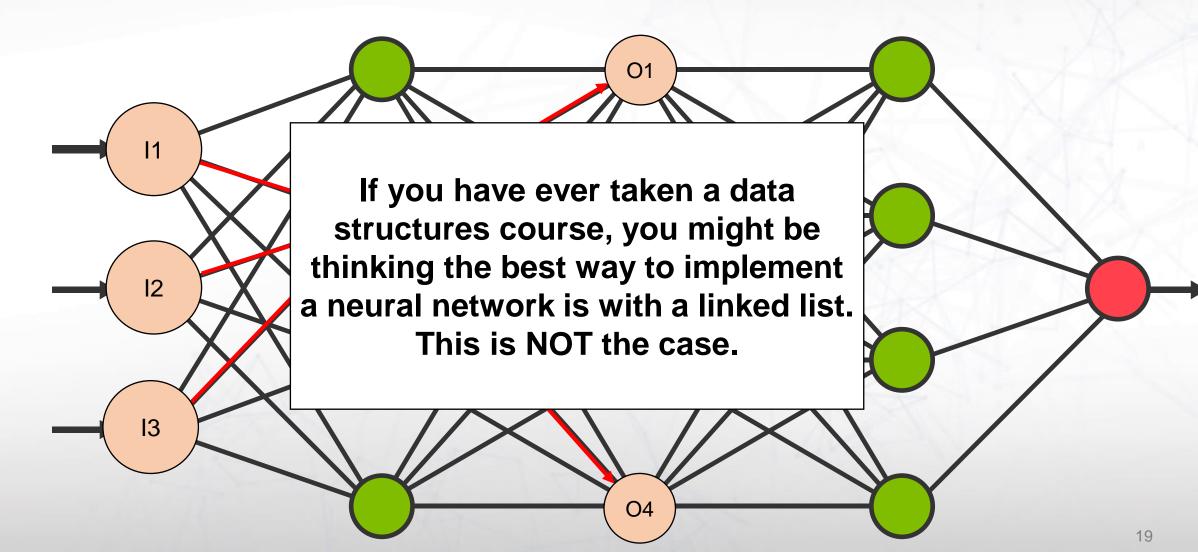
- 1. Activation layer with 24 inputs
- 2. Hidden layer of dimension 1000
- 3. Hidden layer of dimension 500
- 4. Hidden layer of dimension 200
- 5. Singular output layer

Notice how PyTorch focuses on layers of neural networks instead of neurons instead.

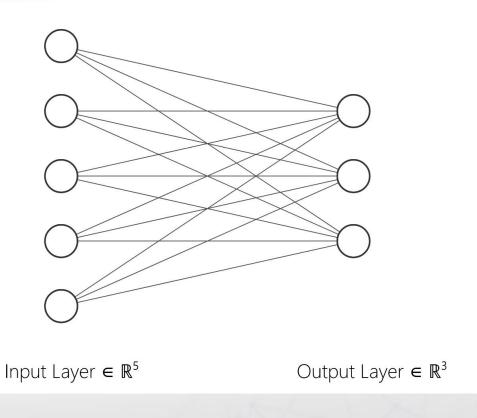
We will be investigating why this is by creating our own version of torch.nn.Linear(input_dim, output_dim)

If one neuron is strong, thousands are stronger



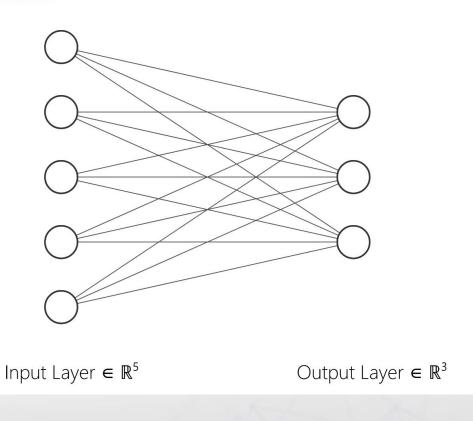






This network has 5 inputs and 3 outputs

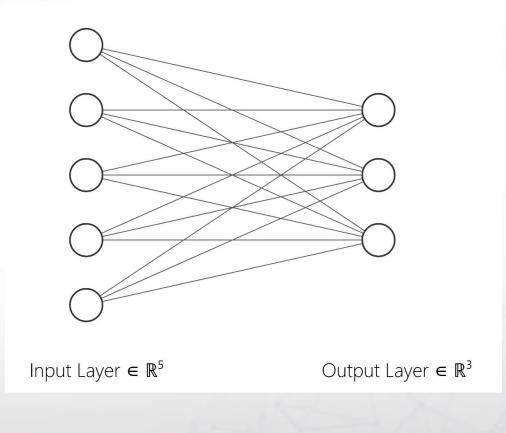




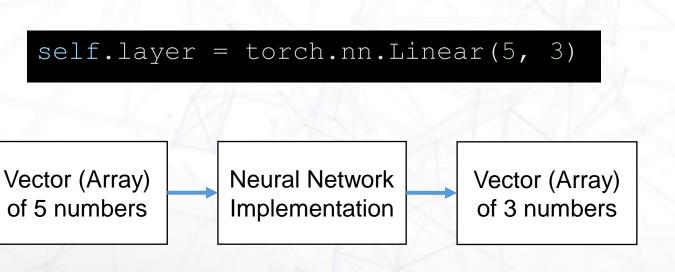
This network has 5 inputs and 3 outputs

self.layer = torch.nn.Linear(5, 3)

