Embedded Computing Architecture – ISAs – Assembly Language

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Outline

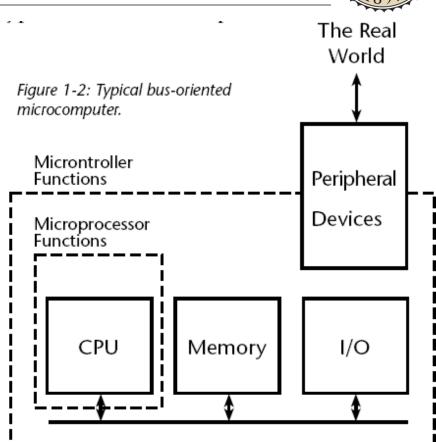


- Microcontroller vs. microprocessor
- Von Neumann vs. Harvard architectures
- AVR examples
- Instruction sets
- Assembly instructions
- Character representations
- ASCII

Microprocessor vs. Microcontroller

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- Microcontroller chip includes
 - Central processor
 - Program memory
 - Data memory
 - I/O
 - Highly integrated, low cost
- Microprocessor chip includes
 - Central processor only
 - Highest performance
 - Highest cost



Microcontroller chips



- Advantages:
 - Fewer chips required
 - Lower cost and smaller
 - Lower power (can be power optimized)
 - Fewer connections
 - More I/O pins
 - Higher reliability

Disadvantages:

- Reduced flexibility
- Expansion is limited
- Limited performance
- Limited I/O
- Design compromised to fit everything on one chip





- Modified Harvard architecture 8-bit RISC single chip microcontroller
- Complete System-on-a-chip
 - On Board Memory (FLASH, SRAM & EEPROM)
 - On Board Peripherals
- Advanced (for 8 bit processors) technology
- Developed by Atmel in 1996
- First In-house CPU design by Atmel



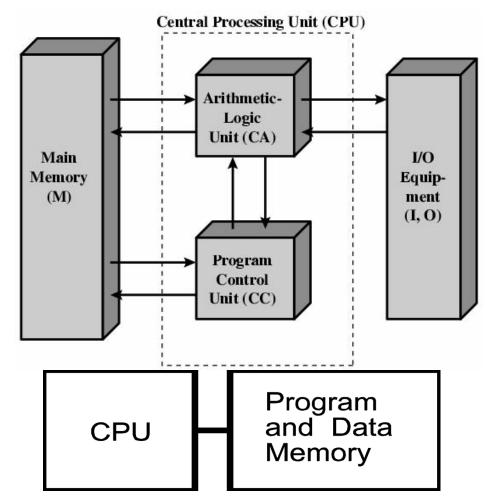


- 8 Bit tinyAVR
 - Small package as small as 6 pins
- 8 Bit megaAVR
 - Wide variety of configurations and packages
- 8 / 16 Bit AVR XMEGA
 - Second Generation Technology
- 32 Bit AVR UC3
 - Higher computational throughput

Von Neumann Architecture



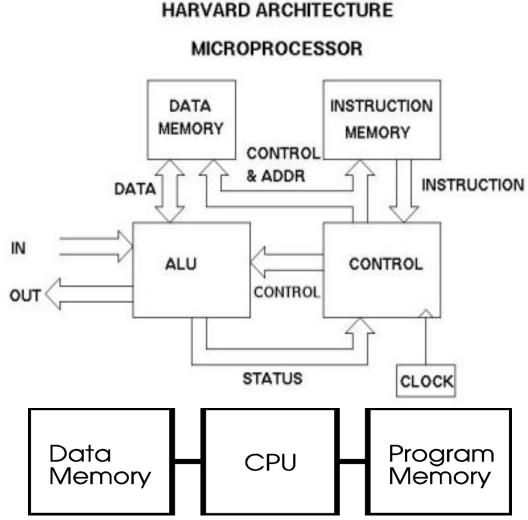
- Single memory for:
 - Programs
 - Data
- Familiar
- Most flexible
- Used in PCs
- Speed bottleneck:
 - Memory Interface



Harvard Architecture

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- Separate memory for:
 - Programs
 - Data
- Advantages:
 - Faster
 - Overlap transfers
 - Instruction Fetch
 - Data Transfer
 - Can't execute data!



