

Properties of new lens: Target Depth (Z) of each CCD segment

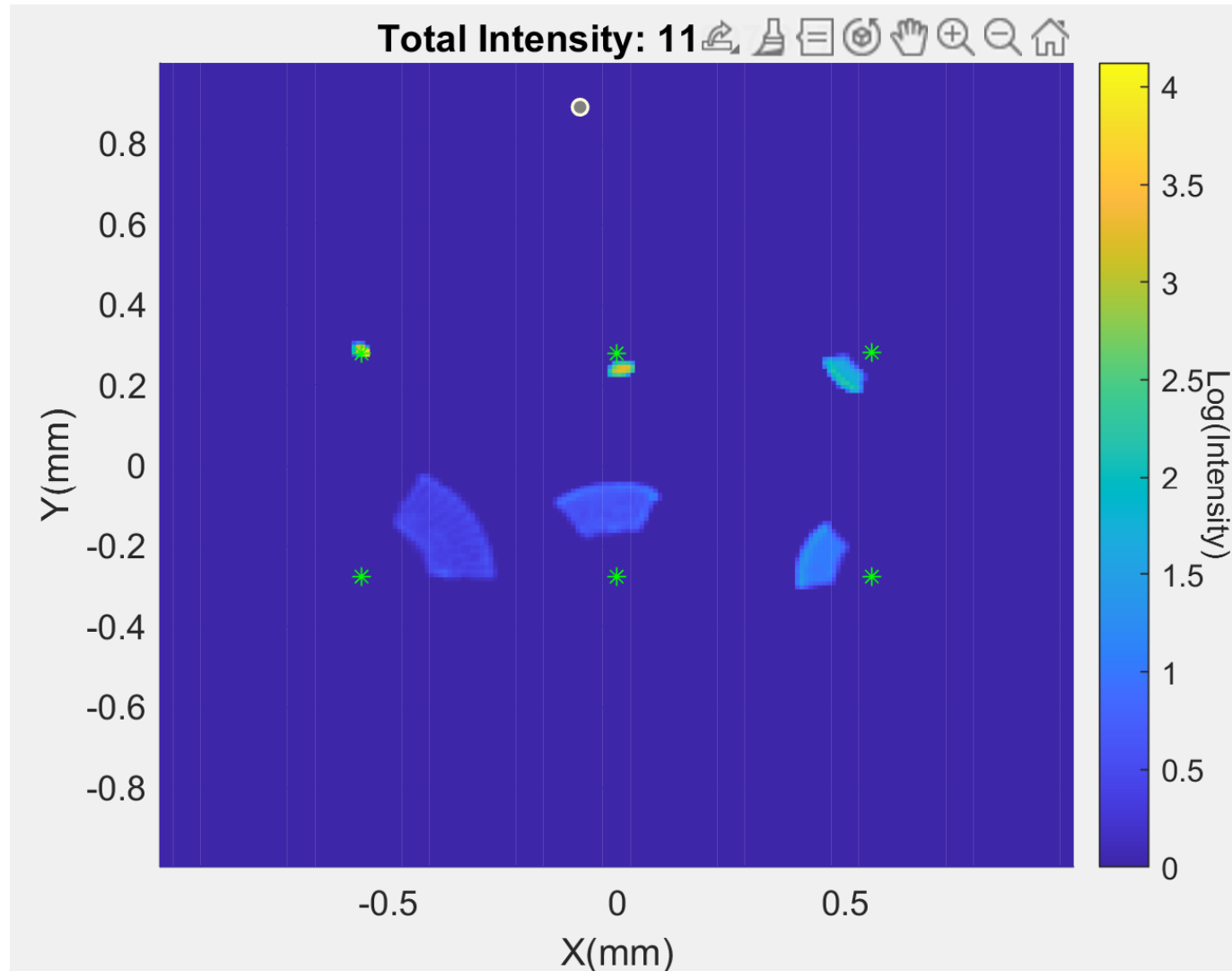
Segment 1 (Z = -5.75)	Segment 2 (Z = -5.85)	Segment 3 (Z = -5.95)
Segment 6 (Z = -6.25)	Segment 5 (Z = -6.15)	Segment 4 (Z = -6.05)

Properties of new lens: Target Range (X/Y) of each CCD segment

	-0.837	-0.279	0.279	0.837
0.558	Centre (-0.558, 0.279)			Centre (0.558, 0.279)
0.000	Centre (-0.559, -0.279)			Centre (0.559, -0.279)
-0.558	Centre (0.000, -0.279)			

