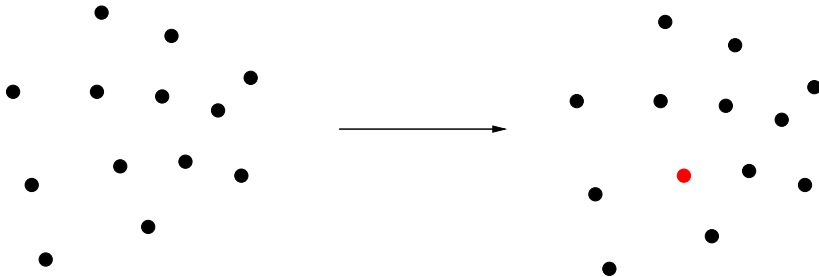


# Leader Election in Swarms of Deterministic Robots

Franck Petit

LiP6, UPMC Paris 6

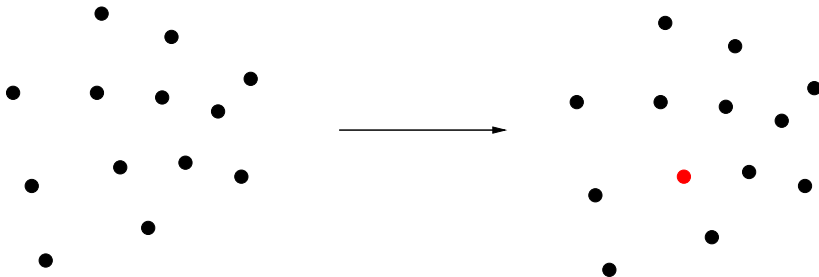
# Problem



## Question

Given a swarm of  $n$  robots, what are the **minimal geometric conditions** to be able to **deterministically** agree on a single robot?

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# Previous Works

## SoD and Chirality

[Flocchini et al., 1999]

A solution exists for **any  $n$** .

## SoD and No Chirality

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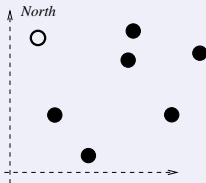
A solution exists if  **$n$  is odd**.

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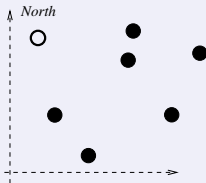
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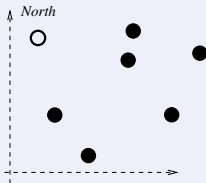
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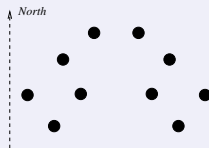
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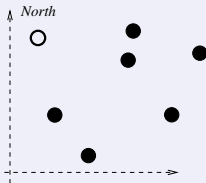


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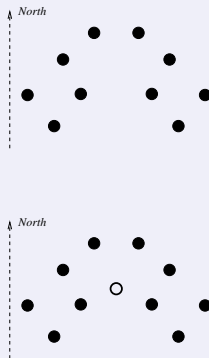
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# Previous Works

No SoD

[\[Prencipe 2002\]](#)

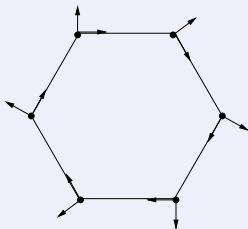
Impossible in general.

# Previous Works

## No SoD

[Prencipe 2002]

Impossible in general.



In such a configuration, it is not possible to break the symmetry.

# Leader Election With No Sense of Direction

## Question

Assuming no sense of direction (with or without chirality), what are the **geometric conditions** to be able to **deterministically** agree on a single robot?

To answer to this question, we need tools from the theory on Combinatoric on Words, specifically **Lyndon Words**.

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# Lyndon Words

## Definition (Word)

Let  $A = \{a_0, a_1, \dots, a_n\}$  be an alphabet. A word is a (possibly empty) sequence of letters in  $A$ .

$$A = \{a, b, c, d\}$$

$$abcc \quad a \quad \epsilon \quad dddddddd \equiv d^8$$

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Let  $u = a_1, \dots, a_i, \dots, a_k$  and  $v = b_1, \dots, b_j, \dots, b_\ell$ .

The concatenation of  $u$  and  $v$ , denoted  $uv$ , is equal to the word  $a_1, \dots, a_i, \dots, a_k, b_1, \dots, b_j, \dots, b_\ell$ .

$$u = UP, v = MC, uv = UPMC$$

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# Lyndon Words

## Definition (Lexicographic Order)

Let  $A$  be an alphabet totally ordered by  $\prec$ , i.e.,  $a_0 \prec a_1 \prec \dots \prec a_n$ .

