1. Popis projektu

Aplikácia by mala pomôcť šoférom alebo ľudom, ktorí si potrebujú načerpať palivo a nevedia, kde

presne sa nachádza. Keďže dáta z druhého datasetu sú z Ameriky, budem sa zameriavať v projekte

na štát Colorado.

Celá aplikácia sa skladá z troch častí a to databáza, kde mám uložené dva zdroje dát, ktoré som

spomínal vyššie. Potom backend(FLASK), ktorý prijíma požiadavky z frontendu a zároveň

spracováva a vytvára dopyty na databázu. Následne všetko konvertuje do formatu GEOJSON a

odosiela na frontend. Frontend(MAPBOX-GL) spracováva a zobrazuje informácie cez formát

geojson, filtruje a posiela requesty na backend.

Celkovo som pracoval s dátami na Mapboxe ako s klastrami, takže sa zobrazujú niektoré stanice až

po priblížení. Na mape je pohyblivý bod, pomocou ktorého sa dajú vykonávať scenáre. Vytvoril

som aj heatmapu, ktorá znázoruje hustotu benziniek na mape. Ikony na mape sú rozdelené podľa

toho aké palivo je možné načerpať, teda palivo z ropy alebo na elektické palivo.

Najdôležitejšie scenáre:

Nájsť najbližších 10 benziniek

Benzínky v okruhu 5 km

Filtrovanie podľa elektrickej benzinky a elektrického paliva

heatmapa benziniek

zobrazenie počtu benziniek a elektrických čerpacích staníc

Zdroj dát: Openstreetmap.com, API na tankovacie

stanice: https://developer.nrel.gov/docs/transportation/alt-fuel-stations-v1/

Použité technológie: POSTGIS, PYTHON, MAPBOX-GL

2. Frontend

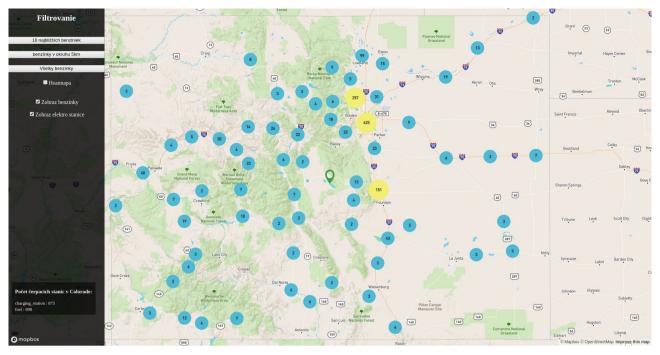
Ako frontend som použil Mapbox-GL, ktorý je novšia verzia mapboxjs. Aplikácia zobrazuje

benzínky a elektro stanice na mape, ktoré sa zobrazujú v klastroch. Na frontende je možné

filtrovanie dát, ktoré sa odosielajú na backend pomocou rôznych requestov. Na frontende je možné

zobrazovať všetky scenáre popísané vyššie. Treba mať spustený plugin CORS, ktorý povoluje

Access-Control-Allow-Origin.



Obr. 1: Ukážka systému

2. Backend

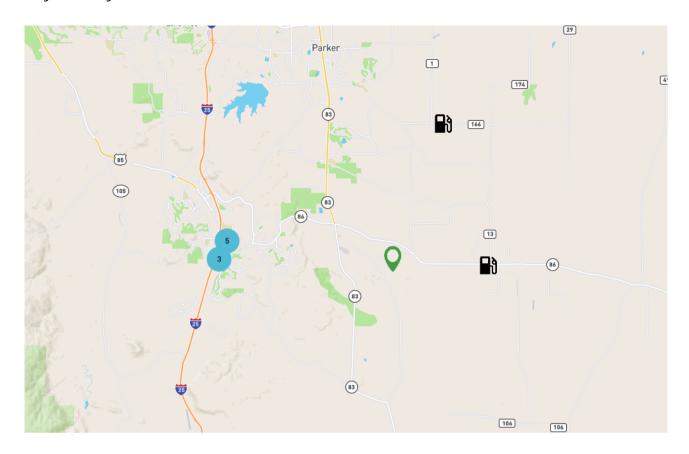
Ako backend som použil Flask, čo je pythonovský framework na routovanie. Tu som písal všetky query potrebné na databázu. Celkovo je práca s týmto frameworkom jednoduchá. Napríklad v porovnaní so SpringBootom od javy.