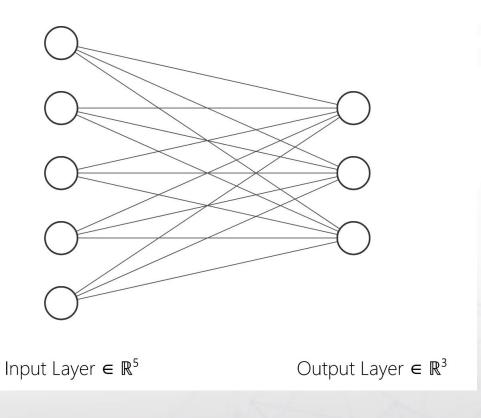


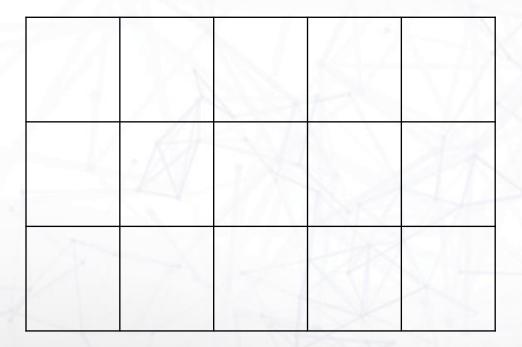


This network has 5 inputs and 3 outputs

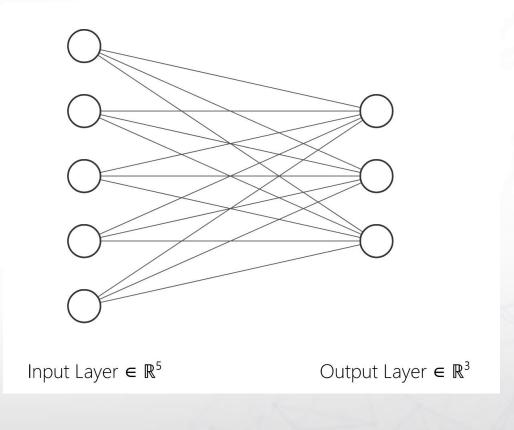


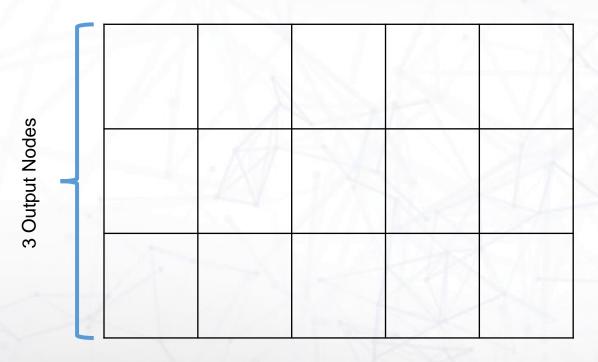




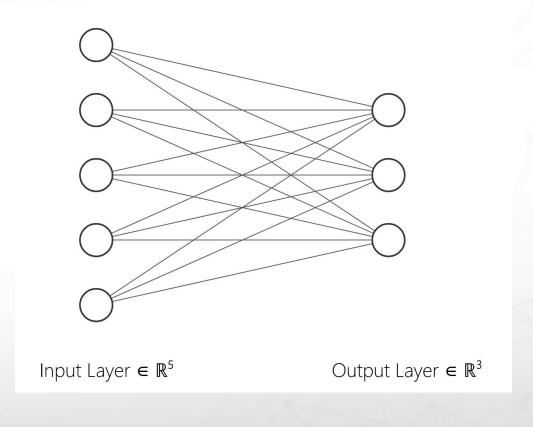


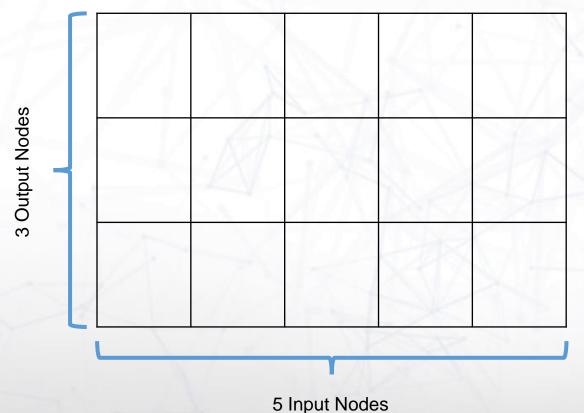




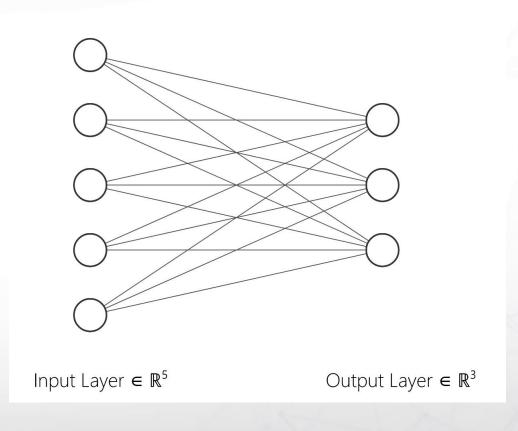




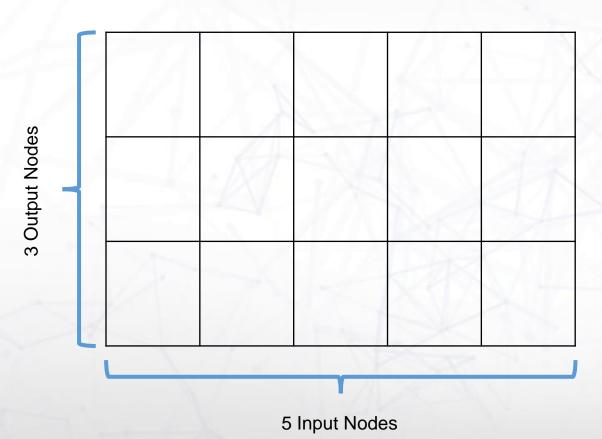






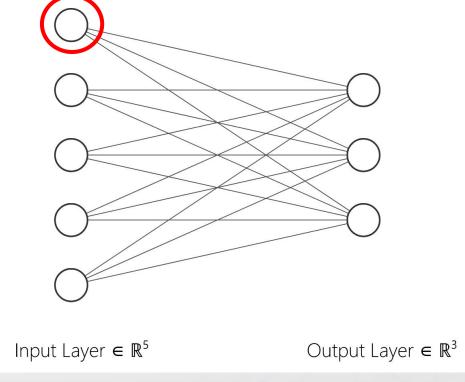


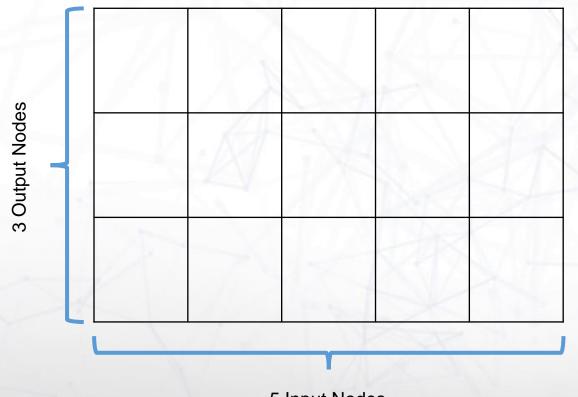
$\mathbf{M} \in \mathbb{R}^{3 \times 5}$





