Optimal Grid Exploration by Asynchronous Oblivious Robots

Franck Petit

INRIA/LIP6-CNRS/UPMC

✓ Impossible if k<3

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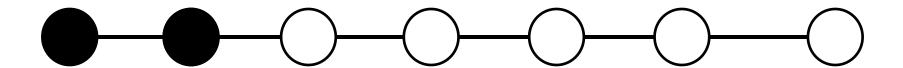
Remark

Any terminal configuration of any (probabilistic or deterministic) exploration protocol for a grid of n nodes using k < n oblivious robots contains at least one tower.

✓ Impossible if k<3

Remark

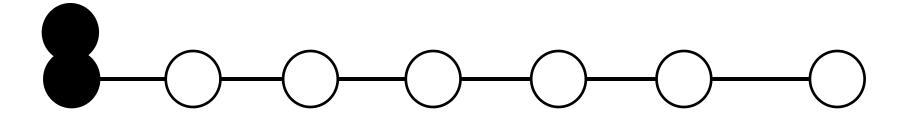
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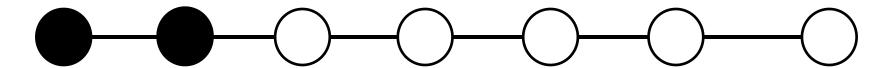
Any terminal configuration of any (probabilistic or deterministic) exploration protocol for a grid of n nodes using k < n oblivious robots contains at least one tower.



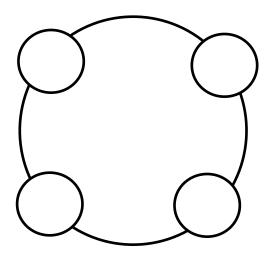
✓ Impossible if k<3

Remark

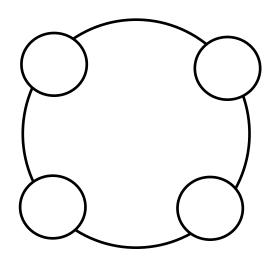
Any terminal configuration of any (probabilistic or deterministic) exploration protocol for a grid of n nodes using k < n oblivious robots contains at least one tower.



Initial configuration



✓ Impossible for (2,2)-grid if k=3



Impossible [Devismes 2009]

✓ Impossible for (3,3)-grid if k=3

☐ Tower of size 3

At most one new node is visited

- ✓ Impossible for (3,3)-grid if k=3
 - ☐ Tower of size 3
- At most one new node is visited

- ☐ Tower of size 2
 - The tower remains idle
- 4 new nodes are visited (7 distinct nodes are visited in total)

✓ Impossible for (3,3)-grid if k=3

☐ Tower of size 3

At most one new node is visited

☐ Tower of size 2

• The tower remains idle

4 new nodes are visited (7 distinct nodes are visited in total)

Impossible since n=6

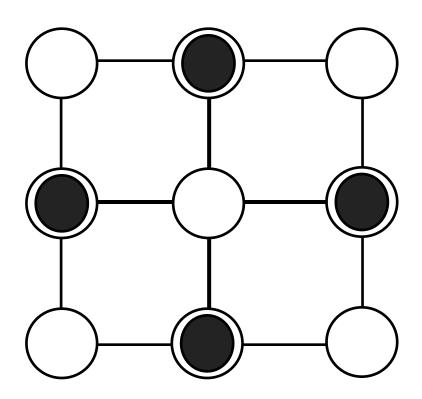
- ✓ Impossible for (3,3)-grid if k=3
 - ☐ Tower of size 3
- At most one new node is visited

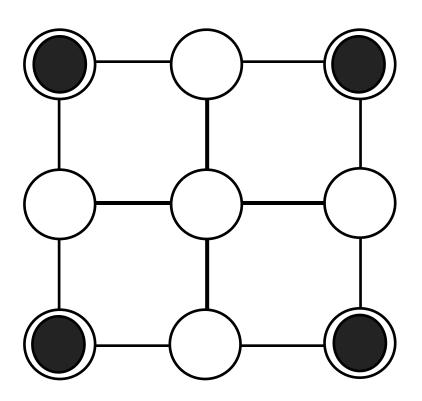
- ☐ Tower of size 2
 - The tower remains idle

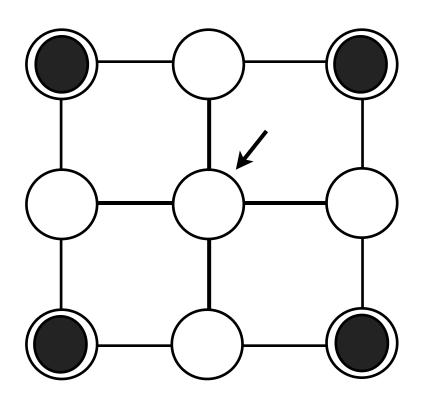
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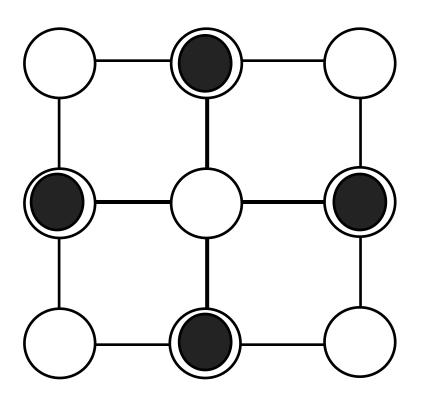
Impossible since n=6

