A PROOFS AND DERIVATIONS

PROOF 1. (Proposition 1) For any two sub-matrix : $X_1, X_2 \in \mathbb{R}^{N \times 1}$, regardless of row or column sub-matrix of the original matrix. Note for any matrix X_S with column = 1, $(X_S^\top X_S)^{-1} = ||X_S||^2 = Vol(X_S)^2$. Considering the pseudo-inverse is denoted as: $X_S^+ := (X_S^\top X_S)^{-1} X_S^\top$, the bias variation is:

$$bias \frac{2}{2} - bias \frac{2}{1} = \|X^{+} - X_{2}^{+}\|^{2} - \|X^{+} - X_{1}^{+}\|^{2}$$

$$= \|X^{+}\|^{2} - 2\langle X^{+}, X_{2}^{+} \rangle + \|X_{2}^{+}\|^{2} - \|X^{+}\|^{2} + 2\langle X^{+}, X_{1}^{+} \rangle - \|X_{1}^{+}\|^{2}$$

$$= \|X^{+}\|^{2} - 2\|X_{2}^{+}\|^{2} + \|X_{2}^{+}\|^{2} - \|X^{+}\|^{2} + 2\|X_{1}^{+}\|^{2} - \|X_{1}^{+}\|^{2}$$

$$= \|X_{1}^{+}\|^{2} - \|X_{2}^{+}\|^{2} = \frac{1}{\|X_{1}\|^{4}} \|X_{1}^{\top}\|^{2} - \frac{1}{\|X_{2}\|^{4}} \|X_{2}^{\top}\|^{2}$$

$$= \frac{1}{\|X_{1}\|^{2}} - \frac{1}{\|X_{2}\|^{2}} = \frac{1}{\text{Vol}(X_{1})^{2}} - \frac{1}{\text{Vol}(X_{2})^{2}}$$

$$(1)$$

Since the Vol(X) is constant under column = 1, a larger volume yields a smaller bias is proved. Combined with the relation $variation_1 - variation_2 = bias_2 - bias_1$, a larger volume yields a larger parameter variation is apparent.

PROPOSITION 2. (Volume wrt. Bias for rank > 1.) For a matrix $X \in \mathbb{R}^{N \times M}$, and its non-zero row submatrices $X1, X2 \in \mathbb{R}^{\frac{N}{2} \times M}$ or column submatrices $X1, X2 \in \mathbb{R}^{N \times \frac{M}{2}}$, the following relation can be constructed by Sylvester's formula:

$$bias_{2}^{2} - bias_{1}^{2} = \|X^{+} - X_{2}^{+}\|^{2} - \|X^{+} - X_{1}^{+}\|^{2}$$

$$= \frac{\|Q_{2}X_{2}^{T}\|^{2}}{Vol(X_{2})^{4}} - \frac{\|Q_{1}X_{1}^{T}\|^{2}}{Vol(X_{1})^{4}} + 2\left(\frac{Q_{X}X^{T}}{Vol(X_{1})^{2}}, \frac{Q_{1}X_{1}^{T}}{Vol(X_{1})^{2}} - \frac{Q_{2}X_{2}^{T}}{Vol(X_{2})^{2}}\right), \tag{2}$$

where,

$$Q = \sum_{l=1}^{k} (\lambda_{l} \sigma_{l})^{-1} \prod_{j=1, j \neq l}^{k} (G - \lambda_{i} I),$$
(3)

$$\sigma_{l} = \sum_{g=1}^{k} (-1)^{g+1} \lambda_{l}^{k-g} \left(\sum_{\mathcal{H} \subseteq \{1,\dots,k\} \setminus \{l\}, |\mathcal{H}| = g-1} \left(\prod_{h \in \{1,\dots,k\} \setminus \mathcal{H}} \lambda_{h}^{-1} \right) \right). \tag{4}$$

 $\{\lambda_l, l=1,...,k\}$ denotes the left Gram matrix G's k unique eigenvalues.