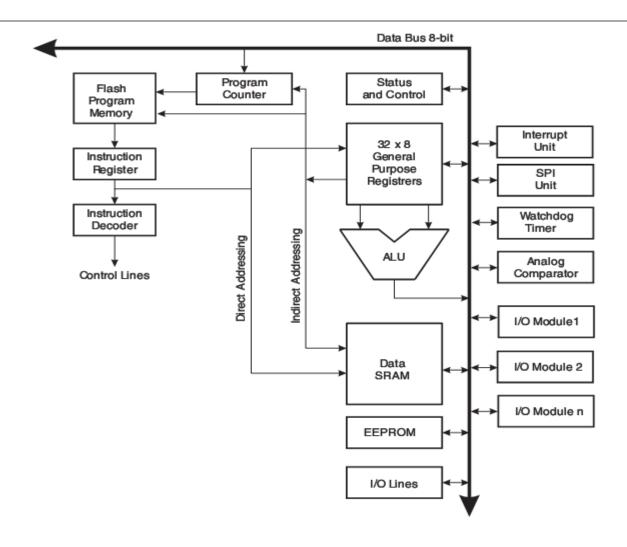




- Separate instruction and data paths
- Simultaneous accesses to instructions & data
- Hardware can be optimized for access type and bus width











- Special instructions can access data from program space
- Data memory is more expensive than program memory
- Don't waste data memory for non-volatile data

Hierarchy of Computer Design



High Level Sum := Sum + 1

Assembly MOV BX,SUM INC (BX)

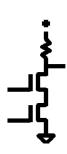
Machine 1101010100001100 0010001101110101 1111100011001

Register Transfer Fetch Instruction, Increment PC, Load ALU with SUM ...

Gate

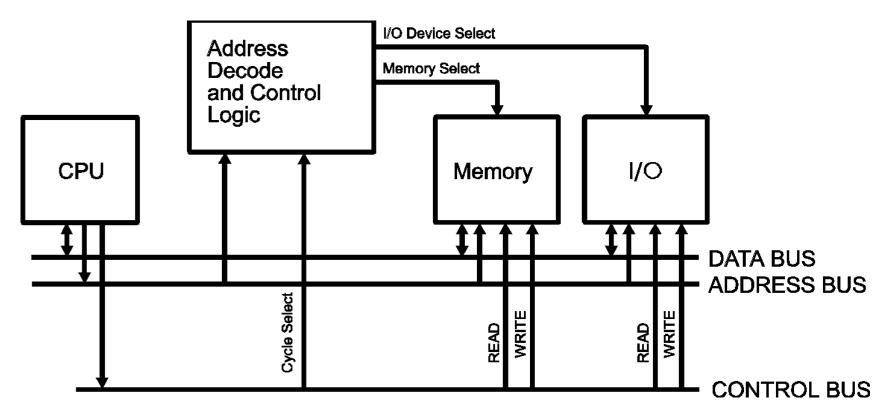
Circuit















- ISA == Instruction Set Architecture
- Common ISAs:
 - CISC, Complex: x86
 - RISC, Reduced Instruction Set:
 - 8 bit: AVR
 - 32 bit: ARM, MIPS
 - WISC: PIC, 8051...
 - WISC == Writeable instruction set computer
 - VLIW = very long instruction word





- Reduced Instruction Set Computer
- As compared to Complex Instruction Set Computers, i.e. x86
- Assumption: simpler instructions execute faster
- Optimized most used instructions
- RISC machines: AVR, ARM, PowerPC, SPARC
- Became popular in mid 1990s





- Faster clock rates
- Single cycle instructions (20 MIPS @ 20 MHz)
- Better compiler optimization
- Typically no divide instruction in core





- Directly connected to all 32 general purpose registers
- Operations between registers executed within a single clock cycle
- Supports arithmetic, logic and bit functions
- On-chip 2-cycle Multiplier





- 131 instructions
 - Arithmetic & Logic
 - Branch
 - Bit set/clear/test
 - Data transfer
 - MCU control