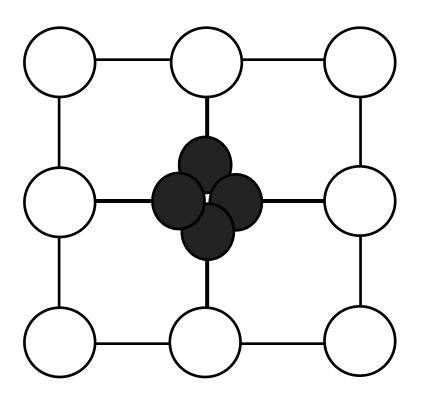
- The tower moves
- Multiplicity of size 3

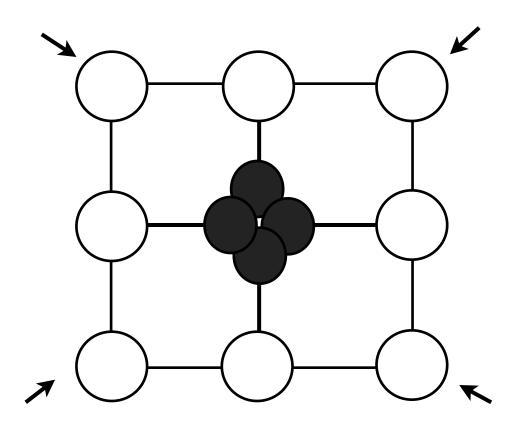


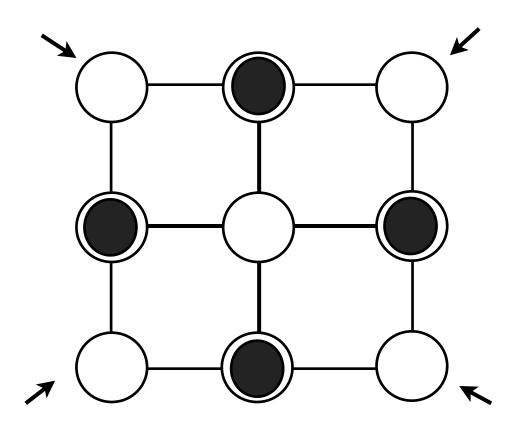








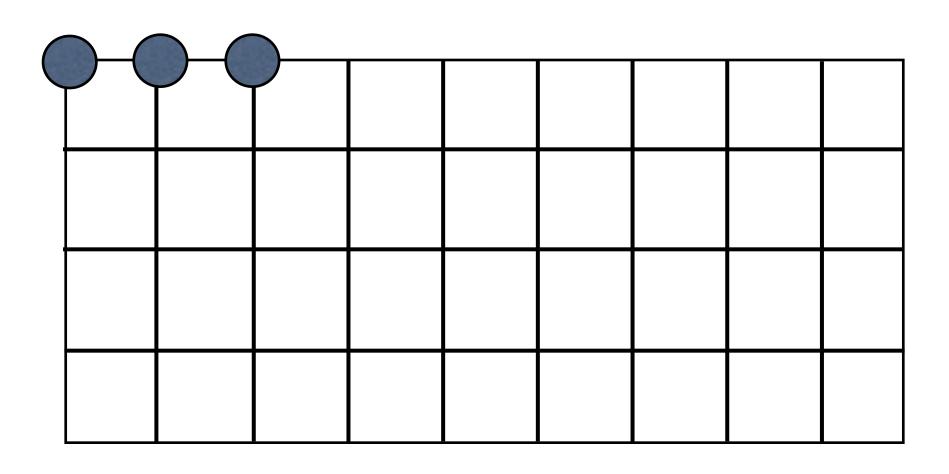


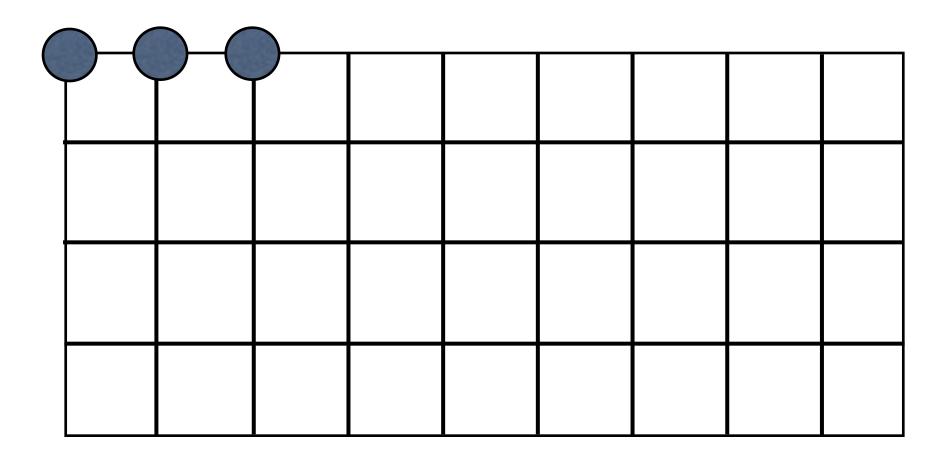


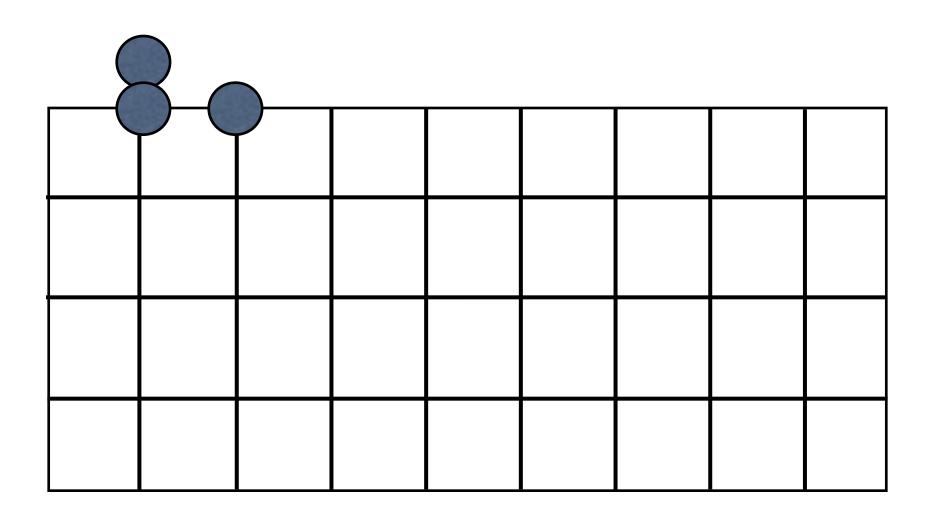
□ Setting

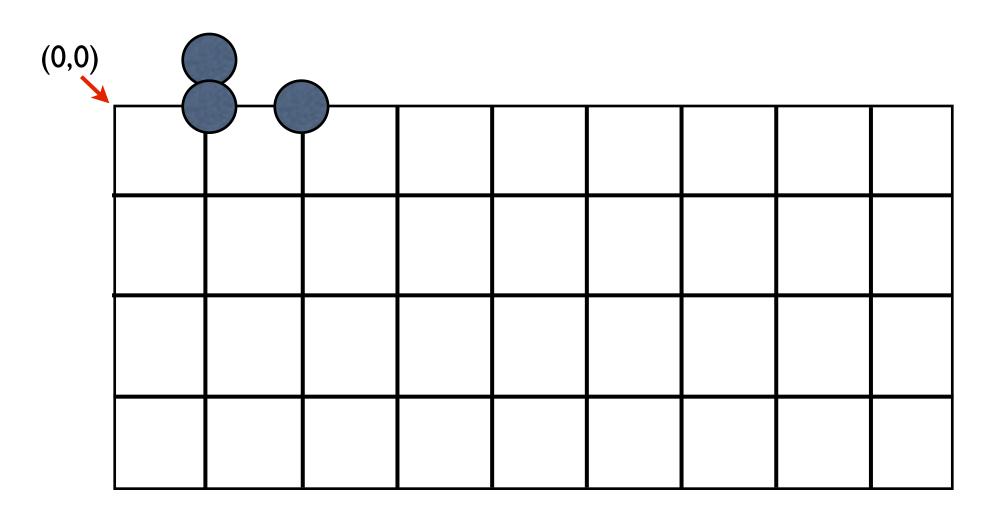
- \checkmark (i,j)-grids such that j >3
- \checkmark k=3
- √ Towerless initial configuration

- ☐Phase I: Set-Up phase
- ☐Phase 2: Orientation phase
- ☐Phase 3: Exploration phase