PROOF 2. (Proposition 2) The proposition 2 is expanded by substituting $X^+ = G^{-1}X^T$, where $G := X^TX$ is the left Gram matrix.

$$\begin{aligned} \operatorname{bias}_{2}^{2} - \operatorname{bias}_{1}^{2} &:= \left\| X^{+} - X_{2}^{+} \right\|^{2} - \left\| X^{+} - X_{1}^{+} \right\|^{2} \\ &= \left\| X^{+} \right\|^{2} - 2 \left\langle X^{+}, X_{2}^{+} \right\rangle + \left\| X_{2}^{+} \right\|^{2} - \left\| X^{+} \right\|^{2} + 2 \left\langle X^{+}, X_{1}^{+} \right\rangle - \left\| X_{1}^{+} \right\|^{2} \\ &= \left\| X_{2}^{+} \right\|^{2} - \left\| X_{1}^{+} \right\|^{2} + 2 \left\langle X^{+}, X_{1}^{+} - X_{2}^{+} \right\rangle \\ &= \left\| G_{2}^{-1} X_{2}^{-} \right\|^{2} - \left\| G_{1}^{-1} X_{1}^{\top} \right\|^{2} + 2 \left\langle G^{-1} X^{\top}, G_{1}^{-1} X_{1}^{\top} - G_{2}^{-1} X_{2}^{\top} \right\rangle \end{aligned} \tag{5}$$

 G^{-1} can be expanded by Sylvester's matrix theorem.

Theory 1. (Sylvester's Matrix Theorem). Given a diagonalizable square matrix X, any analytic function f() can be expanded,

$$f(\mathbf{X}) = \sum_{l=1}^{k} f(\lambda_l) \, \mathbf{X}_l, \tag{6}$$

where λ_l is the i-th distinct eigenvalue of X and X_l is the Frobenius covariant as follows:

$$\mathbf{X}_{l} := \prod_{j=1, j \neq l}^{k} \frac{1}{\lambda_{l} - \lambda_{j}} \left(\mathbf{X} - \lambda_{j} \mathbf{I} \right). \tag{7}$$

COROLLARY 1. Supposing f() is a inverse function, then,

$$f(\mathbf{X}) = \mathbf{X}^{-1} = \sum_{l=1}^{k} \frac{1}{\lambda_l} \mathbf{X}_l$$
 (8)

For G is diagonalizable matrix, G^{-1} can be written as follows by above corollary.

$$\mathbf{G}^{-1} = \sum_{l=1}^{k} \frac{1}{\lambda_l} \mathbf{G}_l = \prod_{j=1, j \neq l}^{k} \frac{1}{\lambda_l - \lambda_j} \prod_{j=1, j \neq l}^{k} (\mathbf{G} - \lambda_j \mathbf{I})$$
(9)

Denoting $p_l = \prod_{j=1, j \neq l}^k \frac{1}{\lambda_l - \lambda_j}$ and expanding the products, we have:

$$\frac{1}{p_l} = \Lambda \underbrace{\sum_{g=1}^k (-1)^{g+1} \lambda_l^{k-g} \left[\sum_{\mathcal{H} \subseteq \{1,\dots,k\} \setminus \{l\}, |\mathcal{H}| = g-1} \left(\prod_{h \in \{1,\dots,k\} \setminus \mathcal{H}} \frac{1}{\lambda_h} \right) \right]}_{\sigma_l}, \tag{10}$$

where $\Lambda = \prod_{i=l}^k \lambda_l = |G|.$ The Equation 9 can be rewritten as:

$$G^{-1} = \frac{1}{|G|} \underbrace{\frac{1}{\sigma_l} \prod_{j=1, j \neq l}^{k} (G - \lambda_j \mathbf{I})}_{\mathbf{Q}}$$

$$= \frac{1}{\text{Vol}(\mathbf{X})^2} \underbrace{\frac{1}{\sigma_l} \prod_{j=1, j \neq l}^{k} (G - \lambda_j \mathbf{I})}_{\mathbf{Q}}$$
(11)

