What does a typical analys scheme look like?

5 Programming the PSE elements

We would like to program: (i) the least squares criterion (consisting of weighted residuals and penalties), (ii) the parameter vector (enabling fixed/free parameters, relations, functional description with higher level parameters, e.g. thermodynamic parameters), (iii) the weighted data, which means compiling the data (e.g. linking) and programming the weights. Special data can be added (with weights) to include apriori knowledge e.g. candidate SAS shapes. The weighted data can be decomposed into *P* parts:

$$\psi_p = X_p(\theta)\beta_p \qquad p = 1, ..., P \tag{107}$$

where each part  $\psi_p$  contains  $n_p$  observations, with weight  $w_p$ , which can be either a scalar or a vector of length  $n_p$ . (iv) the matrices  $X_p(\theta)$  using hierarchical models.

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5.1 Programming the least squares criterion

The weighted residuals are defined as: how calculated how  $z_p = w_p(\psi_p - X_p(\theta)\hat{\beta}_p)$ 

$$z_p = w_p \left( \overline{\psi_p - X_p(\theta) \hat{\beta}_p} \right) \tag{108}$$

Their sum of squares gives

$$SSE(\theta) = \sum_{p=1}^{P} z_p^T z_p$$
 (109)

The conditionally linear parameters  $\beta_p$  can be solved for using the variable projection algorithm, possibly with constraints (e.g. non-negative least squares when the  $\beta_p$  represent non-negative SAS). The penalties from (i) are derived from e.g. the spectra. Thus when spectral constraints (zero, or equality) are used, first the SAS must be resolved from all  $\beta_p$ . Then the area constraint penalty can be computed

instraint penalty can be computed   

$$\begin{array}{c} \text{Removing collams of } \times \text{ or} \\ \text{ refling } \times \text{ps} = \times \text{ps} \text{ thus removing } \times \text{ps} \\ \text{penalty}_{ij} = weight_{ij} \int_{\lambda_{min}}^{\lambda_{max}} \left| SAS_i(\lambda) - \alpha_{ij} SAS_j(\lambda) \right| d\lambda \\ \end{array} \\ \times \text{ps}_{5d} = \times \text{ps}_{5d} \times \text{p$$

In practice, with emission SAS, the proportionality factor  $\alpha_{ii}$  (which is not a parameter) equals one for species with (approximately) equal oscillator strength. The weight is adjusted such that the relative importance of the penalties is not too large, e.g. about 1% of the

 $SSE(\theta)$ . The sum of all penalties and  $SSE(\theta)$  is called  $\Upsilon(\theta)$ . can this be comparted?

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### 5.2 Programming the parameter vector

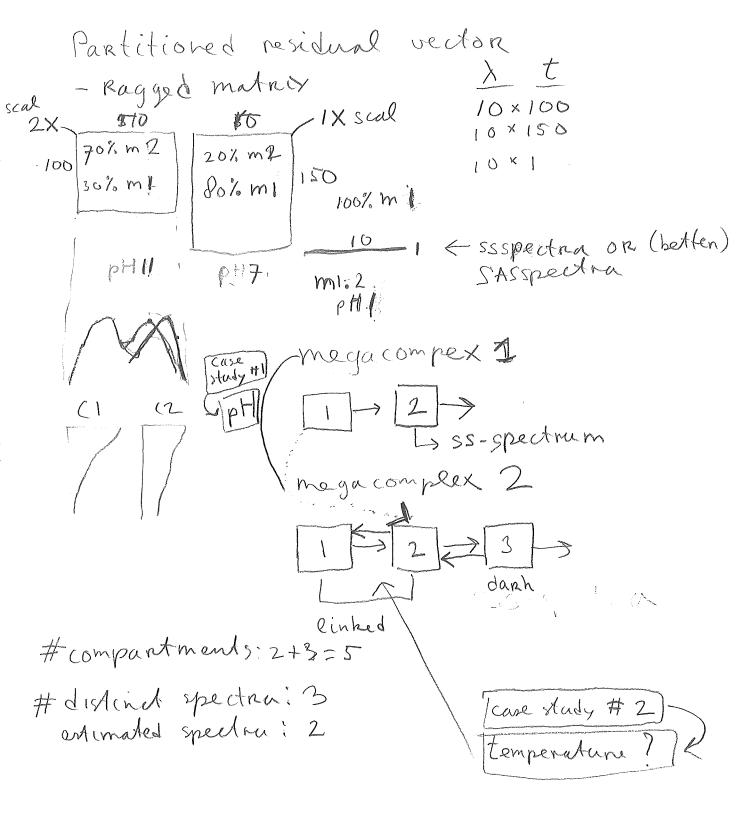
In Kate's thesis the hierarchical modelling of the parameter vector is explained. The user specifies the models and the necessary intrinsically nonlinear parameters. Further specifications are fixed/free parameters, relations between parameters, functional description with higher level parameters (e.g. thermodynamic parameters), detailed balance relations between microscopic rates for a clockwise or anticlockwise traversal of a cycle, constraints on parameters, etc. The optimizer only sees a subset of free parameters  $\tilde{\theta}$ , and minimizes  $\Upsilon(\tilde{\theta})$ . In the function that computes  $\Upsilon(\tilde{\theta})$  (the functor?) this  $\tilde{\theta}$  is then translated to the full parameter vector  $\Theta$  (thereby resolving all the constraints and relations). From  $\Theta$  all sorts of subsets for different aspects of the kinetic model are then extracted, such as microscopic rates, IRF, linking, scaling, inputs or absorptions, fractions, anisotropy, dumping, frequency and damping rate of damped oscillations, etc. With spectral models a parametric description is sought of spectral shape, Stark effect, time or temperature dependence, etc.