(0,0)	(0,1)	$\bigcirc^{(0,2)}$	(0,3) (0,4)) (0,5)	(0,6)	(0,7)	(0,8)	(0,9)
(1,0)	(1,1)	(1,2)	(1,3)	(1,4)	(1,5)	(1,6)	(1,7)	(1,8)	(1,9)
(2,0)	(2,1)	(2,2)	(2,3)	(2,4)	(2,5)	(2,6)	(2,7)	(2,8)	(2,9)
(3,0)	(3,1)	(3,2)	(3,3)	(3,4)	(3,5)	(3,6)	(3,7)	(3,8)	(3,9)
		(4,2)							

(0,0)	(0,1)	(0,2)	(0,3) (0,4) (0,5)	(0,6)	(0,7)	(0,8)	(0,9)
(1,0)	(1,1)	(1,2)	(1,3)	(1,4)	(1,5)	(1,6)	(1,7)	(1,8)	(1,9)
(2,0)	(2,1)	(2,2)	(2,3)	(2,4)	(2,5)	(2,6)	(2,7)	(2,8)	(2,9)
(3,0)	(3,1)	(3,2)	(3,3)	(3,4)	(3,5)	(3,6)	(3,7)	(3,8)	(3,9)
(4,0)	(4,1)	(4,2)	(4,3)	(4,4)	(4,5)	(4,6)	(4,7)	(4,8)	(4,9)