Substituting $G^{-1}(G_1^{-1},G_2^{-1})$ in Equation 5 by above result, the Equation 5 can be rewritten as:

$$\operatorname{bias}_{2}^{2} - \operatorname{bias}_{1}^{2} = \frac{\left\| Q_{2} X_{2}^{T} \right\|^{2}}{\operatorname{Vol}(X_{2})^{4}} - \frac{\left\| Q_{1} X_{1}^{T} \right\|^{2}}{\operatorname{Vol}(X_{1})^{4}} + 2 \left\langle \frac{Q_{X} X^{T}}{\operatorname{Vol}(X)^{2}}, \frac{Q_{1} X_{1}^{T}}{\operatorname{Vol}(X_{1})^{2}} - \frac{Q_{2} X_{2}^{T}}{\operatorname{Vol}(X_{2})^{2}} \right\rangle$$

$$(12)$$

Lemma 1. For any matrix $X = \begin{bmatrix} X_1^T, X_2^T \end{bmatrix}^T \in \mathbb{R}^{N \times M}$ and $X_1^T, X_2^T \in \mathbb{R}^{\frac{N}{2} \times M}$ are submatrices in row, there exists $Vol(X) \gg max(Vol(X_1), Vol(X_2))$ when $N \to \infty$. The relation is same for column submatrices.

LEMMA 2. For a invertible matrix A and any column vector u and v, then there exits:

$$\det\left(A + uv^{T}\right) = \det(A)\left(1 + v^{T}A^{-1}u\right) \tag{13}$$

PROOF 3. (Lemma 1) Considering a matrix $\bar{X} = \begin{bmatrix} X^T, x^T \end{bmatrix}^T$, where $X \in \mathbb{R}^{n \times m}$ is a submatrix, $x \in \mathbb{R}^{1 \times m}$ is a row vector. The square volume of \bar{X} can be written as:

$$Vol(\bar{X})^{2} = \left| \bar{X}^{T} \bar{X} \right| = \left| \left[X^{T}, x^{T} \right] \begin{bmatrix} X \\ x \end{bmatrix} \right|$$
$$= \left| X^{T} X + x^{T} x \right| = \sigma_{1} \left| X^{T} X \right|. \tag{14}$$

According to the property of matrix determinant lemma (Lemma 2) and $x(X^TX)^{-1}x^T > 0$, the constant coefficient $\sigma = 1 + x(X^TX)^{-1}x^T$ is greater than 1. Considering another submatrix $X' = \begin{bmatrix} x_1^T, ..., x_n^T \end{bmatrix}^T$ and adding its row vectors in matrix X row by row, the square volume changing is written as:

$$Vol(\left[X^{T}, X^{\prime T}\right]^{T}) = Vol(\left[X^{T}, x_{1}^{T}, ..., x_{n}^{T}\right]^{T})$$

$$= \sigma_{n} Vol(\left[X^{T}, x_{1}^{T}, ..., x_{n-1}^{T}\right]^{T}) = ... = \prod_{i=1}^{n} \sigma_{i} Vol(X),$$

$$(15)$$

where $\sigma_i = 1 + x_i(X^TX)^{-1}x_i^T$. For each σ_i is greater than 1, $\prod_{i=1}^n \sigma_i \to \infty$ when $n \to \infty$. Above all, **Lemma 1** is proved taking X_1 and X_2 as a new addition submatrix, respectively. Same conclusions can be applied in column submatrices.

PROPOSITION 3. (Volume is not robust to replication) For a N-by-M matrix X, a replicated $(N + |X_S|d)$ -by-M matrix $X_{rep} := [X^T, X_S^T, ..., X_S^T]^T$ or a N-by- $(M + |X_S|d)$ matrix $X_{rep} := [X, X_S, ..., X_S]$ is generated when replicating a row/column submatrix X_S in X_S for d > 0 times. Volume is not robust to replication for $Vol(X_{rep}) > Vol(X)$ and $\lim_{d \to \infty} Vol(X_{rep}) = \infty$.

