



# MONASH University

**My Thesis Title is Long:  
So I added A Line Break For Style**

My Full Name

My previous academic degrees

A Thesis Submitted for the Degree of Doctor of Philosophy at

**Monash University** in year

My Department

My Faculty

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## Abstract

## Publications during enrolment

### Journal Publications

- Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Dynamical modelling of boom tower crane rigging systems: model selection for construction’. In: *Archives of Civil and Mechanical Engineering* 23.3 (2023), p. 162. DOI: [10.1007/s43452-023-00702-x](https://doi.org/10.1007/s43452-023-00702-x)
- Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Crane payload localisation for curtain wall installation: A markerless computer vision approach’. In: *Measurement* (2023). (In press), p. 113459. DOI: [10.1016/j.measurement.2023.113459](https://doi.org/10.1016/j.measurement.2023.113459)

### Conference Publications

- Brandon Johns, Mehrdad Arashpour and Elahe Abdi. ‘Curtain Wall Installation for High-Rise Buildings: Critical Review of Current Automation Solutions and Opportunities’. In: *Proceedings of the 37th International Symposium on Automation and Robotics in Construction (ISARC)*. 2020, pp. 393–400. DOI: [10.22260/ISARC2020/0056](https://doi.org/10.22260/ISARC2020/0056)
- Kerry He, Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Camera View from Crane Payload: Video Stabilization’. In: *Australasian Conference on Robotics and Automation, ACRA*. 2021. URL: [https://ssl.linklings.net/conferences/acra/acra2021\\_proceedings/views/includes/files/pap104s2-file1.pdf](https://ssl.linklings.net/conferences/acra/acra2021_proceedings/views/includes/files/pap104s2-file1.pdf)

### Research Data

- Brandon Johns, Elahe Abdi and Mehrdad Arashpour. *Glass Curtain Wall Installation Dataset*. 2023. DOI: [10.26180/23538198](https://doi.org/10.26180/23538198)

### Free & Open Source Code

- <https://github.com/Brandon-Johns/crane-dynamics-simulator>

## Thesis including published works declaration

I hereby declare that this thesis contains no material which has been accepted for the award of any other degree or diploma at any university or equivalent institution and that, to the best of my knowledge and belief, this thesis contains no material previously published or written by another person, except where due reference is made in the text of the thesis.

This thesis includes COUNT original papers published in peer reviewed journals and COUNT submitted publications.. The core theme of the thesis is THEME. The ideas, development and writing up of all the papers in the thesis were the principal responsibility of myself, the student, working within the My Department under the supervision of NAME and NAME.


The inclusion of co-authors reflects the fact that the work came from active collaboration between researchers and acknowledges input into team-based research.

In the case of Chapters 4 and 5, my contribution to the work involved the following:

Thesis Chapter	Publication Title	Status	Nature and % Student Contribution	Co-author name(s) Nature and % of Co-author's contribution	Co-author(s), Monash student
4	The Title of My First Published Article	Published	(70%)	NAME (10%) NAME (10%) NAME (5%) NAME (5%)	No No No No
5	The Title of My Second Published Article	In Press	(80%)	NAME (10%) NAME (10%)	No No

I have not renumbered sections of submitted or published papers in order to generate a consistent presentation within the thesis.

**Student name:** My Full Name

**Student signature:** 

**Date:** 01/09/2023

I hereby certify that the above declaration correctly reflects the nature and extent of the student's and co-authors' contributions to this work. In instances where I am not the

responsible author I have consulted with the responsible author to agree on the respective contributions of the authors.

**Main Supervisor name:** NAME

**Main Supervisor signature:** `tis I!

**Date:** 01/09/2023

## Acknowledgements

Thank you to everyone who has supported me<sup>1</sup> during my candidature.

NAME<sup>2</sup> — My main supervisor. Thanks for being a great supervisor!

NAME<sup>3</sup> — My 2nd supervisor. Thanks for being a great supervisor!