Obr 2: Ukážka selectu na BE

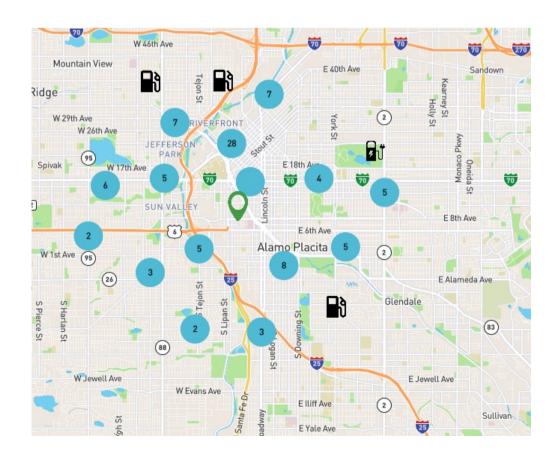
3. Ukážka scenárov

Na mape je možné hýbať pohyblivým bodom a tým neniť súradnice zadávania pri rôznych scenároch. K scenárom vždy pridávam query.

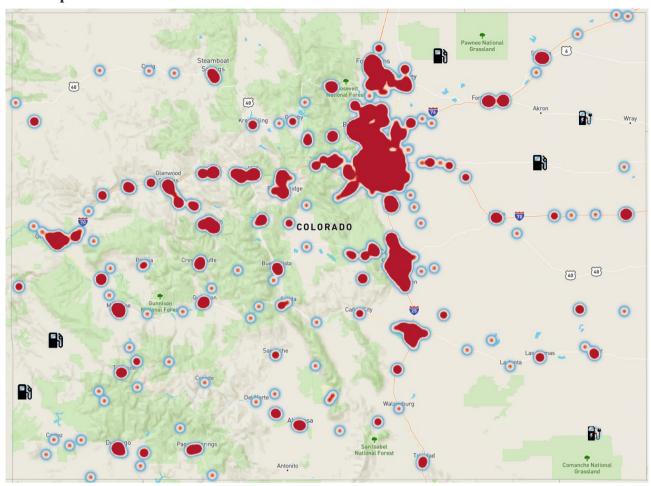
Nájdenie najbližších 10 benziniek:



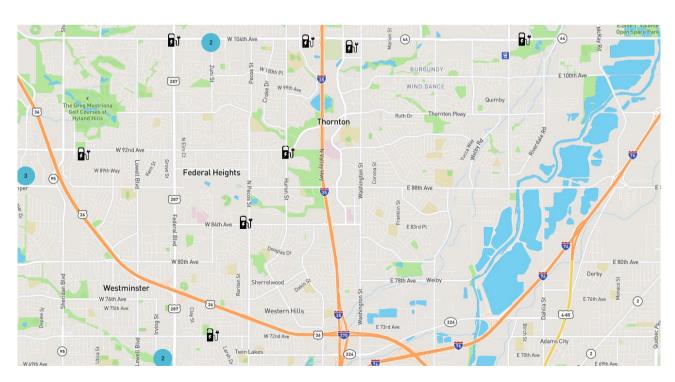
Nájdenie benzíniek v okruhu 5km:



Heatmapa:



Filtrácia elektrostaníc a benziniek:



Zobrazenie počtu benziniek a elektrických čerpacích staníc:

Počet čerpacích staníc v Colorade: charging_station: 875 fuel: 898

4. Ukážka scenárov

Na optimalizáciu query som použil indexovanie na základe parametru amenity. Čo mi v každom scenári zrýchlilo query v prepočte cca o 500 percent. V screenshote explainu je výsledok pred použitím indexu a po použití indexu. Vytvorenie indexu:

create index index planet_osm_point_on_amenity on planet_osm_point(amenity);