A word  $u = a_0 a_1 \dots a_s$  is said to be *lexicographically smaller than or equal to* a word  $v = b_0 b_1 \dots b_t$ , denoted by  $u \preceq v$ , iff:

- either  $u$  is a prefix of  $v$ ,
- or,  $\exists k : \forall i \in [1, \dots, k-1], a_i = b_i$  and  $a_k \prec b_k$ .

 $ab \preceq abc$ 
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A word  $u$  is said to be *primitive* iff  $u = v^k \Rightarrow k = 1$ . Otherwise,  $u$  is said to be *periodic*.

### Primitive Words

 $ab$  $dabcbc$  $dcba$ 

### Periodic Words

 $d^8$  $bcbc$  $\epsilon$

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A word  $u$  is said to be a *rotation* of a word  $v$  iff there exists two words  $x, y$  such that  $u = xy$  and  $v = yx$ .

$u = abcd$  and  $v = cdab$

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A word  $u$  is a *Lyndon word* iff  $u$  is **primitive and minimal**.

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$abc$  ( $abc \preceq cab$  and  $abc \preceq bca$ )

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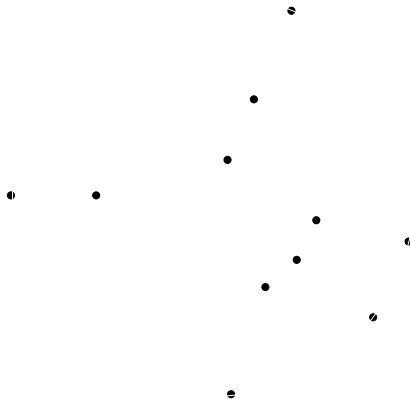
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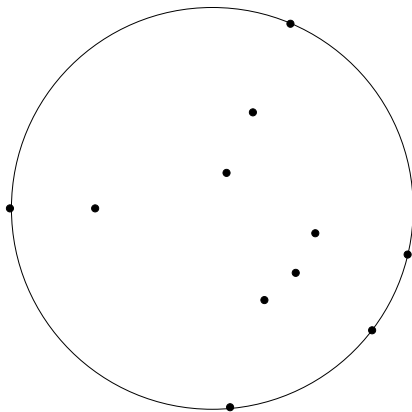
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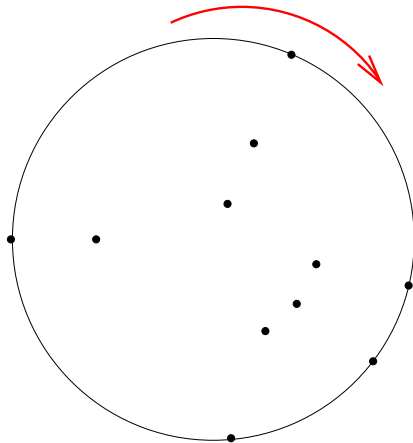
# Leader Election with Chirality



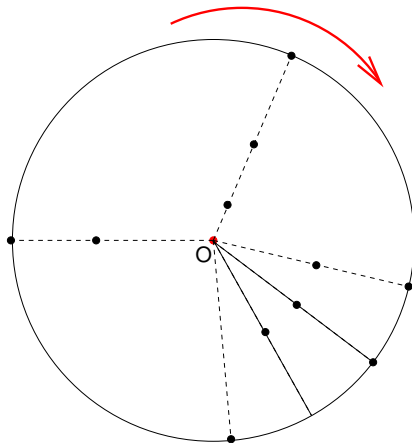
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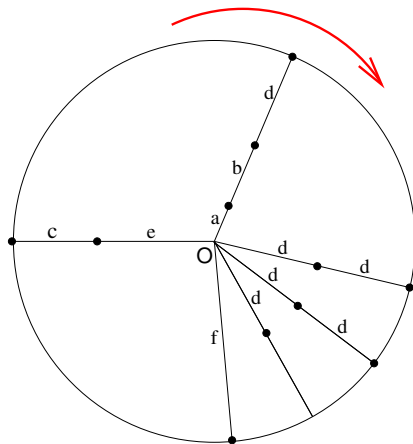
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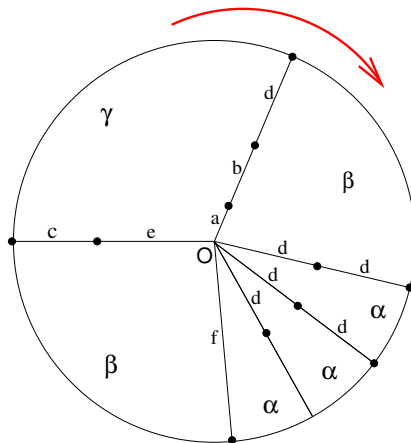
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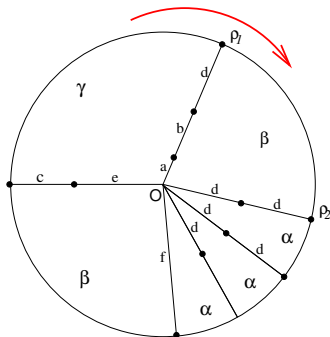
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# Leader Election with Chirality



$$W(\rho_1) = (abc, \beta)(d^2, \alpha)^2(d, \alpha)(f, \beta)(ec, \gamma)$$

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## Lemma

*If two distinct radii  $\rho_1$  and  $\rho_2$  exist such that both  $W(\rho_1)$  and  $W(\rho_2)$  are Lyndon words, then  $\forall \rho, W(\rho) = (0, 0)$ .*

