آزمایش پنجم میکروپروسسور گروه5:محسن فرج پور، عرفان میرحاجی، امیرمحمدحریمی

```
#include "LPC17xx.h"
#include "timer.h"
#include "adc.h"
#include "apio.h"
#include "lcd.h"
#include "uart.h"
// variables
char password[] = "%GROUP 05\n";
char received[8];
char i = 0;
// functions
int main(void)
       //system
      SystemInit();
       //adc pin direction
      GPIO_PinDirection(PO_23,INPUT);
      GPIO PinDirection (PO 24, INPUT);
      GPIO PinDirection (PO 25, INPUT);
      GPIO PinDirection (PO 26, INPUT);
       //lcd pin direction & init
      GPIO PinDirection(PO 0, INPUT);
      GPIO_PinDirection(PO_1,INPUT);
      GPIO PinDirection(P0 2,INPUT);
      GPIO_PinDirection(PO_4,INPUT);
       GPIO_PinDirection(P0_5,INPUT);
      GPIO_PinDirection(PO_6,INPUT);
      GPIO_PinDirection(PO_7,INPUT);
      LCD_SetUp(P0_0,P0_1,P0_2,P_NC,P_NC,P_NC,P_NC,P_NC,P0_4,P0_5,P0_6,P0_7);
      LCD Init(2,16);
      LCD Clear();
       //uart2 init
      UART2 Init(9600);
       for (i=0;i<=9;i++)
             UART2 TxChar(password[i]);
       for (i=0;i<=6;i++)
             received[i] = UART2 RxChar();
      LCD GoToLine(0);
      LCD_Printf("GROUP 05");
      LCD GoToLine(1);
      LCD Printf("pass = %s", received);
```

رمز عبور:



از تابع sprintf برای تبدیل اعداد دسیمال به رشته استفاده شده است، خروجی ها در فیلم موجود است. (زمان ارسال :9.24 دقیقه AM صبح چهارشنبه)





کاارکتر #

```
#include "LPC17xx.h"
#include "timer.h"
#include "adc.h"
#include "gpio.h"
#include "lcd.h"
#include "uart.h"
#include "stdio.h"
// variables
int voltage = 0;
int light = 0;
int temp = 0;
int humid = 0;
char password[] = "%GROUP 05\n";
char received[8];
char c = 0;
int i = 0;
char message_ok;
char string i[1];
char string_temp[2];
char string_light[4];
char string_volt[4];
char string_humid[2];
// functions
int voltage sensor(void);
int light intensity(void);
int temperature_sensor(void);
int humidity_sensor(void);
void myFunction(void)
      i++;
             if(i<=10)
             {
                    LCD GoToLine(0);
                    LCD Printf("&05-");
                    UART2 TxString("&05-");
                    LCD Printf("%s-",received);
                    UART2_TxString(received);
                    UART2_TxChar('-');
                    LCD Printf("%d-",i);
                    sprintf(string_i, "%d", i);
                    UART2_TxString(string_i);
                    UART2_TxChar('-');
                    LCD Printf("%d-",voltage sensor());
                    sprintf(string_volt, "%d", voltage_sensor());
                    UART2_TxString(string_volt);
```

```
UART2 TxChar('-');
                     LCD Printf("%d-",light intensity());
                     sprintf(string light, "%d", light intensity());
                     UART2_TxString(string_light);
                     UART2 TxChar('-');
                     LCD Printf("%d-", temperature sensor());
                     sprintf(string temp, "%d", temperature sensor());
                     UART2 TxString(string temp);
                     UART2_TxChar('-');
                     LCD Printf("%2d", humidity sensor());
                     sprintf(string humid, "%d", humidity sensor());
                     UART2 TxString(string_humid);
                     UART2 TxChar('\n');
                     message ok = UART2 RxChar();
                     LCD Printf("%c",message ok);
              if(i > 10)
              {
              }
}
int main (void)
       //system
       SystemInit();
       //adc pin direction
       GPIO PinDirection (PO 23, INPUT);
       GPIO PinDirection(P0_24,INPUT);
       GPIO_PinDirection(P0_25,INPUT);
       GPIO PinDirection (PO 26, INPUT);
       //lcd pin direction & init
       GPIO PinDirection (PO 0, INPUT);
       GPIO PinDirection(PO 1,INPUT);
       GPIO PinDirection(P0 2,INPUT);
       GPIO_PinDirection(PO_4,INPUT);
       GPIO PinDirection (PO 5, INPUT);
       GPIO PinDirection(PO 6, INPUT);
       GPIO PinDirection (PO 7, INPUT);
       LCD_SetUp(P0_0,P0_1,P0_2,P_NC,P_NC,P_NC,P_NC,P_NC,P0_4,P0_5,P0_6,P0_7);
       LCD_Init(2,16);
       LCD Clear();
       // adc init
      ADC Init();
       //uart2 init
       UART2 Init(9600);
       for (c=0; c <=9; c++)
              UART2 TxChar(password[c]);
       for (c=0; c<=6; c++)
             received[c] = UART2 RxChar();
       //timer
       TIMER Init(TIMER 1, 10000000);
       TIMER AttachInterrupt (TIMER 1, myFunction);
       TIMER Start(TIMER_1);
       while(1){}
```

```
}
int voltage sensor(void)
      int x;
      x = (ADC\_GetAdcValue(0)*3300/(4096));
      return x;
int light intensity(void)
{
      int x;
      x = (ADC GetAdcValue(1));
      x = 10000 - ((x*9990)/4096);
      return x;
int temperature sensor(void)
      int x;
      x = (ADC GetAdcValue(2));
      x = (x*330)/4096;
      return x;
int humidity_sensor(void)
      x = ((3300 - ((ADC_GetAdcValue(3)*3300)/(4096)))/3300)*100;
      return x;
```