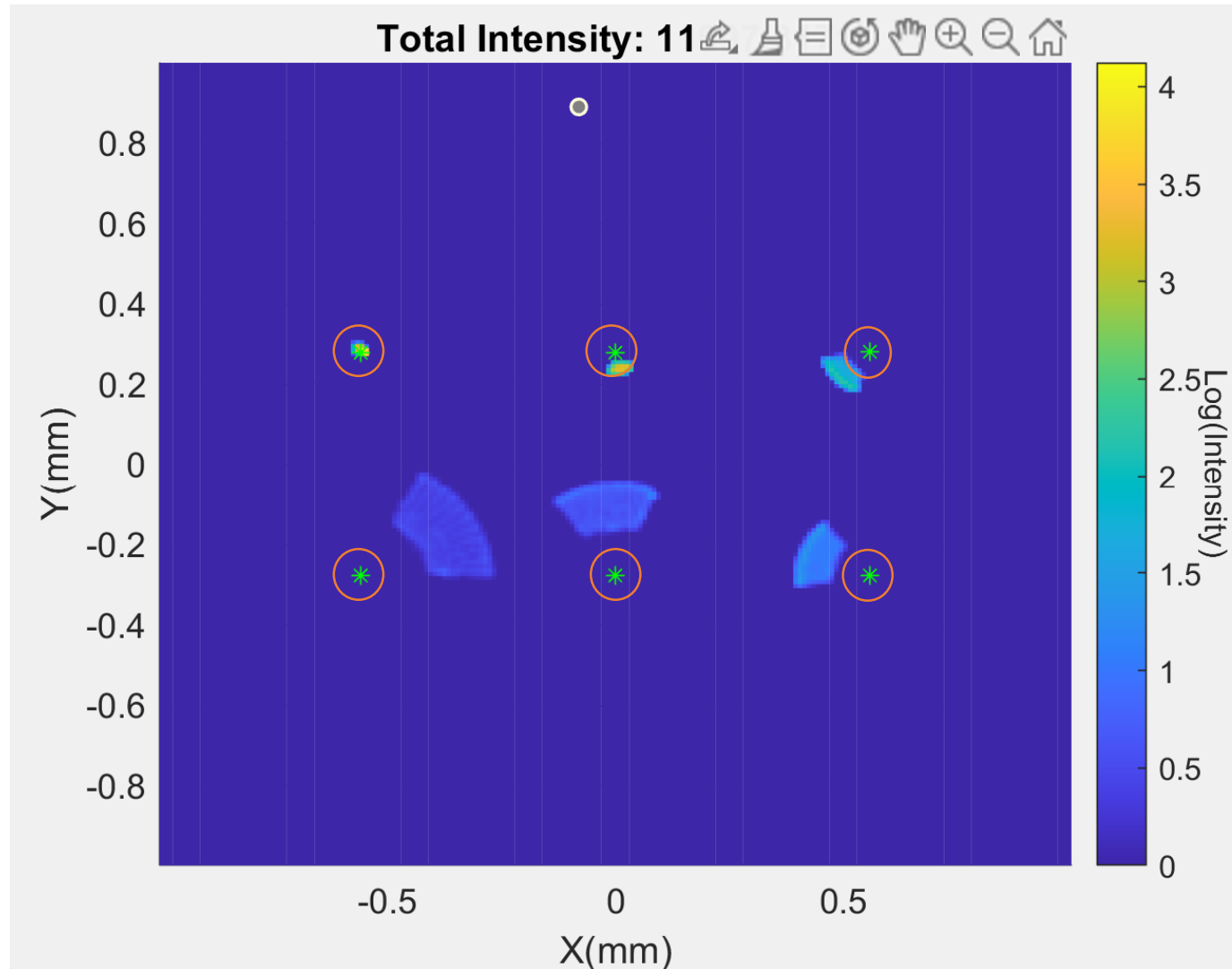
Illumination produced by object point placed at  $(0,0,-5.75)$

**PROBLEM:** Even so the object is placed at  $(X=0,Y=0)$ , it is centered only for the brightest peak!  
(i.e: the peak and green cross are at same location)