PROOF 4. (Proposition 3) Considering a replication-involving dataset $X_{rep} = \begin{bmatrix} X^T, \underbrace{X_S^T, ..., X_S^T}_{d} \end{bmatrix}^T$, where X_S is row vector and is replicated

for d times. According to Equation 15, the square volume of X_{rep} is written as:

$$Vol(X_{rep})^{2} = (1 + X_{S}(X^{T}X)^{-1}X_{S}^{T})^{d} |X^{T}X|$$
(16)

For $(1 + X_S(X^TX)^{-1}X_S^T) > 1$, the exponential increasing of volume under replication is proved and $\lim_{d\to\infty} Vol\left(X_{rep}\right) = \infty$ is hold. The same result can be applied in column submatrices.

Proposition 4. Cluster RV(X) is with outlier robustness, for the datasize $N \to 0$,

$$ClusterRV(\{X, x_{outlier}\}) = ClusterRV(X)$$
 (17)

The proof of Proposition 4 relies on the mechanism that a singleton cluster will be merged to another nearest non-singleton cluster in k-Means. When the dataset size $N \to \infty$, the effect of sporadic outliers on cluster center is tending to 0.

PROPOSITION 5. For $\alpha \in (0,1)$, the cluster RV's inflation has the following inequality: $(1-\alpha)^K \leq \inf\{1-\alpha\}^{-K}$, where K is the number of clusters.

PROOF 5. (Proposition 5) Considering a replication-involving matrix $X_{rep} = replicate(X, c)$, the inflation is written as:

$$inflation = \frac{ClusterRV(X_{rep})}{ClusterRV(X)} = \frac{Vol(\widetilde{X}_{rep})\prod_{i \in K}\rho_{rep,i}}{Vol(\widetilde{X})\prod_{i \in K}\rho_{i}} = \frac{\prod_{i \in K}\rho_{rep,i}}{\prod_{i \in K}\rho_{i}}$$
(18)

Due to direct copying, the clusters in X_{rep} and X are with similar centers, thus, $Vol(\widetilde{X}_{rep}) \approx Vol(\widetilde{X})$.

Following summation formula of geometric progression, when $0 < \alpha < 1$,

$$1 \le \rho_{rep,i} := \sum_{p=0}^{\phi_{rep,i}} \alpha^p = \frac{1 - \alpha^{(\phi_{rep,i} + 1)}}{1 - \alpha} \le \frac{1}{1 - \alpha}$$
 (19)

$$1 \le \rho_i := \sum_{p=0}^{\phi_i} \alpha^p = \frac{1 - \alpha^{(\phi_i + 1)}}{1 - \alpha} \le \frac{1}{1 - \alpha} \tag{20}$$

Thus,

$$(1-\alpha)^K \le \inf\{lation \le (1-\alpha)^{-K}$$
 (21)

PROPOSITION 6. Let $\alpha = 1/(\beta N)$, where N is the size of dataset. If $N \to \infty$, for any cluster number K, the inflation of Cluster RV will converge to 1.

PROOF 6. (Proposition 6) When $\alpha = 1/\beta N$, the following inequality relation exists:

$$1 \le \rho_{rep,i} = \sum_{p=0}^{\phi_{rep,i}} \frac{1}{\beta N}^{p} \le \frac{1}{1 - \frac{1}{\beta N}} = 1 + \frac{1}{\beta N - 1}$$
 (22)

$$1 \le \rho_i = \sum_{p=0}^{\phi_i} \frac{1}{\beta N}^p \le \frac{1}{1 - \frac{1}{\beta N}} = 1 + \frac{1}{\beta N - 1}$$
 (23)

Combined with Equation 18,

$$(1 + \frac{1}{\beta N - 1})^{-K} \le \inf lation \le (1 + \frac{1}{\beta N - 1})^K$$
 (24)

When $N \to \infty$ and K is pre-determined, the following limit theorem is exist.

$$\lim_{N \to \infty} (1 + \frac{1}{\beta N - 1})^{-K} = \lim_{N \to \infty} (1 + \frac{1}{\beta N - 1})^{K} = 1$$
 (25)

Thus, in flation $\to 1$ is hold under $N \to \infty$.