☐Phase 3: Exploration phase

(0,0)	(0,1)	(0,2)	(0,3) (0,4) (0,5)	(0,6)	(0,7)	(0,8)	(0,9)
(1,0)	(1,1)	(1,2)	(1,3)	(1,4)	(1,5)	(1,6)	(1,7)	(1,8)	(1,9)
(2,0)	(2,1)	(2,2)	(2,3)	(2,4)	(2,5)	(2,6)	(2,7)	(2,8)	(2,9)
(3,0)	(3,1)	(3,2)	(3,3)	(3,4)	(3,5)	(3,6)	(3,7)	(3,8)	(3,9)
(4,0)		(4,2)							

☐Phase 3: Exploration phase

(0,0)	(0,1)	(0,2)	(0,3) (0,4)) (0,5)	(0,6)	(0,7)	(0,8)	(0,9)
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(2,0)	(2,1)	(2,2)	(2,3)	(2,4)	(2,5)	(2,6)	(2,7)	(2,8)	(2,9)
(3,0)	(3,1)	(3,2)	(3,3)	(3,4)	(3,5)	(3,6)	(3,7)	(3,8)	(3,9)
(4,0)	(4,1)	(4,2)	(4,3)	(4,4)	(4,5)	(4,6)	(4,7)	(4,8)	(4,9)

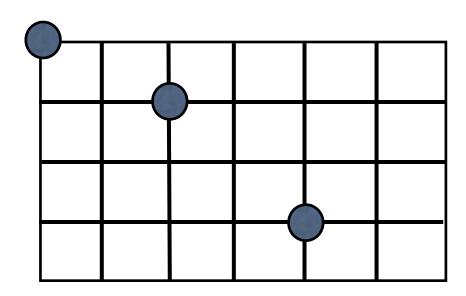
□Phase I: Set-Up

☐Phase I: Set-Up

√ Configuration of type Leader

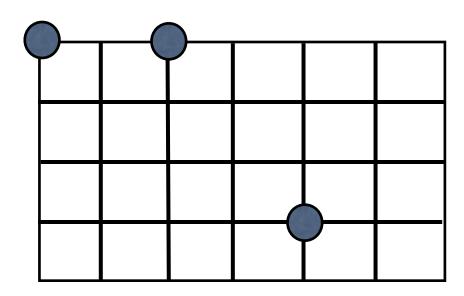
☐Phase I: Set-Up

✓ Configuration of type Leader



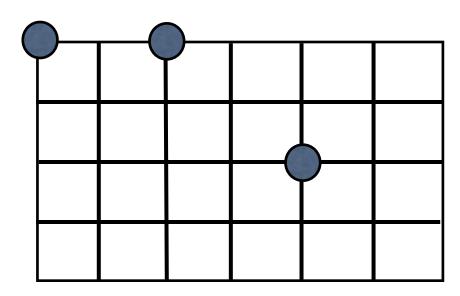
☐Phase I: Set-Up

✓ Configuration of type Leader



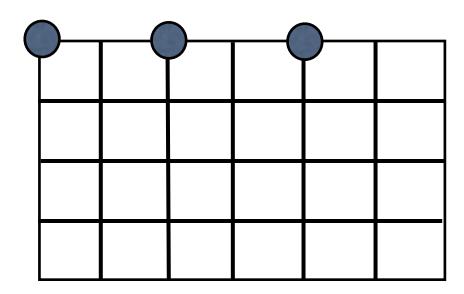
☐Phase I: Set-Up

✓ Configuration of type Leader



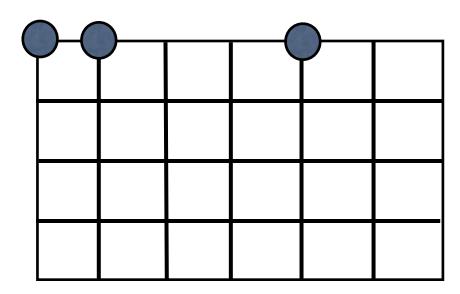
☐Phase I: Set-Up

✓ Configuration of type Leader



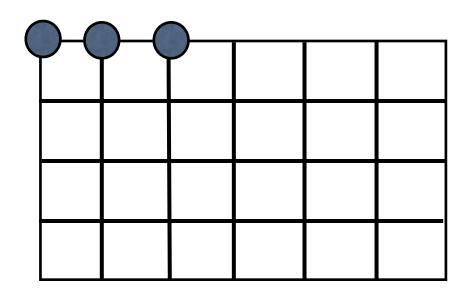
☐Phase I: Set-Up

✓ Configuration of type Leader



☐Phase I: Set-Up

✓ Configuration of type Leader



☐Phase I: Set-Up

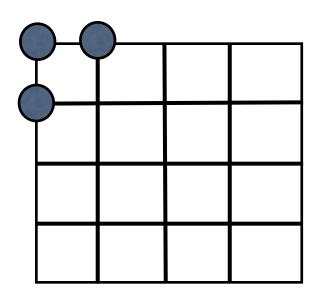
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☐Phase I: Set-Up