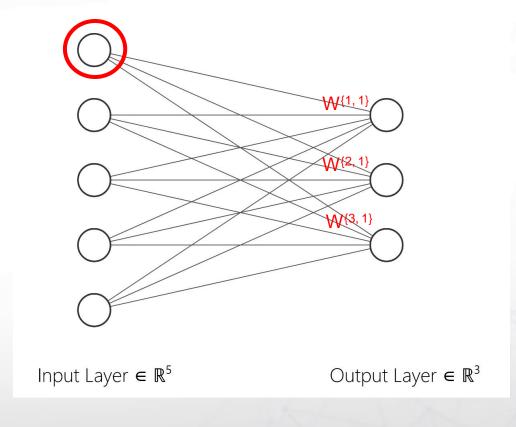








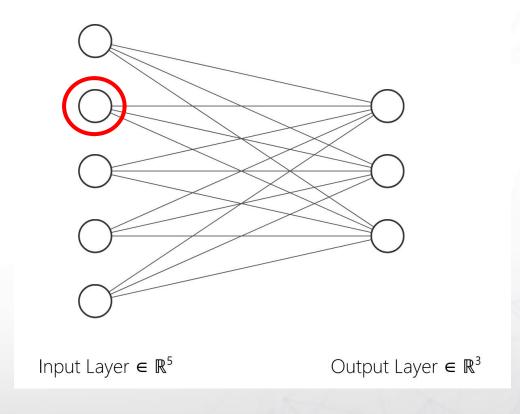








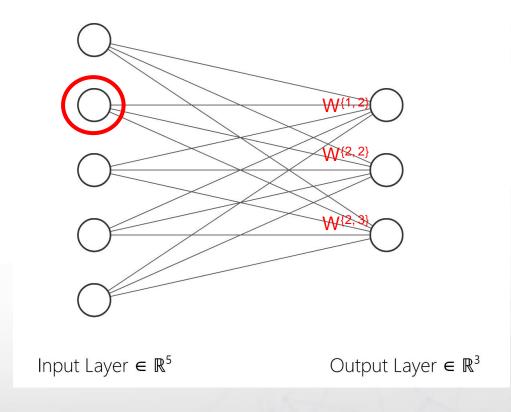


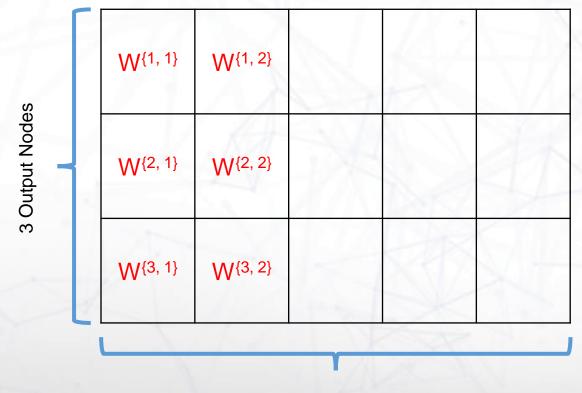






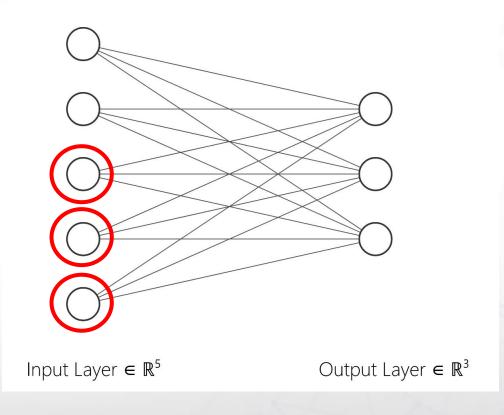


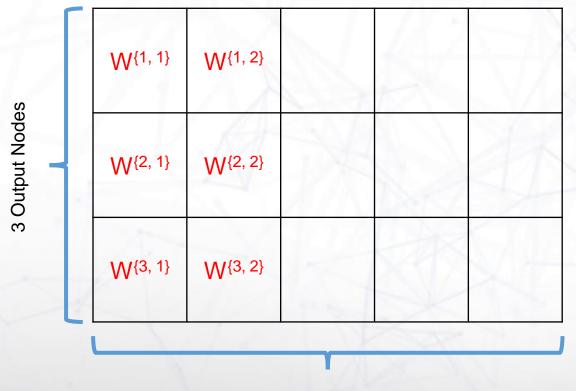






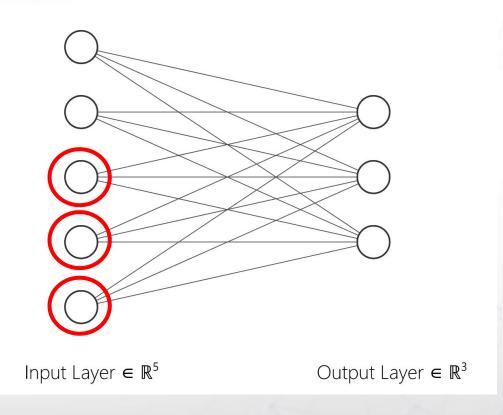


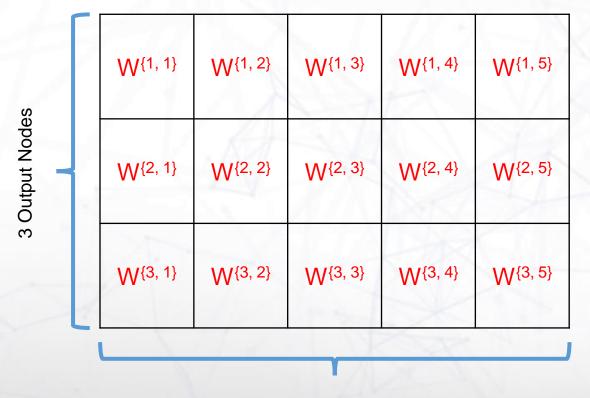












5 Input Nodes

W{Output Node Number, Input Node Number}

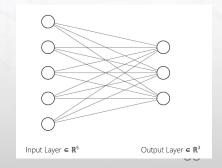


 $\mathbf{v} \in \mathbb{R}^{1 \times 5}$

 $\mathbf{M} \in \mathbb{R}^{3 \times 5}$

Input₁
Input ₂
Input ₃
Input ₄
Input ₅

W{1, 1}	W {1, 2}	W {1, 3}	W{1, 4}	W {1, 5}
W {2, 1}	W {2, 2}	W {2, 3}	W {2, 4}	W {2, 5}
W {3, 1}	W {3, 2}	W {3, 3}	W {3, 4}	W {3, 5}





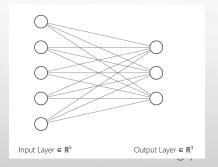
v ∈ R^{1 x 5}

 $\mathbf{M} \in \mathbb{R}^{3 \times 5}$

Input₁
Input₂
Input₃
Input₄

W{1, 1}	W{1, 2}	W{1, 3}	W{1, 4}	W{1, 5}
W {2, 1}	W {2, 2}	W{2, 3}	W{2, 4}	W {2, 5}
W {3, 1}	W {3, 2}	W {3, 3}	W{3, 4}	W {3, 5}

Transpose
Operator
(Flipping
the axis)



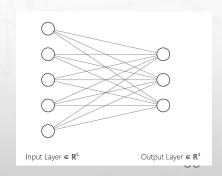


ν ε R^{1 x 5}

 $\mathbf{M} \in \mathbb{R}^{5 \times 3}$

Input₁
Input₂
Input₃
Input₄

X





 $\mathbf{v} \in \mathbb{R}^{1 \times 5}$

 $\mathbf{M} \in \mathbb{R}^{5 \times 3}$

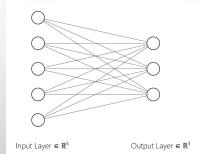
 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input₂
Input₃
Input₄

X

W{1, 1}	W {2, 1}	W {3, 1}
W {1, 2}	W {2, 2}	W {3, 2}
W {1, 3}	W {2, 3}	W {3, 3}
W{1, 4}	W {2, 4}	W{3, 4}
W ^{1, 5}	W {2, 5}	W {3, 5}