This research was supported by an Australian Government Research Training Program (RTP) Scholarship.

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<sup>1</sup>My Full Name  <https://orcid.org/0000-0000-0000-0000>

<sup>2</sup>NAME  <https://orcid.org/0000-0000-0000-0000>

<sup>3</sup>NAME  <https://orcid.org/0000-0000-0000-0000>

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# Abbreviations

<b>BIM</b>	Building Information Modelling
<b>CAD</b>	Computer Aided Design
<b>DAE</b>	Differential Algebraic Equation
<b>DOF</b>	Degrees of Freedom
<b>IMU</b>	Inertial Measurement Unit
<b>LiDAR</b>	Light Detection and Ranging
<b>NIR</b>	Near Infrared
<b>ODE</b>	Ordinary Differential Equation

# Constants

Speed of Light  $c = 2.997\,924\,58 \times 10^8 \text{ ms}^{-2}$

# Symbols

$a$  distance m

$P$  power W ( $\text{Js}^{-1}$ )

$\omega$  angular frequency  $\text{rads}^{-1}$

# 1 Example Content

---

This section showcases the way I formatted my lists, tables, equations, etc. If you decide to do it differently, then you'll be on your own to debug any subsequent formatting problems.

The structure of this chapter is as follows: Section [1.1](#) showcases the use of SSSSR sections. Section [1.2](#) discusses the use of line breaks in section headings. Section [1.3](#) shows how to display many different types of content.

## 1.1 Displaying Sections

This section has many subsections, which I can refer to by their labels. e.g. Section [1.1](#), Section [1.1.1](#), Section [1.1.1.1](#), Section [1.1.1.1.1](#), and Section [1.1.2](#).

Labeling sections is optional. Labels may be anything, but must be unique (hence my naming convention).

Example text.

### 1.1.1 My Subsection

Example text.

#### 1.1.1.1 My Subsubsection

Example text.

##### 1.1.1.1.1 My Subsubsubsection... WAIT WHAT!?

If you get this deep, the command is not 'subsubsubsection', but 'paragraph'. Why?

For the record, I suggest not to use this much depth unless you've really thought about your structure, and you are sure that it is the best way to do it.

#### 1.1.1.1.1.1 My Subsubsubsubsection... rofl

This is the maximum section depth that the titlesec package defines. May you never need it.

### 1.1.2 My Other Subsection

Example text.

## 1.2 Displaying Different Text In The Contents Because You Can

The heading in this section is different to the heading in the table of contents. You can use this method if you wish to force line breaks in your heading, but not in the contents.

## 1.3 Displaying Different Types of Content

### 1.3.1 Citations

This is a citation [3], and this is another [2, 3, 4, 5].

This is a footnote<sup>1</sup>. The text continues.

### 1.3.2 Lists

An example list is as follows:

1. This is a list
2. This is a list
3. This is a list

---

<sup>1</sup>Source: [Example](#).



### 1.3.3 Quotes

Quotes can be used as follows

Inline quotes can use ‘single’ or “double” quotes like this. To this, Brandon stated:

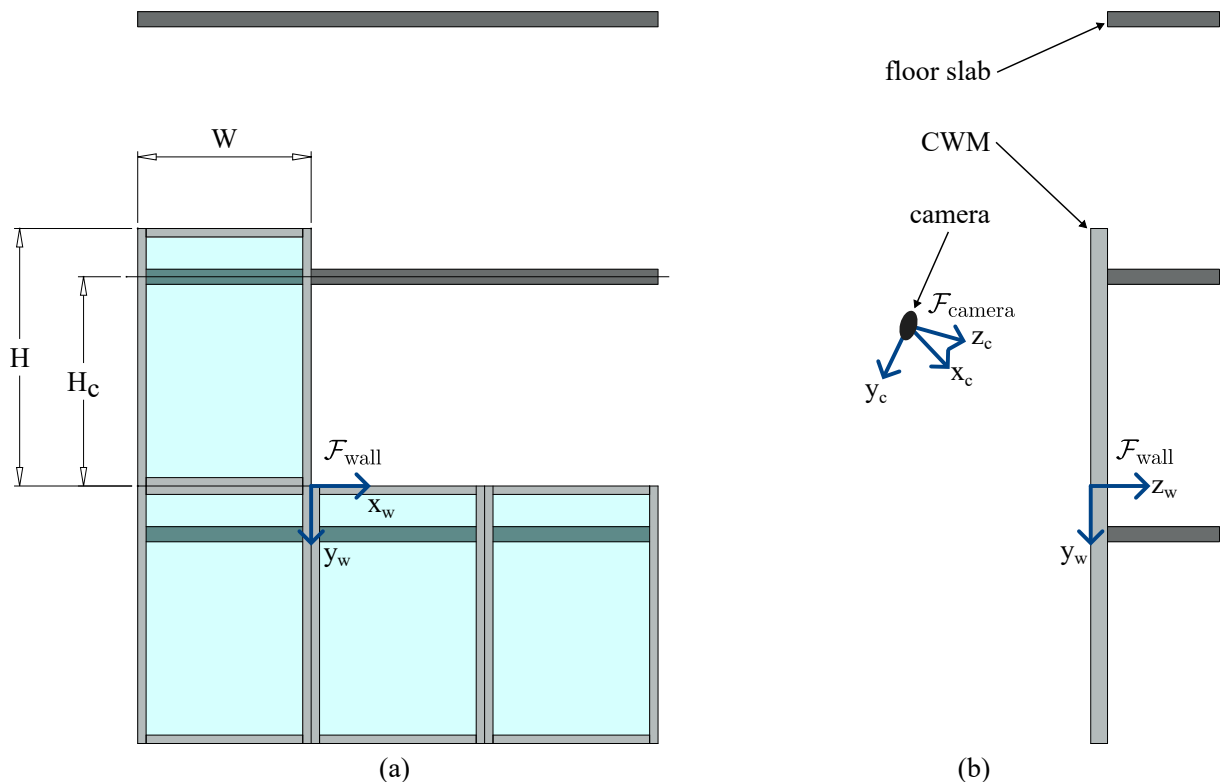
“Turtles are cute.”