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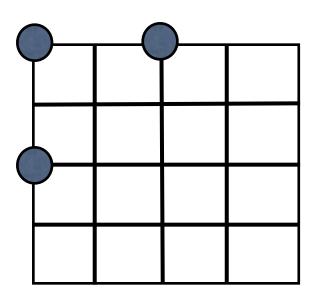
☐Phase I: Set-Up

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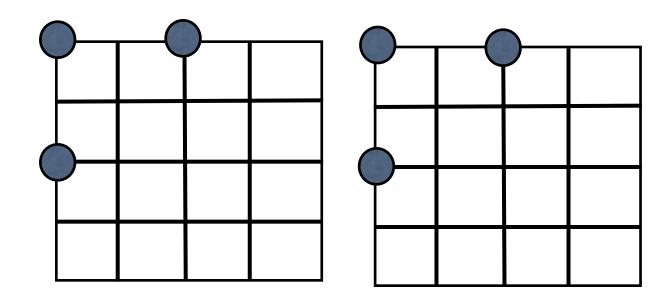
☐Phase I: Set-Up

✓ Configuration of type Leader



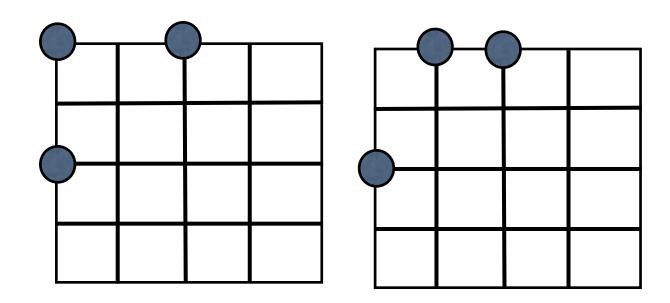
☐Phase I: Set-Up

✓ Configuration of type Leader



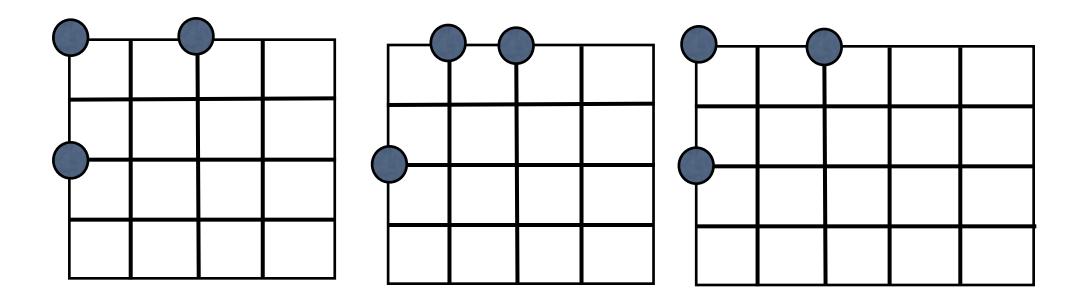
☐Phase I: Set-Up

✓ Configuration of type Leader



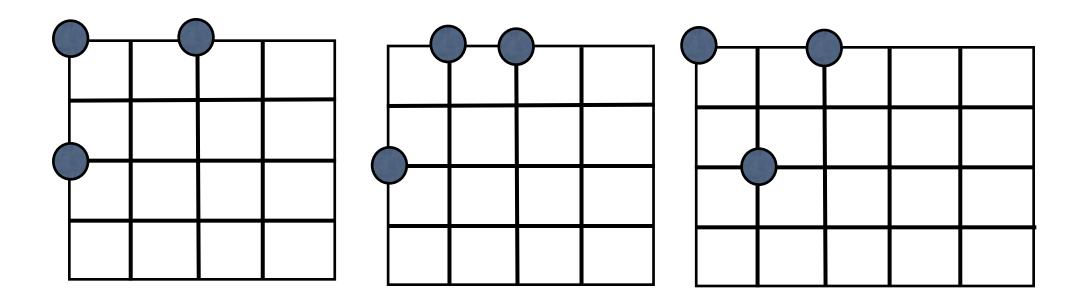
☐Phase I: Set-Up

✓ Configuration of type Leader



☐Phase I: Set-Up

√ Configuration of type Leader



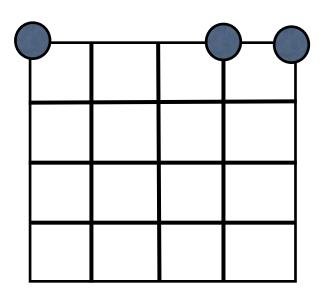
□Phase I: Set-Up

□Phase I: Set-Up

✓ Configuration of type Choice

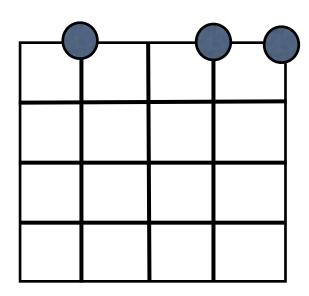
☐Phase I: Set-Up

✓ Configuration of type Choice



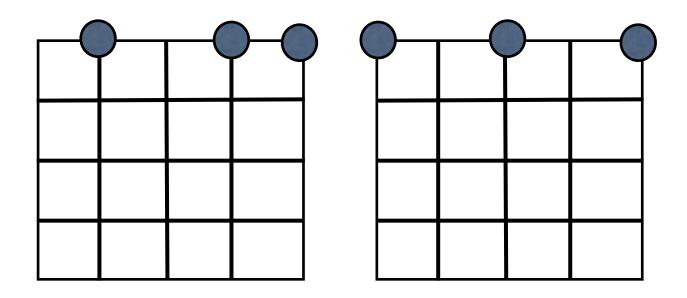
☐Phase I: Set-Up

✓ Configuration of type Choice



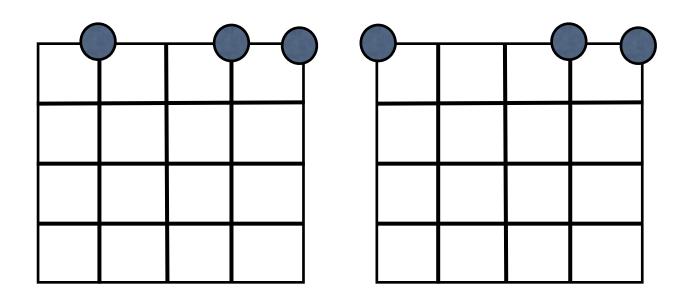
☐Phase I: Set-Up

✓ Configuration of type Choice



☐Phase I: Set-Up

✓ Configuration of type Choice

