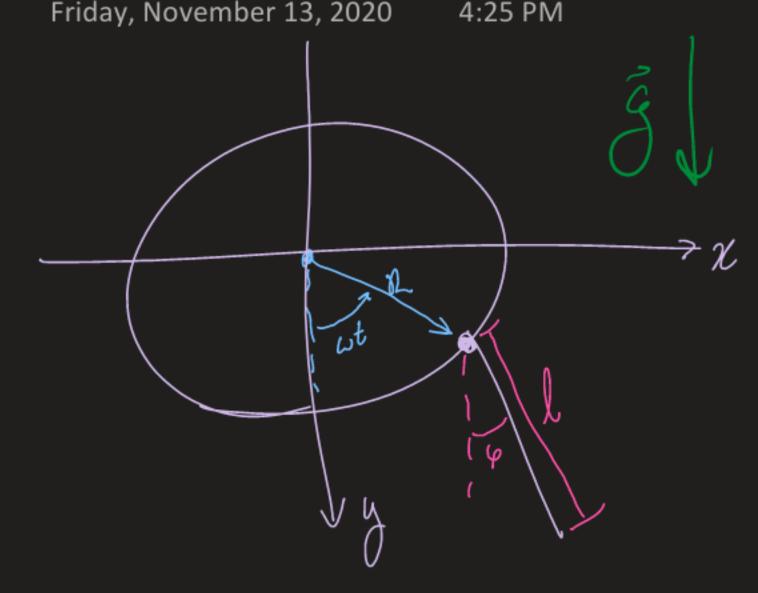
Friday, November 13, 2020 4:25 PM



$$T = \frac{1}{2} m \dot{\vec{r}}^2$$

$$= \frac{1}{2} m \left(\omega^2 R^2 + \frac{\ell^2}{4} \dot{\varphi}^2 \sigma \omega R l \dot{\varphi} \cos (\varphi - \omega t) \right)$$

From here on, I we eg. 2 from

$$\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{\varphi}} = 0 = d \left[\frac{1}{3} \operatorname{ml}^{2} \dot{\varphi} + \frac{1}{2} \operatorname{mkl} \omega \cos (\varphi - \omega t) \right] + \frac{1}{2} \operatorname{mkl} \omega \dot{\varphi} \sin (\varphi - \omega t) + \frac{1}{2} \operatorname{mgh} \sin \varphi$$

$$= \frac{1}{3} \operatorname{ml}^{2} \ddot{\varphi} - \frac{1}{2} \operatorname{mkl} \omega \sin (\varphi - \omega t) (\dot{\varphi} - \omega) + \frac{1}{2} \operatorname{mkl} \omega \dot{\varphi} \sin (\varphi - \omega t) + \frac{1}{2} \operatorname{mgh} \sin \varphi$$

Ring + loop > \(\vec{r} \) \(\lambda \) \\
\(\vec{r} \) + (w Rim wt + 2 mm 4 4)2 = wkws2wt + L2 woo2 q qi2 + wkl wowt voo q q + w2R2 sin wt + 4 sin 29 ip2+ wRl sin wt sin 4 ip $= \omega^2 R^2 + L_{\overline{q}}^2 \dot{\varphi}^2 + \omega R L \dot{\varphi} \omega_{\delta} (\varphi - \omega^{\epsilon})$