# Aerospace Propulsion

Lecture 9

Compressible Flows: Part III



## **Compressible Flows: Part III**

What is a Shockwave?

Normal Shocks

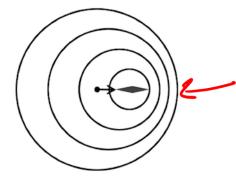
Oblique Shocks

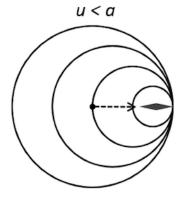
Conical Shocks



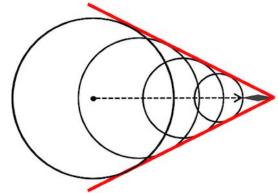
### What is a Shockwave?

- Imagine an object moving in a fluid
  - As it moves, it creates pressure disturbances
    - These move at speed of sound
- Do the surroundings "know" about the object?
  - Only once pressure disturbances reach
- Subsonic
  - Pressure waves ahead of object
- Supersonic
  - Pressure waves behind object













#### What is a Shockwave?

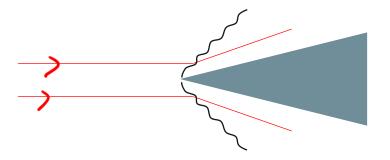
#### Subsonic

- Information (pressure waves) faster than object
- Flow ahead of object "knows" it is arriving
- Flow can gradually adjust



#### Supersonic

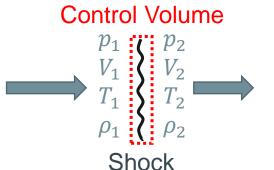
- Information slower than object
- Flow ahead of object does not "know" it is arriving
- Flow must adjust near-instantly (shock)



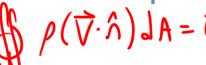


Simplest analysis is flow normal to shock wave

- Assumptions
  - Upstream/downstream flow is isentropic
  - Shock itself is adiabatic but <u>not isentropic</u>
  - Shock is very thin (<100 nm), so area change negligible



Jump Conditions: Mass

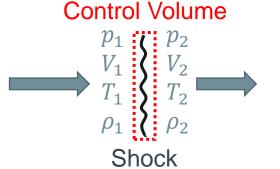


• Jump Conditions: N
$$\rho(\vec{\nabla} \cdot \hat{\Lambda}) JA = 0$$

$$A(\rho_2 V_2 - \rho_1 V_1) = 0$$

$$\rho_1 V_1 = \rho_2 V_2$$

• 
$$\rho_1 V_1 = \rho_2 V_2$$

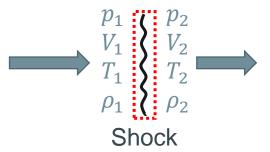


Jump Conditions: Momentum

• Jump Conditions: Momentum

$$\int_{0}^{\infty} \rho(x) \cdot \hat{r}(x) dx = \sum_{i=1}^{\infty} \frac{1}{2\pi} \int_{0}^{\infty} \frac{1}{2\pi} \int_{0}^$$

Control Volume

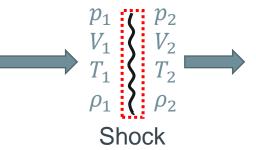




Jump Conditions: Energy

• 
$$h_1 + \frac{1}{2}V_1^2 = h_2 + \frac{1}{2}V_2^2$$
  
•  $T_1 + \frac{1}{2c_p}V_1^2 = T_2 + \frac{1}{2c_p}V_2^2$   
•  $T_1 \left(1 + \frac{\gamma - 1}{2}M_1^2\right) = T_2 \left(1 + \frac{\gamma - 1}{2}M_2^2\right)$ 

#### **Control Volume**

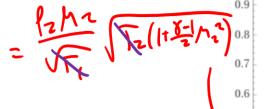




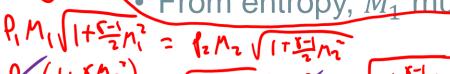
# Normal Shocks =>p= prt

Downstream Mach number









$$\frac{1}{2} = \frac{1}{2} N_2 \sqrt{1 + \frac{1}{2} N_1^2}$$

$$\frac{1}{2} N_1 \sqrt{1 + \frac{1}{2} N_1^2} = \frac{1}{2} N_2 \sqrt{1 + \frac{1}{2} N_2^2}$$