Proposition 7. Considering $\alpha = 1/(\beta N)$ and $\beta > 0$. For any fixed cluster number K, if the size of dataset $N \to \infty$, the bounded distortion of ClusterRV will converge to 1.

PROOF 7. (Proposition 7) When $N \to \infty$, combined with Proposition 6 has proved, the bounded distortion can be rewrittend as:

$$bounded_distortion = \frac{ClusterRV(replicate(X_1, c))Vol(X_2)}{Vol(X_1)ClusterRV(replicate(X_2, c))} \approx \frac{Vol(\widetilde{X_1})Vol(X_2)}{Vol(\widetilde{X_2})Vol(X_1)}$$
 (26)

Taking the scenario where the dataset $X_1 \in \mathbb{R}^{N \times M}$ is clustered to K clusters as an example. The matrix of cluster centers is denoted as $\widetilde{X_1} \in \mathbb{R}^{K \times M}$. When $N \to \infty$, the number of data points within each cluster are also infinite. Denoting each clusters C_i , i = 1, ..., K contains D data points evenly, the volume of X_1 is as follows.

$$Vol(X_1)^2 = \left| \left[(\widetilde{X_1} + \Gamma_1)^T, ..., (\widetilde{X_1} + \Gamma_D)^T \right] \begin{bmatrix} \widetilde{X_1} + \Gamma_1 \\ \vdots \\ \widetilde{X_1} + \Gamma_D \end{bmatrix} \right| = \left| \sum_{i=1}^D (\widetilde{X_1} + \Gamma_i)^T (X_1 + \Gamma_i) \right|$$

$$(27)$$

where $\Gamma_i = \begin{bmatrix} C_{0,i} - \widetilde{X}_0 \\ \vdots \\ C_{K,i} - \widetilde{X}_K \end{bmatrix} \in \mathbb{R}^{K \times M}$ denotes the Euclidean distance of i-th data points in each clusters to its cluster's center. Each cluster center

$$\widetilde{X}_k = \frac{\sum_{i=1}^D \delta_{ik} x_i}{\sum_{i=1}^D \delta_{ik}}.$$
(28)

where δ_{ik} is a cluster indicator variable with $\delta_{ik} = 1$ if x_i in k-th cluster. As the number of data points increases, the distance vectors of the points to cluster center are cancel each other out,

$$\sum_{i=0}^{D} \Gamma_D \to \overrightarrow{0}. \tag{29}$$

In the same way,

generated by k-Means is

$$Vol(X_2)^2 = \left| \sum_{i=1}^{D} (\widetilde{X}_2)^T (\widetilde{X}_2) + \sum_{i=1}^{D} (\widetilde{\Upsilon}_i)^T (\Upsilon_i) \right|$$
(30)

Applying determinant property,

$$\frac{Vol(X_1)^2}{Vol(X_2)^2} = \frac{\left|D \cdot (\widetilde{X}_1)^T (\widetilde{X}_1) + \sum_{i=1}^D (\Gamma_i)^T (\Gamma_i)\right|}{\left|D \cdot (\widetilde{X}_2)^T (\widetilde{X}_2) + \sum_{i=1}^D (\Upsilon_i)^T (\Upsilon_i)\right|} = \frac{\left|(\widetilde{X}_1)^T (\widetilde{X}_1) + \frac{1}{D} \sum_{i=1}^D (\Gamma_i)^T (\Gamma_i)\right|}{\left|(\widetilde{X}_2)^T (\widetilde{X}_2) + \frac{1}{D} \sum_{i=1}^D (\Upsilon_i)^T (\Upsilon_i)\right|}$$
(31)