Všetky výsledky:

```
GroupAggregate (cost=13777.21..13778.57 rows=68 width=64)
GroupAggregate (cost=2640.09..2641.45 rows=68 width=64)
SELECT amenity, SUM(amenityCount) FROM(SELECT amenity, COUNT(amenity) as amenityCount FROM planet_osm_point
        WHERE amenity = 'fuel' OR amenity = 'charging station'
        GROUP BY amenity
        SELECT amenity, COUNT(amenity) as amenityCount from stations
        GROUP BY amenity) AS subquery
GROUP BY amenity;
     QUERY PLAN
    text
    HashAggregate (cost=2663.92..2680.47 rows=1655 width=48)
1
2
     Group Key: planet_osm_point.amenity, (st_x(planet_osm_point.way)), (st_y(planet_osm_point.way))
     -> Append (cost=23.78..2651.51 rows=1655 width=48)
3
4
         -> Bitmap Heap Scan on planet_osm_point (cost=23.78..2597.11 rows=865 width=26)
5
            Recheck Cond: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
6
            -> BitmapOr (cost=23.78..23.78 rows=865 width=0)
7
              -> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.00..18.39 rows=795 width=0)
8
                 Index Cond: (amenity = 'fuel'::text)
9
              -> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.00..4.96 rows=71 width=0)
10
                 Index Cond: (amenity = 'charging_station'::text)
11
         -> Seq Scan on stations (cost=0.00..37.85 rows=790 width=33)
    OUERY PLAN
    text
4
    HashAggregate (cost=13857.05..13873.60 rows=1655 width=48)
1
2
     Group Key: planet_osm_point.amenity, (st_x(planet_osm_point.way)), (st_y(planet_osm_point.way))
3
     -> Append (cost=1000.00..13844.64 rows=1655 width=48)
4
        -> Gather (cost=1000.00..13790.24 rows=865 width=26)
5
           Workers Planned: 2
6
           -> Parallel Seq Scan on planet_osm_point (cost=0.00..12701.21 rows=360 width=26)
               Filter: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
7
8
        -> Seq Scan on stations (cost=0.00..37.85 rows=790 width=33)
```

Nájdenie benzíniek v okruku 15 000 km:

4	QUERY PLAN text
1	Sort (cost=24765.6924767.07 rows=551 width=56)
2	Sort Key: (("111.045"::double precision * degrees(acos(((("0.776589160902741"::double precision * cos(radians(st_y(planet_osm_point.way)))) * cos((radians(st_x(planet_osm_point.way))) - '-1.84440504912245'::double precision * cos(radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) - '-1.84440504912245'::double precision * cos(radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) - '-1.84440504912245'::double precision * cos(radians(st_x(planet_osm_point.way)))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.way)))) * cos((radians(st_x(planet_osm_point.way))) * cos((radians(st_x(planet_osm_point.wa
3	-> HashAggregate (cost=24735.0924740.60 rows=551 width=56)
4	Group Key: planet_osm_pointamenity, (st_x(planet_osm_pointway)), (st_y(planet_osm_pointway)), (("111.045"::double precision * degrees(acos(((("0.776589160902741"::double precision * cos(radians(st_y(planet_osm_pointway)))))
5	-> Append (cost=1000.0024729.58 rows=551 width=56)
6	-> Gather (cost=1000.0024642.13 rows=288 width=34)
7	Workers Planned: 2
8	-> Parallel Seq Scan on planet_osm_point (cost=0.0023605.35 rows=120 width=34)
9	Filter: (((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text)) AND (('111.045'::double precision * degrees(acos(((('0.776589160902741'::double precision * cos(radians(st_y(way))))) * cos((radi
10	-> Seq Scan on stations (cost=0.0081.94 rows=263 width=41)
11	Filter: (('111.045'::double precision * degrees(acos(((('0.776589160902741'::double precision * cos(radians(st_y(geo))))) * cos((radians(st_y(geo)) - '-1.84440504912245'::double precision))) + ('0.6300073