ν ε R^{1 x 5}

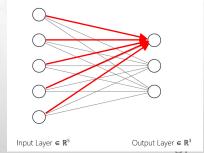
 $M \in \mathbb{R}^{5 \times 3}$

 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input₂
Input₃
Input₄

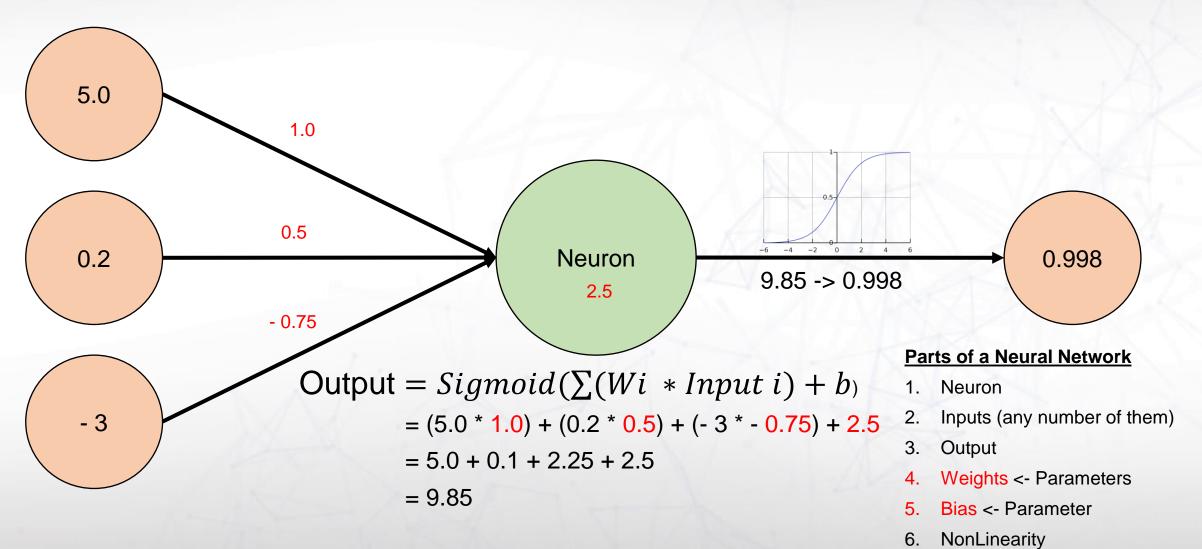
X

 $I_1W^{\{1, 1\}} + I_2W^{\{1, 2\}} + I_3W^{\{1, 3\}} + I_4W^{\{1, 4\}} + I_5W^{\{1, 5\}}$



The Neuron





Remember: Parameters are just numbers



ν ε R^{1 x 5}

 $M \in \mathbb{R}^{5 \times 3}$

 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input₂
Input₃
Input₄

X

 W{1, 1}
 W{2, 1}
 W{3, 1}

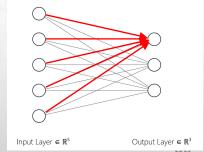
 W{1, 2}
 W{2, 2}
 W{3, 2}

 W{1, 3}
 W{2, 3}
 W{3, 3}

 W{1, 4}
 W{2, 4}
 W{3, 4}

 W{1, 5}
 W{2, 5}
 W{3, 5}

 $I_1W^{\{1, 1\}} + I_2W^{\{1, 2\}} + I_3W^{\{1, 3\}} + I_4W^{\{1, 4\}} + I_5W^{\{1, 5\}}$





ν ε R^{1 x 5}

 $\mathbf{M} \in \mathbb{R}^{5 \times 3}$

 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input₂
Input₃
Input₄

X

 W{1, 1}
 W{2, 1}
 W{3, 1}

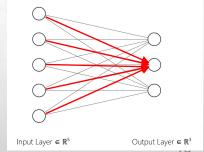
 W{1, 2}
 W{2, 2}
 W{3, 2}

 W{1, 3}
 W{2, 3}
 W{3, 3}

 W{1, 4}
 W{2, 4}
 W{3, 4}

 W{1, 5}
 W{2, 5}
 W{3, 5}

 $I_{1}W^{\{1, 1\}} + I_{2}W^{\{1, 2\}} + I_{3}W^{\{1, 3\}} + I_{4}W^{\{1, 4\}} + I_{5}W^{\{1, 5\}}$ $I_{1}W^{\{2, 1\}} + I_{2}W^{\{2, 2\}} + I_{3}W^{\{2, 3\}} + I_{4}W^{\{2, 4\}} + I_{5}W^{\{2, 5\}}$





ν ε R^{1 x 5}

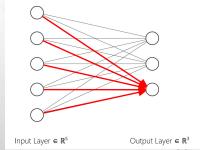
 $\mathbf{M} \in \mathbb{R}^{5 \times 3}$

 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input₂
Input₃
Input₄

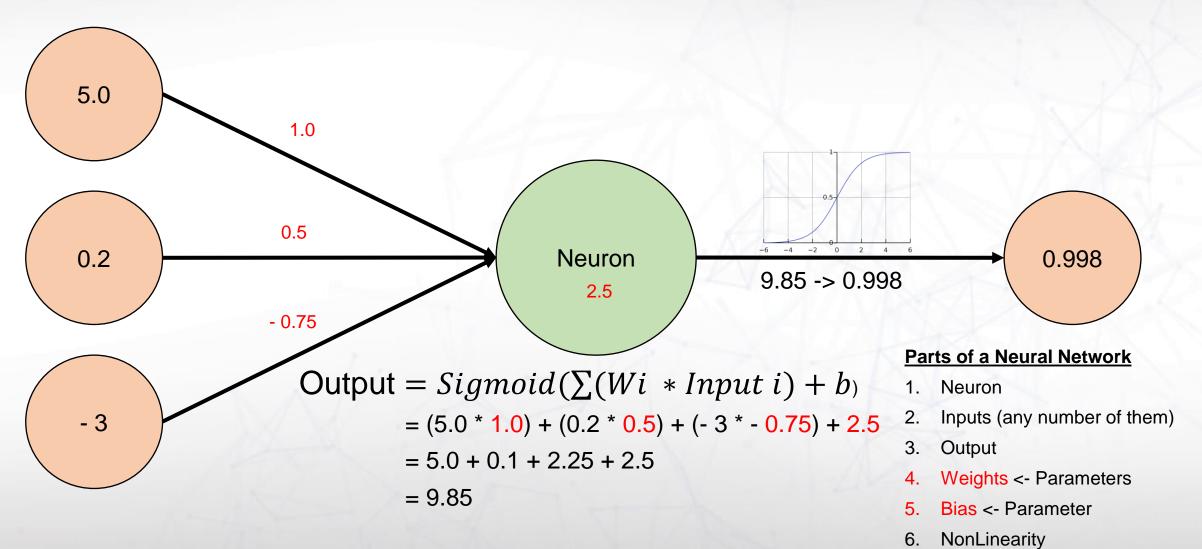
X

 $I_{1}W^{\{1, 1\}} + I_{2}W^{\{1, 2\}} + I_{3}W^{\{1, 3\}} + I_{4}W^{\{1, 4\}} + I_{5}W^{\{1, 5\}}$ $I_{1}W^{\{2, 1\}} + I_{2}W^{\{2, 2\}} + I_{3}W^{\{2, 3\}} + I_{4}W^{\{2, 4\}} + I_{5}W^{\{2, 5\}}$ $I_{1}W^{\{3, 1\}} + I_{2}W^{\{3, 2\}} + I_{3}W^{\{3, 3\}} + I_{4}W^{\{3, 4\}} + I_{5}W^{\{3, 5\}}$



The Neuron





Remember: Parameters are just numbers



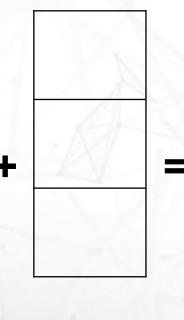
 $\mathbf{v} \in \mathbb{R}^{1 \times 5}$

 $M \in \mathbb{R}^{5 \times 3}$

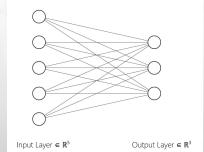
 $\mathbf{v} \in \mathbb{R}^3$

Input₁
Input ₂
Input ₃
Input ₄
Input ₅

W {1, 1}	W{2, 1}	W {3, 1}
W {1, 2}	W{2, 2}	W {3, 2}
W {1, 3}	W{2, 3}	W {3, 3}
W {1, 4}	W{2, 4}	W {3, 4}
W {1, 5}	W {2, 5}	W {3, 5}



$I_1W^{\{1, 1\}} + I_2W^{\{1, 2\}} + I_3W^{\{1, 3\}} + I_4W^{\{1, 4\}} + I_5W^{\{1, 5\}}$	
$I_1W^{\{2, 1\}} + I_2W^{\{2, 2\}} + I_3W^{\{2, 3\}} + I_4W^{\{2, 4\}} + I_5W^{\{2, 5\}}$	
$I_1W^{\{3, 1\}} + I_2W^{\{3, 2\}} + I_3W^{\{3, 3\}} + I_4W^{\{3, 4\}} + I_5W^{\{3, 5\}}$	





 $\mathbf{v} \in \mathbb{R}^{1 \times 5}$

 $\mathbf{M} \in \mathbb{R}^{5 \times 3}$

 $\mathbf{v} \in \mathbb{R}^3$

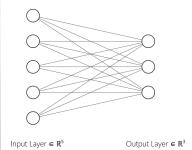
Input ₁
Input ₂
Input ₃
Input ₄
Input ₅

X

B₁
B₂
B₃

+

 $I_{1}W^{\{1, 1\}} + I_{2}W^{\{1, 2\}} + I_{3}W^{\{1, 3\}} + I_{4}W^{\{1, 4\}} + I_{5}W^{\{1, 5\}} + B_{1}$ $I_{1}W^{\{2, 1\}} + I_{2}W^{\{2, 2\}} + I_{3}W^{\{2, 3\}} + I_{4}W^{\{2, 4\}} + I_{5}W^{\{2, 5\}} + B_{2}$ $I_{1}W^{\{3, 1\}} + I_{2}W^{\{3, 2\}} + I_{3}W^{\{3, 3\}} + I_{4}W^{\{3, 4\}} + I_{5}W^{\{3, 5\}} + B_{3}$



In summary...



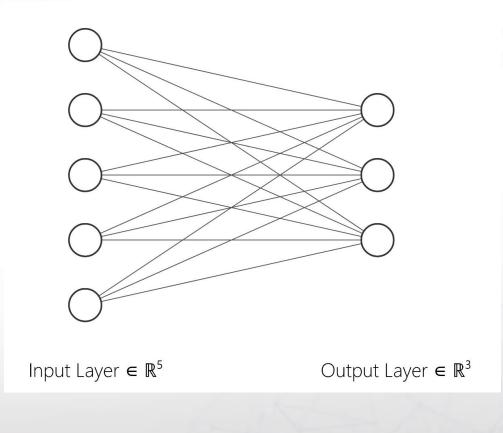
$$y = xA^T + b$$

Why do we use matrix multiplication?