Considering $\Gamma_i^T \Gamma_i = \alpha_i \widetilde{X}_1^T \widetilde{X}_1$, for the data size $N \to \infty$, there will also exists Υ_i in infinite space satisfied $\Upsilon_i^T \Upsilon_i = \alpha_i \widetilde{X}_2^T \widetilde{X}_2$. Whether $\Gamma_{i,k}$ and $\Upsilon_{i,k}$ belong to same clusters k is not necessary, for:

$$\Gamma_{i}^{T}\Gamma = \begin{bmatrix} \Gamma_{i,1}^{T} & \dots & \Gamma_{i,K}^{T} \end{bmatrix} \begin{bmatrix} \Gamma_{i,1} \\ \dots \\ \Gamma_{i,K} \end{bmatrix} = \sum_{k=1}^{K} \Gamma_{i,k}^{T} \Gamma_{i,k} = \underbrace{\begin{bmatrix} \Gamma_{i,K}, \dots & \Gamma_{i,1} \end{bmatrix}}_{anu\,order} \begin{bmatrix} \Gamma_{i,K} \\ \dots \\ \Gamma_{i,1} \end{bmatrix}$$
(32)

Then, the Equation 31 is rewritten as:

$$\frac{Vol(X_1)^2}{Vol(X_2)^2} = \frac{\left| (\widetilde{X}_1)^T (\widetilde{X}_1) + \frac{1}{D} \sum_{i=1}^D (\Gamma_i)^T (\Gamma_i) \right|}{\left| (\widetilde{X}_2)^T (\widetilde{X}_2) + \frac{1}{D} \sum_{i=1}^D (\Upsilon_i)^T (\Upsilon_i) \right|} = \frac{\left| I + \frac{1}{D} \sum_{i=1}^D \alpha_i \right| \left| (\widetilde{X}_1)^T (\widetilde{X}_1) \right|}{\left| I + \frac{1}{D} \sum_{i=1}^D \alpha_i \right|} = \frac{Vol(\widetilde{X}_1)^2}{Vol(\widetilde{X}_2)^2}$$
(33)

Thus, when $N \to \infty$, the data points in each cluster $D \to \infty$,

$$bounded_distortion \approx \frac{Vol(\widetilde{X_1})Vol(X_2)}{Vol(\widetilde{X_2})Vol(X_1)} \to 1.$$
 (34)

DEFINITION 1. (Unbounded subset-sum problem) Given a set of positive integers $\{k_0, ..., k_n\}$, an unbounded subset-sum problem is defined as to find the non-negative integers α_i so that $\sum_{i=1}^n \alpha_i k_i = K$, for we can achieve K by k_i for any times, it's known that unbounded subset-sum problem is NP-hard.

Lemma 3. Let $v_i = p_i, i = 1, ..., n, p_{n+1} = K + \Delta$ when $v_{n+1} = K$ and $\Delta \in (0, 1), a$ subadditive and monotone function p(x) interpolating on the points (v_i, p_i) exist if and only if unbounded subset sum $\sum_{i=1}^n \alpha_i v_i = K$ not exists.

PROOF 8. (Lemma 3) If $\sum_{i=1}^{n} \alpha_i p_i = K$ exists, then we have:

$$K + \Delta = p(K) = p\left(\sum_{i=1}^{n} \alpha_i v_i\right) \le \sum_{i=1}^{n} \alpha_i p_i \stackrel{v_i = p_i}{=} K$$

$$(35)$$

 $K + \Delta = K$ is a contradiction so that if $\sum_{i=1}^{n} \alpha_i v_i = K$ exists, a subadditive and monotone function p(x) interpolating on the n + 1 points (v_i, p_i) is not exist.