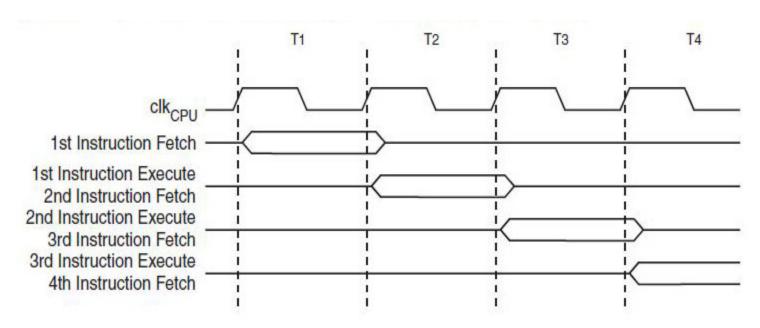




- Register ↔ register in 1 cycle
- Branch instruction 1-2 cycles
- Subroutine call & return 3-5 cycles
- Some operations may take longer for external memory











- Basic instructions:
 - INC, DEC
 - ADD, ADDC, SUBB
- Multi-byte/word Math for 8 bit CPU
 - Byte by byte: Use carry and overflow
 - Software has to do it one byte at a time!
 - (0x1FFF)+(0x0201) = (0x2200)
 - Is this a signed or unsigned example?





- INC
 - Increment
 - operands: registers, memory, +??

- DEC
 - Decrement
 - operands: registers, memory, +??





- ADD a b
 - Add a to b
 - Set carry bit if carry result
 - No dependence on carry bit in
- ADC a b
 - Add a + b plus carry bit
 - Set carry bit if carry result
 - Result depends on carry bit in





MOV destination, source?

MOV source, destination?

It depends, even with the same ISA...





- Load register with memory contents
 - Load register from memory address
- Store register at memory location
 - Store register at memory address
- x86 MOV instruction is really Load/Store

MOV Instructions



- Move between different code spaces
 - Harvard architecture requires special moves
 - Code memory is usually non-volatile
 - But it is also used for lookup tables
 - Data memory is usually volatile
 - SRAM, DRAM
 - Secondary memory:
 - Solid state: Flash, EEPROM,
 - Rotating disk: magnetic, optical

Control Transfer



- JMP/Branch addr
 - Go to address
- Conditional
- JZ jump if zero
 - if Z status bit = o
- JNZ jump if NOT zero
 - if Z status bit = o
- Same for Carry, Sign...

- CALL/BL addr
 - Save PC on stack
 - Go to subroutine address
- RET return from sub
 - Pop PC from stack
- Special: RETI
 - Return from ISR
 - Allows for Interrupts
 - "Hardware" Call





- AND Used to mask/clear specific bits
- OR Used to set specific bits
- XOR Used to toggle specific bits
- Typical Instructions (bitwise and bit oriented)
 - ANL, ORL, XRL, CLR, SET, CPL
- C language equivalents
 - & bitwise AND, | bitwise OR, ^ bitwise XOR
 - Don't confuse with logical operations: &&, ||





- ASCII
- ISO Latin 1
- Unicode
- Baudot
- EBCDIC

ASCII



- American Standard Code for Information Interchange
- 7 bit code: Values 128..255 are undefined!
- Used extensively with serial communications
- Formally defined by ANSI X_{3.4}.
- Subset of ISO Latin 1, which also defines characters for European languages.
- Other extended codes: 8+bit supersets of ASCII

ASCII Printable Characters



- Digits, Alphabet, Specials
 - Digits are 30h..39h
 - Alphabet
 - 'A'..'Z' are 41h..5Ah
 - 'a'..'z' are 61h..7Ah
 - Specials are '+', <space>, '>', <bell>
- See ASCII tables:
 - https://en.wikipedia.org/wiki/ASCII





- Null or \o == oxoo
- Newline \n or End-of-line (EOL)
- May be single control character: Unix uses oxA (line feed)
- May be multiple control characters: MS uses oxD, oxA (carriage return+line feed)
- Transmitter and receiver must agree
- Unix vs. MS





- BCD (Binary Coded Decimal)
- Fixed point
- Floating point
- Error Detection and Correction Coding
 - Parity
 - Hamming Codes
 - Block Error Coding