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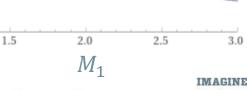
$$\frac{1}{2} N_1 \sqrt{1 + \frac{1}{2} N_1^2} = \frac{1}{2} N_2 \sqrt{1 + \frac{1}{2} N_2^2}$$

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$$\frac{1}{2} N_1 \sqrt{1 + \frac{1}{2} N_1^2} = \frac{1}{2} N_2 \sqrt{1 + \frac{1}{2} N_2^2}$$



Other downstream static properties

• 
$$\frac{T_2}{T_1} = \frac{1 + \frac{\gamma - 1}{2} M_1^2}{1 + \frac{\gamma - 1}{2} M_2^2} = \frac{\left(1 + \frac{\gamma - 1}{2} M_1^2\right) \left(\frac{2\gamma}{\gamma - 1} M_1^2 - 1\right)}{\left[\frac{(\gamma + 1)^2}{2(\gamma - 1)}\right] M_1^2}$$

• 
$$\frac{p_2}{p_1} = \frac{1+\gamma M_1^2}{1+\gamma M_2^2} = \frac{2\gamma M_1^2}{\gamma+1} - \frac{\gamma-1}{\gamma+1}$$

• 
$$\frac{\rho_2}{\rho_1} = \frac{(\gamma+1)M_1^2}{(\gamma-1)M_1^2+2}$$

• For  $M_1 > 1$ , all these ratios are > 1

- Normal shocks are not isentropic
  - How does stagnation pressure change?

• 
$$ds = c_p \frac{dT}{T} - R \frac{dp}{p} = c_p \frac{dT_t}{T_t} R \frac{dp_t}{p_t}$$

- X Stagnation temperature constant across shock
  - $s_2 s_1 = -R \ln \frac{p_{t2}}{p_{t1}}$
  - X Stagnation pressure decreases (non-isentropic loss)

- **Important:** Stronger shocks (larger  $M_1$ ) experience larger stagnation pressure loss
  - Try to avoid strong normal shocks in practical systems



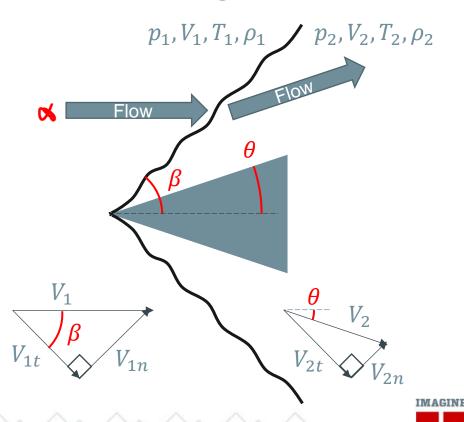
#### • Example:

• Compute  $M_2$ ,  $T_2$ ,  $p_2$  after a normal shock

$$\begin{array}{c|c}
 & M_{1} = 2 \\
 & T_{1} = 600 \text{ K} \\
 & M_{2} = 101325 \text{ Pa} \\
\hline
 & M_{1} = 101325 \text{ Pa} \\
\hline
 & M_{2} = 101325 \text{ Pa} \\$$

- What if the flow approaches the shockwave at an angle?
- New quantities
  - $\beta$  = Shock Angle
  - $\theta$  = Deflection Angle (flow angle)
- How do we tackle this problem?
  - Decompose velocity to normal/tangent
  - Treat normal component as before
  - Tangential velocity unchanged





- Jump Conditions
  - Mass:

$$\bullet \quad \rho_1 V_{n1} = \rho_2 V_{n2}$$

• N-Momentum:

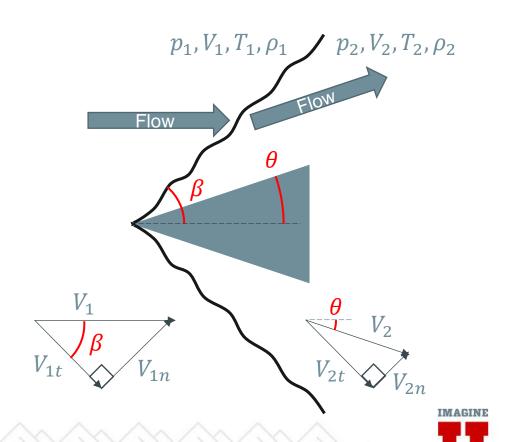
• T-Momentum:

$$V_{t2} = V_{t1}$$

• Energy:

• 
$$h_1 + \frac{1}{2}V_1^2 = h_2 + \frac{1}{2}V_2^2$$

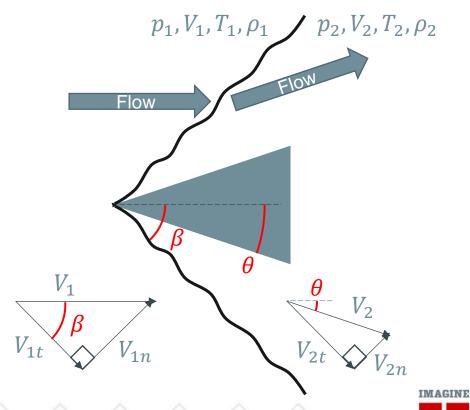
• 
$$h_1 + \frac{1}{2}V_{n1}^2 = h_2 + \frac{1}{2}V_{n2}^2$$



- Jump Conditions
  - Same conditions as normal shock
    - Just replace V with  $V_n$
  - For static properties, use same shock relations with  $M_{n1}$  and  $M_{n2}$  replacing  $M_1$  and  $M_2$  as follows:

• 
$$M_{n1} = \frac{V_{n1}}{a_1} = \frac{V_1}{a_1} \sin \beta = M_1 \sin \beta$$

• 
$$M_{n2} = M_2 \sin(\beta - \theta)$$





While these equations exist, I highly recommend avoiding them and instead working with the normal velocity component and angles

Downstream properties

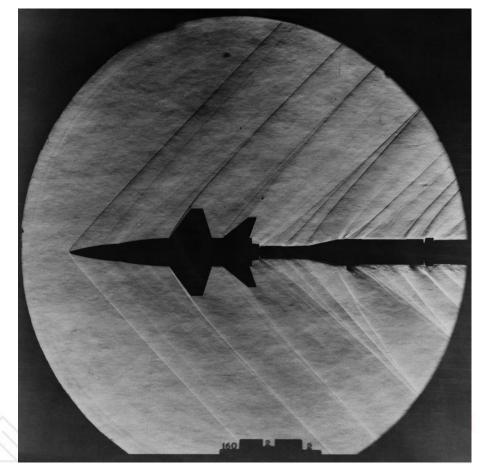
• 
$$\frac{T_2}{T_1} = \frac{\left(1 + \frac{\gamma - 1}{2} M_1^2 \sin^2 \beta\right) \left(\frac{2\gamma}{\gamma - 1} M_1^2 \sin^2 \beta - 1\right)}{\left[\frac{(\gamma + 1)^2}{2(\gamma - 1)}\right] M_1^2 \sin^2 \beta}$$

• 
$$\frac{p_2}{p_1} = \frac{2\gamma M_1^2 \sin^2 \beta}{\gamma + 1} - \frac{\gamma - 1}{\gamma + 1}$$

• 
$$\frac{\rho_2}{\rho_1} = \frac{(\gamma+1)M_1^2 \sin^2 \beta}{(\gamma-1)M_1^2 \sin^2 \beta + 2}$$

$$\bullet \frac{p_{t2}}{p_{t1}} = \left[ \frac{\frac{\gamma+1}{2} M_1^2 \sin^2 \beta}{1 + \frac{\gamma-1}{2} M_1^2 \sin^2 \beta} \right]^{\frac{\gamma}{\gamma-1}} \left[ \frac{1}{\frac{2\gamma}{\gamma+1} M_1^2 \sin^2 \beta - \frac{\gamma-1}{\gamma+1}} \right]^{\frac{1}{\gamma-1}}$$

• 
$$M_2^2 = \frac{1 + \frac{\gamma - 1}{2} M_1^2}{\gamma M_1^2 \sin^2 \beta - \frac{\gamma - 1}{2}} + \frac{M_1^2 \cos^2 \beta}{1 + \frac{\gamma - 1}{2} M_1^2 \sin^2 \beta}$$