Conversely, in the next, we prove if $\sum_{i=1}^{n} \alpha_i p_i = K$ not exists, we can construct a subadditive and monotone function p(x) that interpolates the (n+1) points. First, we introduce a function (x) to reflect the smallest possible unbounded subset sum at x. (x) at least contrains an unbounded subset sum constains x, thus $(x) \ge x$. Then, we define a function $p(x) = \min((x), K + \Delta)$ and our goal is to prove such p(x) is satisfied subadditive, monotone and interpolating on the n+1 points (v_i, p_i) . It is apparent that p(x) is monotone. Since a set containing x-self is a minumum unbounded subset sum, we have $i = v_i = p_i \le K + \Delta$. For we have assumed that $\sum_{i=1}^{n} \alpha_i p_i = K$ is not exist, thus $(v_{i+1}) \ge K + 1$. Then the p(x) can be written as:

$$p(x) = \begin{cases} \mu(x), & \mu(x) \le K \\ K + \Delta, \mu(x) \ge K + 1 \end{cases}$$
(36)

If $\mu(x) \ge K+1$, then $p(x+y) \le K+\Delta = p(x) \le p(x)+p(y)$. The relation is also holds when $\mu(y) \ge K+1$. When both $\mu(x) \le K$ and $\mu(x) \le K$, we have $p(x) = (x) = \sum_{i=1}^n \alpha_i v_i$ and $p(y) = (y) = \sum_{i=1}^n \alpha_i v_i$. Then, $x+y \le p(x)+p(y) = \sum_{i=1}^n (\alpha_i + \alpha_i) v_i$. According to the definition of (x), $p(x+y) = (x+y) = \min(x+y) \sum_{i=1}^n \gamma_i$ and $p(x) \le \sum_{i=1}^n (\alpha_i + \alpha_i) v_i = p(x) + p(y)$.

Above all, we have proved Lemma 3). For the unbounded subset-sum problem is NP-hard, proving the unbounded subset sum $\sum_{i=1}^{n} \alpha_i v_i = K$ not exists in Lemma 3) is a co-NP hard problem.

Proposition 8. Given a pricing function p satisfying the constraint of $p(x)/x \ge p(y)/y$, $x \le y$, it also satisfy $p(x+y) \le p(x) + p(y)$ strictly.

PROOF 9. (Proposition 8) For the pricing function p satisfies $p(x)/x \ge p(y)/y$ when $x \le y$, there exists:

$$\frac{p(x+y)}{x+y} \le \min\left(\frac{p(x)}{x}, \frac{p(y)}{y}\right) \Rightarrow \\
p(x+y) \le \min\left(p(x) + \underbrace{\frac{yp(x)}{x}, p(y) + \underbrace{xp(y)}{y}}_{\ge p(y)}\right) \\
\le p(x) + p(y)$$
(37)

Constraint $p(x)/x \ge p(y)/y$, $x \le y$ representing a subspace of sub-additivity constraint is proved.

B ADDITIONAL EXPERIMENT RESULTS

EXPERIMENT 1. (Higher Cluster Diversity vs. Higher Data Diversity) In a MNIST handwritten digit classification problem, for example, subset 1 contains 100 randomly sampled handwritten pictures ranging from clusters labeled "0" to "9", while subset 2 contains 200 handwritten pictures sampled from clusters labeled "0" to "5". Compared to subset 1, subset 2 is with higher data diversity for containing more unique data and lower cluster diversify for sampling from 5 clusters. Figure 1 shows that a model trained on subset 1 is with better classification performance than subset 2, meaning that a higher cluster diversity is more valuable to indicate better learning performance.

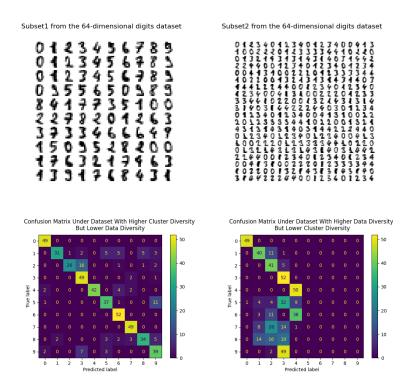


Figure 1: Confusion matrix under different training datasets.