

Problem 1

$$\int_C \vec{F} \times d\vec{r}, \quad \vec{F} = y\hat{i} + x\hat{j} \quad (0, 0, 0) \quad (3, 0, 0)$$

$$y = \frac{x^3}{3}, \quad z = 0$$

$$\text{Let } x = t$$

$$\Rightarrow y = \frac{t^3}{3}$$

$$r = x\hat{i} + y\hat{j} + z\hat{k}$$

$$r = t\hat{i} + \frac{t^3}{3}\hat{j} + 0\hat{k}$$

$$dr = (\hat{i} + t^2\hat{j})dt$$

$$F = \frac{t^3}{3}\hat{i} + t\hat{j}$$

$$\Rightarrow \vec{F} \times d\vec{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{t^3}{3} & t & 0 \\ 1 & t^2 & 0 \end{vmatrix} = 0\hat{i} + 0\hat{j} + \left(\frac{t^5}{3} - t\right)\hat{k}$$

$$\int_0^3 \left(\frac{t^5}{3} - t\right) dt = \hat{k} \left[\frac{t^6}{18} - \frac{t^2}{2} \right]_0^3$$

$$= [0, 0, 36]$$

Problema 4 $\oint_C P dx + Q dy = \iint_S \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$

como

$$r = P \hat{i} + Q \hat{j} \quad y \quad ds = K dx dy$$

$$\nabla \times r = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & 0 \end{vmatrix} = -\frac{\partial Q}{\partial z} \hat{i} + \frac{\partial P}{\partial z} \hat{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) \hat{k}$$

$$r \cdot dr = P dx + Q dy$$

$$\nabla \times r \cdot ds = \nabla \times r \cdot K dx dy = \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy$$

$$\therefore \oint_C P dx + Q dy = \iint_R \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy \quad \text{qed}$$

então $\oint_C (3x + 4y) dx + (2x - 3y) dy$

onde C é o círculo $x^2 + y^2 = 4$

$$x = 2 \cos t, \quad y = 2 \sin t \quad 0 \leq t \leq 2\pi$$

$$\int_0^{2\pi} (3(2 \cos t) + 4(2 \sin t))(2 \cos t) + (2(2 \cos t) - 3(2 \sin t))(2 \sin t) dt$$

$$= \int_0^{2\pi} (6 \cos^2 t + 16 \sin t \cos t + 4 \cos^2 t - 6 \sin^2 t) dt$$

$$= \boxed{-8\pi}$$

Problema 5

$$\vec{F}(\rho, \phi) = f_\rho(\rho, \phi) \hat{e}_\rho + f_\phi(\rho, \phi) \hat{e}_\phi$$

$$\nabla \times \vec{F}$$

$$\nabla \times \vec{F} = \begin{vmatrix} \hat{e}_\rho & \hat{e}_\phi & \hat{e}_z \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ f_\rho & f_\phi & 0 \end{vmatrix} = \frac{\partial f_\phi}{\partial z} \hat{e}_\rho + \frac{\partial f_\rho}{\partial z} \hat{e}_\phi + \left(\frac{\partial f_\phi}{\partial \rho} - \frac{\partial f_\rho}{\partial \phi} \right) \hat{e}_z$$

Como

$f_\rho(\rho, \phi)$ y $f_\phi(\rho, \phi)$ no dependen de z

$$\Rightarrow \frac{\partial f_\rho}{\partial z} = \frac{\partial (f_\rho(\rho, \phi))}{\partial z} = 0$$

además

$$\frac{\partial f_\phi}{\partial z} = \frac{\partial (f_\phi(\rho, \phi))}{\partial z} = 0$$

$$\therefore \nabla \times \vec{F} = \left(\frac{\partial (f_\phi(\rho, \phi))}{\partial \rho} - \frac{\partial (f_\rho(\rho, \phi))}{\partial \phi} \right) \hat{e}_z$$

y por tanto solo tiene componente en z y en ϕ