### 1.3.4 Figures

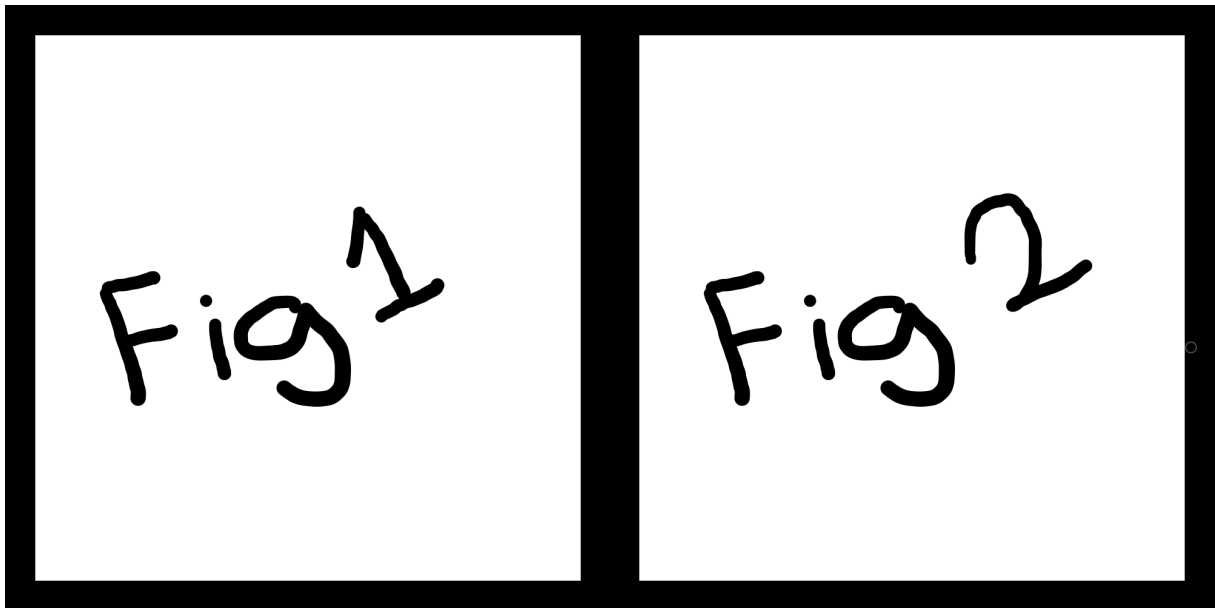
This is a figure reference: Figure 1.1

Some different ways to show figures include full page width (Figure 1.1), side-by-side (Figure 1.2 and Figure 1.3), and subfigures (Figure 1.4 which consists of Figure 1.4a and Figure 1.4b).

If you have mathematical symbols in your figures and you’re using inkscape, you can input latex maths into the figure with: Extensions > Render > Formula (pdflatex).

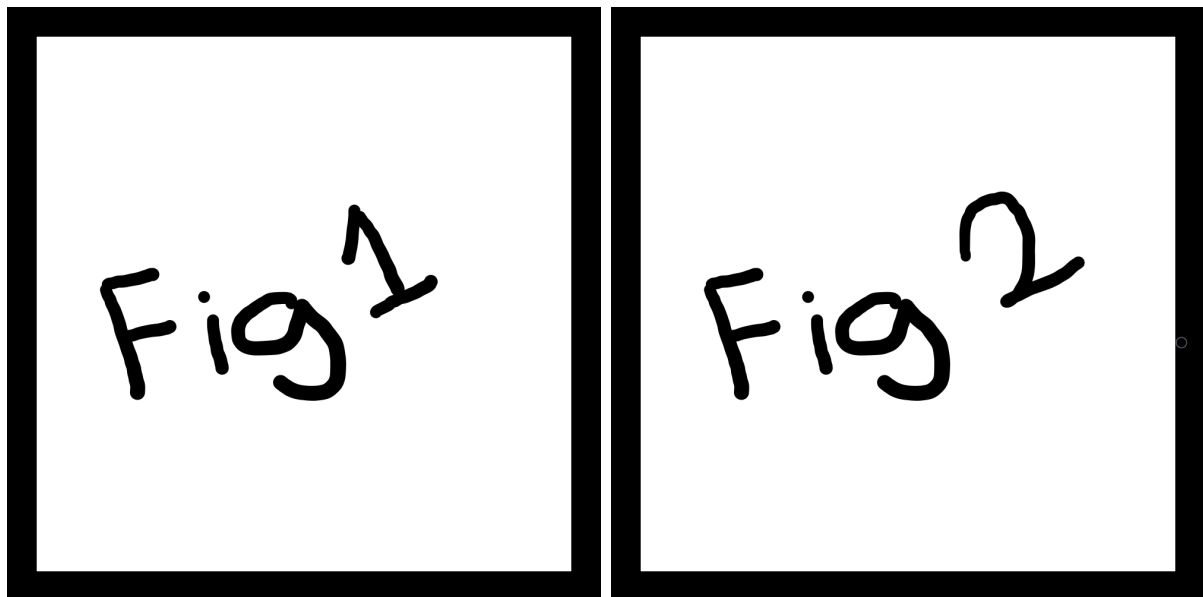


**Figure 1.1:** Export your graphics to pdf. Lovely vector graphics! If I see any jpeg text I am sad.



**Figure 1.2:** Cool graphic!

**Figure 1.3:** This is a very long caption that takes up multiple lines.



**(a)** Cool graphic!

**(b)** This is a very long caption that takes up multiple lines.

**Figure 1.4:** Cool graphics!

### 1.3.5 Equations

This is an equation reference: (1.1).

$$a = 2 \tag{1.1}$$

where  $a$  is a variable.