4	QUERY PLAN text
1	Sort (cost=2768.662770.04 rows=551 width=56)
2	Sort Key: (('111.045'::double precision * degrees(acos(((('0.776589160902741'::double precision * cos(radians(st_y(planet_osm_point.way)))) * cos((radians(st_y(planet_osm_point.way)))) * cos((radians(st_y(planet_osm_point.way))) * cos((radians(st_y(planet_osm_point.way)))) * cos((radians(st_y(planet_osm_point.way)))) * cos((radians(st_y(planet_osm_point.way))) * cos((radians(st_y(planet_osm_point.way)))) * cos((radians(st_y(planet_osm_point.way))) * cos((radians(st_y(planet_osm_point.way))) * cos((radians(st_y(planet_osm_point.way))) * cos((radians(st_y(p
3	-> HashAggregate (cost=2738.062743.57 rows=551 width=56)
4	Group Key: planet_osm_point.amenity, (st_x(planet_osm_point.way)), (st_y(planet_osm_point.way)), (('111.045'::double precision * degrees(acos(((('0.7
5	-> Append (cost=23.492732.55 rows=551 width=56)
6	-> Bitmap Heap Scan on planet_osm_point (cost=23.492645.10 rows=288 width=34)
7	Recheck Cond: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
8	Filter: (('111.045'::double precision * degrees(acos(((('0.776589160902741'::double precision * cos(radians(st_y(way)))) * cos((radians(st_x(way)))) * cos((radians(st_x(w
9	-> BitmapOr (cost=23.4923.49 rows=865 width=0)
10	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.0018.39 rows=795 width=0)
11	Index Cond: (amenity = 'fuel'::text)
12	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.004.96 rows=71 width=0)
13	Index Cond: (amenity = 'charging_station'::text)
14	-> Seq Scan on stations (cost=0.0081.94 rows=263 width=41)
15	Filter: (('111.045'::double precision * degrees(acos(((('0.776589160902741'::double precision * cos(radians(st_y(geo)))) * cos((radians(st_x(geo

Najbližších 10 benziniek:

```
Limit (cost=13983.84..13983.86 rows=10 width=56)
Limit (cost=2790.71..2790.74 rows=10 width=56)
SELECT amenity, ST_X(way), ST_Y(way), 111.045 * DEGREES(ACOS(COS(RADIANS(39.04))
       * COS(RADIANS(ST_Y(way)))
       * COS(RADIANS(ST_X(way)) - RADIANS(-105.558522))
       + SIN(RADIANS(39.04))
       * SIN(RADIANS(ST Y(way)))))
       AS distance in km
       FROM planet osm point
       WHERE amenity = 'fuel' OR amenity = 'charging station'
       SELECT amenity, ST_X(geo), ST_Y(geo), 111.045 * DEGREES(ACOS(COS(RADIANS(39.04)))
        * COS(RADIANS(ST_Y(geo)))
       * COS(RADIANS(ST_X(geo)) - RADIANS(-105.558522))
        + SIN(RADIANS(39.04))
        * SIN(RADIANS(ST_Y(geo)))))
       AS distance in km
       FROM stations
       ORDER BY distance in km ASC
       LIMIT 10;
```

4	QUERY PLAN text
1	Limit (cost=13983.8413983.86 rows=10 width=56)
2	-> Sort (cost=13983.8413987.98 rows=1655 width=56)
3	Sort Key: (('111.045'::double precision * degrees(acos(((('0.776706423591959'::double precision * cos(radians(st_y(planet_osm_point.wa
4	-> HashAggregate (cost=13931.5213948.07 rows=1655 width=56)
5	Group Key: planet_osm_point.amenity, (st_x(planet_osm_point.way)), (st_y(planet_osm_point.way)), (('111.045'::double precision * degr
6	-> Append (cost=1000.0013914.98 rows=1655 width=56)
7	-> Gather (cost=1000.0013827.00 rows=865 width=34)
8	Workers Planned: 2
9	-> Parallel Seq Scan on planet_osm_point (cost=0.0012716.51 rows=360 width=34)
10	Filter: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
11	-> Seq Scan on stations (cost=0.0071.42 rows=790 width=41)