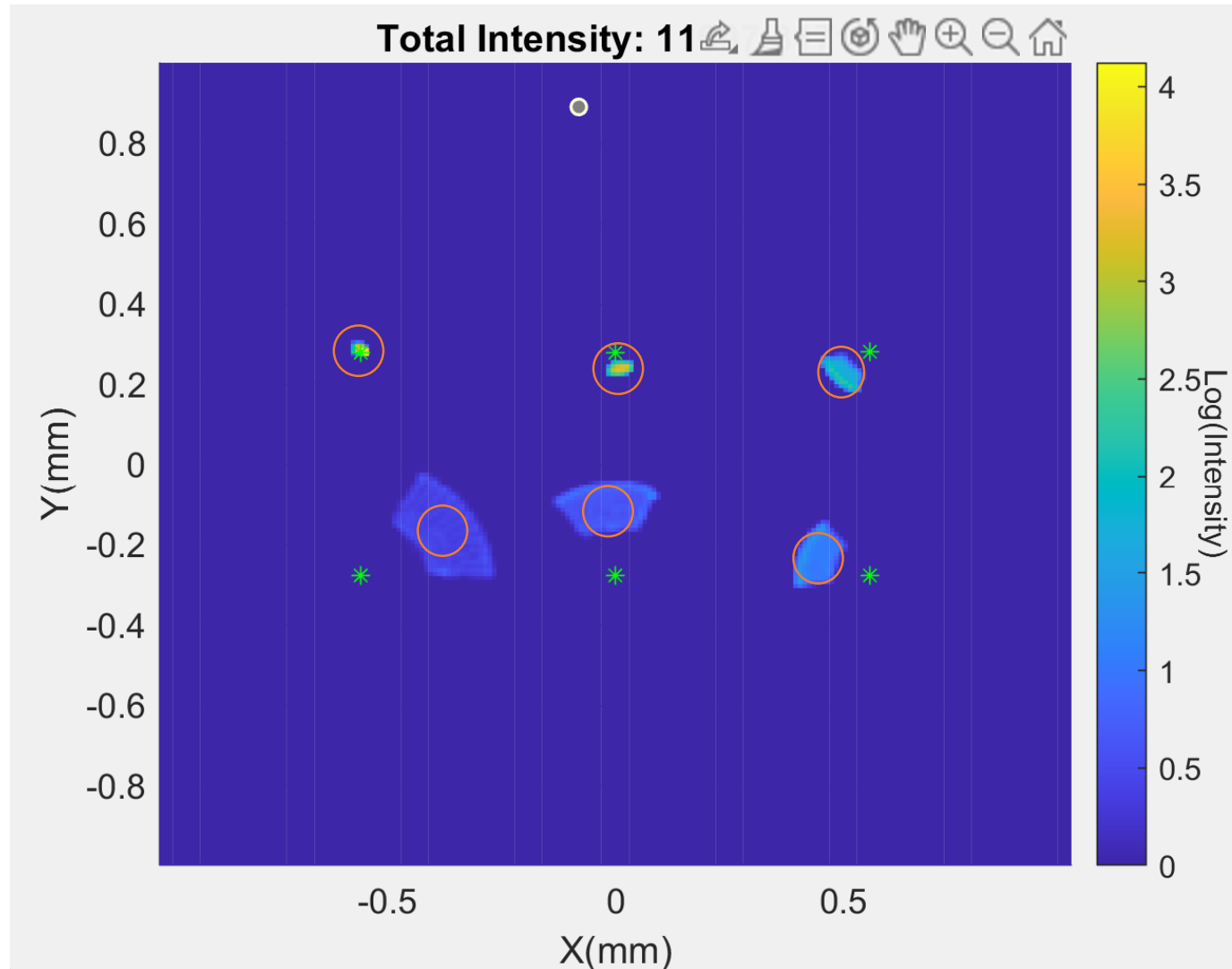
Illumination produced by object point placed at (0,0,-5.75)