### 1.3.6 Tables

This is a table reference: Table [1.1](#).

This is a fairly basic table. See `threeparttable` if you want table notes (footnotes for tables). For more fancy tables, use `NiceTabular` of the package `NiceMatrix`.

Measurement	Unit	Measurement error	
		Mean	Standard deviation
$x_n$	mm	5.2	8.6
$y_n$	mm	3.5	3.0
$z_n$	mm	-6.5	9.1
$\theta_q$	degrees	$1.6^\circ$	$2.9^\circ$

**Table 1.1:** Average measurement error over all 99 successful measurements.  $(x_n, y_n, z_n)$  are defined somewhere else.  $\theta_q$  is the rotational misalignment as a quaternion angular distance.

### 1.3.7 Algorithms

Pseudocode of the algorithm is Algorithm [1](#). In the first stage of the algorithm, Lines [2–7](#) validate the inputs. Then Lines [8–12](#) do the calculation. Then Line [13](#) outputs the result.

---

**Algorithm 1:** Algorithm to find the area of an object.

---

*Type Definitions*

**Length:** A length measurement, with units in mm

**Area** : An area measurement, with units in mm<sup>2</sup>

1 **Function** Multiply

**Input**

$L$  : [Length] Object length

$W$  : [Length] Object width

**end**

2   **if**  $L < 0$

3   |   **return** *Bad input:  $L$*

4   **else if**  $W < 0$

5   |   **return** *Bad input:  $W$*

6   **else**

7   |   Carry on citizen

**end**

8   Copy  $L$  into the calculator

9   press the  $\times$  button on the calculator

10   Copy  $W$  into the calculator

11   Press the = button on the calculator

12   **Area**  $A \leftarrow$  The result shown on the calculator

13   **return**  $A$ , *The area as measured in units of mm<sup>2</sup>*

**end**

---

# 2 Introduction

---

This thesis pertains to the field of ...

## 2.1 Motivations

## 2.2 Aims and Objectives

This thesis aims to ...

The key objectives are:

- Something
- Something
- Something

## 2.3 Summary of Thesis Contributions

Overall, this thesis contributes to ...

The key contributions of this thesis are:

- Something
- Something
- Something

## 2.4 Thesis Outline

Chapter 3 introduces the background and related literature.

Chapter 4 explores ...

Chapter 5 introduces ...

Chapter 6 concludes the thesis and discusses directions for future research.

# 3 Background and Literature Review

---

*This chapter contains content from my publication [3].*

*The ... was undertaken with approval from the Monash University Human Research Ethics Committee (MUHREC) – project ID 00000.*

This chapter introduces the background and related literature. ...

## 3.1 MySection

## 3.2 Summary & Research Directions

Background

This thesis focuses on ...

...

Key directions to ... are:

- Something
- Something
- Something

The remainder of this thesis investigates these research directions. Chapter 4 evaluates ... Chapter 5 introduces ...

# 4 My First Published Article

---

*This chapter embeds a copy of my publication [\[1\]](#), which is distributed under the [Creative Commons CC BY 4.0 license](#).*

## 4.1 The Title of My First Published Article

List of Amendments to [\[1\]](#)

- Equation 6 contains a typographical error, in which  ${}^O\mathbf{p}_i$  should be  ${}^O\dot{\mathbf{p}}_i$



This document represents your published article. It is **letterpaper size**.

Example citation [\[1\]](#). Test that clicking it jumps you to the reference list, and test that clicking the DOI in the reference list opens the webpage. You can also check the links in a pdf reader (e.g. In PDF XChange Editor, use ‘View/Edit Links’).

