

First - and second-order Systems

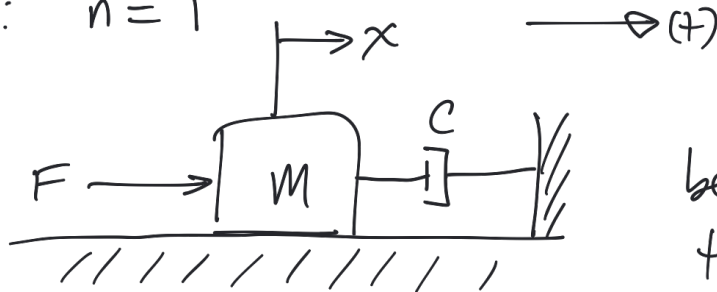
①

$$T(s) = \frac{N(s)}{D(s)} \quad \begin{array}{l} \swarrow \text{polynomial in } s \\ \searrow \end{array}$$

First-order system:

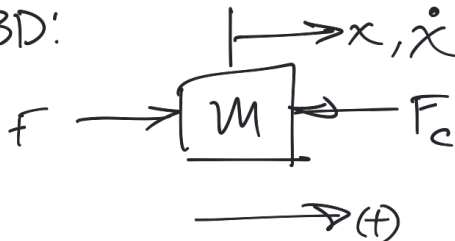
Means: $n = 1$

Ex



Find model
between Force to
the velocity of the mass

FBD:



Sum forces:

$$\sum F = m\ddot{x}, \text{ let } \dot{x} = v$$

②

$$F - c \dot{x} = m \ddot{x}, \quad \text{we have } \dot{x} = v$$

$$\Rightarrow m \ddot{x} + c \dot{x} = F \Rightarrow m \dot{v} + c v = F$$

$$\Rightarrow \dot{v} + \frac{c}{m} v = \frac{1}{m} F$$

Take L.T. w/ zero I.C.

$$sV(s) + \frac{c}{m} V(s) = \frac{1}{m} F(s)$$

Find the transfer function: $T(s) = \frac{V(s)}{F(s)}$

$$\Rightarrow V(s) \left[s + \frac{c}{m} \right] = \frac{1}{m} F(s)$$

$$\Rightarrow \frac{V(s)}{F(s)} = \frac{1/m}{s + c/m} = \frac{b_0}{s + a_0}$$

In general, 1st-order system transfer function can be written as follows:

③

$$T(s) = \frac{V(s)}{F(s)} = \frac{b_0}{s + a_0} \cdot 1 = \frac{b_0 \longleftrightarrow a_0}{s + a_0} \cdot \frac{a_0}{a_0}$$

$$= \frac{a_0}{s + a_0} \cdot \underbrace{\left(\frac{b_0}{a_0} \right)}_K = K \frac{1/\tau}{s + 1/\tau}$$

$$\Rightarrow T(s) = K \frac{1/\tau}{s + 1/\tau} \quad \text{where} \quad K = \frac{b_0}{a_0} \quad \text{and} \quad \frac{1}{\tau} = a_0$$

τ is the time constant, the time it takes the output to reach 63% of final value when the input is a step input.

(4)

Ex: $T(s) = \frac{3}{s+8}$ we want K
and τ

$$\Rightarrow T(s) = K \frac{1/\tau}{s + 1/\tau} ; \quad \begin{array}{l} b_0 = 3 \\ a_0 = 8 \end{array}$$

$$K = \frac{b_0}{a_0} \quad \frac{1}{\tau} = a_0 \Rightarrow \tau = \frac{1}{a_0}$$

Sub int numbers, we get:

$$K = \frac{3}{8} \quad \text{and} \quad \tau = 1/8$$

$$\Rightarrow T(s) = 3 \cdot \frac{8}{s+8}$$

(5)

Ex

$$T(s) = \frac{s+3}{s+9}$$

$\leftarrow m=1$
 $\leftarrow \underline{\underline{n=1}}$

First order

$$T(s) = \underbrace{\frac{s}{s+9}}_{\substack{1^{\text{st}}\text{-order} \\ \text{system}}} + \underbrace{\frac{3}{s+9}}_{\substack{1^{\text{st}}\text{-order} \\ \text{system}}}$$