#### • Example:

- Compute  $M_2, p_2$
- $M_1 = 2$
- $p_1 = 101325 \text{ Pa}$
- $\beta = 50$  degrees
- $\theta = 18.13$  degrees

$$M_{2} = M_{12}$$

$$M_{2} = M_{12}$$

$$Sin(\beta-0) = \frac{0.69}{5in(50^{\circ} - 18.13^{\circ})} = \frac{2(14)}{1.4-1} (1.532)^{\circ} - 1$$

$$M_{12} = 0.69$$

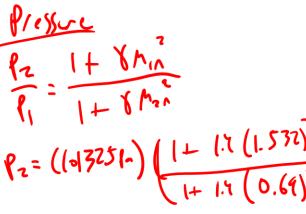
weak

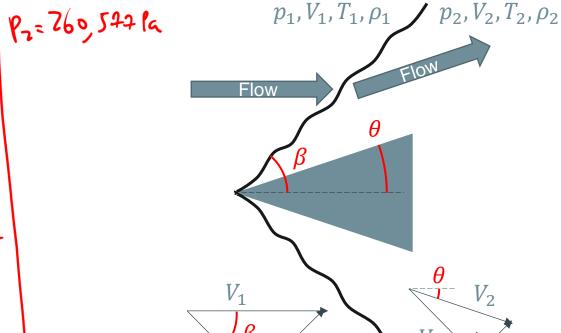
Opliance

#### Mach #

$$M_{\Lambda_1} = M_1 \sin \beta$$
 $M_{\Lambda_1} = (2) \sin (50^{\circ})$ 
 $M_{\Lambda_1} = 1.532$ 

$$\dot{M}_{N2} = 0.69$$







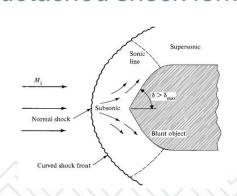
- Shock Angle
  - If given the deflection angle  $\theta$ , need to compute the shock angle  $\beta$  to evaluate the oblique shock jump conditions

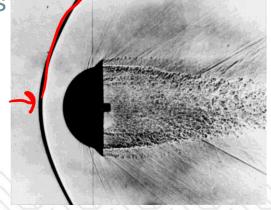
• 
$$\tan \theta = \cot \beta \frac{(M_1^2 \sin^2 \beta - 1)}{(\frac{\gamma + 1}{2} M_1^2 - (M_1^2 \sin^2 \beta - 1))}$$

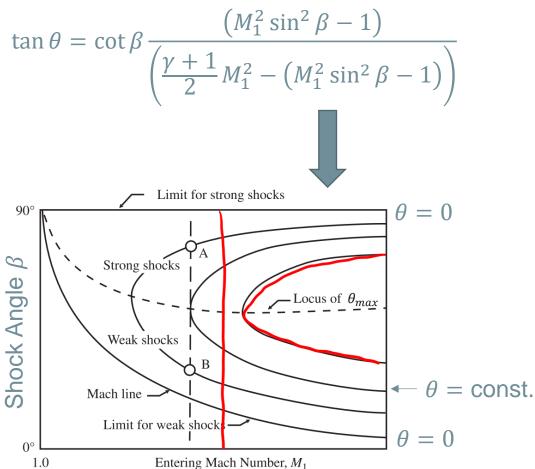
- No explicit expression for  $\beta$  in terms of  $\theta$ 
  - In this course, you will be given the shock angle

- Shock Angle
  - For given deflection angle and upstream Mach number, can be two, one, or zero possible shock angles
  - Zero angles

 Deflection angle too large, curved detached shock forms







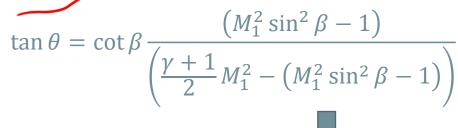


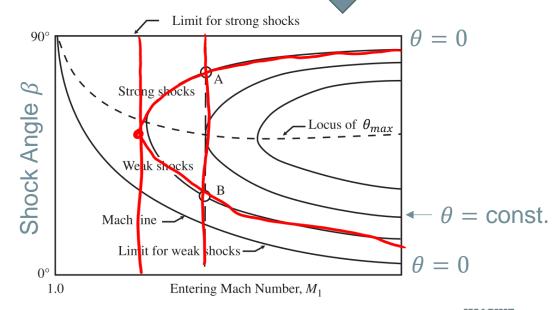






- Shock Angle
  - Two angles
    - Strong shock: Larger shock angle with subsonic  $M_2$
    - Weak shock: Smaller shock angle with generally supersonic  $M_2$
    - Exact results mainly depend on boundary conditions
    - Weak shocks are far more common in our applications – assume weak unless otherwise specified
  - One angle
    - Maximum deflection angle, strong/weak oblique shocks coincide





#### **Conical Shocks**

- Conical shocks occur in conical geometries
- Qualitatively similar to planar shocks
  - Additional considerations
- No time to discuss
- Read Farokhi if interested
  - Section 2.13

