Friday, November 13, 2020 5:14 PM

$$\vec{N} = \frac{d}{dt} \vec{L} + \vec{\omega} \times \vec{L}, \quad \text{where} \quad \vec{L} = \vec{L} \vec{\omega} = \begin{pmatrix} A \omega \times i \\ B \omega y i \\ C \omega y i \end{pmatrix}$$

$$\frac{d}{dt} \vec{L} = \begin{pmatrix} \dot{A} \omega_{X'} + A \dot{\omega}_{X'} \\ \dot{B} \omega_{Y'} + B \dot{\omega}_{Y'} \\ \dot{C} \omega_{Y'} + C \dot{\omega}_{Y'} \end{pmatrix}$$

$$\frac{d}{dt} \vec{L} = \begin{pmatrix} \dot{A} \omega_{X'} + A \dot{\omega}_{X'} \\ \dot{B} \omega_{Y'} + B \dot{\omega}_{Y'} \\ \dot{C} \omega_{Y'} + C \dot{\omega}_{Y'} \end{pmatrix}$$

 $N_{3'} = -\frac{2}{5}Ma^{2} \epsilon \Omega \cos(\Omega t) \omega_{3'} + \frac{2}{5}Ma^{2}(1 + \epsilon \sin \Omega t) \omega_{3'}$

Star in space, so
$$\vec{N} = \vec{0}$$
:
$$\vec{W}_{2} = \frac{2\Omega \cdot \omega \sigma(\Omega t) \omega_{2}}{1 + 2m(\Omega t)}$$

In the case where derivatives of A, B, and C can be ignored (52 << way),

$$Ai\omega_{xi} + (A-C)\omega_{yi}\omega_{xj} = 0,$$
 $Ai\omega_{yi} + (C-A)\omega_{zi}\omega_{xi} = 0,$
 $Ci\omega_{yi} = 0.$

Then the value Ip can be defined ur follows:

From the Euler equations above,

$$\dot{\omega}_{x'} = - \Omega_{p} \omega_{y'}, \quad \dot{\omega}_{y'} = \Omega_{p} \omega_{x'},$$

This gives

where I is just some constant.

Die the angular velocity is precising wound the z' axis with a frequency of Sup.

$$\Omega_{p} = \frac{\frac{2}{5} Ma^{2} (1 + \xi \sin \Omega t) - \frac{1}{5} M(\xi^{2} + k^{2}) (1 - \frac{\epsilon}{2} \sin \Omega t)}{\frac{1}{5} M(\xi^{2} + k^{2}) (1 - \frac{\epsilon}{2} \sin \Omega t)} \omega_{2}$$

$$= \left[\frac{2a^{2} (1 + \epsilon \sin \Omega t)}{(\epsilon^{2} + k^{2}) (1 - \frac{\epsilon}{2} \sin \Omega t)} - 1 \right] \omega_{2}'(t)$$

$$\approx \left[\frac{a^{2} - k^{2}}{\epsilon^{2} + k^{2}} + \frac{3a^{2} \sin \Omega t}{a^{2} + k^{2}} + \Omega(\epsilon^{2}) \right] \omega_{2}'(t)$$

If a=b=h the star is spherical (?),

the Q(1) term vanisher, and the Q(2) term simplifies to,

3 mmse E.

The first term dictater precession.

The first term dictater precession and bordier, and the second term is a correction.

The second term is a correction of the second term is a correction.