#### 5.3 Programming the weighted data

Each part consists of subparts, which are the experiments. Each experiment has its own IRF, which in general is wavelength dependent (thus differs for all parts). Weight  $w_p$  can be either a scalar or a vector of length  $n_p$ . The programming of  $w_p$  is possible both at the part level or at the subpart level. Special data that represent apriori knowledge on candidate SAS shapes are a special subpart with a single data point (the value at the wavelength of the part). The linkelp mechanism links those wavelengths in different experiments whose difference is less than a tolerance *linktol*. Typically, *linktol* must be smaller than the smallest wavelength step divided by 2, to avoid linking all data. Most often all experiments are linked (because the spectra can be assumed to be equal), although it is possible to specify a linkage scheme (which would be appropriate when analysing multiple experiments at different temperatures, where the spectra differ for with temperature).

# 5.4 Programming the matrices $X_p(\theta)$ using hierarchical models

An example was given in Hierarchical modelling of time-resolved polarized difference absorption on page 79. Here we describe two new developments: usage of megacomplexes and damped oscillations (for now, see separate pdf).



## 5.4.1 Megacomplexes

Assume that we have M megacomplexes. Each megacomplex m is described by a linear compartmental model with  $n_m$  compartments. The differential equation for the concentrations of megacomplex m is:

$$\frac{d}{dt}c_m(t) = K_m c_m(t) + j_m(t)$$
(111)

where the input to the system is described by a vector  $j_m(t) = i(t) \begin{bmatrix} x_1 & x_2 & \dots & x_{n_m} \end{bmatrix}^T$ , with i(t) the IRF (§2.1.1) and  $x_l$  representing the input to compartment l. Note that each megacomplex can contain only a *subset* of all the species present in the system. An extreme case are special data that represent apriori knowledge on candidate SAS shapes. In that case the full c vector contains only one non-zero element for the index of the candidate SAS. In addition a scaling parameter is still necessary. The amount of megacomplex m present in an experiment is determined by the parameters that describe the inputs  $x_l$ . The inputs  $x_l$  contains two elements: the absorption and the amount present of species l. The absorption is dependent upon the excitation wavelength, and is common for all equivalent experiments.

The modelling is summarized in Table 5. Note the intricate summations needed for  $X_p(\theta)$  , for

Table 5 Hierarchical modelling of time-resolved emission with megacomplexes

level of modelling	parametric description of	
linking of experiments, resolving the parts, computation of $X_p(\theta)$	relative scaling, linkage schemes	§2.7.5.2
resolving the spectral constraints, $c_l(t)\varepsilon_l(\lambda)$	spectral constraints for component $l$ , $\varepsilon_l(\lambda)$	§2.7.2
summation over all complexes containing component $l: c_l(t) = \sum_{m=1}^{M} c_{l \in m}(t)$		
convolution $c_m(t) = c_m^{\delta}(t) \otimes i(t)$	Instrument Response Function $i(t)$	§2.4.2
MA concentration $c_m^{\delta}(t)$ with $\delta$ -input	compartmental scheme for megacomplex $m$ with microscopic rates for $n_m$ compartments	§2.4.3

each experiment all  $c_m(t)$  have to be computed for those megacomplexes that are present in that experiment, taking into account the appropriate inputs  $\begin{bmatrix} x_1 & x_2 & \dots & x_{n_m} \end{bmatrix}^T$ . Furthermore, keeping track of the indices is essential.