**PROBLEM:** When searching for peaks belonging to the same group, the peaks are quickly out of the search range.



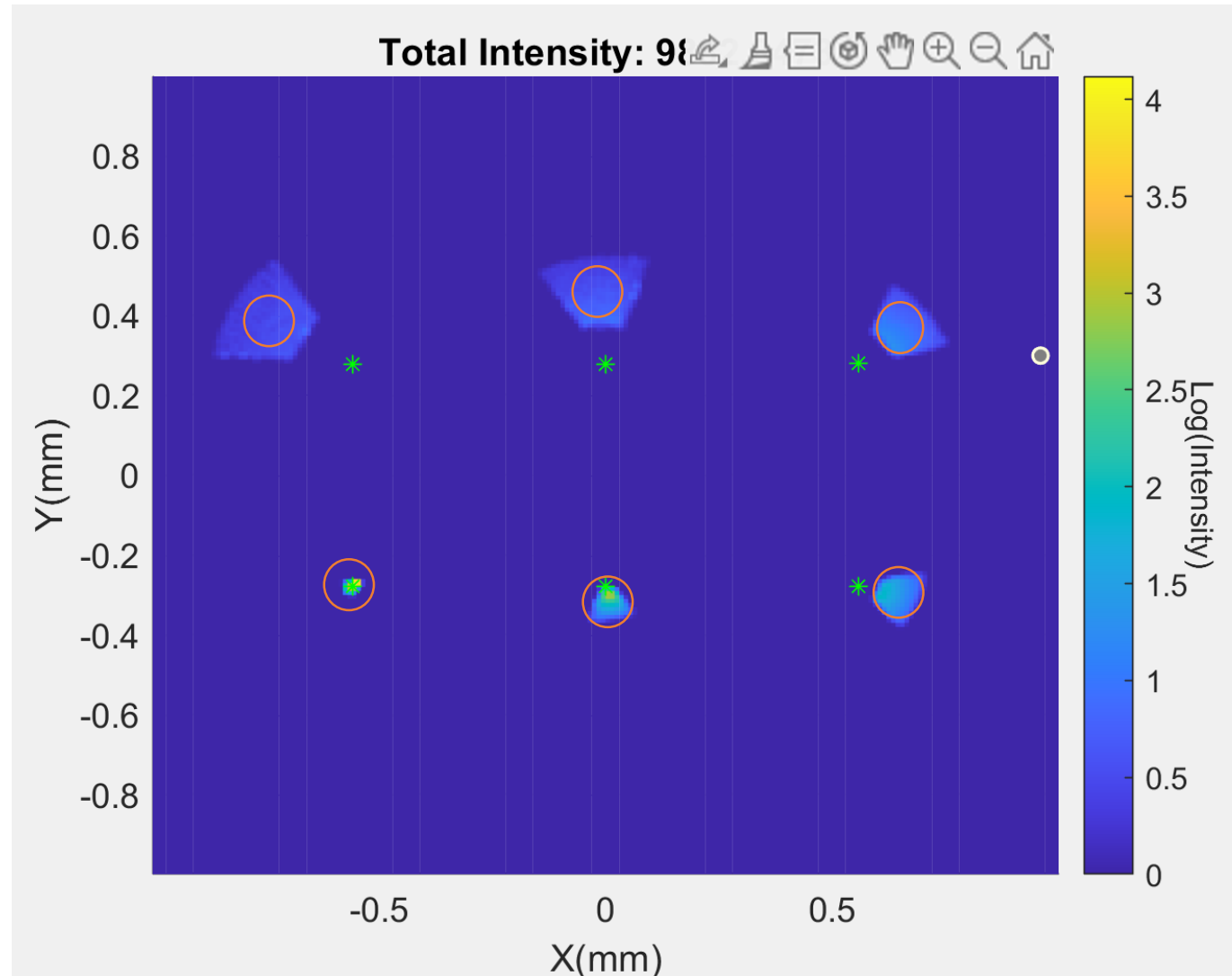
Illumination produced by object point placed at (0,0,-5.75)

**SOLUTION:** After selecting a bright peak, it is necessary to offset the search zone when looking for the other peaks



Illumination produced by object point placed at (0,0,-6.25)

**SOLUTION:** After selecting a bright peak, it is necessary to offset the search zone when looking for the other peaks



## Tasks for next week:

- Using the 6 images in the archive called “calibration.zip”:
  - Read each calibration image then perform the Gaussian blurring.
  - Detect the position of all 6 peaks (**WITHOUT** thresholding)
  - For each peak, save the offset between the peak position and center of segment in a table, as follows:

	Calib 1	Calib 2	Calib 3	Calib 4	Calib 5	Calib 6
Object	(0,0,-5.75)	(0,0,-5.85)	(0,0,-5.95)	(0,0,-5.75)	(0,0,-5.75)	(0,0,-5.75)
Segment 1	0.000, 0.000	?	?	?	?	?
Segment 2	?	0.000, 0.000	?	?	?	?
Segment 3	?	?	0.000, 0.000	?	?	?
Segment 4	?	?	?	0.000, 0.000	?	?
Segment 5	?	?	?	?	0.000, 0.000	?
Segment 6	?	?	?	?	?	0.000, 0.000

## Tasks for next week:

2. Analyse the images in the archive scanXYZ.zip:

- Read each image then perform the Gaussian blurring.
- Detect the peaks positions (**WITH** 10% thresholding)
- Select the brightest peak and record it coordinates ( $x_p, y_p$ ) and segment number as  $\text{Calib}_p$ .
- Search for associated peaks in another segment “n” at the coordinates:  $(x_p + x_{\text{offset}}, y_p + y_{\text{offset}})$ .  
Where  $(x_{\text{offset}}, y_{\text{offset}})$  corresponds the value  $\text{Calib}_p / \text{Segment}_n$  in previous table.