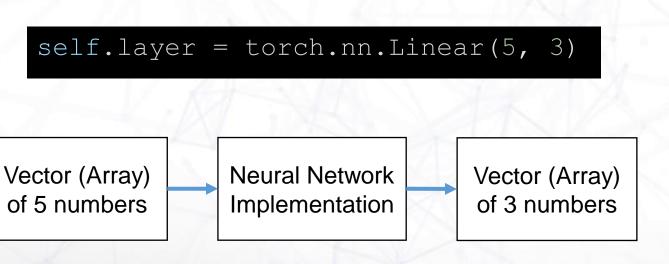


1.It's fast2.It's easily differentiable3.It produces the same results as a series of linked lists

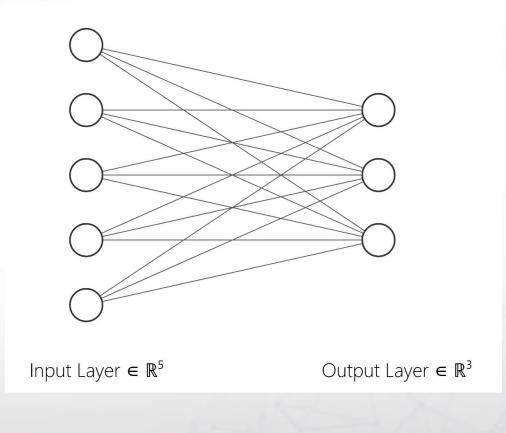




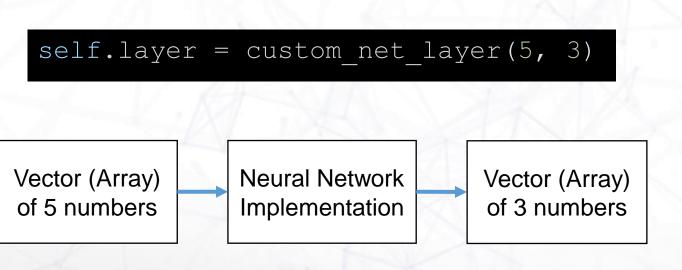
This network has 5 inputs and 3 outputs







This network has 5 inputs and 3 outputs



Initializing and basic operations

A tensor can be constructed from a Python list or sequence using the torch.tensor() constructor:

WARNING

h.html#torch.Tensor.detach

torch.tensor() always copies data. If you have a Tensor data and just want to change its requires_grad
flag, use requires_grad_() or detach() to avoid a copy. If you have a numpy array and want to avoid a copy,
use torch.as_tensor().

A tensor of specific data type can be constructed by passing a torch.dtype and/or a torch.device to a constructor or tensor creation op:





Classification Loss

A new kind of loss function



Week 1 & 2:

Question:

Given a cost weight, what **number** should the cow's cost be?

Given information about a diamond, what **number** should the diamond's value be

How We Approach the Loss:

Model's Prediction vs Ground Truth:

We need to make the model's prediction as close to the ground truth as possible.

MSE =
$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

A new kind of loss function



Week 1 & 2:

Question:

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How We Approach the Loss:

Model's Prediction vs Ground Truth:

We need to make the model's prediction as close to the ground truth as possible.

MSE =
$$\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y}_i)^2$$

Week 3:

Question:

Given a list of pixels, which number do those pixels correlate to

How We Approach the Loss:

Model's Prediction vs Ground Truth:

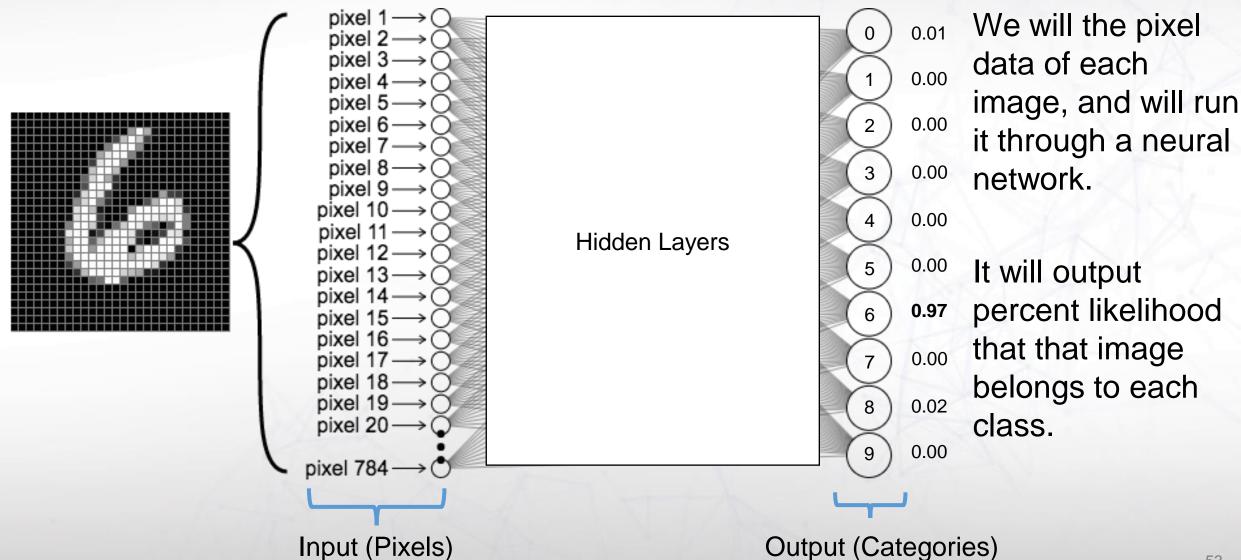
Model will output 10 different numbers correlating to the likelihood it believes the picture to belong to a certain classification.