سوال سوم:

متن خوانده شده به صورت زیر است (پس از capitalize first letter):



باید مشابه سوال قبل ارسال شده و کاراکتر شارپ دریافت شود: (ارسال 9.19 چهارشنبه صبح AM)

```
#include "LPC17xx.h"
#include "timer.h"
#include "adc.h"
#include "gpio.h"
#include "lcd.h"
#include "uart.h"
#include "stdio.h"
#define MAX 53
// variables
char password[4] = \$05\n";
char received[MAX];
char i = 0;
char message ok;
char str[MAX];
int main (void)
      //system
      SystemInit();
       //adc pin direction
      GPIO PinDirection (PO 23, INPUT);
      GPIO_PinDirection(PO_24,INPUT);
```

```
GPIO PinDirection (PO 25, INPUT);
       GPIO PinDirection (PO 26, INPUT);
       //lcd pin direction & init
      GPIO_PinDirection(PO_0,INPUT);
      GPIO PinDirection (PO 1, INPUT);
       GPIO PinDirection (PO 2, INPUT);
       GPIO_PinDirection(PO_4,INPUT);
      GPIO PinDirection(P0 5,INPUT);
      GPIO PinDirection(PO 6,INPUT);
      GPIO_PinDirection(PO_7,INPUT);
      LCD SetUp(P0 0,P0 1,P0 2,P NC,P NC,P NC,P NC,P0 4,P0 5,P0 6,P0 7);
      LCD Init(2,16);
       LCD Clear();
       //uart2 init
      UART2_Init(9600);
       for (i=0;i<=3;i++)
             UART2_TxChar(password[i]);
       for (i=0;i<=MAX;i++)</pre>
              received[i] = UART2_RxChar();
for(i=0; received[i]!='\0'; i++)
             if(i==0)
              {
                     if((received[i]>='a' && received[i]<='z'))</pre>
                     received[i]=received[i]-32;
                     continue;
              }
              if(received[i]==' ')
              {
                     ++i;
                     if(received[i]>='a' && received[i]<='z')</pre>
                            received[i]=received[i]-32;
                            continue;
                     }
              }
              else
                     if(received[i]>='A' && received[i]<='Z')</pre>
                            received[i]=received[i]+32;
              }
       }
       /*LCD GoToLine(0);
       for(i=32;i<=MAX;i++)
              LCD Printf("%c",received[i]);
       } * /
       UART2 TxString("@05:");
      UART2 TxString(received);
      UART2 TxChar('\n');
      message ok=UART2 RxChar();
      LCD Printf("%c", message ok);
}
```