And the time constant $\Rightarrow \tau = 1/9$

$$\frac{V(s)}{F(s)} = T(s) = K \frac{1/\tau}{s + 1/\tau} \Rightarrow \frac{V(s)}{F(s)} = K \frac{1/\tau}{s + 1/\tau} \quad (6)$$

$$(s + 1/\tau) V(s) = K (1/\tau) F(s) \Rightarrow sV(s) + \frac{1}{\tau} V(s) = \frac{K}{\tau} F(s)$$

we can take the Laplace inverse:

$$\Rightarrow \underbrace{\dot{V}(t) + \frac{1}{\tau} V(t)}_{\text{Natural response}} = \underbrace{\frac{K}{\tau} f(t)}_{\text{Input}} \Rightarrow \text{response due to forcing function}$$

"free response"
"Forced response"

if we solve O.D.E.

solution $V(t) = \underbrace{\text{free response}}_{\text{Transient}} + \underbrace{\text{forced response}}_{\text{steady-state}}$

Solution :

$$\dot{V}(t) + \frac{1}{\tau} V(t) = \frac{K}{\tau} f(t)$$

(7)

$$sV(s) + \frac{1}{\tau} V(s) = \frac{K}{\tau} F(s)$$

Suppose the input is a unit step,

$$u(t) = \begin{cases} 0 & t \leq 0 \\ 1 & t > 0 \end{cases}$$

Assume zero I.C.

The solution $V(t)$:

$$V(t) = K (1 - e^{-t/\tau})$$

L.T. Approach

$$\mathcal{L}\{u(t)\} = \frac{1}{s}$$

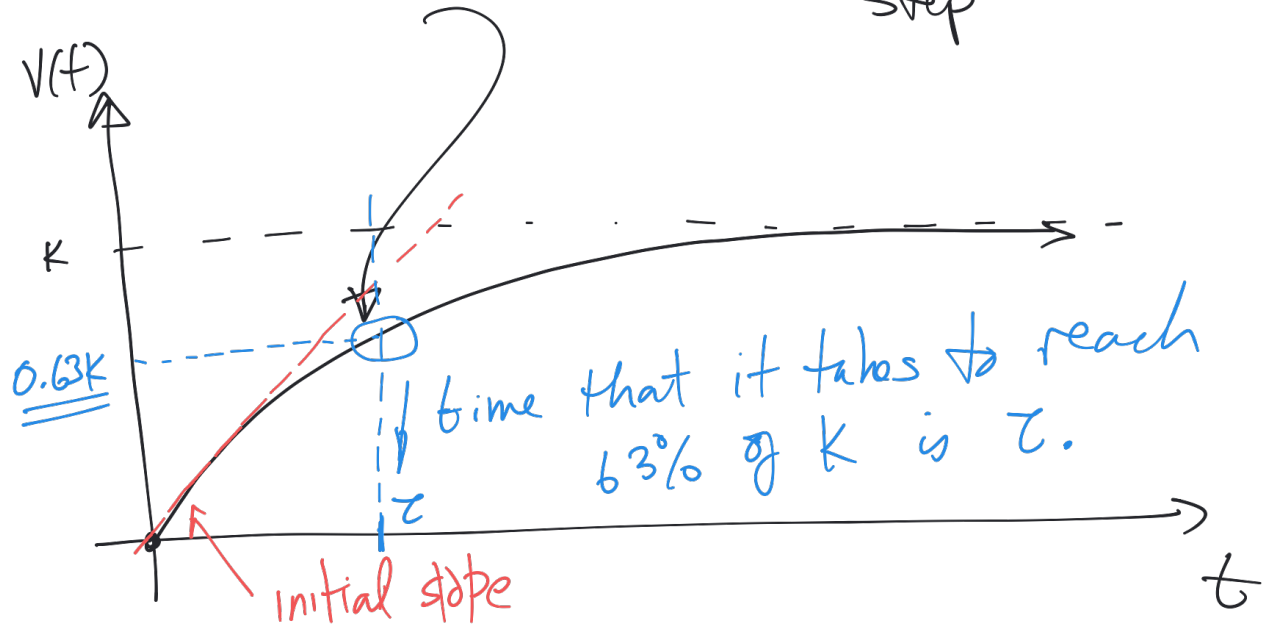
$$V(t) = \mathcal{L}^{-1}\left\{ \frac{K}{s(s + \frac{1}{\tau})} \right\}$$

τ = time constant.

(8)

$$V(t) = K(1 - e^{-t/\tau})$$

input was a unit step



When $t=0 \Rightarrow V(0)=0$; $t \rightarrow \infty \quad V(\infty)=K$

Initial slope: $\frac{d}{dt} V(t) \Big|_{t=0} = \frac{K}{\tau} e^{-t/\tau} \Big|_{t=0} \Rightarrow \frac{K}{\tau}$