We need to compare that to the image's actual label

CrossEntropy Loss

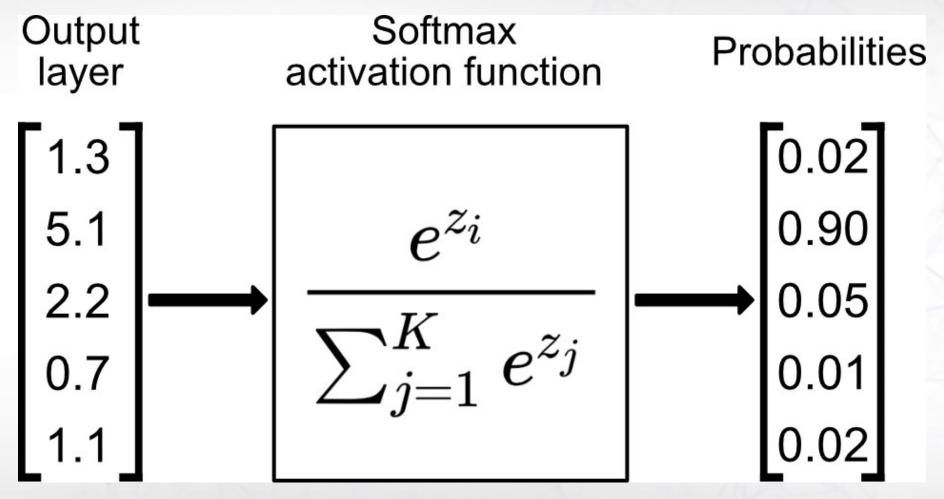
How we going to tackle this problem





What is SoftMax

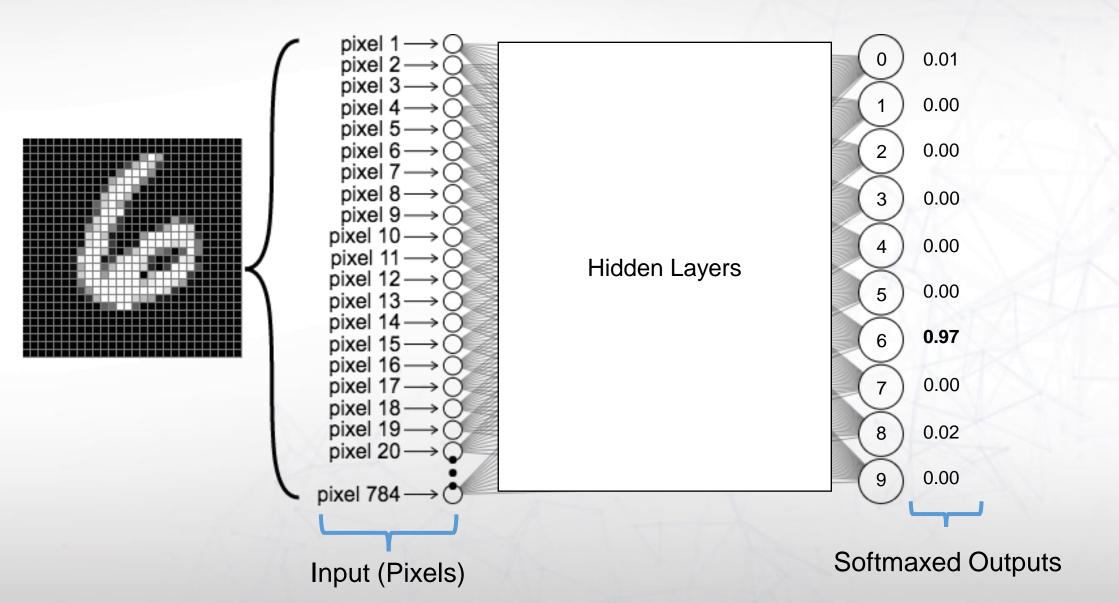




Models can output a large range of numbers, the SoftMax function will transform those values into "percentages". They will all add up to 1. This is how we will evaluate what class the images belong to.

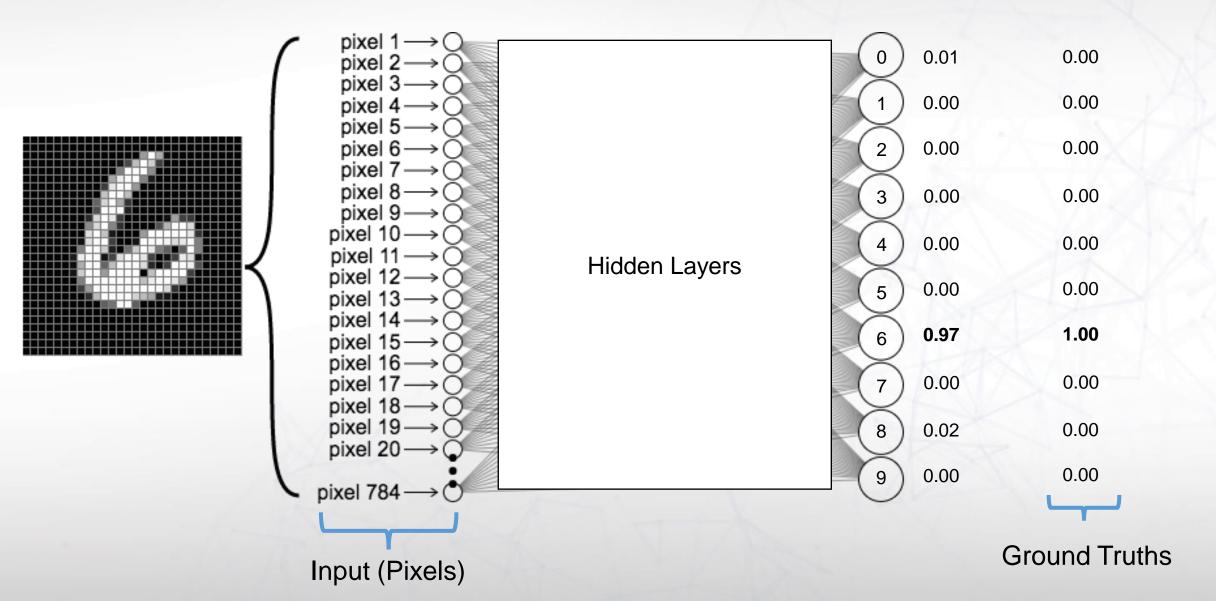
How we going to tackle this problem



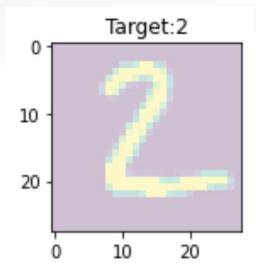


How we going to tackle this problem





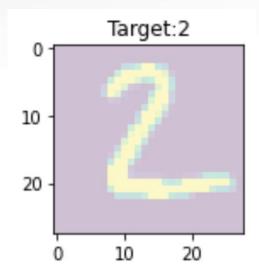




This correlates to a "number 2". We can also see that the model has done a very poor job of classifying it

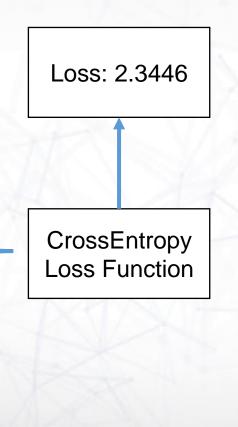
#	Model Prediction	Ground Truth
0.	0.10	0.00
1.	0.10	0.00
2.	0.10	1.00
3.	0.10	0.00
4.	0.10	0.00
5.	0.10	0.00
6.	0.10	0.00
7.	0.10	0.00
8.	0.10	0.00
9.	0.10	0.00



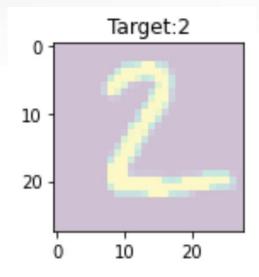


This correlates to a "number 2". We can also see that the model has done a very poor job of classifying it

#	Model Prediction	Ground Truth
0.	0.10	0.00
1.	0.10	0.00
2.	0.10	1.00
3.	0.10	0.00
4.	0.10	0.00
5.	0.10	0.00
6.	0.10	0.00
7.	0.10	0.00
8.	0.10	0.00
9.	0.10	0.00

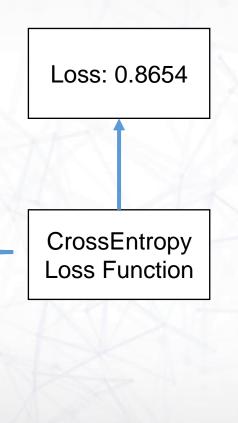




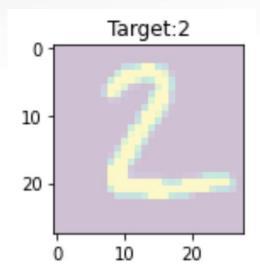


The model is now doing a better job at predicting "2", but it could be better.

#	Model Prediction	Ground Truth
0.	0.12	0.00
1.	0.11	0.00
2.	0.46	1.00
3.	0.01	0.00
4.	0.03	0.00
5.	0.04	0.00
6.	0.10	0.00
7.	0.03	0.00
8.	0.05	0.00
9.	0.05	0.00

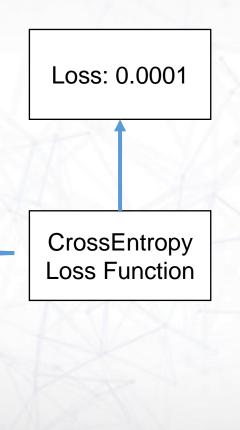






The model does an amazing job predicting "2"

#	Model Prediction	Ground Truth
0.	0.00	0.00
1.	0.00	0.00
2.	0.99	1.00
3.	0.00	0.00
4.	0.00	0.00
5.	0.01	0.00
6.	0.00	0.00
7.	0.00	0.00
8.	0.00	0.00
9.	0.00	0.00





$$\ell(x,y) = L = \{l_1,\ldots,l_N\}^ op, \quad l_n = -\sum_{c=1}^C w_c \log rac{\exp(x_{n,c})}{\exp(\sum_{i=1}^C x_{n,i})} y_{n,c} \}$$

The CrossEntropy Loss function is quite involved and tough to understand. CrossEntropy loss will be provided to you when coding today.