## Lemma ( $\Rightarrow$ )

*If there exists a radius  $\rho$  such that  $W(\rho)$  is a **Lyndon word**, then the robots are able to **deterministically** agree on the same leader.*



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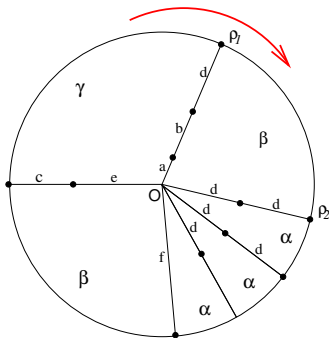
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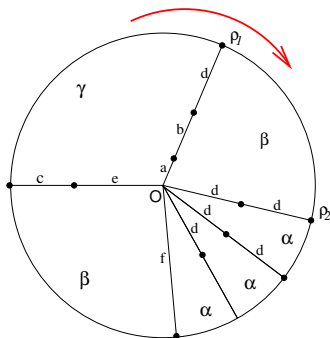
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## Lemma ( $\Leftarrow$ )

*If there exists **no** radius  $\rho$  such that  $W(\rho)$  is a **Lyndon word**, then the robots are **not** able to **deterministically** agree on the same leader.*

## Property

[Lothaire 1983]

If no rotation of a word  $u$  is a Lyndon word, then  $u$  is periodic.

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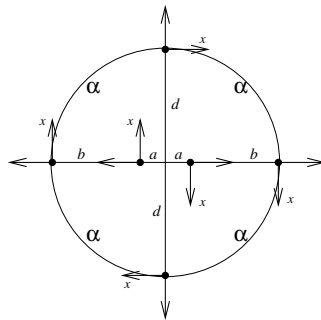
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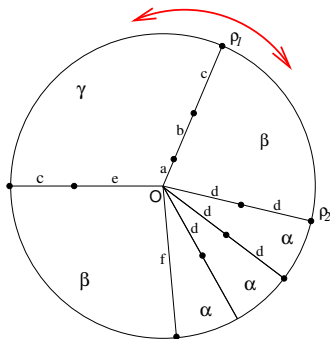
# Leader Election with Chirality

## Theorem

*Assuming **chirality**, a swarm of robots is able to **deterministically** agree on the same leader if and only if there exists a radius  $\rho$  such that  $W(\rho)$  is a **Lyndon word**.*

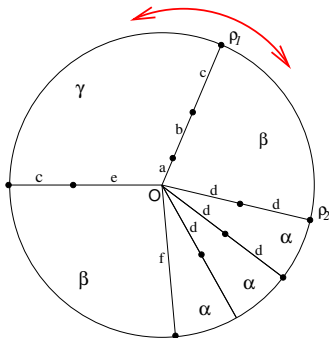
# Leader Election without Chirality

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# Leader Election without Chirality



For each  $\rho$ , there are 2 ways to compute  $W(\rho)$

$W(\rho_1) =$

either

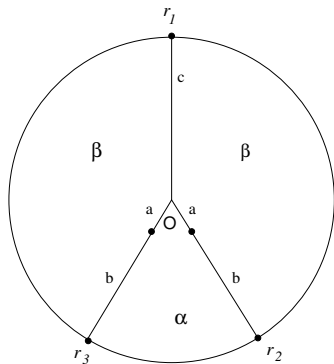
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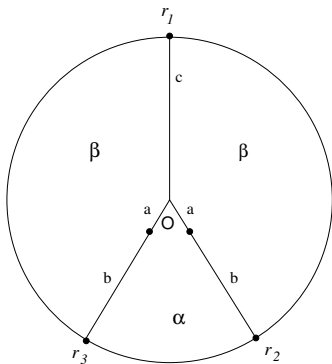
$(abc, \gamma)(ec, \beta)(f, \alpha)(d, \alpha)(d^2, \alpha)(d^2, \beta)$

depending on either  $\curvearrowright$  or  $\curvearrowleft$ , respectively.

