* The trackers are initialiazed with a list of bboxes. The bboxes are:

cv2.rectangle(image, start\_point, end\_point, color, thickness)

*image 🡪 image as taken from cvCapture.read()*

*start\_point 🡪 (x, y)*

*end\_point 🡪 (x, y)*

*color 🡪 BGR (not RGB)*

*thickness 🡪 integer in* ***px***

*return value 🡪 image*

* multitracker.update(frame):

return value 🡪 success, boxes

*success 🡪 bool*

*boxes 🡪 list of cv2.rectangle(….)*