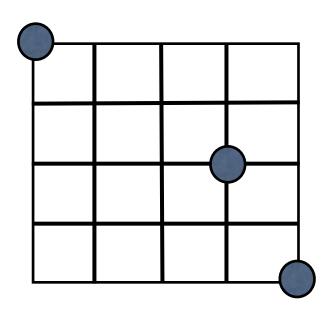


□Phase I: Set-Up

✓ Configuration of type Choice

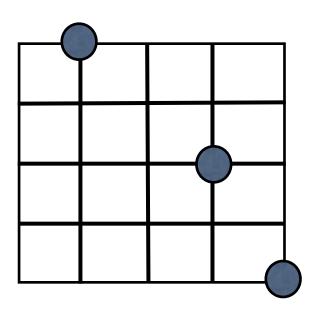
☐Phase I: Set-Up

✓ Configuration of type Choice



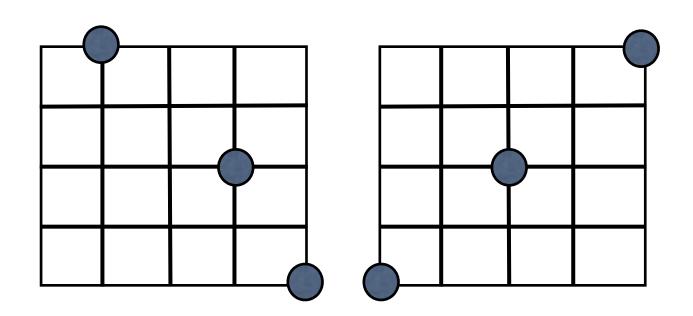
☐Phase I: Set-Up

✓ Configuration of type Choice



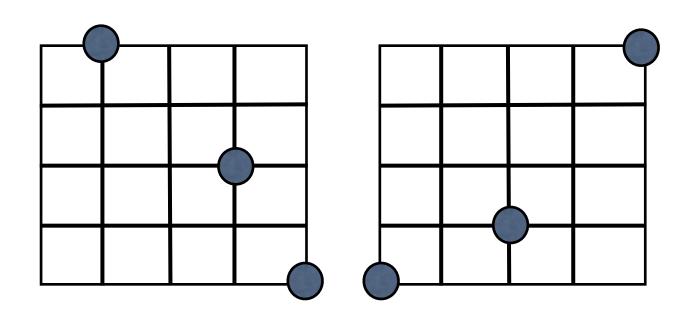
☐Phase I: Set-Up

✓ Configuration of type Choice



☐Phase I: Set-Up

✓ Configuration of type Choice

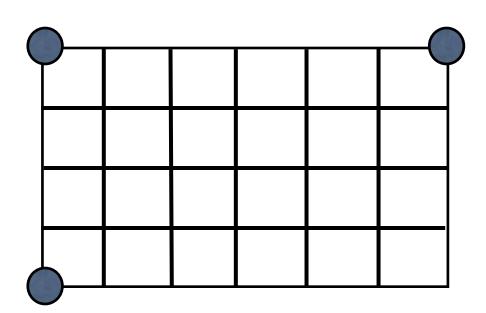


□Phase I: Set-Up

✓ Configuration of type Choice

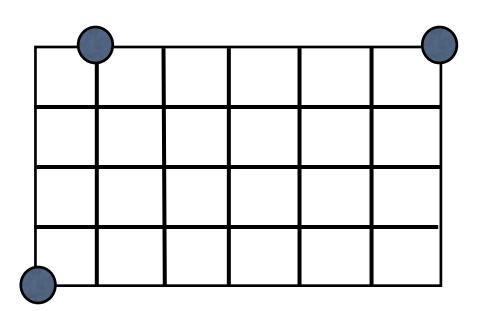
□Phase I: Set-Up

✓ Configuration of type Choice



□Phase I: Set-Up

✓ Configuration of type Choice

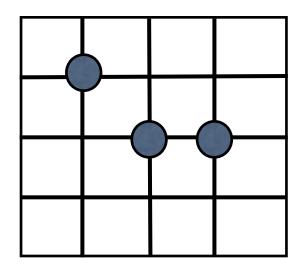


☐Phase I: Set-Up

✓ Configuration of type Undefined

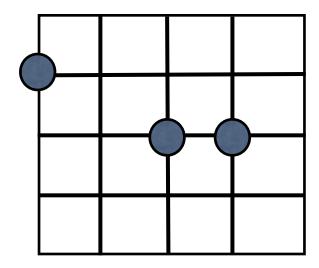
□Phase I: Set-Up

✓ Configuration of type Undefined



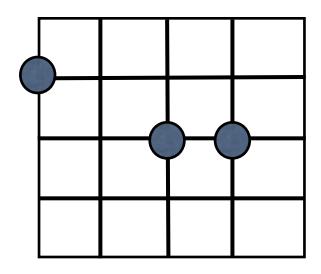
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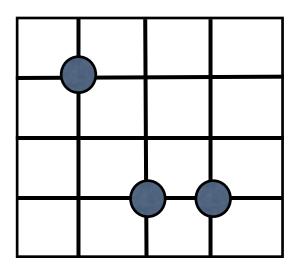
✓ Configuration of type Undefined