# Leader Election without Chirality



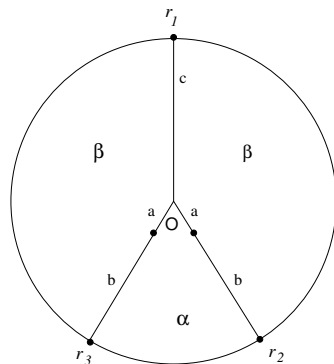
# Leader Election without Chirality



The word

$W(\rho_2)^{\circ} = W(\rho_3)^{\circ} = (ab, \alpha)(ab, \beta)(c, \beta)$  is a  
**Lyndon word**.

# Leader Election without Chirality



## Definition (Type of Symmetry)

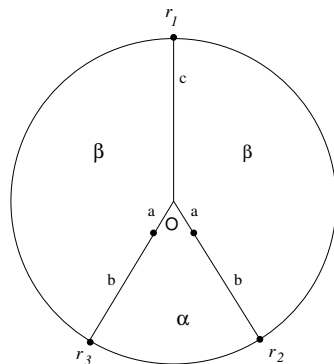
A radius  $\rho_i$  is of Type (of symmetry) **0** if there exists no radius  $\rho_j$  such that  $W(\rho_i)^\circ = W(\rho_j)^\circ$ . Otherwise,  $\rho_i$  is said to be of Type **1**.

A radius of Type ***t*** is said to be ***t*-symmetric**.

$\rho_1$  is **0**-symmetric.

$\rho_2$  and  $\rho_3$  are **1**-symmetric.

# Leader Election without Chirality



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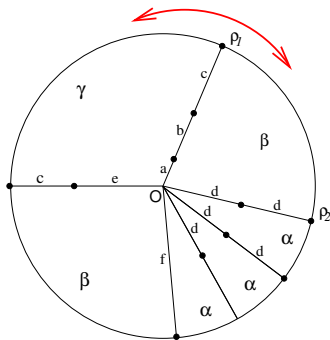
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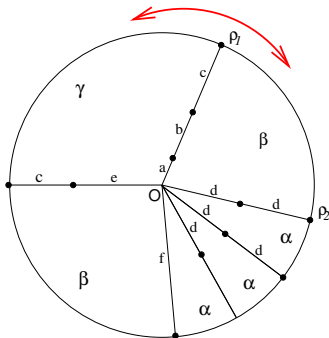
$\rho_2$  and  $\rho_3$  are **1**-symmetric.

# Leader Election without Chirality



For each radius  $\rho_i$ , every robot computes  $W(\rho_i)^{\odot}$  and  $W(\rho_i)^{\ominus}$  of the form *(type, radiusword, angle)*.

# Leader Election without Chirality

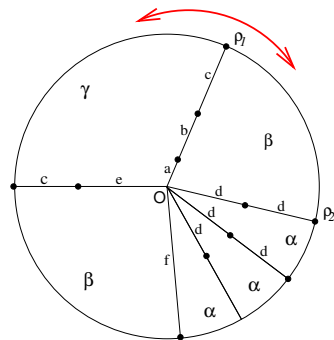


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# Leader Election without Chirality



## Lemma

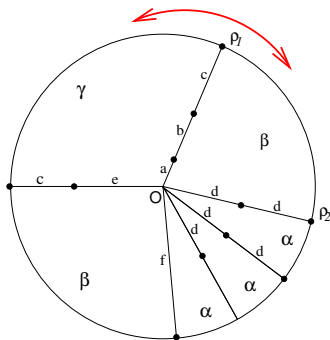
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*If there exists a pair of radii  $\{\rho_1, \rho_2\}$  so that  $W(\rho_i)^\circ$  or  $W(\rho_i)^\circ$  is a **Lyndon word** ( $i \in \{1, 2\}$ ), then the robots are able to **deterministically** agree on the same leader if and only if  $\rho_1$  and  $\rho_2$  are **0-symmetric**.*



# Leader Election without Chirality



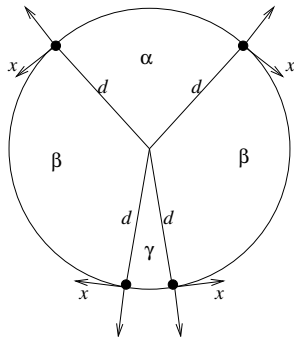
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# Leader Election without Chirality



No leader exists.

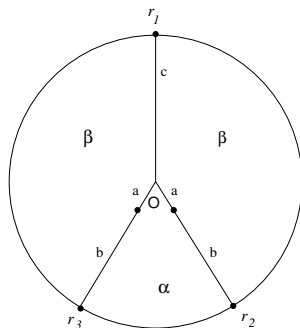
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# Leader Election without Chirality



The robot on  $\rho_1$  is the leader.

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# Leader Election without Chirality

## Theorem

Assuming *no chirality*, a swarm of robots is able to *deterministically* agree on the same leader if and only if there exists a radius  $\rho$  such that  $W(\rho)$  is a *0-symmetric Lyndon word*.