## References

- [1] Brandon Johns, Elahe Abdi, and Mehrdad Arashpour. “Dynamical modelling of boom tower crane rigging systems: model selection for construction”. In: *Archives of Civil and Mechanical Engineering* 23.3 (2023), p. 162. DOI: [10.1007/s43452-023-00702-x](https://doi.org/10.1007/s43452-023-00702-x).

## 4.2 Outlook

The outcomes of this work ...

The work finds that ...

The next chapter applies these results to ...

## 5 My Second Published Article

---

*This chapter embeds a copy of my publication [\[2\]](#), which is distributed under the [Creative Commons CC BY 4.0 license](#).*

### 5.1 The Title of My Second Published Article

This document represents your published article. It is **A4 size**.

Example citation [1]. Test that clicking it jumps you to the reference list, and test that clicking the DOI in the reference list opens the webpage. You can also check the links in a pdf reader (e.g. In PDF XChange Editor, use ‘View/Edit Links’).

## References

- [1] Brandon Johns, Elahe Abdi, and Mehrdad Arashpour. “Dynamical modelling of boom tower crane rigging systems: model selection for construction”. In: *Archives of Civil and Mechanical Engineering* 23.3 (2023), p. 162. DOI: [10.1007/s43452-023-00702-x](https://doi.org/10.1007/s43452-023-00702-x).

## 5.2 Outlook

The outcomes of this work ...

# 6 Conclusions and Outlook

---

This thesis contributes to ... The key contributions are:

- Something
- Something
- Something

The outcomes of this work ...:

- In Chapter [4](#), it is found that ...
- In Chapter [5](#), ...

Future work is recommended to ... Specific directions for future work are:

- Something
- Something
- Something



# A An Appendix

---

todo

## A.1 Displaying Sections

Example text.

### **A.1.1 My Subsection**

Example text.

#### **A.1.1.1 My Subsubsection**

Example text.

#### **A.1.1.1.1 My Subsubsubsection... WAIT WHAT!?**

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#### **A.1.1.1.1.1 My Subsubsubsubsection... rofl**

This is the maximum section depth that the titlesec package allows. May you never need it.

### **A.1.2 My Other Subsection**

Example text.

# B Another Appendix

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todo

# Bibliography

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- [1] Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Dynamical modelling of boom tower crane rigging systems: model selection for construction’. In: *Archives of Civil and Mechanical Engineering* 23.3 (2023), p. 162. DOI: [10.1007/s43452-023-00702-x](https://doi.org/10.1007/s43452-023-00702-x).
- [2] Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Crane payload localisation for curtain wall installation: A markerless computer vision approach’. In: *Measurement* (2023). (In press), p. 113459. DOI: [10.1016/j.measurement.2023.113459](https://doi.org/10.1016/j.measurement.2023.113459).
- [3] Brandon Johns, Mehrdad Arashpour and Elahe Abdi. ‘Curtain Wall Installation for High-Rise Buildings: Critical Review of Current Automation Solutions and Opportunities’. In: *Proceedings of the 37th International Symposium on Automation and Robotics in Construction (ISARC)*. 2020, pp. 393–400. DOI: [10.22260/ISARC2020/0056](https://doi.org/10.22260/ISARC2020/0056).
- [4] Kerry He, Brandon Johns, Elahe Abdi and Mehrdad Arashpour. ‘Camera View from Crane Payload: Video Stabilization’. In: *Australasian Conference on Robotics and Automation, ACRA*. 2021. URL: [https://ssl.linklings.net/conferences/acra/acra2021\\_proceedings/views/includes/files/pap104s2-file1.pdf](https://ssl.linklings.net/conferences/acra/acra2021_proceedings/views/includes/files/pap104s2-file1.pdf).
- [5] Brandon Johns, Elahe Abdi and Mehrdad Arashpour. *Glass Curtain Wall Installation Dataset*. 2023. DOI: [10.26180/23538198](https://doi.org/10.26180/23538198).