□Phase I: Set-Up

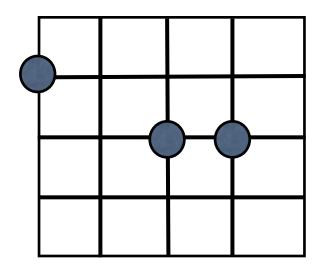
✓ Configuration of type Undefined

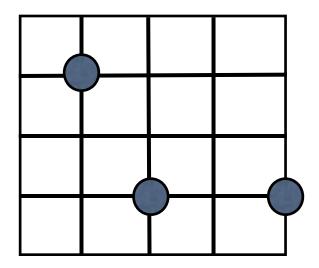




□Phase I: Set-Up

✓ Configuration of type Undefined

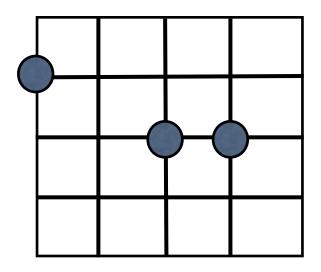


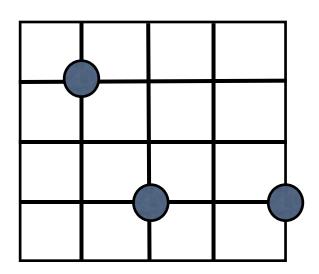


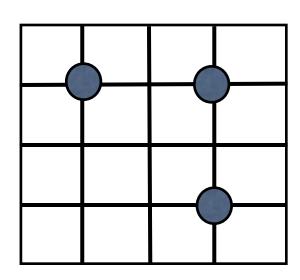
☐Phase I: Set-Up

✓ Configuration of type Undefined

All the corners of the grid are free



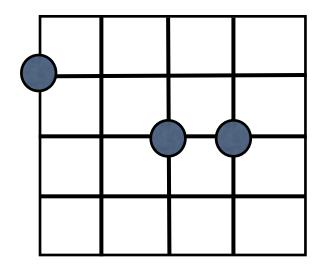


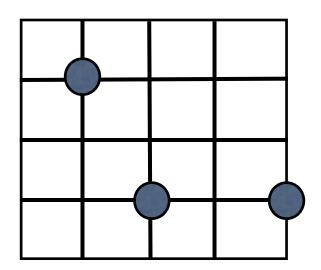


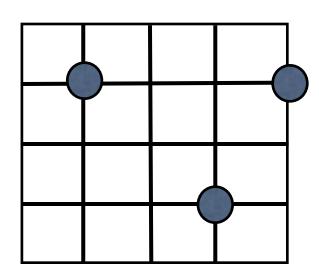
☐Phase I: Set-Up

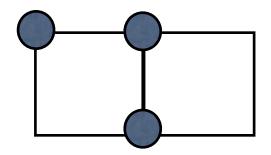
✓ Configuration of type Undefined

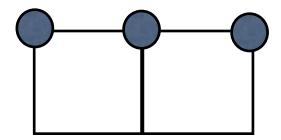
All the corners of the grid are free

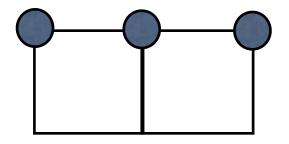


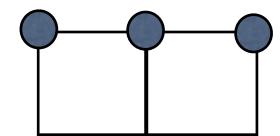


