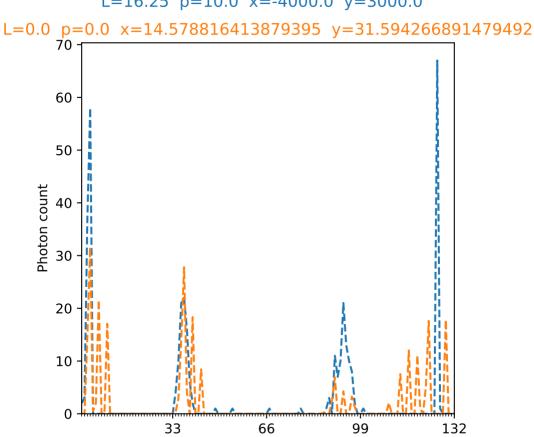
L=16.25 p=10.0 x=-4000.0 y=3000.0



Detector position