4	QUERY PLAN text
1	Limit (cost=2790.712790.74 rows=10 width=56)
2	-> Sort (cost=2790.712794.85 rows=1655 width=56)
3	Sort Key: (('111.045'::double precision * degrees(acos(((('0.776706423591959'::double precision * cos(radians(st_y(planet_osm_point.way)))) * cos((
4	-> HashAggregate (cost=2738.402754.95 rows=1655 width=56)
5	$Group \ Key: planet_osm_point.amenity, (st_x(planet_osm_point.way)), (st_y(planet_osm_point.way)), (('111.045'::double\ precision* degrees(acos(((acos)), (st_y(planet_osm_point.way)), (('111.045'::double\ precision* degrees(acos), ((acos)), ((acos))$
6	-> Append (cost=23.782721.85 rows=1655 width=56)
7	-> Bitmap Heap Scan on planet_osm_point (cost=23.782633.87 rows=865 width=34)
8	Recheck Cond: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
9	-> BitmapOr (cost=23.7823.78 rows=865 width=0)
10	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.0018.39 rows=795 width=0)
11	Index Cond: (amenity = 'fuel'::text)
12	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.004.96 rows=71 width=0)
13	Index Cond: (amenity = 'charging_station'::text)
14	-> Seq Scan on stations (cost=0.0071.42 rows=790 width=41)

Zobrazenie počtu benziniek a elektrických čerpacích staníc(agregačná funkcia):

4	QUERY PLAN text
1	GroupAggregate (cost=13777.2113778.57 rows=68 width=64)
2	Group Key: planet_osm_point.amenity
3	-> Sort (cost=13777.2113777.38 rows=68 width=40)
4	Sort Key: planet_osm_point.amenity
5	-> HashAggregate (cost=13773.7813774.46 rows=68 width=40)
6	Group Key: planet_osm_point.amenity, (count(planet_osm_point.amenity))
7	-> Append (cost=13714.7213773.44 rows=68 width=40)
8	-> Finalize GroupAggregate (cost=13714.7213734.90 rows=67 width=18)
9	Group Key: planet_osm_point.amenity
10	-> Gather Merge (cost=13714.7213733.56 rows=134 width=18)
11	Workers Planned: 2
12	-> Partial GroupAggregate (cost=12714.7012718.07 rows=67 width=18)
13	Group Key: planet_osm_point.amenity
14	-> Sort (cost=12714.7012715.60 rows=360 width=10)
15	Sort Key: planet_osm_point.amenity
16	-> Parallel Seq Scan on planet_osm_point (cost=0.0012699.41 rows=360 width=10)
17	Filter: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
18	-> HashAggregate (cost=37.8537.86 rows=1 width=25)
19	Group Key: stations.amenity
20	-> Seq Scan on stations (cost=0.0033.90 rows=790 width=17)

4	QUERY PLAN text
1	GroupAggregate (cost=2640.092641.45 rows=68 width=64)
2	Group Key: planet_osm_point.amenity
3	-> Sort (cost=2640.092640.26 rows=68 width=40)
4	Sort Key: planet_osm_point.amenity
5	-> HashAggregate (cost=2636.662637.34 rows=68 width=40)
6	Group Key: planet_osm_point.amenity, (count(planet_osm_point.amenity))
7	-> Append (cost=2597.112636.32 rows=68 width=40)
8	-> HashAggregate (cost=2597.112597.78 rows=67 width=18)
9	Group Key: planet_osm_point.amenity
10	-> Bitmap Heap Scan on planet_osm_point (cost=23.782592.78 rows=865 width=10)
11	Recheck Cond: ((amenity = 'fuel'::text) OR (amenity = 'charging_station'::text))
12	-> BitmapOr (cost=23.7823.78 rows=865 width=0)
13	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.0018.39 rows=795 width=0)
14	Index Cond: (amenity = 'fuel'::text)
15	-> Bitmap Index Scan on index_planet_osm_point_on_amenity (cost=0.004.96 rows=71 width=0)
16	Index Cond: (amenity = 'charging_station'::text)
17	-> HashAggregate (cost=37.8537.86 rows=1 width=25)
18	Group Key: stations.amenity
19	-> Seg Scan on stations (cost=0.0033.90 rows=790 width=17)