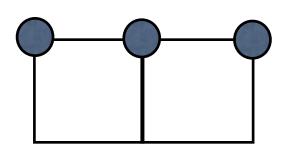


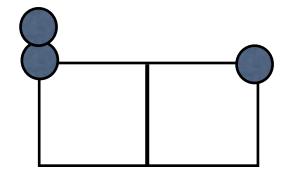


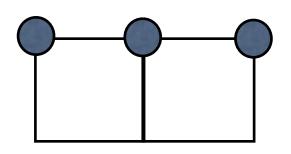


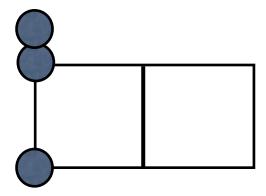


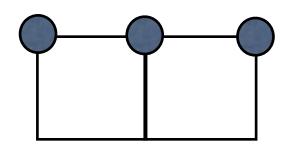


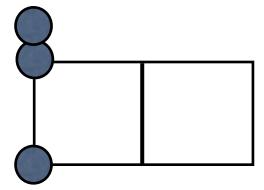




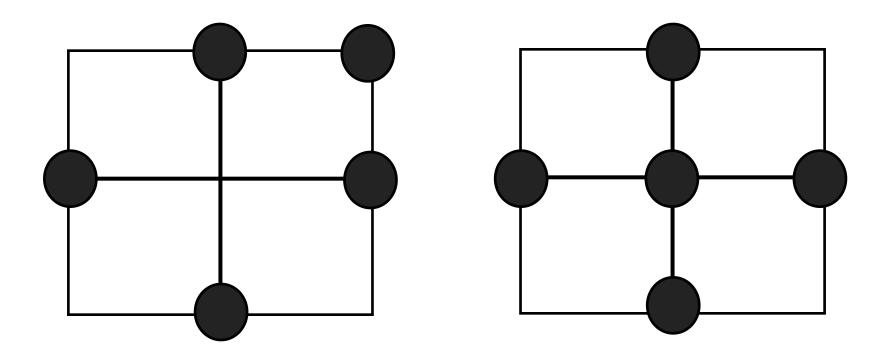


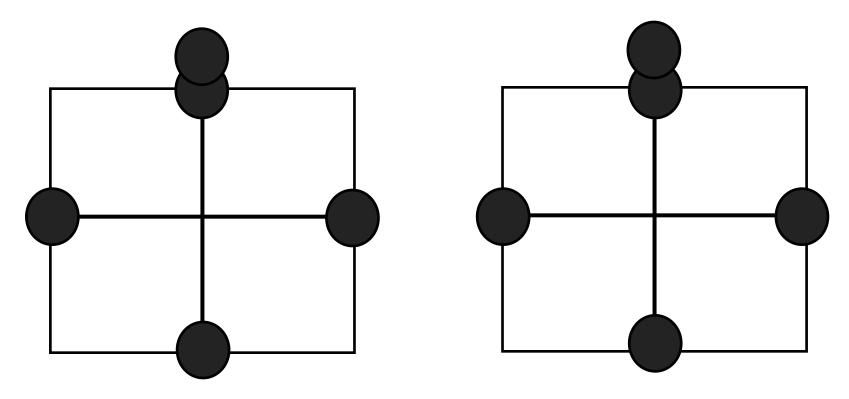


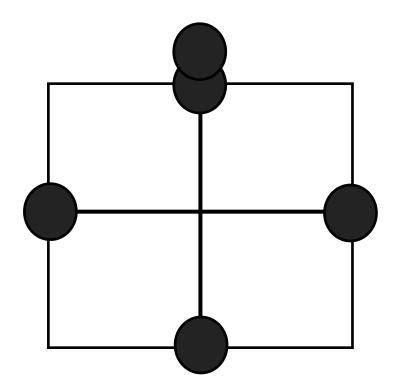


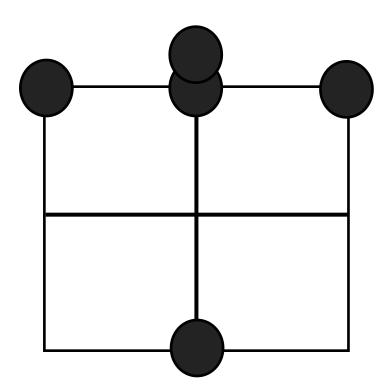


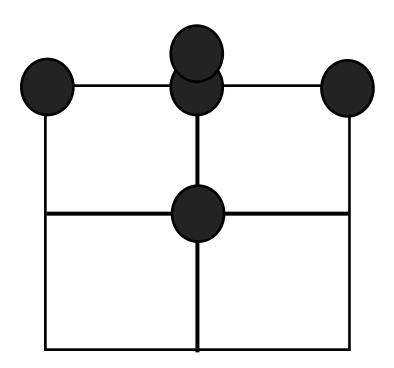
Final Configuration



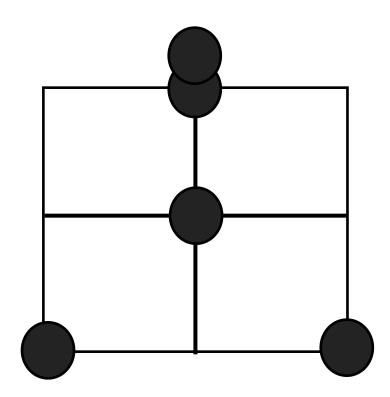








 \square (3,3)-grids with 5 robots



Final Configuration

Conclusion

- ✓ 5 robots are necessary and sufficient to explore (3,3)-grids
- ✓ 4 robots are necessary and sufficient to explore (2,2)-grids
- \checkmark 3 robots are necessary and sufficient to explore (i,j)-grids such that j >3