Even though it is a tough function it shares many of the same properties as other loss functions you are comfortable with.

- 1. A more incorrect algorithm will create a high level of loss on average
- 2. A more correct algorithm will create a low level of loss on average
- 3. The optimizer's job is to minimize loss in the model

You should also understand it's purpose; Namely, in classification problems.



Mini-Batching



- 1. Initialize your model. Randomly assign your parameters a value.
- 2. Grab a single entry from the dataset. An input and the ground truth associated with that input.
- 3. Take that input and put it through the model and save the result.
- 4. Use the loss function to measure how different the result is from the ground truth.
- 5. Give the OPTIMIZER, it will then measure how it needs to change the parameters (numbers we change to get a desired result).
- 6. Repeat steps 2-5 many many times, until the model can perform the task you are asking it to do





- 1. Initialize your model. Randomly assign your parameters a value.
- 2. Grab a minibatch of data from the dataset. A few inputs and their associated groundtruths with those inputs.
- 3. Take the inputs and put it through the model and save the results.
- 4. Use the loss function to measure how different the results are from the ground truths.
- 5. Give the OPTIMIZER, it will then measure how it needs to change the parameters (numbers we change to get a desired result).
- 6. Repeat steps 2-5 many many times, until the model can perform the task you are asking it to do

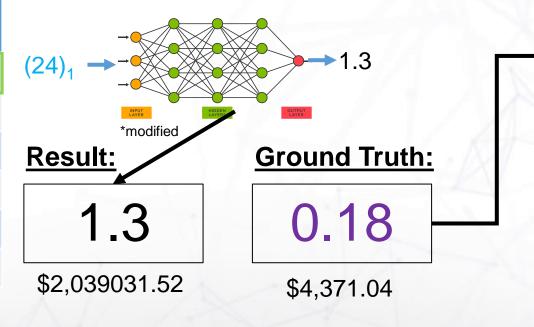




Dataset:

Price of Diamond	Input Features
0.18	(24) ₁
0.52	(24) ₂
1.00	$(24)_3$
0.00	$(24)_4$
0.35	(24) ₅

Model:



Loss Function (measure of model success):

L = (Result – Ground Truth)² L = $(1.3 - 0.18)^2$ L = 1.254

OPTIMIZER:

The OPTIMIZER will look at the loss, and use it to determine how to adjust the models parameters. We want the loss to be small and the model will try and reduce it for us.

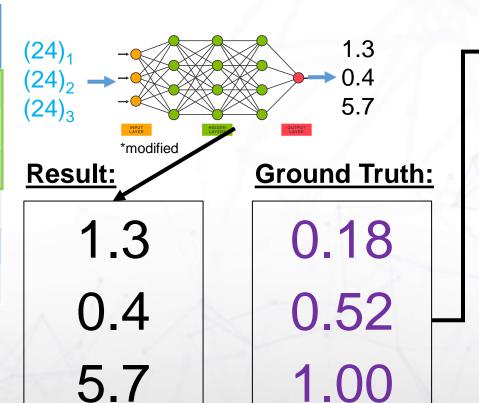


L = (Result -

Dataset:

Price of Diamond	Input Features
0.18	(24) ₁
0.52	(24) ₂
1.00	(24) ₃
0.00	(24) ₄
0.35	(24) ₅

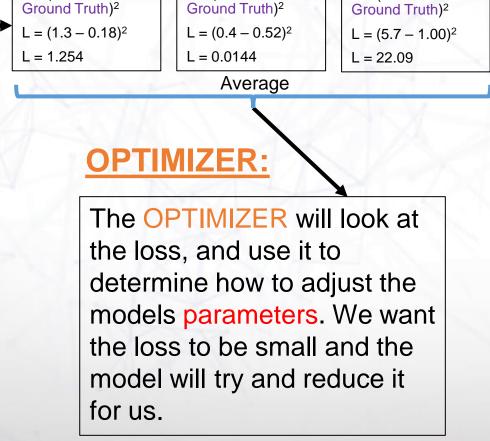
Model:



Loss Function (measure of model success):

L = (Result -

L = (Result -



Why Use Mini-Batching?

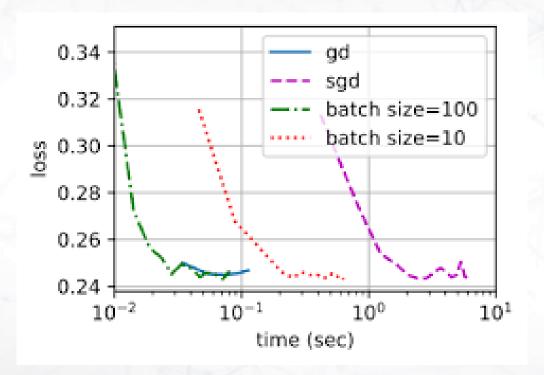


Mini-Batching is done to make training **FASTER.**

The same data is being inputted, and each piece of data in the batch is independent from the other pieces of data. As a result, the model will still learn the same way.

However, instead of calculating loss and optimizing on every piece of data, it does it in bunches, speeding the process up.

The standard length of a batch is 32. But, it can very depending on a number of factors.





Saving and Loading Model

PyTorch Makes Saving and Loading Easy



```
Save:
  torch.save(model.state dict(), PATH)
Load:
  model = TheModelClass(*args, **kwargs)
  model.load state dict(torch.load(PATH))
  model.eval()
```

PyTorch makes it easy to train once, and to test multiple times. Often, models are saved after every couple of epochs. State_dict() refers to the model's state dictionary, which contains the parameters for the model.



The Deep Learning Flow

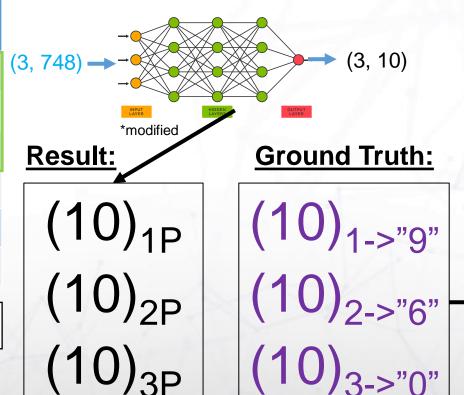


Dataset:

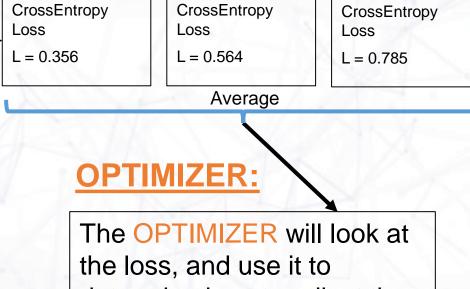
Image Label	Input Features
"9"	(1, 28, 28) ₁
"6"	$(1, 28, 28)_2$
"0"	$(1, 28, 28)_3$
"4"	(1, 28, 28) ₄
"9"	(1, 28, 28) ₅

Mini-Batch Size: 3

Model:



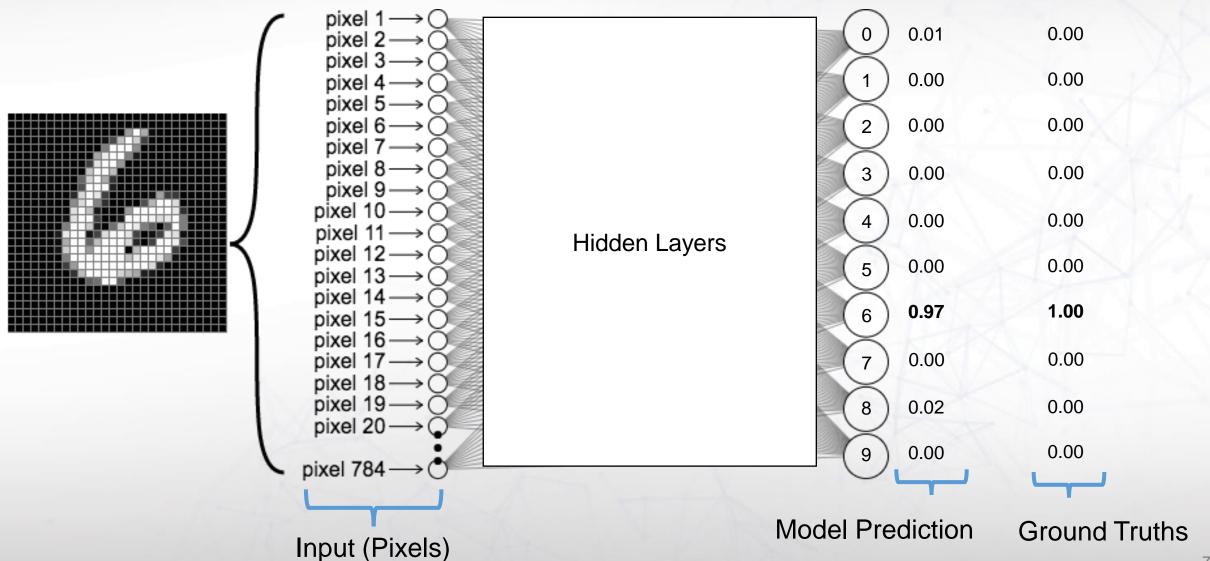
Loss Function (measure of model success):



the OPTIMIZER will look at the loss, and use it to determine how to adjust the models parameters. We want the loss to be small and the model will try and reduce it for us.

How we going to tackle this problem







CrossEntropy

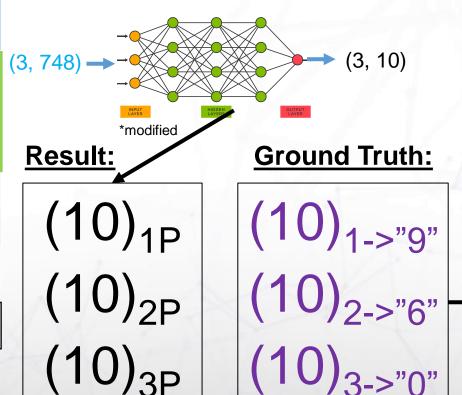
Loss

Dataset:

Image Label	Input Features
"9"	(1, 28, 28) ₁
"6"	$(1, 28, 28)_2$
"0"	$(1, 28, 28)_3$
"4"	(1, 28, 28) ₄
"9"	(1, 28, 28) ₅

Mini-Batch Size: 3

Model:



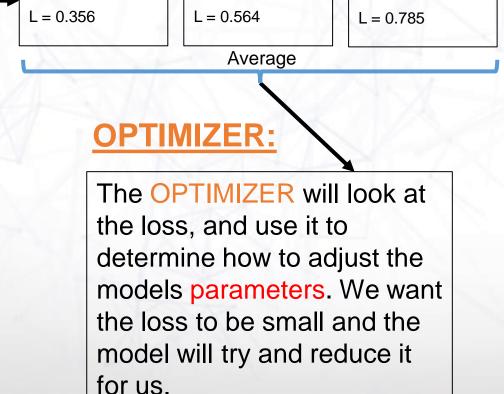
Loss Function (measure of model success):

CrossEntropy

Loss

CrossEntropy

Loss



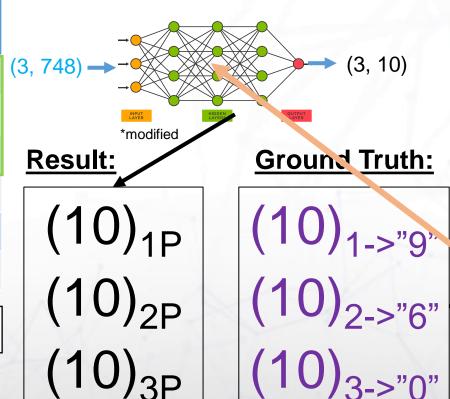


Dataset:

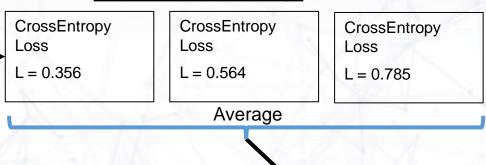
Image Label	Input Features
"9"	(1, 28, 28) ₁
"6"	(1, 28, 28) ₂
"0"	$(1, 28, 28)_3$
"4"	(1, 28, 28) ₄
"9"	(1, 28, 28) ₅

Mini-Batch Size: 3

Model:



Loss Function (measure of model success):



OPTIMIZER:

The OPTIMIZER will look at the loss, and use it to determine how to adjust the models parameters. We want the loss to be small and the model will try and reduce it for us.



CrossEntropy

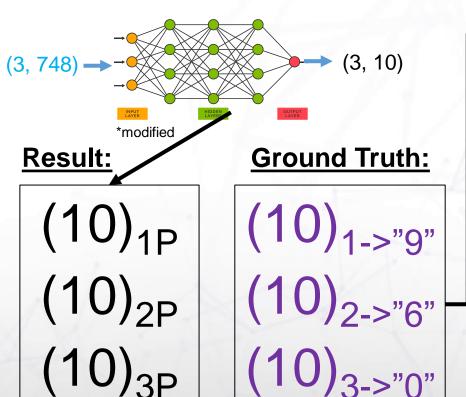
Loss

Dataset:

Image Label	Input Features
"9"	(1, 28, 28) ₁
"6"	(1, 28, 28) ₂
"0"	$(1, 28, 28)_3$
"4"	(1, 28, 28) ₄
"9"	(1, 28, 28) ₅

Mini-Batch Size: 3

Model:



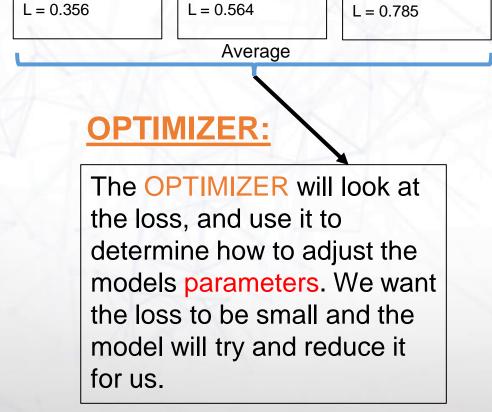
Loss Function (measure of model success):

CrossEntropy

Loss

CrossEntropy

Loss





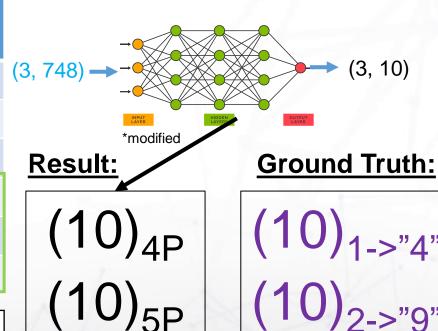
Dataset:

Image Label	Input Features
"9"	$(1, 28, 28)_1$
"6"	(1, 28, 28) ₂
"0"	(1, 28, 28) ₃
"4"	(1, 28, 28) ₄
"9"	(1, 28, 28) ₅

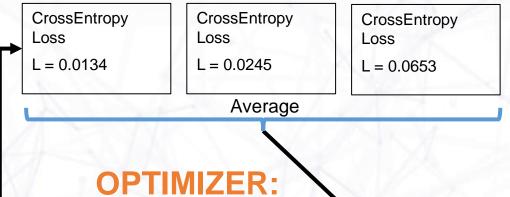
Mini-Batch Size: 3

Model:

 $(10)_{6P}$



Loss Function (measure of model success):



The OPTIMIZER will look at the loss, and use it to determine how to adjust the models parameters. We want the loss to be small and the model will try and reduce it for us.

